### MAT22A-Waldron-Fall-2010

## WeBWorK ReadingHomework1 is due : 09/27/2010 at 11:59pm PDT.

Visit http://www.math.ucdavis.edu/ wally/teaching/22A/22A.html for the syllabus, grading policy and other information.

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Give 4 or 5 significant digits for (floating point) numerical answers. For most problems when entering numerical answers, you can if you wish enter elementary expressions such as  $2 \wedge 3$  instead of 8, sin(3 \* pi/2)instead of -1,  $e \wedge (ln(2))$  instead of 2,  $(2 + tan(3)) * (4 - sin(5)) \wedge 6 - 7/8$  instead of 27620.3413, etc. Here's the **list of the functions** which WeBWorK understands.

You can use the Feedback button on each problem page to send e-mail to the professor.

Which of the following equations is linear? Select all that apply.

- A.  $\sqrt{x} = y$
- B. 12x = 11y 20
- C.  $\frac{4x 2y}{7} = \frac{-4x + 5y}{19}$

р	4x - 2y	_	19
D.	7	_	$\overline{-4x+5y}$

- E.  $\sin x + 9y = -6$
- F.  $x^2 + y^2 = -6$
- G. 12x + 11y = -20

Compute the product:	5	-4 ]	-3	]_[	]
Compute the product.	2	6	-2		]

#### MAT22A-Waldron-Fall-2010

### WeBWorK ReadingHomework2 is due : 09/29/2010 at 03:00pm PDT.

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					-2x - 2y + 9z = 58
Consider the following even ented matrix	1	3	19 15	21	29
Consider the following augmented matrix:	9 11	5 7	15 23	13	$\begin{vmatrix} 25\\17 \end{vmatrix} \qquad 9x + 9y - 3z = 39$
Using the notation from the lecture notes, what	are tl	ne v	alues	of	
the following entries?					
$a_1^2 = \_\_$				has the following augmented matrix: -2 -2 9 58	
$a_2^3 = \_\_$				9 9 -3 39	
$b^2 = \_\_$				The reduced row echelon form of this matrix is:	
$a_3^1 = \_\$ $b^1 = \_\$				$\begin{bmatrix} 1 & 0 & 0 & 2 \\ 0 & 1 & 0 & 5 \\ 0 & 0 & 1 & 8 \end{bmatrix}$ What is the solution to the original system of	
<i>Warning:</i> The superscripts here (and in the lecture notes) are NOT exponents.					equations?
The system of equations			$\begin{array}{c} x = \underline{} \\ y = \underline{} \end{array}$		
8x - 10y + 5z = 6					<i>z</i> =

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## WeBWorK ReadingHomework3 is due : 10/01/2010 at 03:00pm PDT.

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Give 4 or 5 significant digits for (floating point) numerical answers. For most problems when entering numerical answers, you can if you wish enter elementary expressions such as  $2 \wedge 3$  instead of 8, sin(3 \* pi/2)instead of -1,  $e \wedge (ln(2))$  instead of 2,  $(2+tan(3)) * (4-sin(5)) \wedge 6-7/8$  instead of 27620.3413, etc. Here's the **list of the functions** which WeBWorK understands. You can use the Feedback button on each problem page to send e-mail to the professor.

To which

To which of the three elementary row operations does step 2 of the Gaussian elimination algorithm correspond?

To which of the three elementary row operations does step 3 of the Gaussian elimination algorithm correspond?

To which of the three elementary row operations does step 4 of the Gaussian elimination algorithm correspond?

#### MAT22A-Waldron-Fall-2010

## WeBWorK ReadingHomework4 is due : 10/04/2010 at 03:00pm PDT.

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Geometrically describe the set of solutions to the following system:

 $\begin{cases} 3x + 6y = 24 \\ 6x + 3y = 21 \end{cases}$ 

Geometrically describe the set of solutions to the following system:

$$\begin{cases} 3x + 6y = 24 \\ 9x + 18y = 72 \end{cases}$$

?

?

Geometrically describe the set of solutions to the following system:

$$\begin{cases} 3x + 6y = 24 \\ 9x + 18y = 24 \end{cases}$$

?

Geometrically describe the set of solutions to the following system: 0x + 0y = 0

?

Suppose that MX = V is a linear system, for some matrix M and some vector V. Let the vector P be a particular solution to the system and the vector H a homogeneous solution to the system. Which of the following vectors must be a particular solution to the system? Select all that apply.

- A. P + 2H
- B. H P
- C. 2H P
- D. 2P + 2H
- E. P + 3H
- F. 2P + H
- G. 3P + 3H
- H. 2*H P*
- I. P H
- J. 3P + H
- K. P
- L. P + H
- M. 3*H P*
- N. P 2H
- O. P 3H
- P. *H*

### MAT22A-Waldron-Fall-2010

### WeBWorK ReadingHomework5 is due : 10/06/2010 at 03:00pm PDT.

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Let $a,b,c,d,e$ and $f$ be vectors such that $\langle a,b\rangle =$
$-4$ , $\langle a,c\rangle = -5$ , $\langle b,c\rangle = 1$ , $b+c = d$ , $-6a+2b = e$
and $-5b + 3c = f$ . Compute the following inner products:
$\langle b,a angle =$
$\langle a,d angle =$
$\langle e,c angle =$
$\langle a, f \rangle =$

Suppose that *u* and *v* are vectors and that ||u|| = 6 and ||v|| = 5.

Which of the following could be the value of  $u \cdot v$ ? Select all that apply.

- A. -30
- B. 15
- C. -27
- D. -15
- E.0
- F. 6
- G. -35
- H. 30

all Which of the following could be the value of ||u+v||? Select all that apply.

A. 16
B. 11
C. 1
D. -11
E. -1
F. 17
G. 5
H. 6

• I. 25

• J. -60

• K. 60

• L. 33

• M. 5

#### MAT22A-Waldron-Fall-2010

### WeBWorK ReadingHomework6 is due : 10/08/2010 at 03:00pm PDT.

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The vector space

$$V = \{ f | f \colon \mathbb{N} \to \mathbb{R} \}$$

consists of functions from  $\mathbb{N}$  to  $\mathbb{R}$ . Another way to think of these functions is as "infinite column vectors": f(0) is the first entry, f(1) is the second entry, and so on. Then for example the function  $f(n) = n^3$  would look like this:

$$f = \begin{bmatrix} 0\\1\\8\\27\\\vdots\\n^3\\\vdots \end{bmatrix}$$

Then V is the space of all "infinite column vectors".

Notice that for any "infinite column vector"  $\begin{bmatrix} f(0) \end{bmatrix}$ 

$$f = \begin{vmatrix} f(0) \\ f(1) \\ f(2) \\ f(3) \\ \vdots \end{vmatrix}$$

and any scalar *c* we have

$$c \cdot f = \begin{bmatrix} c \cdot f(0) \\ c \cdot f(1) \\ c \cdot f(2) \\ c \cdot f(3) \\ \vdots \end{bmatrix} = \begin{bmatrix} cf(0) \\ cf(1) \\ cf(2) \\ cf(3) \\ \vdots \end{bmatrix}$$

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is itself an infinite column vector.

This is an illustration of which of the vector space axioms?

Notice that we have  $f \cdot 1 = \begin{bmatrix} f(0) \\ f(1) \\ f(2) \\ f(3) \\ \vdots \end{bmatrix} \cdot \begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \\ \vdots \end{bmatrix} = \begin{bmatrix} f(0) \cdot 1 \\ f(1) \cdot 1 \\ f(2) \cdot 1 \\ f(3) \cdot 1 \\ \vdots \end{bmatrix} = \begin{bmatrix} f(0) \\ f(1) \\ f(2) \\ f(3) \\ \vdots \end{bmatrix} = f.$ 

This is an illustration of which of the vector space axioms?

Notice that for any

$$g = \begin{bmatrix} g(0) \\ g(1) \\ g(2) \\ g(3) \\ \vdots \end{bmatrix}$$

we have

?

$$f+g = \begin{bmatrix} f(0) \\ f(1) \\ f(2) \\ f(3) \\ \vdots \end{bmatrix} + \begin{bmatrix} g(0) \\ g(1) \\ g(2) \\ g(3) \\ \vdots \end{bmatrix} = \begin{bmatrix} f(0) + g(0) \\ f(1) + g(1) \\ f(2) + g(2) \\ f(3) + g(3) \\ \vdots \end{bmatrix} = \begin{bmatrix} g(0) + f(0) \\ g(1) + f(1) \\ g(2) + f(2) \\ g(3) + f(3) \\ \vdots \end{bmatrix} =$$

This is an illustration of which of the vector space axioms?

### MAT22A-Waldron-Fall-2010

## WeBWorK ReadingHomework7 is due : 10/11/2010 at 03:00pm PDT.

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Suppose that *V* is a vector space and that *u* and *v* are two vectors in *V*. The linear transformation  $L: V \to \mathbb{R}$  is such that L(u) = -4 and L(v) = -5. What is the value of L(2u + 5v)?  $L(2u + 5v) = \_\_\_$ 

Let  $L: \mathbb{R}^3 \to \mathbb{R}^3$  be a linear transformation defined by

$$L\left(\begin{array}{c}x\\y\\z\end{array}\right) = \left(\begin{array}{c}4x-y\\7y-z\\x+y\end{array}\right)$$

Write *L* using a matrix:

$$L\begin{pmatrix} x\\ y\\ z \end{pmatrix} = \begin{bmatrix} \dots & \dots & \dots \\ y\\ z \end{pmatrix} = \begin{bmatrix} \dots & \dots & \dots \\ \dots & \dots & \dots \end{bmatrix} \begin{pmatrix} x\\ y\\ z \end{pmatrix}$$

### MAT22A-Waldron-Fall-2010

# WeBWorK ReadingHomework8 is due : 10/13/2010 at 03:00pm PDT.

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Suppose that A is a  $7 \times 10$  matrix and that B is a  $10 \times 2$  matrix. What are the dimensions of the product AB?

AB is a  $\_\_$  ×  $\_\_$  matrix. (Enter "DNE" in both spaces if the product does not exist, that is, if A and B cannot be multiplied together.)

Suppose that A is a  $10 \times 7$  matrix and that B is a  $10 \times 2$  matrix. What are the dimensions of the product AB?

AB is a  $\_\_$  ×  $\_\_$  matrix. (Enter "DNE" in both spaces if the product does not exist, that is, if A and B cannot be multiplied together.)

Suppose that A is a  $7 \times 10$  matrix and that B is a  $2 \times 10$  matrix. What are the dimensions of the product AB? AB is a  $\_\_\times \_$  matrix. (Enter "DNE" in both spaces if the

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product does not exist, that is, if A and B cannot be multiplied together.)

Suppose that A is a  $10 \times 7$  matrix and that B is a  $2 \times 10$  matrix. What are the dimensions of the product AB?

AB is a  $\_\_$  ×  $\_\_$  matrix. (Enter "DNE" in both spaces if the product does not exist, that is, if A and B cannot be multiplied together.)

The matrix A is given by

$$A = \left(\begin{array}{rrrr} 1 & -19 & 3\\ -17 & 9 & 10\\ 2 & -7 & 10 \end{array}\right).$$

What is  $A^T$ ?  $A^T = \begin{bmatrix} & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & \\ & & & & & \\ & & & & \\ & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ &$ 

What is  $A^T$ 

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### WeBWorK ReadingHomework9 is due : 10/15/2010 at 03:00pm PDT.

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• B  $\left( \begin{array}{c|c} A & B \end{array} \right)$  where

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The matrix *M* is given by

• A.  $\left(\begin{array}{c|c} A & B \\ \hline C & D \end{array}\right)$  where

$$M = \begin{pmatrix} -14 & -11 & -5 & -11 & 16\\ 19 & -13 & -2 & 18 & -4\\ -6 & 11 & -16 & -4 & -4\\ -10 & 19 & 11 & 15 & 3\\ -1 & 19 & 5 & 6 & 4 \end{pmatrix}.$$

Which of the following makes sense as a block decomposition of M? Select all that apply.

The matrix *M* is given by  

$$M = \begin{pmatrix} -14 & -11 & -5 & -11 & 16 \\ 19 & -13 & -2 & 18 & -4 \\ -6 & 11 & -16 & -4 & -4 \\ -10 & 19 & 11 & 15 & 3 \\ -1 & 19 & 5 & 6 & 4 \end{pmatrix}.$$
Which of the following makes sense as a block decomposition of *M*? Select all that apply.  
• A.  $\left(\frac{A}{C} \mid \frac{B}{D}\right)$  where  

$$A = \begin{pmatrix} -14 & -11 \\ 19 & -13 \end{pmatrix}, \quad B = \begin{pmatrix} -5 \\ -2 \end{pmatrix}, \quad C = \begin{pmatrix} -10 & 19 & 11 \\ -1 & 19 & 5 \end{pmatrix}$$

$$A = \begin{pmatrix} -14 & -11 \\ 19 & -13 \end{pmatrix}, \quad B = \begin{pmatrix} -5 \\ -2 \end{pmatrix}, \quad C = \begin{pmatrix} -11 & 16 \\ 18 & -4 \end{pmatrix}, \quad D = \begin{pmatrix} -12 & -11 & 16 \\ 18 & -4 \end{pmatrix}, \quad D = \begin{pmatrix} -14 & -11 \\ 19 & -13 \end{pmatrix}, \quad B = \begin{pmatrix} -5 \\ -2 \end{pmatrix}, \quad C = \begin{pmatrix} -11 & 16 \\ 18 & -4 \end{pmatrix}, \quad D = \begin{pmatrix} -14 & -11 \\ 5 \end{pmatrix}, \quad I = \begin{pmatrix} 15 & -2 \\ 6 & -2 \end{pmatrix}$$

$$A = \begin{pmatrix} -14 & -11 \\ 19 & -13 \end{pmatrix}, \quad B = \begin{pmatrix} -5 & -11 & 16 \\ -2 & 18 & -4 \end{pmatrix}, \quad C = \begin{pmatrix} -6A \pm 1 \\ -10 & 19 \\ -1 & 19 \end{pmatrix}$$

$$E = None of the above A = \begin{pmatrix} -11 & 16 \\ 18 & -4 \end{pmatrix}, \quad C = \begin{pmatrix} -10 & 19 \\ -1 & 19 \\ -1 & 19 \end{pmatrix}$$

### MAT22A-Waldron-Fall-2010

## WeBWorK ReadingHomework10 is due : 10/18/2010 at 03:00pm PDT.

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You can use the Feedback button on each problem page to send e-mail to the professor.

The matrix *M* is given by

$$M = \left(\begin{array}{rrrr} 15 & 2 & 53 \\ -8 & -3 & -36 \\ 21 & -3 & 51 \end{array}\right)$$

Further, M is row-equivalent to the matrix N which is given by

$$N = \left(\begin{array}{rrrr} 1 & 0 & 3\\ 0 & 1 & 4\\ 0 & 0 & 0 \end{array}\right)$$

Which of the following is true? Select all that apply.

- A. The matrix  $M^{-1}$  does not exist.
- B. NM = I.
- C. It is impossible to tell whether M has an inverse without writing the augmented matrix (M|I) and rowreducing.
- D. The matrix  $M^{-1}$  is equal to N.
- E. MN = I.

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- F. The matrix  $M^{-1}$  exists; to compute it, we would need to write the augmented matrix (M|I) and row-reduce.
- G. None of the above

$$\begin{cases} 2x + 1y + 6z = 9 \\ -5x - 2y - 2z = 5 \\ -12x - 4y + 16z = 56 \end{cases}$$

has solution set

The system

$$\left\{ \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} -23 \\ 55 \\ 0 \end{pmatrix} + \lambda \begin{pmatrix} 10 \\ -26 \\ 1 \end{pmatrix} \right\}.$$
  
Compute the inverse of the matrix  $A = \begin{pmatrix} 2 & 1 & 6 \\ -5 & -2 & -2 \\ -5 & -2 & -2 \end{pmatrix}$ 

 $\begin{bmatrix} -12 & -4 & 16 \end{bmatrix}$ (Enter "DNE" in all spaces if

the inverse does not exist.

### MAT22A-Waldron-Fall-2010

## WeBWorK ReadingHomework11 is due : 10/22/2010 at 03:00pm PDT.

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Suppose that the matrix *A* is given by  $A = \begin{pmatrix} 1 & 0 \\ 2 & 1 \end{pmatrix}$ . Then multiplying on the left by *A* corresponds to which of the three elementary row operations? For example,  $\begin{pmatrix} 1 & 0 \end{pmatrix} \begin{pmatrix} 9 & -7 \end{pmatrix} \begin{pmatrix} 9 & -7 \end{pmatrix}$ 

$$\begin{pmatrix} 1 & 0 \\ 2 & 1 \end{pmatrix} \begin{pmatrix} 9 & -7 \\ -8 & 7 \end{pmatrix} = \begin{pmatrix} 9 & -7 \\ 10 & -7 \end{pmatrix}.$$

Multiplying on the left by *A* corresponds to: ?

Suppose that the matrix *B* is given by  $B = \begin{pmatrix} 3 & 0 \\ 0 & 1 \end{pmatrix}$ . Then multiplying on the left by *B* corresponds to which of the three elementary row operations? For example,

$$\left(\begin{array}{cc}3&0\\0&1\end{array}\right)\left(\begin{array}{cc}9&-7\\-8&7\end{array}\right)=\left(\begin{array}{cc}27&-21\\-8&7\end{array}\right)$$

Multiplying on the left by *B* corresponds to: ?

Suppose that the matrix *C* is given by  $C = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$ . Then multiplying on the left by *C* corresponds to which of the three elementary row operations? For example,

$$\left(\begin{array}{cc} 0 & 1 \\ 1 & 0 \end{array}\right) \left(\begin{array}{cc} 9 & -7 \\ -8 & 7 \end{array}\right) = \left(\begin{array}{cc} -8 & 7 \\ 9 & -7 \end{array}\right)$$

Multiplying on the left by *C* corresponds to: |?|

Let	λ	be	a	nor	n-zer	0	sca	ılar.	The	product
$\int a_1^1$	$a_{2}^{1}$	$a_3^1$	(	$b_1^1$	$b_{2}^{1}$	$b_3^1$				
$a_1^2$	$a_{2}^{2}$	$a_3^2$		$b_{1}^{2}$	$b_{2}^{2}$	$b_{3}^{2}$		is the	same as	which of
$a_1^3$	$a_{2}^{3}$	$a_3^3$ )	l	$b_{1}^{3}$	$b_{2}^{3}$	$b_{3}^{3}$	J			

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the following products? Select all that apply. Hint: Think, don't calculate!

• A. 
$$\begin{pmatrix} \frac{1}{\lambda}a_1^1 & a_2^1 & a_3^1 \\ a_1^2 & \frac{1}{\lambda}a_2^2 & a_3^2 \\ a_1^3 & a_2^3 & \frac{1}{\lambda}a_3^3 \end{pmatrix} \begin{pmatrix} \lambda b_1^1 & b_2^1 & b_3^1 \\ b_1^2 & \lambda b_2^2 & b_3^2 \\ b_1^3 & b_2^3 & \lambda b_3^3 \end{pmatrix}$$
  
• B.  $\begin{pmatrix} a_1^1 & a_2^1 & a_3^1 \\ a_1^2 & a_2^2 & a_3^2 \\ \lambda a_1^3 & \lambda a_2^3 & \lambda a_3^3 \end{pmatrix} \begin{pmatrix} b_1^1 & b_2^1 & \frac{1}{\lambda}b_3^1 \\ b_1^2 & b_2^2 & \frac{1}{\lambda}b_3^2 \\ b_1^3 & b_2^3 & \frac{1}{\lambda}b_3^3 \end{pmatrix}$   
• C.  $\begin{pmatrix} a_1^1 & \lambda a_2^1 & a_3^1 \\ a_1^2 & \lambda a_2^2 & a_3^2 \\ a_1^3 & \lambda a_2^3 & a_3^3 \end{pmatrix} \begin{pmatrix} b_1^1 & b_2^1 & b_3^1 \\ \frac{1}{\lambda}b_1^2 & \frac{1}{\lambda}b_2^2 & \frac{1}{\lambda}b_3^2 \\ b_1^3 & b_2^3 & b_3^3 \end{pmatrix}$   
• D.  $\begin{pmatrix} a_1^1 & a_2^1 & a_3^1 \\ \frac{1}{\lambda}a_1^2 & \frac{1}{\lambda}a_2^2 & \frac{1}{\lambda}a_3^2 \\ \frac{1}{\lambda}a_1^3 & a_2^3 & a_3^3 \end{pmatrix} \begin{pmatrix} \lambda b_1^1 & \lambda b_2^1 & \lambda b_3^1 \\ b_1^2 & \frac{1}{\lambda}b_2^2 & b_3^2 \\ b_1^3 & \frac{1}{\lambda}b_2^3 & b_3^3 \end{pmatrix}$   
• E.  $\begin{pmatrix} \frac{1}{\lambda}a_1^1 & \frac{1}{\lambda}a_2^1 & \frac{1}{\lambda}a_3^1 \\ \frac{1}{\lambda}a_1^2 & \frac{1}{\lambda}a_2^2 & \frac{1}{\lambda}a_3^2 \\ \frac{1}{\lambda}a_1^3 & \frac{1}{\lambda}a_2^2 & \frac{1}{\lambda}a_3^2 \end{pmatrix} \begin{pmatrix} \lambda b_1^1 & \lambda b_2^1 & \lambda b_3^1 \\ b_1^2 & \lambda b_2^2 & \lambda b_3^2 \\ b_1^3 & b_2^3 & b_3^3 \end{pmatrix}$   
• G.  $\begin{pmatrix} \lambda a_1^1 & \lambda a_2^1 & \lambda a_3^1 \\ a_1^2 & \frac{1}{\lambda}a_3^2 & a_3^2 \end{pmatrix} \begin{pmatrix} b_1^1 & \frac{1}{\lambda}b_2^1 & \lambda b_3^1 \\ \lambda b_1^2 & \lambda b_2^2 & \lambda b_3^2 \\ \lambda b_1^3 & \lambda b_2^3 & \lambda b_3^3 \end{pmatrix}$   
• H. None of the above

### MAT22A-Waldron-Fall-2010

### WeBWorK ReadingHomework12 is due : 10/25/2010 at 03:00pm PDT.

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Give 4 or 5 significant digits for (floating point) numerical answers. For most problems when entering numerical answers, you can if you wish enter elementary expressions such as  $2 \wedge 3$  instead of 8, sin(3 \* pi/2)instead of -1,  $e \wedge (ln(2))$  instead of 2,  $(2 + tan(3)) * (4 - sin(5)) \wedge 6 - 7/8$  instead of 27620.3413, etc. Here's the **list of the functions** which WeBWorK understands.

You can use the Feedback button on each problem page to send e-mail to the professor.

Let  $\sigma_1$  be the permutation given by  $\sigma_1 = [1, 2, 3]$ . What is its sign? sgn( $\sigma_1$ ) = \_\_\_\_

Let  $\sigma_2$  be the permutation given by  $\sigma_2 = [1,3,2]$ . What is its sign? sgn( $\sigma_2$ ) = \_\_\_\_

Let  $\sigma_3$  be the permutation given by  $\sigma_3 = [2, 1, 3]$ . What is its sign? sgn( $\sigma_3$ ) = \_\_\_\_

Let  $\sigma_4$  be the permutation given by  $\sigma_4 = [2,3,1]$ . What is its sign? sgn( $\sigma_4$ ) = \_\_\_\_ Let  $\sigma_5$  be the permutation given by  $\sigma_5 = [3, 1, 2]$ . What is its sign?

 $sgn(\sigma_5) =$ \_\_\_\_

Let  $\sigma_6$  be the permutation given by  $\sigma_6 = [3, 2, 1]$ . What is its sign?

 $sgn(\sigma_6) =$ \_\_\_\_

Compute  

$$det \begin{pmatrix} 2 & 4 & 6 \\ 35 & 40 & 50 \\ 28 & 35 & 42 \end{pmatrix},$$
given that  

$$det \begin{pmatrix} 2 & 4 & 6 \\ 28 & 35 & 42 \\ 35 & 40 & 50 \end{pmatrix} = -210.$$

The determinant of the first matrix is equal to \_\_\_\_\_.

#### MAT22A-Waldron-Fall-2010

### WeBWorK ReadingHomework13 is due : 10/27/2010 at 03:00pm PDT.

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Give 4 or 5 significant digits for (floating point) numerical answers. For most problems when entering numerical answers, you can if you wish enter elementary expressions such as  $2 \wedge 3$  instead of 8, sin(3 \* pi/2) instead of -1,  $e \wedge (ln(2))$  instead of 2,  $(2 + tan(3)) * (4 - sin(5)) \wedge 6 - 7/8$  instead of 27620.3413, etc. Here's the **list of the functions** which WeBWorK understands.

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### MAT22A-Waldron-Fall-2010

### WeBWorK ReadingHomework14 is due : 10/29/2010 at 03:00pm PDT.

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Give 4 or 5 significant digits for (floating point) numerical answers. For most problems when entering numerical answers, you can if you wish enter elementary expressions such as  $2 \wedge 3$  instead of 8, sin(3 \* pi/2)instead of -1,  $e \wedge (ln(2))$  instead of 2,  $(2 + tan(3)) * (4 - sin(5)) \wedge 6 - 7/8$  instead of 27620.3413, etc. Here's the **list of the functions** which WeBWorK understands.

You can use the Feedback button on each problem page to send e-mail to the professor.

The permutation $\sigma$ is given by $\sigma = \begin{bmatrix} 3 & 1 & 2 & 4 \end{bmatrix}$ . Compute
the inverse of $\sigma$ .
$\sigma^{-1} = [ \_\_\_\_\_]$
The sign of the permutation $\sigma$ above is given by $sgn(\sigma) = 1$ . Compute the sign of $\sigma^{-1}$ . $sgn(\sigma^{-1}) = \_$
The matrix A is given by $A = \begin{pmatrix} 46 & 33 & 12 & -7 \\ 32 & -9 & -50 & -9 \\ -47 & -16 & 12 & 23 \\ 44 & 8 & -11 & -49 \end{pmatrix}$ Then the adjoint matrix $B = \operatorname{adj} A$ is given by $\operatorname{adj} A = \begin{pmatrix} b_1^1 & b_2^1 & b_3^1 & b_4^1 \\ b_1^2 & b_2^2 & b_3^2 & b_4^2 \\ b_1^3 & b_2^3 & b_3^3 & b_4^3 \\ b_1^4 & b_2^4 & b_3^4 & b_4^4 \end{pmatrix}$ .



Express  $b_2^4$  as  $\pm 1$  times the determinant of a 3 × 3 matrix:

### MAT22A-Waldron-Fall-2010

## WeBWorK ReadingHomework15 is due : 11/01/2010 at 03:00pm PDT.

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Give 4 or 5 significant digits for (floating point) numerical answers. For most problems when entering numerical answers, you can if you wish enter elementary expressions such as  $2 \wedge 3$  instead of 8, sin(3 \* pi/2)instead of -1,  $e \wedge (ln(2))$  instead of 2,  $(2 + tan(3)) * (4 - sin(5)) \wedge 6 - 7/8$  instead of 27620.3413, etc. Here's the **list of the functions** which WeBWorK understands.

You can use the Feedback button on each problem page to send e-mail to the professor.

The linear transformation  $L: \mathbb{R}^2 \to \mathbb{R}^2$  maps the vector *u* to L(u) and the vector *v* to L(v). The vectors u, v, L(u), and L(v) are shown below; *u* and *v* in red and L(u) and L(v) in blue.



Which of the following could be an eigenvector of L? Select all that apply.

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A. u - 3v
B. -u - v
C. u
D. u - v
E. v
F. u + v

- G. v u
- H. 2u + v
- I. None of the above

The linear transformation  $L: \mathbb{R}^2 \to \mathbb{R}^2$  has eigenvalues 2 and 3. The vector *u* is an eigenvector of *L* for the eigenvalue 2, and the vector *v* is an eigenvector of *L* for the eigenvalue 3.

If w = xu + yv, then compute L(w) in terms of u and v.  $L(w) = (\underline{\qquad} x)u + (\underline{\qquad} y)v.$ 

Let  $\begin{pmatrix} x \\ y \end{pmatrix}$  denote the vector xu + yv. In terms of this notation, write a matrix for *L*.  $L\begin{pmatrix} x \\ y \end{pmatrix} = \begin{bmatrix} - & - \\ - & - \end{bmatrix} \begin{pmatrix} x \\ y \end{pmatrix}$ 

### MAT22A-Waldron-Fall-2010

## WeBWorK ReadingHomework16 is due : 11/03/2010 at 03:00pm PDT.

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Give 4 or 5 significant digits for (floating point) numerical answers. For most problems when entering numerical answers, you can if you wish enter elementary expressions such as  $2 \wedge 3$  instead of 8, sin(3 \* pi/2)instead of -1,  $e \wedge (ln(2))$  instead of 2,  $(2 + tan(3)) * (4 - sin(5)) \wedge 6 - 7/8$  instead of 27620.3413, etc. Here's the <u>list of the functions</u> which WeBWorK understands.

You can use the Feedback button on each problem page to send e-mail to the professor.

Let M be a matrix with eigenvalues 5 and 9. Suppose that u and v are eigenvectors of M associated to the eigenvalue 5 and that w is an eigenvector of M associated to the eigenvalue 9.

Which of the following must also be an eigenvector of M? Select all that apply.

- A. 5*u*
- B. v + w
- C. u + w
- D. 14w
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- E. -5*u*
- F. u v
- G. w u
- H. 5u + 9w
- I. -9v
- J. u + v
- K. 9v
- L. *v w*
- M. 9v + 5w
- N. 9u + 5v
- O. -14w
- P. None of the above

### MAT22A-Waldron-Fall-2010

## WeBWorK ReadingHomework17 is due : 11/05/2010 at 03:00pm PDT.

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Give 4 or 5 significant digits for (floating point) numerical answers. For most problems when entering numerical answers, you can if you wish enter elementary expressions such as  $2 \wedge 3$  instead of 8, sin(3 \* pi/2)instead of -1,  $e \wedge (ln(2))$  instead of 2,  $(2+tan(3)) * (4-sin(5)) \wedge 6-7/8$  instead of 27620.3413, etc. Here's the <u>list of the functions</u> which WeBWorK understands. You can use the Feedback button on each problem page to send e-mail to the professor.

Which of the following are vector spaces? Select all that apply. • A. The set of all vectors  $\in \mathbb{R}^3$  such that y = z. 0 • B. The set of all vectors  $\in \mathbb{R}^3$  such that  $x^2 +$ 0 0  $y^2 = z.$ 0 6  $\in \mathbb{R}^3$  such that x = 7. • C. The set of all vectors 18 z 0 • B. 18 х • D. The set of all vectors  $\in \mathbb{R}^3$  such that y = 0. 0 0 0  $\in \mathbb{R}^3$  such that |x| = |y|. • E. The set of all vectors 6 0 • C. 6 • F. The set of all vectors  $\in \mathbb{R}^3$  such that x =0 0 y + 9.6 3 • G. The set of all vectors  $\in \mathbb{R}^3$  such that 7x +0 D. 6 9v = 0.0 0 • H. The set of all vectors  $\in \mathbb{R}^3$  such that x + y +0 0 z = 0.3 • E. • I. None of the above 0 6 Let S be the vectors S set of given by 0 6 0 0 3 1 0 0 0 1 6 0 1 0 6 0 0 6 0 \_1 6 Which of the following are in span(S)? Select all that apply.



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#### MAT22A-Waldron-Fall-2010

### WeBWorK ReadingHomework18 is due : 11/08/2010 at 03:00pm PST.

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Give 4 or 5 significant digits for (floating point) numerical answers. For most problems when entering numerical answers, you can if you wish enter elementary expressions such as  $2 \wedge 3$  instead of 8, sin(3 \* pi/2)instead of -1,  $e \wedge (ln(2))$  instead of 2,  $(2+tan(3)) * (4-sin(5)) \wedge 6-7/8$  instead of 27620.3413, etc. Here's the <u>list of the functions</u> which WeBWorK understands. You can use the Feedback button on each problem page to send e-mail to the professor.

Suppose that vectors  $v_1, v_2, v_3$  are such that  $9v_1 + 5v_2 - 5v_3 =$ 0. Are the three vectors linearly independent? ? Suppose that vectors  $v_1, v_2, v_3$  are such that  $9v_1 + 5v_2 =$  $-5v_3$ . Are the three vectors linearly independent? ? Suppose that vectors  $v_1, v_2, v_3, v_4$  are such that  $\overline{9v_1} + 5v_2 =$  $-5v_3 - 4v_4$ . Are the four vectors linearly independent? ? Suppose that vectors  $v_1, v_2, v_3, v_4$  are such that  $9v_1 = -5v_3 - 5v_3 - 5v_3 - 5v_4 + 5v_4 +$  $4v_4$ . Are the four vectors linearly independent? ? Suppose that vectors  $v_1, v_2, v_3, v_4$  are such that  $9v_1 = -5v_4$ . Are the four vectors linearly independent? ? Suppose that vectors  $v_1, v_2, v_3, v_4$  are such that  $9v_1 + 5v_2 -$  $5v_3 = 5v_2 - 5v_3 - 4v_4$ . Are the four vectors linearly independent? ? Which of the following sets of vectors in  $\mathbb{R}^6$  are linearly independent? Select all that apply. 14 0 0 3 7 0 0

0

3

0

0

3

0

0

3

0

0

14

0

0 14

0

0 14

7

0

0

7

0

0

7

0

• B.



#### MAT22A-Waldron-Fall-2010

### WeBWorK ReadingHomework19 is due : 11/10/2010 at 03:00pm PST.

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Give 4 or 5 significant digits for (floating point) numerical answers. For most problems when entering numerical answers, you can if you wish enter elementary expressions such as  $2 \wedge 3$  instead of 8, sin(3 \* pi/2)instead of -1,  $e \wedge (ln(2))$  instead of 2,  $(2+tan(3)) * (4-sin(5)) \wedge 6 - 7/8$  instead of 27620.3413, etc. Here's the <u>list of the functions</u> which WeBWorK understands. You can use the Feedback button on each problem page to send e-mail to the professor.

We are going to follow the idea of the proof of lemma 19.2 in order to show that a particular set of set *T* of linearly independent vectors in  $\mathbb{R}^3$  has no more elements than a particular basis *S* of the vector space  $\mathbb{R}^3$ .

Let the set *S* be given by  

$$S = \left\{ \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} \right\}.$$

You can check for yourself that *S* is a basis for  $\mathbb{R}^3$ . Let the set *T* be given by

$$T = \left\{ \begin{pmatrix} 9\\9\\0 \end{pmatrix}, \begin{pmatrix} 6\\6\\6 \end{pmatrix} \right\}.$$

You can check for yourself that the vectors in T are linearly independent.

Express 
$$\begin{pmatrix} 9\\9\\0 \end{pmatrix}$$
 as a linear combination of elements in *S*.  
 $\begin{pmatrix} 9\\9\\0 \end{pmatrix} = --- \cdot \begin{pmatrix} 1\\0\\0 \end{pmatrix} + --- \cdot \begin{pmatrix} 0\\1\\0 \end{pmatrix} + -- \cdot \begin{pmatrix} 0\\1\\0 \end{pmatrix}$ 

Use the equation you found to express 
$$\begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}$$
 as

a linear combination of the vectors in the set 
$$S' = \begin{cases} \begin{pmatrix} 9\\9\\0 \end{pmatrix}, \begin{pmatrix} 0\\1\\0 \end{pmatrix}, \begin{pmatrix} 0\\0\\1 \end{pmatrix} \end{cases}, \begin{pmatrix} 0\\0\\1 \end{pmatrix} \rbrace.$$
$$\begin{pmatrix} 1\\0\\0 \end{pmatrix} = \underbrace{\qquad} \cdot \begin{pmatrix} 9\\9\\0 \end{pmatrix} + \underbrace{\qquad} \cdot \begin{pmatrix} 0\\1\\0 \end{pmatrix}$$

This means that the set S' is a basis for  $\mathbb{R}^3$ . You can check for yourself that it is a basis.

Express 
$$\begin{pmatrix} 6\\6\\6 \end{pmatrix}$$
 as a linear combination of elements in S'.  
 $\begin{pmatrix} 6\\6\\6 \end{pmatrix} = - \cdot \begin{pmatrix} 9\\9\\0 \end{pmatrix} + - \cdot \begin{pmatrix} 0\\1\\0 \end{pmatrix} + - \cdot \begin{pmatrix} 0\\1\\0 \end{pmatrix} + - \cdot \begin{pmatrix} 0\\1\\0 \end{pmatrix} + - \cdot \begin{pmatrix} 0\\0\\1 \end{pmatrix}$ 
Use the equation you found to express  $\begin{pmatrix} 0\\0\\1 \end{pmatrix}$  as  
a linear combination of the vectors in the set S'' =  
 $\begin{cases} \begin{pmatrix} 9\\9\\0\\1 \end{pmatrix}, \quad \begin{pmatrix} 0\\1\\0 \end{pmatrix}, \quad \begin{pmatrix} 6\\6\\6 \end{pmatrix} \end{cases}$ .  
 $\begin{pmatrix} 0\\0\\1 \end{pmatrix} = - \cdot \begin{pmatrix} 9\\9\\0 \end{pmatrix} + - \cdot \begin{pmatrix} 0\\1\\0 \end{pmatrix} + - \cdot \begin{pmatrix} 0\\1\\0 \end{pmatrix} + - \cdot \begin{pmatrix} 6\\1\\0 \end{pmatrix} + - \cdot \begin{pmatrix} 6\\1\\0 \end{pmatrix} + - \cdot \begin{pmatrix} 6\\6\\6 \end{pmatrix}$ 

This means that the set S'' is a basis for  $\mathbb{R}^3$ . You can check for yourself that it is a basis.

We've made a new basis from S by replacing some of its elements with elements of T. Since all the elements of T are in this new basis S'', and the new basis S'' has exactly as many elements as S did, we can conclude that the number of elements in T is less than or equal to the number of elements in S.

Of course, we could have just counted the number of elements in T and the number of elements of S at the beginning, but the point is that this process always works: if S is any basis for a vector space V and T is any set of linearly independent vectors in V, then we can do what we did above to conclude that the number of elements in T is less than or equal to the number of elements in S.

Suppose that the set  $S = \{v_1, v_2, ..., v_n\}$  is a basis for the vector space *V*. Decide whether each of the following statements is true or false. If you do not have enough information to decide whether a statement is true or false, select "Impossible to tell".

1. The vectors  $v_1, \ldots, v_n$  span *V*. ?

2. The vectors  $v_1, \ldots, v_n$  are linearly independent. ?

3. If  $T = \{w_1, w_2, \dots, w_m\}$  is a different basis for V, then m could be equal to n+1. ?

4. If x is any vector in V, then it may be impossible to write x as

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a linear combination of elements of *S*. ? 5. There exist nonzero constants  $c^1, \ldots, c^n$  such that  $c^1v_1 + \cdots + c^nv_n = 0$ . ?

6. The dimension of V is equal to n. ?

### MAT22A-Waldron-Fall-2010

### WeBWorK ReadingHomework20 is due : 11/17/2010 at 03:00pm PST.

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Give 4 or 5 significant digits for (floating point) numerical answers. For most problems when entering numerical answers, you can if you wish enter elementary expressions such as  $2 \wedge 3$  instead of 8, sin(3 \* pi/2)instead of -1,  $e \wedge (ln(2))$  instead of 2,  $(2 + tan(3)) * (4 - sin(5)) \wedge 6 - 7/8$  instead of 27620.3413, etc. Here's the **list of the functions** which WeBWorK understands.

You can use the Feedback button on each problem page to send e-mail to the professor.

Let  $\{e_1, e_2, e_3\}$  be a basis for  $\mathbb{R}^3$  and let  $\{f_1, f_2, f_3, f_4\}$  be a basis for  $\mathbb{R}^4$ . Let  $L: \mathbb{R}^3 \to \mathbb{R}^4$  be a linear transformation which acts in the following way on basis elements:  $L(e_1) = -45f_1 - 35f_2 - 21f_3 - 20f_4,$   $L(e_2) = -10f_1 + 25f_2 + 5f_3 - 2f_4,$  $L(e_3) = 26f_1 - 21f_2 + 22f_3 + 46f_4.$ 

Given our choice of bases, write a matrix M for the linear transformation L.

	—	 —
M =	—	 
		 —
	L —	 ]

Suppose that V is a 5-dimensional vector space. Let  $L: V \rightarrow V$  be a linear transformation. Decide whether each of the following statements is true or false. If you do not have enough information to decide whether a statement is true or false, select "Impossible to tell".

1. If  $u_1, \ldots, u_5$  is any basis of *V*, then it is possible to write a matrix for *L* in terms of this basis. ?

2. If *L* has eigenvectors  $v_1, \ldots, v_5$  which are linearly independent, then *L* is diagonalizable. ?

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3. Fix some nonzero vector *v*. If every eigenvector of *L* is a constant multiple of *v*, then *L* is diagonalizable. ? 4. If there is some basis  $w_1, \ldots, w_5$  with respect to which the matrix of *L* is a diagonal matrix, then  $w_1, \ldots, w_5$  are eigenvectors of *L*. ?

Suppose that *V* is a 5-dimensional vector space. Let  $S = \{v_1, \ldots, v_5\}$  be some basis of *V*, and let  $T = \{w_1, \ldots, w_5\}$  be some other basis of *V*. Let *L*:  $V \rightarrow V$  be a linear transformation. Let *M* be the matrix of *L* in the basis *S* and let *N* be the matrix of *L* in the basis *T*. Decide whether each of the following statements is true or false. If you do not have enough information to decide whether a statement is true or false, select "Impossible to tell".

1. There is a change of basis matrix which takes us from the basis *S* to the basis *T*. ?

2. If *P* is a change of basis matrix, then det P = 0.

3. The matrices *M* and *N* are similar. ?

4. If *M* is a diagonal matrix, then *N* is a diagonalizable matrix.

### MAT22A-Waldron-Fall-2010

### WeBWorK ReadingHomework21 is due : 11/19/2010 at 03:00pm PST.

Visit http://www.math.ucdavis.edu/ wally/teaching/22A/22A.html for the syllabus, grading policy and other information.

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Give 4 or 5 significant digits for (floating point) numerical answers. For most problems when entering numerical answers, you can if you wish enter elementary expressions such as  $2 \wedge 3$  instead of 8, sin(3 \* pi/2) instead of -1,  $e \wedge (ln(2))$  instead of 2,  $(2 + tan(3)) * (4 - sin(5)) \land 6 - 7/8$  instead of 27620.3413, etc. Here's the **list of the functions** which WeBWorK understands.

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The set 
$$S = \left\{ \begin{pmatrix} \frac{-1}{\sqrt{2}} \\ \frac{1}{\sqrt{3}} \\ \frac{1}{\sqrt{6}} \end{pmatrix}, \begin{pmatrix} \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{3}} \\ \frac{1}{\sqrt{6}} \end{pmatrix}, \begin{pmatrix} 0 \\ \frac{-1}{\sqrt{3}} \\ \frac{2}{\sqrt{6}} \end{pmatrix} \right\}$$

is an orthonormal basis of  $\mathbb{R}^3$ .

What are the dot products of the vectors in *S* with each other?



What are the dot products of the vectors in S with themselves?



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Express the standard basis vector  $e_3$  in terms of the basis S:



Write the matrix P for the change of basis from S to the standard basis  $\{e_1, e_2, e_3\}$  of  $\mathbb{R}^3$ .



### WeBWorK ReadingHomework22 is due : 11/24/2010 at 03:00pm PST.

### MAT22A-Waldron-Fall-2010

Visit http://www.math.ucdavis.edu/ wally/teaching/22A/22A.html for the syllabus, grading policy and other information.

The primary purpose of WeBWorK is to let you know that you are getting the correct answer or to alert you if you are making some kind of mistake. Usually you can attempt a problem as many times as you want before the due date. However, if you are having trouble figuring out your error, you should consult the book, or ask a fellow student, one of the TAs or your professor for help. Don't spend a lot of time guessing – it's not very efficient or effective.

Give 4 or 5 significant digits for (floating point) numerical answers. For most problems when entering numerical answers, you can if you wish enter elementary expressions such as  $2 \wedge 3$  instead of 8, sin(3 \* pi/2)instead of -1,  $e \wedge (ln(2))$  instead of 2,  $(2 + tan(3)) * (4 - sin(5)) \wedge 6 - 7/8$  instead of 27620.3413, etc. Here's the **list of the functions** which WeBWorK understands.

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The matrix A is a real symmetric  $5 \times 5$  matrix with eigenvalues 3,7,11,16, and 20. The vector  $x_1$  is an eigenvector of A with eigenvalue 3, the vector  $x_2$  is an eigenvector of A with eigenvalue 7, the vector  $x_3$  is an eigenvector of A with eigenvalue 11, the vector  $x_4$  is an eigenvector of A with eigenvalue 16, and the vector  $x_5$  is an eigenvector of A with eigenvalue 20.

Compute the dot products of the eigenvectors  $x_i$  with each other.

$x_1 \cdot x_2 =$	
$x_1 \cdot x_3 =$	
$x_1 \cdot x_4 =$	
$x_1 \cdot x_5 =$	
$x_2 \cdot x_3 =$	
$x_2 \cdot x_4 =$	
$x_2 \cdot x_5 =$	
$x_3 \cdot x_4 =$	
$x_3 \cdot x_5 =$	
$x_4 \cdot x_5 =$	

We are going to follow the idea of the proof of Theorem 22.2 in order to show that a particular real  $3 \times 3$  symmetric matrix is similar to a diagonal matrix of its eigenvalues.

	1	14	14	0 )	
Let $M$ be the matrix given by $M =$		14	0	14	
		0	14	14 /	

Compute the eigenvalues of *M*. Call the largest eigenvalue  $\lambda_1$ , the middle eigenvalue  $\lambda_2$ , and the smallest eigenvalue  $\lambda_3$ .

$$\lambda_1 = \underline{\qquad}$$
  
 $\lambda_2 = \underline{\qquad}$   
 $\lambda_3 = \underline{\qquad}$ 

Find an eigenvector  $x_1$  of M so that  $x_1$  has eigenvalue  $\lambda_1$  and length 1. Choose  $x_1$  so that its first nonzero entry is positive.

$x_1 = $			
	$x_1 =$		
		L	

Let the vector  $x_2$  be given by  $x_2 = \begin{pmatrix} 0 \\ \frac{\sqrt{2}}{2} \\ -\frac{\sqrt{2}}{2} \end{pmatrix}$ . You can

check for yourself that  $x_1$  and  $x_2$  are orthonormal. Find a third vector  $x_3$  so that  $\{x_1, x_2, x_3\}$  is an orthonormal basis for  $\mathbb{R}^3$ . Choose  $x_3$  so that its first nonzero entry is positive.



Let the matrix P be given by  $P = (x_1 \ x_2 \ x_3)$ . Notice that P is orthogonal, so  $P^{-1} = P^T$ . Compute the matrix  $P^T M P$ .



Now we repeat this process to finish diagonalizing M. Let  $\hat{M}$  be the two-by-two block in the lower-right corner of the matrix  $P^T M P$  which you computed above. You can check for yourself that the eigenvalues of  $\hat{M}$  are the eigenvalues  $\lambda_2, \lambda_3$  which you computed earlier. Find an eigenvector  $y_2$  of  $\hat{M}$  so that  $y_2$  has eigenvalue  $\lambda_2$  and length 1. Choose  $y_2$  so that its first nonzero entry is positive.



Find a second vector  $y_3$  so that  $\{y_2, y_3\}$  is an orthonormal basis for  $\mathbb{R}^2$ . Choose  $y_3$  so that its first nonzero entry is positive.

$$y_3 =$$

Let the matrix Q be given by  $Q = (y_2 \ y_3)$ . Notice that Q is orthogonal, so  $Q^{-1} = Q^T$ . Compute the matrix  $Q^T \hat{M} Q$ .

$$Q^T \hat{M} Q = \begin{bmatrix} & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & &$$

You should have ended up with a diagonal matrix. This shows that the matrix M is similar to the diagonal matrix  $\begin{pmatrix} \lambda \\ \lambda \end{pmatrix} = 0$ 

$$\begin{pmatrix} \lambda_1 & 0 & 0 \\ 0 & \lambda_2 & 0 \\ 0 & 0 & \lambda_3 \end{pmatrix}$$

### MAT22A-Waldron-Fall-2010

## WeBWorK ReadingHomework23 is due : 11/29/2010 at 03:00pm PST.

Visit http://www.math.ucdavis.edu/ wally/teaching/22A/22A.html for the syllabus, grading policy and other information.

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Give 4 or 5 significant digits for (floating point) numerical answers. For most problems when entering numerical answers, you can if you wish enter elementary expressions such as  $2 \wedge 3$  instead of 8, sin(3 \* pi/2)instead of -1,  $e \wedge (ln(2))$  instead of 2,  $(2 + tan(3)) * (4 - sin(5)) \wedge 6 - 7/8$  instead of 27620.3413, etc. Here's the **list of the functions** which WeBWorK understands.

You can use the Feedback button on each problem page to send e-mail to the professor.

Decide whether each of the following linear transformations is injective but not surjective, surjective but not injective, bijective, or neither injective nor surjective. Remember that "injective" means one-to-one, "surjective" means onto, and "bijective" means both one-to-one and onto.

1.  $L: \mathbb{R}^3 \to \mathbb{R}^3$  given by L(x, y, z) = (x, y, z) ? 2.  $L: \mathbb{R}^3 \to \mathbb{R}^2$  given by L(x, y, z) = (x, y) ? 3.  $L: \mathbb{R}^3 \to \mathbb{R}^3$  given by L(x, y, z) = (0, 0, 0) ? 4.  $L: \mathbb{R}^2 \to \mathbb{R}^3$  given by L(x, y) = (x, y, 0) ?

Decide whether each of the following statements is true or false. If the statement could be true and could be false, i.e., if you need more information to decide, choose "Impossible to tell".

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1. If  $L: \mathbb{R}^2 \to \mathbb{R}^3$  is an injective (one-to-one) linear transformation, then null L = 0. ?

2. If  $L: \mathbb{R}^2 \to \mathbb{R}^3$  is an injective (one-to-one) linear transformation, then rank L = 3. ?

3. If  $L: \mathbb{R}^2 \to \mathbb{R}^3$  is a linear transformation, then rank L = 3.

4. If  $L: \mathbb{R}^2 \to \mathbb{R}^3$  is a linear transformation, then ker *L* must be a vector space. ?

5. If  $L: \mathbb{R}^2 \to \mathbb{R}^3$  is a linear transformation, then Im*L* must be a vector space. ?

6. If  $L: \mathbb{R}^2 \to \mathbb{R}^3$  is a linear transformation whose kernel is a one-dimensional vector space, then *L* is injective (one-to-one).

#### MAT22A-Waldron-Fall-2010

### WeBWorK ReadingHomework24 is due : 12/03/2010 at 03:00pm PST.

Visit http://www.math.ucdavis.edu/ wally/teaching/22A/22A.html for the syllabus, grading policy and other information.

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Give 4 or 5 significant digits for (floating point) numerical answers. For most problems when entering numerical answers, you can if you wish enter elementary expressions such as  $2 \wedge 3$  instead of 8, sin(3 \* pi/2)instead of -1,  $e \wedge (ln(2))$  instead of 2,  $(2 + tan(3)) * (4 - sin(5)) \wedge 6 - 7/8$  instead of 27620.3413, etc. Here's the <u>list of the functions</u> which WeBWorK understands.

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Decide whether each of the following statements is true or false. If the statement could be true and could be false, i.e., if you need more information to decide, choose "Impossible to tell".

1. Let *U* be the subspace of  $\mathbb{R}^3$  consisting of the *x*-axis, and let *V* be the subspace of  $\mathbb{R}^3$  consisting of the *xy*-plane. Then  $U \oplus V = \text{span}(U \cup V)$ .

2. Let *U* be the subspace of  $\mathbb{R}^3$  consisting of the *z*-axis, and let *V* be the subspace of  $\mathbb{R}^3$  consisting of the *xy*-plane. Then  $U \oplus V = \text{span}(U \cup V)$ .

3. Let *U* and *V* be subspaces of *W*, and suppose that there exist vectors  $u \in U, v \in V, w \in U \oplus V$  such that u + v = w. Then it is possible to find vectors  $u' \in U, v' \in V$  with  $u' \neq u, v' \neq v$ , such that u' + v' = w. ?

4. Let  $\mathbb{R}^2$  be equal to  $U \oplus V$ , where U is the span of the vector (a,b) and V is the span of the vector (c,d). Certainly it is true that (0,0) is in both U and V, and that (0,0) + (0,0) = (0,0). There are no nonzero vectors  $u \in U, v \in V$  such that u + v = (0,0). ?

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5. Let *U* and *V* be subspaces of *W* with  $U \cap V = \{0_W\}$  and let  $u \in U$  and  $v \in V$  be vectors. Then for any constants  $a, b \in \mathbb{R}$ , we have that  $au + bv \in U \oplus V$ . ?

6. Let *U* and *V* be subspaces of *W*. Then  $U \oplus V = V \oplus U$ . ?

Decide whether each of the following statements is true or false. If the statement could be true and could be false, i.e., if you need more information to decide, choose "Impossible to tell". (Assume all vector spaces are finite-dimensional.)

1. Let U be the subspace of  $\mathbb{R}^3$  consisting of the z-axis. Then  $U^{\perp}$  is the xy-plane. ?

2. Let *U* be a subspace of *W*. Then given any vector  $w \in W$ , there exist vectors  $u \in U, v \in U^{\perp}$  such that u + v = w.

3. Let U be a subspace of W. Then there exist vectors  $u \neq u' \in U, v \neq v' \in U^{\perp}$  such that u + v = u' + v'. ?

4. Let U be a subspace of W equal to all of W. That is, let U = W and consider it as a subspace of itself. Then  $U^{\perp}$  is empty, that is, there are no vectors at all inside  $U^{\perp}$ .

5. Let U and V be subspaces of W with  $U^{\perp} = V$ . Then  $V^{\perp} = U$ . ?

#### WeBWorK ReadingHomework25 is due : 12/05/2010 at 03:00pm PST.

### MAT22A-Waldron-Fall-2010

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Let *M* be an  $m \times n$  matrix and let *V* be a vector in  $\mathbb{R}^m$ .

Decide whether each of the following statements is true or false.

1. The matrix  $M^T M$  must be a square matrix. ?

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2. The equation MX = V must have a solution. That is, there must be some vector *X* such that MX = V. ?

3. If  $X_0$  is some vector in  $\mathbb{R}^n$  such that  $\overrightarrow{MX_0} = V$ , then  $X = X_0$  must be a least-squares solution to MX = V. ?

4. If  $X_0$  is some vector in  $\mathbb{R}^n$  so that  $X = X_0$  is a least-squares solution to MX = V, then it must also be true that  $MX_0 = V$ . ?