

SECTION-2
Introduction to Fluid Mechanics

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Math-280: A Mathematical Introduction
to
Shock Waves

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FLUID MECHANICS

REF: HUGH'S & MARSDEN - "Short course in FL. Mech" Pt. 1
 COURANT-FRIEDRICH'S "Supersonic Flow & Shock Waves"

①

- Assume that a fluid is moving in \mathbb{R}^3
 Assume that particles fixed wrt fluid move with a given smooth velocity field $u(x, t)$, $x \in \mathbb{R}^3$, $u \in \mathbb{R}^3$

- If a particle is at position $a = (a_1, a_2, a_3)$ at time $t=0$, let $x(a, t) \equiv x_t(a)$ be its position at time t . Call $x(a, \cdot)$ the trajectory of the initial particle a . Thus

$$(ODE) \quad \frac{\partial}{\partial t} x(a, t) = u(x, t), \quad x(a, 0) = a$$

I.e. "particle trajectories solve ODE."

Thm If u is smooth, then (ODE) has unique soln for some t -interval

DEFN: We call a the Lagrangian coordinates of the fluid particle

DEFN: We call $x \equiv x(a, t)$ the Eulerian coordinates of fluid particles



②

- Consider a scalar function $f(x, t)$ (think of f as being the density of the fluid). Then f is a fn of (a, t) also:

$$f[a, t] = f(x(a, t), t)$$

\uparrow Lagrangian coordinates \uparrow Eulerian coordinates

Moreover: $\frac{\partial f}{\partial t}[a, t]$ is the rate at which f changes in a frame fixed wrt the particle

$$\frac{\partial f}{\partial t}[a, t] = \frac{\partial f}{\partial t}(x(a, t), t) = \frac{\partial f}{\partial x} \frac{\partial x}{\partial t} + \frac{\partial f}{\partial t}$$

$$= \nabla f \cdot u + f_t \equiv \frac{Df}{Dt}$$

$$\nabla f = (f_{x_1}, f_{x_2}, f_{x_3})(x, t)$$

\uparrow
 f in Eulerian coordinates

③

DEFN. the material derivative of $f(x, t)$ is defined to be

$$\dot{f} \equiv \frac{Df}{Dt} \equiv f_t + \nabla f \cdot u$$

" \dot{f} is the rate of change of f along particle path."

H.W.#1 SHOW

$$\begin{aligned} \dot{(fg)} &= \dot{f}g + f\dot{g} \\ \dot{h(f(x, t), g(x, t))} &= h_f \dot{f} + h_g \dot{g} \end{aligned}$$

④

Let $\Omega(t)$ be a 3-D open set moving with the fluid

$$\Omega(t) \equiv \{x \in \mathbb{R}^3 : x = x(a, t) \text{ for some } a \in \Omega(0)\}$$

We wish to calculate

$$\frac{d}{dt} \int_{\Omega(t)} f(x, t) dx^3$$

PROBLEM: we can't pass the deriv. thru the \int sign because the region is changing with time

THEOREM ② (REYNOLDS TRANSPORT THEOREM)

$$\frac{d}{dt} \int_{\Omega(t)} f(x, t) dx^3 = \int_{\Omega(t)} f_t + \operatorname{div}(fu) dx^3$$

BASIC IDENTITY: Let $J(a, t) = \det \left| \frac{\partial x}{\partial a} \right|$
(J measures the local volume change from $t=0$ to $t=t$)
then

$$(\dot{J}) \quad \dot{J} = \frac{\partial}{\partial t} J(a, t) = J \operatorname{div} u$$

⑤

CONCLUDE: the rate and which volumes are changing is proportional to $\text{div } u$.

HW#2 Verify (J)

HINT: differentiate the determinant using the multilinearity of det plus the fact that

$$\frac{\partial}{\partial t} \frac{\partial}{\partial a} x = \frac{\partial}{\partial a} \frac{\partial}{\partial t} x = \frac{\partial}{\partial a} u$$

Proof of Reynolds Transport:

$$\int_{\Omega(t)} f(x,t) dx^3 = \int_{\Omega_0} f(x(a,t), t) \underbrace{J(a,t)} da$$

$dx = \left| \frac{\partial x}{\partial a} \right| da$ gives the volume change.



⑥

$$\frac{d}{dt} \int_{\Omega(t)} f(x,t) dx = \frac{d}{dt} \int_{\Omega_0} f(x(a,t), t) J(a,t) da$$

$$= \int_{\Omega_0} \frac{\partial}{\partial t} \{ f(x(a,t), t) J(a,t) \} da$$

$$= \int_{\Omega_0} \frac{Df}{Dt} J + f \frac{\partial}{\partial t} J(a,t) da$$

$$= \int_{\Omega_0} (f_t + \nabla f \cdot u) J + (f \text{div } u) J da$$

$$= \int_{\Omega(t)} f_t + \underbrace{\nabla f \cdot u + f \text{div } u}_{\text{div}(fu)} dx$$

$$= \int_{\Omega(t)} f_t + \text{div } fu dx \quad \checkmark$$

⑦

CONSERVATION OF MASS: (Continuity Equation)

- Assume the fluid has a density

$$\rho(x, t) = \frac{\text{mass}}{\text{volume}}$$

Conservation of mass reads:

$$\frac{d}{dt} \int_{\Omega(t)} \rho(x, t) dx = \int_{\Omega(t)} \rho_t + \text{div}(\rho u) dx = 0$$

$$(MA) \quad \rho_t + \text{div}(\rho u) = 0 \quad \Leftrightarrow$$

HOMEWORK: Assume (MA) holds. Prove the identity

$$(HW)\#3) \quad (\rho f)_t + \text{div}(\rho f u) = \rho \frac{Df}{Dt}$$

hold for all smooth $f \equiv f(x, t)$.

$$\underline{\text{Cor.}}: \frac{d}{dt} \int_{\Omega(t)} \rho f dx = \int_{\Omega(t)} \rho \frac{Df}{Dt} dx$$

⑧

Balance of momentum

Assume: \exists a stress tensor $\sigma \equiv (\sigma^{ij}) = (\sigma_{ij})$ such that the force on $\partial\Omega(t)$ is given by

$$F_{\partial\Omega} = \int_{\partial\Omega} \sigma \cdot n ds \quad (\sigma \cdot n = \sigma^{ij} n_j)$$

(σ ~ $\frac{\text{force}}{\text{area}}$)

$n \equiv$ outward normal to $\partial\Omega$

(we don't say what σ depends on - this determines the equations)

Defn: $F \equiv \sigma \cdot n$ equals the force per area exerted by fluid on an area element oriented by \vec{n} (The force exerted inward so)

$\sigma = -pI$ for perfect fluid

⑨

- "Conservation of Momentum" means that the time rate of change of the momentum in $\Omega(t)$ equals the total force acting on $\partial\Omega$:

$$\begin{matrix} 3 \\ \text{eqs} \end{matrix} \rightarrow \frac{d}{dt} \int_{\Omega(t)} \rho u \, dx = \int_{\partial\Omega(t)} \sigma \cdot n \, ds = \int_{\Omega(t)} \operatorname{div} \sigma \, dx$$

$$\int_{\Omega(t)} \left\{ (\rho u)_t + \operatorname{div}(\rho u \otimes u) - \operatorname{div} \sigma \right\} dx = 0$$

$$(M_0) \quad (\rho u)_t + \operatorname{div} \{ (\rho u \otimes u) - \sigma \} = 0$$

$$u \otimes u = u \cdot u^t = [u^i u^j]$$

$$(M_0)^i \quad (\rho u^i)_t + \operatorname{div} \{ \rho u^i u - \sigma^{i\cdot} \} = 0.$$

↑ i th row of σ

⑩

- If (MA) holds, then (M0) can be rewritten as:

$$(M_0)' \quad \rho \frac{Du}{Dt} = \operatorname{div} \sigma \quad \leftarrow \begin{cases} \text{infinitesimal} \\ \text{version of} \\ \text{Newton's Laws} \end{cases}$$

↑
"mass x acc" = "force"

(HW #4) Derive (M0)'

- Theorem ③ Assume (MA) & (MB) hold. Then ^⑪
 σ is symmetric ($\sigma^{ij} = \sigma^{ji}$) iff the
 balance of angular momentum holds:

$$(AM) \quad \frac{d}{dt} \int_{\Omega(t)} \rho (x \times u) dx = \int_{\partial\Omega(t)} (x \times \sigma \cdot n) dA$$

I.e., $\int_{\Omega(t)} \rho (x \times u) dx$ is the angular momentum
 in $\Omega(t)$, and this changes at a rate given
 by the moment of the forces on the $\partial\Omega$

(PROOF OMITTED - see Hughes & Marsden)

Ex: $F = m \ddot{x}$, $\frac{d}{dt} m(x \times \dot{x}) = m(\dot{x} \times \dot{x}) + m(x \times \ddot{x})$
 \uparrow
 one particle case $\quad \quad \quad = x \times F$

- We always assume σ symmetric.

⑫ CONSERVATION of ENERGY

ASSUME: $E \equiv$ Energy/volume in fluid

$$E = \rho e + \frac{1}{2} \rho |u|^2$$

$e =$ specific internal energy $\equiv \frac{\text{energy}}{\text{mass}}$

$e \equiv$ "the energy per mass stored in the
 vibrations of molecules"

$\frac{1}{2} \rho |u|^2 \equiv$ kinetic energy

$$\sigma^{ij} u^j = (\sigma u) \cdot n$$

Work = $\int F \cdot ds$
 $= \int F \cdot u dt \Rightarrow \frac{d(\text{work})}{dt}$
 $= F \cdot u = \frac{\text{force} \times \text{dist}}{\text{time}}$ ✓

$$(En) \quad \frac{d}{dt} \int_{\Omega(t)} E dx = \underbrace{\int_{\partial\Omega(t)} F \cdot u ds}_{\text{Rate Work is done on } \Omega \text{ by boundary forces}} - \underbrace{\int_{\partial\Omega(t)} q \cdot n ds}_{\text{Heat flux through } \partial\Omega}$$

$q =$ heat flux vector.

Fourier's LAW: $q = -k \nabla T$; $k \equiv$ conductivity

$T \equiv$ temperature

(13)

$$\frac{d}{dt} \int_{\Omega(t)} E dx = \int_{\Omega(t)} \operatorname{div}(\sigma \cdot u) dx + \int_{\Omega(t)} k \operatorname{div} \nabla T dx$$

$$\int_{\Omega(t)} E_t + \operatorname{div}(Eu) - \operatorname{div}(\sigma \cdot u) - k \Delta T dx = 0$$

$$(En) \quad E_t + \operatorname{div}(Eu - \sigma u) = k \Delta T$$

$$\begin{aligned} & E_t + \operatorname{div}(Eu) \\ &= (\rho e + \frac{1}{2} \rho u^2)_t + \operatorname{div}[\rho u \cdot u] \\ &= \rho \frac{De}{Dt} + \frac{1}{2} \rho \frac{Du^2}{Dt} \end{aligned}$$

Theorem (4) Assume (MA), (MO) hold and that

σ is symmetric. Then

$$\frac{d}{dt} K = - \int_{\Omega(t)} \sigma \cdot D dx + \int_{\partial \Omega(t)} F \cdot u ds$$

work per time
generated by interior
stresses

work per time
generated by stresses
acting on $\partial \Omega$

Here: $K = \int_{\Omega(t)} \frac{1}{2} \rho u^2 dx \equiv$ kinetic energy in $\Omega(t)$

$D \equiv$ symmetric part of velocity gradient:

(14)

I.e., $u = \begin{bmatrix} u^1 \\ u^2 \\ u^3 \end{bmatrix}$ velocity

$$\nabla u = \left[\frac{\partial u^i}{\partial x^j} \right] = \begin{bmatrix} \nabla u^1 \\ \nabla u^2 \\ \nabla u^3 \end{bmatrix}$$

$$D = \frac{1}{2} \left[\frac{\partial u^i}{\partial x^j} + \frac{\partial u^j}{\partial x^i} \right] \equiv \text{symmetric part of } \nabla u$$

$$A = \frac{1}{2} \left[\frac{\partial u^i}{\partial x^j} - \frac{\partial u^j}{\partial x^i} \right] \equiv \text{antisymmetric part of } \nabla u$$

$$D + A = \nabla u.$$

$$\sigma \cdot D = \sum_{i,j} \sigma_{ij} D_{ij}$$

Proof: By H.W. #4, (NO)' \Rightarrow AN#5 derive formula $\textcircled{15}$ for integration by parts
 $\int_{\Omega} f_{x_i} g = -\int_{\Omega} f g_{x_i} + \int_{\partial\Omega} f g n_i ds$
 from the divergence theorem

$$\rho \frac{Du}{Dt} = \text{div } \sigma$$

thus, $\textcircled{\text{HW}\#3}$

$$\frac{d}{dt} K = \frac{d}{dt} \frac{1}{2} \int_{\Omega(t)} \rho u^2 dx \stackrel{\text{HW}\#5}{=} \frac{1}{2} \int_{\Omega(t)} \rho \frac{Du^2}{Dt} dx$$

$$= \frac{1}{2} \int_{\Omega(t)} 2 \rho \frac{Du}{Dt} \cdot u dx = \int_{\Omega(t)} \text{div } \sigma \cdot u dx$$

$$= \int_{\Omega(t)} \sigma^{ij}_{,j} u^i dx \stackrel{\text{integrate by parts}}{=} - \int_{\Omega(t)} \sigma^{ij} u^i_{,j} dx + \int_{\partial\Omega(t)} \sigma^{ij} u^i n_j ds$$

\uparrow sum on i, j

$$= - \int_{\Omega(t)} \sigma^{ij} (D_{ij} + A_{ij}) dx + \int_{\partial\Omega} F \cdot u ds$$

(FIP) $\sum_{ij} \sigma^{ij} A_{ij} = 0$ since A antisymmetric, D symmetric.
 \Rightarrow Answer.

Note: since σ, D are symmetric, $\textcircled{16}$

$$\sigma \cdot D \stackrel{\text{dot product}}{=} \sum_{ij} \sigma^{ij} D_{ij} \stackrel{\text{summation convention - sum repeated indices}}{=} \sigma^{ij} D_{ij}$$

$$\text{tr}[\sigma \cdot D] \stackrel{\text{matrix product}}{=} \text{tr}[\sigma^{ik} D_{kj}] = \sigma^{ik} D_{ki} \stackrel{\text{symmetry of } D \text{ or } \sigma}{=} \sigma^{ij} D_{ij}$$

$$\therefore \frac{d}{dt} K = \frac{d}{dt} \int_{\Omega(t)} \frac{1}{2} \rho u^2 dx = \int_{\Omega(t)} -\text{tr}(\sigma \cdot D) + \text{div}(\sigma u) dx$$

$$(KE) \quad \frac{1}{2} \rho \frac{Du^2}{Dt} = -\text{tr}(\sigma \cdot D) + \text{div}(\sigma u)$$

$$(En) \quad \rho \frac{De}{Dt} + \frac{1}{2} \rho \frac{Du^2}{Dt} = \text{div}(\sigma u) + k \Delta T$$

$$(KE) + (En) \Rightarrow$$

$$(En)' \quad \rho \frac{De}{Dt} = \text{tr}(\sigma \cdot D) + k \Delta T$$

⑰

Note: We obtain $(En)'$ by substituting a formula for (KE) in terms of stress obtained from (M0). In fact, the integration by parts is simply a derivation for a vector identity:

$$\frac{1}{2} \rho \frac{Du^2}{Dt} = \rho u \cdot \frac{Du}{Dt} \stackrel{\uparrow}{=} u \cdot \text{div} \sigma = \text{div}(\sigma u) - \text{tr}(\sigma \cdot D)$$

(M0) $\rho \frac{Du}{Dt} = \text{div} \sigma$

$$u \cdot \text{div} \sigma = \text{div}(\sigma u) - \nabla u \cdot \sigma$$

$$(D+A) \cdot \sigma = D\sigma$$

⑱

Example ①: Perfect Fluid

Defn: A fluid is perfect if it can exert no tangential forces; i.e.

$$[\sigma_{ij}] = -p[\delta_{ij}] = -pI$$

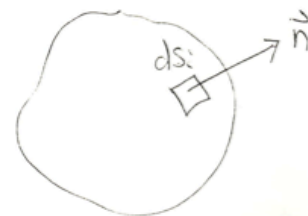
where p is a scalar called the pressure. Note:

$$F_{\Omega} = \int_{\partial\Omega} \sigma \cdot n \, ds \approx \sum_i F_{ds_i}$$

$$F_{ds_i} = -p \vec{n} = -p[\delta_{ij}] \vec{n}$$

↑
"force on Ω "

$$\Rightarrow \sigma_{ij} = -p \delta_{ij}$$



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In case of Perfect Fluid:

$$(MA)_p \rho_t + \text{div}(\rho u) = 0$$

$$(M0)_p^i (\rho u^i)_t + \text{div}(\rho u^i u + p e^i) = 0$$

$$\text{div } \sigma = \text{div}[-p \delta_{ij}] = \begin{bmatrix} \text{div } p e_1 \\ \text{div } p e_2 \\ \text{div } p e_3 \end{bmatrix} = -\nabla p$$

$e^i = e_i = (0 \dots 1 \dots 0)$
 ↑
 ith slot

$$e^1 = e_1 = (1, 0, 0)$$

$$e^2 = e_2 = (0, 1, 0)$$

$$e^3 = e_3 = (0, 0, 1)$$

$$(M0)_p (\rho u)_t + \text{div}[\rho u \otimes u + p I] = 0$$

3x3 identity matrix

$$(M0)_p' \rho \frac{Du}{Dt} = -\nabla p$$

$$\text{div}(pI) = \nabla p$$

"force on a fluid element is given by the gradient of the pressure"

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$$(En)_p E_t + \text{div}[(E+p)u] = k \Delta T$$

$$-\sigma u = p I u = p u$$

$$(KE)_p \frac{1}{2} \rho \frac{Du^2}{Dt} = -\nabla p \cdot u$$

$$-\text{tr}(\sigma \cdot D) + \text{div}(\sigma u) + p \text{tr} D - \text{div}(p u) = -\nabla p \cdot u$$

(Changes in KE are due to accelerations caused by ∇p)

$$(En)_p' \rho \frac{De}{dt} = -p \text{div} u + k \Delta T$$

$$\text{tr}(\sigma \cdot D) = -p \text{div} u$$

(Changes in internal energy are due to the compressive action of pressure forces and transfers due to heat conduction)

②

Note ① $\dot{J} = J \operatorname{div} u$, thus

$$\operatorname{div} u = \frac{\dot{J}}{J} \equiv \frac{\text{rate at which local volumes change}}{\text{per volume}}$$

$$\operatorname{div} u \sim \frac{\Delta[\text{Vol}]}{\text{Vol} \Delta t}$$

$$\therefore -p \operatorname{div} u \sim \frac{\text{force} \cdot \Delta \text{Vol}}{\Delta \text{area} \text{Vol} \cdot \Delta t} \sim \frac{\text{force} \cdot \Delta \text{dist}}{\text{Vol} \Delta t}$$

$$\sim \frac{\Delta \text{work}}{\Delta t \text{ Vol}} \sim \text{work per time}$$

done on fluid element (per volume!) due to compression by pressure forces

②

• We can make this precise:

Let $v = 1/\rho \equiv \text{specific volume} \equiv \frac{\text{volume}}{\text{mass}}$

$$(\text{MA})' \Rightarrow \frac{D\rho}{Dt} = -\rho \operatorname{div} u$$

$$(\text{Vol}) \quad \frac{Dv}{Dt} = \frac{D(1/\rho)}{Dt} = -\frac{1}{\rho^2} \frac{D\rho}{Dt} = \frac{1}{\rho} \operatorname{div} u$$

$$\therefore -p \operatorname{div} u = -\rho p \frac{Dv}{Dt}$$

and we obtain

$$(\text{En})_p'' \quad \rho \frac{De}{Dt} = -\rho p \frac{Dv}{Dt} + k \Delta T$$

• $k \Delta T \equiv$ rate at which energy is transferred into the fluid element by heat conduction due to the temperature gradient. If $k=0$, then $(\text{En})''$ says

$$\frac{De}{Dt} = -p \frac{Dv}{Dt}$$

- Thus we can interpret $(En)'$ (23)

$$\rho \frac{De}{Dt} = -P \operatorname{div} u + k \Delta T$$

↑	↑	↑
rate at which internal energy changes in fluid element	rate at which work is done on fluid element due to compression	rate at which heat enters fluid element due to heat conduction.

Note ②: If we assume $k=0$, then $(En)'$ says that all of the work done locally by the compressive action of pressure forces* is stored locally in the internal energy \Rightarrow None of the work is converted into heat and diffused \Rightarrow no viscosity or heat conduction
 *(The part that doesn't chng KE)

- The five conservation laws which result when we assume $\sigma \equiv -PI$ and $k=0$ are called the Compressible (24)

Euler Equations:

$$(MA) \quad \rho_t + \operatorname{div} \rho u = 0$$

$$(Mo)^2 \quad (\rho u^i)_t + \operatorname{div} [\rho u^i u + P e^i] = 0$$

$$(En) \quad E_t + \operatorname{div} [(E+P)u] = 0 \quad E = \rho e + \frac{1}{2} \rho u^2$$

\Leftrightarrow No viscosity and no heat conduction.
 5 equations

6 unknowns: $\rho, u^1, u^2, u^3, P, e$

To close system we need a constitutive relation between ρ, P, e .

Thermo: any two of ρ, P, e, T determine other two: we return to this.

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Note ③ The equations are closed by giving $e = e(v, s)$, (e, v, s specific quantities = per mass)

Then 2nd Law Thermo says

$$de = Tds - pdv \Rightarrow \frac{\partial e}{\partial s} = T, \quad \frac{\partial e}{\partial v} = -p < 0$$

defines T and p . Modelling real gases \Rightarrow assumptions

$$p_v < 0, \quad p_w > 0, \quad e_v < 0$$

The polytropic eqn of state $e(s, v) = C_v \frac{1}{\gamma-1} \exp\left(\frac{s}{C_v}\right)$

satisfies these conditions

Theorem: If we assume 2nd Law $de = Tds - pdv$,

then (MA), (M0) & (En) are equivalent to (MA), (M0) & (S) where

$$(S) \quad S_t + \operatorname{div}(Su) = 0 \quad S = \rho s = \frac{\text{entropy}}{\text{vol}}$$

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Proof: First note that

$$S_t + \operatorname{div}(Su) = (\rho s)_t + \operatorname{div}(\rho s u) = \frac{Ds}{Dt}, \text{ so that (S)}$$

is equivalent to

$$(S) \quad \frac{Ds}{Dt} = 0.$$

Now (HW) 2nd Law $\Rightarrow \frac{De}{Dt} = T \frac{Ds}{Dt} - p \frac{Dv}{Dt}$.

Since we have shown that if we assume (MA) & (M0), then (K) holds, and so then

(En) holds iff (En)' holds

$$(En') \quad \frac{De}{Dt} = -p \frac{Dv}{Dt}$$

Conclude: from 2nd Law that (En)' holds

iff $\frac{Ds}{Dt} = 0$ holds \checkmark

②

Note ④ ^(FIP) By Note ② we expect that the flow is reversible in a thermodynamical sense. To this end, note that if p is independent of u , and p is independent of t except through the variables ρ and e , then if $\rho(x,t)$, $e(x,t)$, $u(x,t)$ solve (MA), (MO) and (En), then so does $\rho(x,-t)$, $-u(x,-t)$, $e(x,-t)$. \Rightarrow the flow is reversible. Thus in (En)'

$$(En)' \quad \rho \frac{De}{Dt} = -p \operatorname{div} u$$

it makes sense to call $-p \operatorname{div} u$ the reversible work.

②

EXAMPLE ②: Compressible Navier Stokes
(Stress tensor accounts for viscosity)

• Assume: $\sigma = -pI + \tilde{\sigma}(D)$

where $\tilde{\sigma}$ depends only on the symmetric part of velocity gradient D . ($\tilde{\sigma}$ is symmetric as we assume)

Theorem: Assume $\tilde{\sigma}$ satisfies the following assumptions:

- ① $\tilde{\sigma}$ is a smooth function of D
- ② $\tilde{\sigma}(0) = 0$
- ③ $\tilde{\sigma}$ is isotropic: (i.e., rotationally invariant)

$$\tilde{\sigma}(U D U^{-1}) = U \tilde{\sigma}(D) U^{-1} \quad \forall U \text{ orthog. } U^t U = \text{id}$$

④ $\tilde{\sigma}$ is linear in D .

Then

$$\tilde{\sigma} = \lambda \operatorname{div} u I + 2\mu D$$

for some constants λ, μ .

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If we take

$$(*) \quad \sigma = -pI + \lambda \operatorname{div} u I + 2\mu D$$

then we obtain compressible Navier Stokes:

$$(MA) \quad \rho_t + \operatorname{div} \rho u = 0$$

$$(MO)_{NS} \quad (\rho u)_t + \operatorname{div} (\rho u \otimes u + pI) = (\lambda + \mu) \nabla \operatorname{div} u + \mu \Delta u$$

μ called dynamic/shear viscosity

$\lambda + \mu \equiv$ bulk viscosity
 $k =$ thermal conductivity

2nd order linear in $u \approx$ dissipation term if you see this as $\approx u_t = \Delta u$

H.W. #6 verify that (*) implies $(MO)_{NS}$

Note: assume $\mu, \lambda \geq 0$ so RHS represent dissipation

Note: for incompressible Navier-Stokes $\rho = \text{const}$, $\operatorname{div} u = 0$ so RHS reduces to $\mu \Delta u$

(30)

$$(E_n)^{FIP} \quad \rho \frac{Dc}{Dt} = \operatorname{tr}(\sigma \cdot D) + k \Delta T$$

$$\sigma = -pI + \lambda \operatorname{div} u I + 2\mu D$$

$$\sigma \cdot D = [-p + \lambda \operatorname{div} u] \cdot D + 2\mu D^2$$

$$\operatorname{tr}(\sigma \cdot D) = -p \operatorname{div} u + \lambda (\operatorname{div} u)^2 + 2\mu \operatorname{tr} D^2$$

$$(E_n)_{NS} \quad \rho \frac{Dc}{Dt} = -\rho p \frac{Dv}{Dt} + \lambda \left[\rho \frac{Dv}{Dt} \right]^2 + 2\mu |\nabla u|^2$$

or

$$(E_n)_{NS} \quad \frac{Dc}{Dt} = -p \frac{Dv}{Dt} + \frac{\lambda}{\rho} \left[\rho \frac{Dv}{Dt} \right]^2 + 2 \frac{\mu}{\rho} |\nabla u|^2$$

Defn: $-p \frac{Dv}{Dt}$ is called the reversible work (per mass), because we have reversibility when $\lambda = \mu = 0$.

Defn: $\frac{\lambda}{\rho} \left[\rho \frac{Dv}{Dt} \right]^2 + 2 \frac{\mu}{\rho} |\nabla u|^2$ is called the irreversible work because it is always positive, and hence it represents viscous work due to stresses being turned into heat

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• Using 2nd Law & $(En)_{NS}$ we can see that evolution by Navier Stokes is irreversible:

By $(En)_{NS}$,

$$\frac{De}{Dt} = -p \frac{Dv}{Dt} + \frac{\lambda}{\rho} \left[\rho \frac{Dv}{Dt} \right]^2 + 2 \frac{\mu}{\rho} |\nabla u|^2$$

& by 2nd Law

$$\frac{De}{Dt} = T \frac{Ds}{Dt} - p \frac{Dv}{Dt}$$

so

$$\frac{Ds}{Dt} = \frac{1}{T} \frac{De}{Dt} + \frac{p}{T} \frac{Dv}{Dt} = \frac{1}{T} \left\{ -p \frac{Dv}{Dt} + \frac{\lambda}{\rho} \left[\rho \frac{Dv}{Dt} \right]^2 + 2 \frac{\mu}{\rho} |\nabla u|^2 \right\} + \frac{p}{T} \frac{Dv}{Dt}$$

$$\boxed{\frac{Ds}{Dt} = \frac{\lambda}{\rho T} \left[\rho \frac{Dv}{Dt} \right]^2 + \frac{2\mu}{\rho T} |\nabla u|^2}$$

Conclude: when $\lambda, \mu > 0$, entropy per mass strictly increases along particle paths unless both $\frac{Dv}{Dt} = 0$ & $|\nabla u| = 0$.

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