

Math 21C

Final Exam

7/31/08

Name:

Solutions

Signature:

Student ID:

- There are **ten** (plus cover and bonus) pages to the exam.
- The exam totals 100 points, plus 10 bonus points.
- You will have 100 minutes to complete the exam.
- No calculators, notes, or books allowed.
- Good luck!

Problem	Points	Your Score
1	10	
2	10	
3	10	
4	10	
5	10	
6	10	
7	10	
8	10	
9	10	
10	10	
Bonus	10	
Total	100	

1. Definitions and Examples: consider a smooth function $f(x, y, z)$.

a. (2 points) Write the definition of the *partial derivative*, $\frac{\partial f}{\partial y}$. (an example is **not** sufficient for full credit)

$$\frac{\partial f}{\partial y} = \lim_{\Delta y \rightarrow 0} \frac{f(x, y + \Delta y, z) - f(x, y, z)}{\Delta y}$$

b. (2 points) Write the definition of the *gradient*, ∇f . (an example is **not** sufficient for full credit)

$$\vec{\nabla} f = \begin{pmatrix} \partial f / \partial x \\ \partial f / \partial y \\ \partial f / \partial z \end{pmatrix}$$

c. (2 points) Write the definition of the *directional derivative* of f at the point \mathbf{c} in the direction of \mathbf{v} , $(D_{\mathbf{v}}f)(\mathbf{c})$. (an example is **not** sufficient for full credit)

$$(D_{\hat{\mathbf{v}}} f)(\mathbf{c}) = (\vec{\nabla} f|_{\mathbf{c}}) \cdot \hat{\mathbf{v}}$$

d. (2 points) Write the definition of the *Hessian*, $H(f)$. (an example is **not** sufficient for full credit)

$$Hf = \begin{pmatrix} \frac{\partial^2 f}{\partial x^2} & \frac{\partial^2 f}{\partial x \partial y} & \frac{\partial^2 f}{\partial x \partial z} \\ \frac{\partial^2 f}{\partial y \partial x} & \frac{\partial^2 f}{\partial y^2} & \frac{\partial^2 f}{\partial y \partial z} \\ \frac{\partial^2 f}{\partial z \partial x} & \frac{\partial^2 f}{\partial z \partial y} & \frac{\partial^2 f}{\partial z^2} \end{pmatrix}$$

e. (2 points) Consider a sequence a_n . Write the "epsilon" definition for the following statement: "the sequence a_n converges to L ", i.e. $\lim_{n \rightarrow \infty} a_n = L$. (an example is **not** sufficient for full credit)

for all $\epsilon > 0$, there exists
an N such that

$$n > N \Rightarrow |a_n - L| < \epsilon.$$

2. Short Answers: let $f(x, y, z) = 2x - y + z \cos z$

a. (5 points) Compute ∇f , $H(f)$, $\frac{\partial^3 f}{\partial x \partial y \partial z}$, and the directional derivative of f at the point $(0, 0, 0)$ in the direction of $\begin{pmatrix} 1 \\ 1 \\ -1 \end{pmatrix}$.

$$\vec{\nabla} f = \begin{pmatrix} 2 \\ -1 \\ \cos z - z \sin z \end{pmatrix} \quad Hf = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & (-2 \sin z - z \cos z) \end{pmatrix}$$

$$\frac{\partial^3 f}{\partial x \partial y \partial z} = \frac{\partial}{\partial x} \frac{\partial^2 f}{\partial y \partial z} = \frac{\partial}{\partial x} 0 = 0.$$

$$(D_{\begin{pmatrix} 1 \\ 1 \\ -1 \end{pmatrix}} f)(\vec{0}) = (\vec{\nabla} f|_{\vec{0}}) \cdot \frac{\begin{pmatrix} 1 \\ 1 \\ -1 \end{pmatrix}}{\sqrt{3}} = \begin{pmatrix} 2 \\ -1 \\ 1 \end{pmatrix} \cdot \begin{pmatrix} 1 \\ 1 \\ -1 \end{pmatrix} / \sqrt{3} = 0$$

b. (5 points) Let $x(s, t, p) = s + t$, $y(s, t, p) = p^2 - t$, and $z(s, t, p) = 2$. Calculate $\frac{\partial f}{\partial t}$.

$$\frac{\partial f}{\partial t} = \frac{\partial f}{\partial x} \frac{\partial x}{\partial t} + \frac{\partial f}{\partial y} \frac{\partial y}{\partial t} + \frac{\partial f}{\partial z} \frac{\partial z}{\partial t}$$

$$= 2(1) + (-1)(-1) + (\cos z - z \sin z) 0$$

$$= 2 + 1 = 3.$$

3

3. a. (5 points) Write an equation for the plane tangent to the surface $F = x^3 - y^2 + z = -1$ at the point $(0, 1, 0)$.

$$\vec{\nabla} F = \begin{pmatrix} 3x^2 \\ -2y \\ 1 \end{pmatrix} \quad \vec{\nabla} F|_{(0,1,0)} = \begin{pmatrix} 0 \\ -2 \\ 1 \end{pmatrix} = \vec{n}$$

$$0x - 2y + z = d$$

~~$2x$~~

$$-2(1) + 0 = -2 = d$$

$$-2y + z = -2$$

b. (5 points) Write an equation for the line orthogonal to the surface through the point $(-1, 1, 1)$.

$$\vec{\nabla} F|_{(0,1,0)} = \begin{pmatrix} 0 \\ -2 \\ 1 \end{pmatrix} = \vec{m}$$

$$\vec{p}(t) = \begin{pmatrix} -1 \\ 1 \\ 1 \end{pmatrix} + \begin{pmatrix} 0 \\ -2 \\ 1 \end{pmatrix} t$$

$$-\infty < t < \infty$$

4. a. (5 points) Find and classify all critical points for the function
 $f(x, y) = x^4 - x^2 - y^2$.

$$\vec{\nabla} f = \begin{pmatrix} 4x^3 - 2x \\ -2y \end{pmatrix} = \vec{0} \Rightarrow \begin{aligned} 2x(2x^2 - 1) &= 0 \\ -2y &= 0 \end{aligned}$$

\Rightarrow 3 CPs @ $(0, 0), (\sqrt{1/2}, 0), (-\sqrt{1/2}, 0)$

$$\det(Hf) = \det \begin{pmatrix} 12x^2 - 2 & 0 \\ 0 & -2 \end{pmatrix} = 4 - 24x^2 = D$$

$$D(0, 0) = 4 > 0, \frac{\partial^2 f}{\partial y^2} = -2 < 0 \Rightarrow \underline{(0, 0) \text{ is a max.}}$$

$$D(\sqrt{1/2}, 0) = D(-\sqrt{1/2}, 0) = -8 < 0$$

b. (5 points) Find all local extrema for this function subject to the constraint $x = y$

$$\vec{\nabla} f = \lambda \vec{\nabla} g$$

$$g(x, y) = x - y = 0$$

$$\begin{pmatrix} 4x^3 - 2x \\ -2y \end{pmatrix} = \lambda \begin{pmatrix} 1 \\ -1 \end{pmatrix} \Rightarrow \begin{cases} \lambda = 2y \\ \lambda = 4x^3 - 2x \\ x = y \end{cases}$$

$$\Rightarrow 4x^3 - 2x = 2x \Rightarrow x^3 = x$$

$$\Rightarrow x = 0 \text{ or } x = \pm 1$$

\Rightarrow
 $(\sqrt{1/2}, 0),$
 $(-\sqrt{1/2}, 0)$
 are
 saddles

\Rightarrow 3 CPs @ $(0, 0), (1, 1), (-1, -1)$.

5. Consider the trajectory $\mathbf{p}(t) = \begin{pmatrix} 1 - 2t^{-2} \\ 1 + t^{-2} \\ 3t^{-2} \end{pmatrix}$, $1 < t < \infty$.

a. (5 points) Calculate the arclength of this path.

$$\begin{aligned}
 L &= \int_1^{\infty} \|\vec{p}'(t)\| dt = \int_1^{\infty} \left\| \begin{pmatrix} 4t^{-3} \\ -2t^{-3} \\ -6t^{-3} \end{pmatrix} \right\| dt \\
 &= \int_1^{\infty} t^{-3} \left\| \begin{pmatrix} 4 \\ -2 \\ -6 \end{pmatrix} \right\| dt = \int_1^{\infty} \sqrt{56} t^{-3} dt \\
 &= \lim_{b \rightarrow \infty} \sqrt{56} \left. \frac{t^{-2}}{-2} \right|_1^b = \lim_{b \rightarrow \infty} \left(\sqrt{56} \left(-\frac{b^{-2}}{2} + \frac{1}{2} \right) \right) \\
 &= \boxed{\frac{1}{2} \sqrt{56}}
 \end{aligned}$$

b. (5 points) Let $\theta(t)$ denote the angle between the trajectory's velocity,

written $\vec{p}'(t)$, and the vector $\begin{pmatrix} -1 \\ 1 \\ 6 \end{pmatrix}$. Compute $\lim_{t \rightarrow \infty} \theta(t)$

$$\vec{p}'(t) = \begin{pmatrix} 4t^{-3} \\ -2t^{-3} \\ -6t^{-3} \end{pmatrix}$$

$$\lim_{t \rightarrow \infty} \theta(t) = \lim_{t \rightarrow \infty} \text{Arccos} \left(\frac{\vec{p}' \cdot \vec{v}}{\|\vec{p}'\| \|\vec{v}\|} \right) = \text{Arccos} \lim_{t \rightarrow \infty} \left(\frac{-42t^{-3}}{t^{-3} \sqrt{56} \sqrt{38}} \right)$$

$$= \text{Arccos} \lim_{t \rightarrow \infty} \left(\frac{-42}{\sqrt{56} \sqrt{38}} \right)$$

$$= \boxed{\text{Arccos} \left(\frac{-42}{\sqrt{56} \sqrt{38}} \right)}$$

6. (10 points) Write an equation for the plane containing the following two lines: one line is orthogonal to the surface $x + y - z^2 = 1$ through $(1, 1, 1)$, while the other line is parallel to the line of intersection of $x + y = 1$ with $x - y = 0$, and also contains the point $(1, 1, 1)$.

$$\vec{\nabla}f = \begin{pmatrix} 1 \\ 1 \\ -2z \end{pmatrix} \quad \vec{\nabla}f|_{(1,1,1)} = \begin{pmatrix} 1 \\ 1 \\ -2 \end{pmatrix} = \vec{m}_1$$

$$\cdot \vec{P}_1(t) = \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} + \begin{pmatrix} 1 \\ 1 \\ -2 \end{pmatrix} t$$

$$\vec{n}_1 = \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix}, \quad \vec{n}_2 = \begin{pmatrix} 1 \\ -1 \\ 0 \end{pmatrix}$$

$$\vec{n}_1 \times \vec{n}_2 = \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix} \times \begin{pmatrix} 1 \\ -1 \\ 0 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ -2 \end{pmatrix} = \vec{m}_2$$

$$\cdot \vec{P}_2(t) = \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} + \begin{pmatrix} 0 \\ 0 \\ -2 \end{pmatrix} t$$

plane contains \vec{P}_1, \vec{P}_2 so is parallel to \vec{m}_1, \vec{m}_2 . then

$$\vec{n} = \vec{m}_1 \times \vec{m}_2 = \begin{pmatrix} 1 \\ 1 \\ -2 \end{pmatrix} \times \begin{pmatrix} 0 \\ 0 \\ -2 \end{pmatrix} = \begin{pmatrix} -2 \\ 2 \\ 0 \end{pmatrix}$$

$$\begin{aligned} -2x + 2y + 0z &= d \\ -2(1) + 2(1) &= 0 = d \end{aligned}$$

$$\boxed{-2x + 2y = 0}$$

7. Determine whether the following sequences or series converge or diverge:

a. (2 points) $a_n = n^{-2}$.

$$\lim_{n \rightarrow \infty} a_n = \lim_{n \rightarrow \infty} \frac{1}{n^2} = 0 \Rightarrow a_n \rightarrow 0.$$

b. (2 points) $b_n = \frac{1-n}{1+n^2}$.

$$\lim_{n \rightarrow \infty} b_n = \lim_{n \rightarrow \infty} \frac{1-n}{1+n^2} = 0 \Rightarrow b_n \rightarrow 0.$$

c. (3 points) $\sum_{n=0}^{\infty} \frac{n}{n+1}$.

$$\lim_{n \rightarrow \infty} \frac{n}{n+1} = 1 \neq 0$$

$\Rightarrow \sum_{n=0}^{\infty} \frac{n}{n+1}$ diverges (Nth term test)

d. (3 points) $\sum_{n=0}^{\infty} \frac{n}{n^3+1}$.

LCT vs. $\frac{1}{n^2}$

recall, $\sum_{n=1}^{\infty} \frac{1}{n^2}$ is a convergent p-series. (p=2 > 1)

$$\lim_{n \rightarrow \infty} \frac{\frac{n}{n^3+1}}{\frac{1}{n^2}} = \lim_{n \rightarrow \infty} \frac{n^3}{n^3+1} = 1, \text{ so both}$$

series do the same. hence,

$$\sum_{n=0}^{\infty} \frac{n}{n^3+1} \text{ converges.}$$

8. a. (5 points) Provide examples of *nonzero* vectors \mathbf{u} , \mathbf{v} , and \mathbf{w} such that $\mathbf{u} \times \mathbf{w} = \mathbf{v} \times \mathbf{w}$, but $\mathbf{u} \neq \mathbf{v}$.

$$\text{let } \vec{u} = \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}, \vec{v} = \begin{pmatrix} 2 \\ 2 \\ 2 \end{pmatrix}, \vec{w} = \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}.$$

clearly, $\vec{u} \neq \vec{v}$. however

$$\vec{v} = 2\vec{u} = 2\vec{w}, \text{ i.e. } \vec{u} \parallel \vec{v} \parallel \vec{w}, \text{ so}$$

$$\vec{u} \times \vec{v} = \vec{u} \times \vec{w} = \vec{v} \times \vec{w} = \vec{0}.$$

b. (5 points) Provide examples of *nonzero* vectors \mathbf{u} , \mathbf{v} , and \mathbf{w} such that $\mathbf{u} \cdot \mathbf{w} = \mathbf{v} \cdot \mathbf{w}$, but $\mathbf{u} \neq \mathbf{v}$.

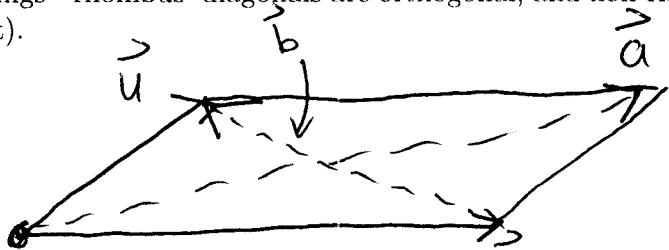
$$\text{let } \vec{u} = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}, \vec{v} = \begin{pmatrix} 2 \\ 0 \\ 0 \end{pmatrix},$$

$$\vec{w} = \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}.$$

clearly, $\vec{u} \neq \vec{v}$. however,

$$\vec{u} \cdot \vec{w} = \vec{v} \cdot \vec{w} = 0.$$

9. a. (5 points) Prove that the diagonals of a parallelogram are orthogonal exactly when the parallelogram is a rhombus. (Hint: you need to prove two things - rhombus' diagonals are orthogonal, and non-rhombus' diagonals are not).




$$\vec{a} = \vec{u} + \vec{v}$$

$$\vec{b} = \vec{u} - \vec{v}$$

$$\vec{a} \cdot \vec{b} = (\vec{u} + \vec{v}) \cdot (\vec{u} - \vec{v}) = \vec{u} \cdot \vec{u} + \vec{v} \cdot \vec{u} - \vec{u} \cdot \vec{v} - \vec{v} \cdot \vec{v}$$

$$= \|\vec{u}\|^2 - \|\vec{v}\|^2, \quad \text{hence } \vec{a} \cdot \vec{b} = 0$$

(diags orthogonal)

$\iff \|\vec{u}\| = \|\vec{v}\|$, i.e.  is a rhombus.

b. (5 points) Prove or disprove: if $a_n > 0$ for all n , and $\sum_{n=0}^{\infty} a_n$ converges,

then $\sum_{n=0}^{\infty} a_n^2$ also converges.

LCT: Since $\sum_{n=0}^{\infty} a_n$ converges,

$$\text{then } \lim_{n \rightarrow \infty} \frac{a_n^2}{a_n} = \lim_{n \rightarrow \infty} a_n = 0 \quad a_n \rightarrow 0.$$

\implies Since $\sum_{n=1}^{\infty} a_n$ converges,

$\sum_{n=1}^{\infty} a_n^2$ also converges

(limit comparison)

10. Consider vector-valued functions (with three components) $\mathbf{u}(t)$ and $\mathbf{v}(t)$. Prove or disprove the following:

a. (5 points) $\frac{d}{dt}(\mathbf{u}(t) \cdot \mathbf{v}(t)) = \mathbf{u}'(t) \cdot \mathbf{v}(t) + \mathbf{u}(t) \cdot \mathbf{v}'(t)$.

Proof:
$$\frac{d}{dt}(\vec{u} \cdot \vec{v}) = \frac{d}{dt}(u_1 v_1 + u_2 v_2 + u_3 v_3)$$

$$= (u_1' v_1 + u_1 v_1' + u_2' v_2 + u_2 v_2' + u_3' v_3 + u_3 v_3')$$

$$= (\vec{u}' \cdot \vec{v}) + (\vec{u} \cdot \vec{v}')$$

b. (5 points) $\frac{d}{dt}(\mathbf{u}(t) \times \mathbf{v}(t)) = \mathbf{u}'(t) \times \mathbf{v}(t) - \mathbf{u}(t) \times \mathbf{v}'(t)$.

Disproof: (should be +)

Counterexample

let $\vec{u} = \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}$, $\vec{v} = \begin{pmatrix} -t \\ t \\ 0 \end{pmatrix}$

then $\frac{d}{dt}(\vec{u} \times \vec{v}) = \frac{d}{dt} \begin{pmatrix} +1 \\ t \\ 0 \end{pmatrix} = \begin{pmatrix} +1 \\ 1 \\ 0 \end{pmatrix}$, but

$\vec{u}' \times \vec{v} - \vec{u} \times \vec{v}' = \vec{0} \times \vec{v} - \vec{u} \times \begin{pmatrix} -1 \\ 1 \\ 0 \end{pmatrix} = -\vec{u} \times \begin{pmatrix} -1 \\ 1 \\ 0 \end{pmatrix}$

$= \begin{pmatrix} -1 \\ -1 \\ -1 \end{pmatrix} \times \begin{pmatrix} -1 \\ 1 \\ 0 \end{pmatrix} = \begin{pmatrix} -1_{11} \\ 1 \\ 0 \end{pmatrix}$

argh!!

bad CX, good strategy

instead, one should use
 $\vec{u} = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}$, $\vec{v} = \begin{pmatrix} 0 \\ t \\ 0 \end{pmatrix}$

Bonus. (10 points) Given a vector-valued function

$$\mathbf{V}(x, y, z) = \begin{pmatrix} V_x(x, y, z) \\ V_y(x, y, z) \\ V_z(x, y, z) \end{pmatrix}, \text{ the curl of } \mathbf{V}, \text{ written } \nabla \times \mathbf{V},$$

is defined similarly to the cross product:

$$\nabla \times \begin{pmatrix} V_x(x, y, z) \\ V_y(x, y, z) \\ V_z(x, y, z) \end{pmatrix} = \begin{pmatrix} \frac{\partial V_z}{\partial y} - \frac{\partial V_y}{\partial z} \\ \frac{\partial V_x}{\partial z} - \frac{\partial V_z}{\partial x} \\ \frac{\partial V_y}{\partial x} - \frac{\partial V_x}{\partial y} \end{pmatrix}. \text{ Prove the following:}$$

The curl of any gradient is zero, i.e. if $f(x, y, z)$ is a smooth scalar-valued function, then $\nabla \times (\nabla f) = \mathbf{0}$. (Warning: it is not necessarily true (unless you can prove) that $\nabla \times (\nabla f) = (\nabla \times \nabla)f$.)

$$\begin{aligned} \vec{\nabla} \times (\vec{\nabla} f) &= \vec{\nabla} \times \begin{pmatrix} \partial f / \partial x \\ \partial f / \partial y \\ \partial f / \partial z \end{pmatrix} \\ &= \begin{pmatrix} \frac{\partial}{\partial y} \frac{\partial f}{\partial z} - \frac{\partial}{\partial z} \frac{\partial f}{\partial y} \\ \frac{\partial}{\partial z} \frac{\partial f}{\partial x} - \frac{\partial}{\partial x} \frac{\partial f}{\partial z} \\ \frac{\partial}{\partial x} \frac{\partial f}{\partial y} - \frac{\partial}{\partial y} \frac{\partial f}{\partial x} \end{pmatrix} = \begin{pmatrix} \frac{\partial^2 f}{\partial y \partial z} - \frac{\partial^2 f}{\partial z \partial y} \\ \frac{\partial^2 f}{\partial z \partial x} - \frac{\partial^2 f}{\partial x \partial z} \\ \frac{\partial^2 f}{\partial x \partial y} - \frac{\partial^2 f}{\partial y \partial x} \end{pmatrix} \\ &= \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} = \vec{0}. \end{aligned}$$

(mixed partials are equal for smooth functions)

$$\vec{\nabla} = \begin{pmatrix} \partial / \partial x \\ \partial / \partial y \\ \partial / \partial z \end{pmatrix}$$