# PROBLEM SET 8: Solutions Math 207A, Fall 2018

**1.** Sketch the phase plane of the system

$$x_t = x^2, \qquad y_t = -y.$$

Linearize the system about the equilibrium (0,0) and determine the unstable, stable, and center subspaces of the equilibrium. What is the stable manifold  $W^s(0,0)$ ? Show that there are many possible choices of an invariant  $(C^1)$ center manifold  $W^c(0,0)$  that is tangent to the center subspace at (0,0).

## Solution

• the linearized system at (0,0) is

$$x_t = 0, \qquad y_t = -y.$$

This has eigenvalues  $\lambda = -1, 0$  with corresponding eigenvectors  $\vec{r} = (0, 1)^T, (1, 0)^T$  which span the (one-dimensional) stable and center subspaces, respectively. The (zero-dimensional) unstable subspace consists of 0.

• The equation of the trajectories is

$$\frac{dy}{dx} = -\frac{y}{x^2}$$

Separating variables and solving this equation, we find that

$$y = Ce^{1/x}$$

where C is a constant of integration.

- For  $C \neq 0$ , the trajectories approach the origin smoothly  $(C^{\infty})$  as  $x \to 0^-$ , go to infinity as  $x \to 0^+$ , a and approach the horizontal asymptote y = C as  $|x| \to \infty$ .
- The stable subspace of the origin, the *y*-axis, is invariant under the flow, so it is also the stable manifold. The unstable manifold is 0.

• Any curve of the form

$$y = \begin{cases} Ce^{1/x} & -\infty < x < 0\\ 0 & 0 \le x \end{cases}$$

for some constant C is a smooth  $(C^{\infty})$  invariant manifold. (It consists of three trajectories: the part for x < 0, the equilibrium 0, and the positive x-axis.) It is tangent to the center subspace at 0, so any such curve is a center manifold. In particular, the whole x-axis is a center manifold (C = 0), but it is not the only one. **2.** The following Selkov system for  $x(t), y(t) \ge 0$ , depending on parameters  $a, \mu > 0$ , provides a simple model of glycolysis:

$$x_t = -x + ay + x^2y, \qquad y_t = \mu - ay - x^2y.$$

(a) Find the fixed point and classify it as a function of the parameters. Show that if 0 < a < 1/8, then there are possible Hopf bifurcations as  $\mu$  increases from 0 to  $\infty$ . What are the possible Hopf bifurcation points  $(x_0, y_0; \mu_0)$ ? (b) By plotting the phase planes numerically, show that Hopf bifurcations

occur at the points in (a) and determine whether they are subcritical or supercritical.

### Solution

• The fixed point is

$$\bar{x} = \mu, \qquad \bar{y} = \frac{\mu}{a + \mu^2}.$$

The fixed point changes stability, with a complex conjugate pair of eigenvalues passing through the imaginary axis, when

$$\mu^2 = \frac{1}{2} \left( 1 - 2a \pm \sqrt{1 - 8a} \right),\,$$

so these are the possible Hopf bifircation points.

• Numerical solutions show that there is a supercritical Hopf bifurcation as  $\mu$  increases through the smaller value, and a subcritical Hopf bifurcation as  $\mu$  increases through the larger value.

**Remark.** See S. H Strogatz, *Nonlinear dynamics and Chaos*, pp. 205–209 for more details (where  $\mu = b$ ). The Wikipedia page on Hopf Bifurcation has a nice animation of the numerical solutions.

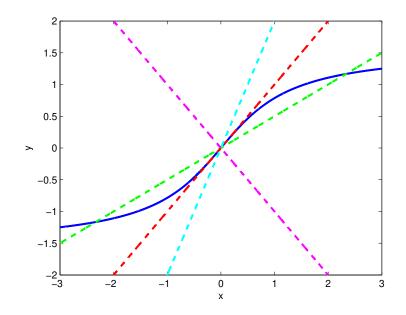


Figure 1: Graphs of  $y = \tan^{-1} x$  (blue) and  $y = -2x/\mu$  for:  $\mu = -4$  (green);  $\mu = -2$  (red);  $\mu = -1$  (cyan);  $\mu = 2$  (magenta).

**3.** Consider the following discrete dynamical system for  $x_n \in \mathbb{R}$  depending on a parameter  $\mu \in \mathbb{R}$ :

$$x_{n+1} = -\frac{\mu}{2} \tan^{-1} x_n.$$

(a) Describe the fixed point(s) of the system and determine their stability. What bifurcations of fixed points occur as  $\mu$  increases from  $-\infty$  to  $\infty$ ?

(b) Show that a period-doubling bifurcation occurs at  $\mu = 2$ . Is the resulting period-two orbit stable or unstable?

### Solution

• (a) The fixed points of the map

$$f(x;\mu) = -\frac{\mu}{2} \tan^{-1} x$$

correspond to intersections of the line  $\mu y = -2x$  with the graph  $y = \tan^{-1} x$ . (See Figure 1.)

• If  $\mu < -2$ , then the slope of the line is positive and less than the slope of the inverse tangent at x = 0, and there are three such points with

$$x = 0, \quad x = \pm \bar{x}(\mu)$$

where  $\bar{x}(\mu) > 0$  satisfies

$$-\frac{2}{\mu}\bar{x} = \tan^{-1}\bar{x}.$$

If  $\mu \geq -2$ , then there is a unique fixed point at x = 0.

- If  $\mu = -2$ , then the line is tangent to the graph of the inverse tangent at x = 0, and a subcritical pitchfork bifurcation occurs as  $\mu$  increases through -2. There are no other bifurcations of fixed points.
- We have

$$f_x(x;\mu) = -\frac{\mu}{2} \frac{1}{1+x^2}$$

Thus,  $f_x(0;\mu) = -\mu/2$ , so  $|f_x(0,\mu)| < 1$  if  $|\mu| < 2$  and  $|f_x(0,\mu)| > 1$  if  $|\mu| > 2$ . It follows that the fixed point x = 0 is asymptotically stable if  $|\mu| < 2$  and unstable if  $|\mu| > 2$ .

- The fixed point x = 0 gains stability as  $\mu$  increases through -2 and the eigenvalue  $f_x(0;\mu)$  decreases through 1 (corresponding to a bifurcation of fixed points); and loses stability as  $\mu$  increases through 2 and the eigenvalue  $f_x(0;\mu)$  decreases through -1.
- If  $\mu < -2$ , then

$$f_x(\pm \bar{x}(\mu);\mu) = -\frac{\mu}{2} \frac{1}{1 + \bar{x}^2(\mu)}$$

The graph of  $y = \tan x$  has smaller slope than the line  $y = -2x/\mu$  at  $x = \bar{x}(\mu)$ , so  $0 < f_x(\bar{x}(\mu); \mu) < 1$ , and these fixed points are stable. This claim is clear geometrically, but we omit an analytical proof.

• (b) A period doubling bifurcation can occur at (x, mu) = (0, 2) since the eigenvalue  $f_x(0; \mu)$  decreases through -1. A discussion of whether the bifurcation is subcritical or supercritical and the stability of the periodic orbit is omitted. **4.** The Hénon map on  $\mathbb{R}^2$  is given by

$$x_{n+1} = a - by_n - x_n^2;$$
  
$$y_{n+1} = x_n.$$

(a) Find the fixed points and determine their stability.

(b) Carry out a numerical exploration of this map for various values of the parameters  $a, b \in \mathbb{R}$ . It's up to you how much you want to explore, especially at the end of the quarter, but you should provide a plot of the forward orbit of the point  $(x_0, y_0) = (0, 0)$  for a = 1.4 and b = -0.3 in the region  $-2 \le x \le 2$ ,  $-2 \le y \le 2$  and briefly discuss the result.

#### Solution

• (a) The fixed points (x, y) satisfy

$$x = a - by - x^2, \qquad y = x$$

which gives

$$x = y = \frac{1}{2} \left[ -(1+b) \pm \sqrt{(1+b)^2 + 4a} \right].$$

There are no fixed points if  $4a < -(1+b)^2$ .

• The Jacobian matrix is

$$D_{(x,y)}f = \begin{pmatrix} -2x & -b \\ 1 & 0 \end{pmatrix},$$

with eigenvalues

$$\lambda = -x \pm \sqrt{x^2 - b}.$$

The fixed points are asymptotically stable if  $|\lambda| < 1$  for both eigenvalues, and unstable if  $|\lambda| > 1$  for at least one eigenvalue.

- For a = 1.4, b = -0.3, we find (hopefully correctly) that  $x \approx 0.884$ with eigenvalues  $\lambda \approx 0.156, -1.924$ , or  $x \approx -1.584$  with eigenvalues  $\lambda \approx -0.092, 3.260$ . Both fixed points are (orientation reversing) saddle points with  $|\lambda_1| < 1$  and  $|\lambda_2| > 1$ .
- (b) Numerical solutions should show that the orbit approaches the Hénon attractor, which is a strange attractor with a fractal, Cantor set structure. This chaotic behavior is associated with a homoclinic tangle that results from transverse intersection of the stable and unstable manifolds of the saddle points.