### PARTIAL DIFFERENTIAL EQUATIONS

## Math 118A, Fall 2013 Midterm 1: Solutions

## **1.** [15%] Is the PDE

$$yu_{xx} + u_{yy} = 0$$

linear or nonlinear? For what constants A, B, C is the function

$$u(x,y) = Ax^2y + Bxy^2 + Cy^4$$

a solution of the PDE?

### Solution.

- The PDE is linear (and homogeneous with variable coefficients).
- For the given function,

$$u_{xx} = 2Ay, \qquad u_{yy} = 2Bx + 12Cy^2,$$

SO

$$yu_{xx} + u_{yy} = (2A + 12C)y^2 + 2Bx.$$

This is zero if and only if A=-6C and B=0, so the most general such solution is

$$u(x,y) = A(y^4 - 6x^2y)$$
.

**2.** [20%] Find the solution u(x,t) of the following initial value problem for the wave equation

$$u_{tt} = c^2 u_{xx},$$
  $u(x,0) = \sin x,$   $u_t(x,0) = e^x.$ 

# Solution.

• Using d'Alembert's solution

$$u(x,t) = \frac{1}{2} \left[ \phi(x+ct) + \phi(x-ct) \right] + \frac{1}{2c} \int_{x-ct}^{x+ct} \psi(\xi) \, d\xi$$

with  $\phi(x) = \sin x$  and  $\psi(x) = e^x$ , we get

$$u(x,t) = \frac{1}{2} \left[ \sin(x+ct) + \sin(x-ct) \right] + \frac{1}{2c} \int_{x-ct}^{x+ct} e^{\xi} d\xi$$
$$= \frac{1}{2} \left[ \sin(x+ct) + \sin(x-ct) \right] + \frac{1}{2c} \left[ e^{x+ct} - e^{x+ct} \right].$$

**3.** [25%] (a) Give a particular solution of the PDE

$$u_t + 2u_x = x.$$

- (b) What is the general solution of this PDE?
- (c) Find the solution u(x,t) of the initial value problem

$$u_t + 2u_x = x,$$
  $u(x,0) = 0.$ 

#### Solution.

• (a) We look for a particular solution  $u = u_p(x)$  depending only on x. Then  $2u'_p(x) = x$ , so a particular solution is

$$u_p(x) = \frac{1}{4}x^2.$$

• (b) By linearity, the general solution has the form

$$u(x,t) = u_p(x) + v(x,t)$$

where v is a solution of the homogeneous equation  $v_t + 2v_x = 0$ . The general solution of this advection equation is v = f(x - 2t), so

$$u(x,t) = \frac{1}{4}x^2 + f(x-2t)$$

where f(x) is an arbitrary function of integration.

• (c) Imposing the initial condition on the general solution, we get that

$$0 = \frac{1}{4}x^2 + f(x),$$

so  $f(x) = -x^2/4$ , and the solution is

$$u(x,t) = \frac{1}{4}x^2 - \frac{1}{4}(x-2t)^2 = xt - t^2.$$

**4.** [20%] (a) Suppose that a, c, k are constants. Show that

$$u(x,t) = e^{at}v(x - ct, t)$$

is a solution of the PDE

$$u_t + cu_x = ku_{xx} + au$$

if and only if v(x,t) is a solution of  $v_t = kv_{xx}$ .

(b) Give an expression for the solution of the initial value problem

$$u_t + cu_x = ku_{xx} + au,$$
  $u(x,0) = \phi(x)$ 

in terms of the source function

$$S(x,t) = \frac{1}{\sqrt{4\pi kt}} e^{-x^2/4kt}$$

of the heat equation.

#### Solution.

• (a) By the product and chain rules,

$$u_t = ae^{at}v - ce^{at}v_x + e^{at}v_t$$
$$= e^{at}(av - cv_x + v_t),$$
$$u_x = e^{at}v_x,$$
$$u_{xx} = e^{at}v_{xx}.$$

It follows that

$$u_t + cu_x - ku_{xx} - au = e^{at} (av - cv_x + v_t + cv_x - kv_{xx} - av)$$
  
=  $e^{at} (v_t - kv_{xx})$ 

which shows that u is a solution of the original PDE if and only if v is a solution of the heat equation  $v_t = kv_{xx}$ .

• (b) Since u(x,0) = v(x,0), we have  $v(x,0) = \phi(x)$ . It follows that v is given by the solution of the initial value problem for the heat equation,

$$v(x,t) = \int_{-\infty}^{\infty} S(x-y,t)\phi(y) \, dy.$$

Therefore

$$u(x,t) = e^{at} \int_{-\infty}^{\infty} S(x - ct - y)\phi(y) dy$$
$$= \frac{e^{at}}{\sqrt{4\pi kt}} \int_{-\infty}^{\infty} e^{-(x - y - ct)^2/4kt} \phi(y) dy.$$

**5.** [20%] Suppose that vehicles moving in one direction down a freeway have a density u(x,t) (measured e.g. in vehicles/mile). Also suppose that at density  $0 \le u \le k$  the vehicles move at speed

$$V(u) = \frac{m}{k}(k - u)$$

(measured e.g. in miles/hour) where m and k are constants.

- (a) Give an interpretation of the constants m, k.
- (b) How many vehicles are there in a section of the road with  $a \le x \le b$ ? What is the rate (measured e.g. in vehicles/hour) at which vehicles cross some point x on the road?
- (c) Assume there are no exits or entrances. Write down an equation that expresses "conservation of vehicles" and derive a PDE for u(x,t). Is this PDE linear or nonlinear?

#### Solution.

- (a) The constant m is the maximum speed of vehicles on an empty road (e.g.  $m = \text{speed limit} + 10 \,\text{m.p.h.}$ ). The constant k is the maximum density of vehicles at which traffic stops moving.
- (b) We have

number of vehicles in 
$$a \le x \le b = \int_a^b u(x,t) \, dx$$
,  
rate at which vehicles cross  $x = \text{density} \times \text{velocity}$   
 $= u(x,t) V\left(u(x,t)\right)$ 

• (c) If no vehicles enter or leave the road, then

rate of change of number of vehicles in  $a \le x \le b$ 

= rate at which vehicles enter through a and leave through b,

which implies that

$$\frac{d}{dt} \int_a^b u(x,t) dx = u(a,t)V(u(a,t)) - u(b,t)V(u(b,t)).$$

Writing

$$\frac{d}{dt} \int_a^b u(x,t) dx = \int_a^b u_t(x,t) dx,$$
$$u(a,t)V(u(a,t)) - u(b,t)V(u(b,t)) = -\int_a^b [uV(u)]_x dx,$$

and combining the integrals, we get that

$$\int_{a}^{b} \{u_t + [uV(u)]_x\} \ dx = 0.$$

Since this equation holds for all a < b, the integrand must be zero (assuming that it's a continuous function) and we find that u(x,t) satisfies the PDE

$$u_t + [uV(u)]_x = 0,$$

or, after use of the explicit expression for V,

$$u_t + \frac{m}{k} \left[ u(k-u) \right]_x = 0.$$

This equation can also be written as

$$u_t + mu_x - \frac{2m}{k}uu_x = 0$$

• This equation is nonlinear (because of the  $uu_x$  term).