

PROBLEM SET 2: SOLUTIONS  
Math 207B, Winter 2016

1. A particle of mass  $m$  with position  $\vec{x}(t)$  at time  $t$  has potential energy  $V(\vec{x})$  and kinetic energy

$$T = \frac{1}{2}m|\vec{x}_t|^2.$$

The action of the particle over times  $t_0 \leq t \leq t_1$  is the time-integral of the difference between the kinetic and potential energy:

$$S(\vec{x}) = \int_{t_0}^{t_1} (T - V) dt.$$

(a) Show that an extremal  $\vec{x}(t)$  of  $S$  satisfies Newton's second law  $\vec{F} = m\vec{a}$  for motion in a conservative force field  $\vec{F} = -\nabla V$ .

(b) Show that the total energy of the particle  $E = T + V$  is a constant independent of time.

**Solution.**

- (a) The Euler-Lagrange equation for the action

$$S(\vec{x}) = \int_{t_0}^{t_1} L(\vec{x}, \vec{x}_t) dt, \quad L(\vec{x}, \vec{x}_t) = \frac{1}{2}m|\vec{x}_t|^2 - V(\vec{x})$$

is given by

$$-\frac{d}{dt} \left( \frac{\partial L}{\partial \vec{x}_t} \right) + \frac{\partial L}{\partial \vec{x}} = 0.$$

- Using the summation convention, and the Kronecker- $\delta$  defined by

$$\delta_{ij} = \begin{cases} 1 & \text{if } i = j, \\ 0 & \text{if } i \neq j, \end{cases}$$

we have

$$\left[ \frac{\partial |\vec{a}|^2}{\partial \vec{a}} \right]_i = \frac{\partial}{\partial a_i} (a_j a_j) = 2a_j \delta_{ij} = 2a_i = [2\vec{a}]_i,$$

so  $\partial F / \partial \vec{x}_t = m\vec{x}_t$ , and  $\partial F / \partial \vec{x} = -\nabla V(\vec{x})$ .

- The Euler-Lagrange equation is

$$m\vec{x}_{tt} = -\nabla V(\vec{x}),$$

which is Newton's second law.

- (b) Taking the scalar product of the ODE with  $\vec{x}_t$ , we get that

$$m\vec{x}_t \cdot \vec{x}_{tt} = -\vec{x}_t \cdot \nabla V(\vec{x}).$$

It follows that

$$\frac{d}{dt} \left[ \frac{1}{2} m \vec{x}_t \cdot \vec{x}_t + V(\vec{x}) \right] = 0,$$

so

$$\frac{1}{2} m |\vec{x}_t|^2 + V(\vec{x}) = \text{constant}.$$

2. Let  $\Omega \subset \mathbb{R}^n$  be a bounded region with smooth boundary (so the divergence theorem holds) and  $f : \overline{\Omega} \rightarrow \mathbb{R}$  a smooth function. Derive the Euler-Lagrange equation and natural boundary condition that are satisfied by a smooth extremal  $u : \overline{\Omega} \rightarrow \mathbb{R}$  of the functional

$$J(u) = \int_{\Omega} \left( \frac{1}{2} |\nabla u|^2 - fu \right) dx.$$

**Solution.**

- For  $\phi \in C^\infty(\overline{\Omega})$ , we have

$$\begin{aligned} \frac{d}{d\epsilon} J(u + \epsilon\phi)|_{\epsilon=0} &= \frac{d}{d\epsilon} \int_{\Omega} \left[ \frac{1}{2} (\nabla u + \epsilon\nabla\phi) \cdot (\nabla u + \epsilon\nabla\phi) - f(u + \epsilon\phi) \right] dx \Big|_{\epsilon=0} \\ &= \int_{\Omega} (\nabla u \cdot \nabla\phi - f\phi) dx \end{aligned}$$

- The divergence theorem implies that

$$\begin{aligned} \int_{\Omega} (\nabla u \cdot \nabla\phi) dx &= \int_{\Omega} [\nabla \cdot (\phi\nabla u) - \phi\Delta u] dx \\ &= \int_{\partial\Omega} \phi \frac{\partial u}{\partial n} dS - \int_{\Omega} \phi\Delta u dx. \end{aligned}$$

- If  $\phi = 0$  on  $\partial\Omega$ , then

$$\frac{d}{d\epsilon} J(u + \epsilon\phi)|_{\epsilon=0} = - \int_{\Omega} (\Delta u + f) \phi dx.$$

The fundamental lemma of the calculus of variations implies that an extremal  $u$ , with

$$\frac{d}{d\epsilon} J(u + \epsilon\phi)|_{\epsilon=0} = 0,$$

for all  $\phi$  satisfies the Euler-Lagrange equation

$$-\Delta u = f \quad \text{in } \Omega.$$

- For functions  $\phi$  that do not necessarily vanish on the boundary, we have

$$\frac{d}{d\epsilon} J(u + \epsilon\phi)|_{\epsilon=0} = \int_{\partial\Omega} \phi \frac{\partial u}{\partial n} dS.$$

It follows that the natural boundary condition for an extremal  $u$  is the Neumann condition

$$\frac{\partial u}{\partial n} = 0 \quad \text{on } \partial\Omega.$$

**3.** The transverse displacement at position  $x$  and time  $t$  of an elastic string vibrating in the  $(x, y)$ -plane is given by  $y = u(x, t)$ , where  $a \leq x \leq b$  and  $t_0 \leq t \leq t_1$ . If the density of the string per unit length is  $\rho(x)$  and the tension in the string is a constant  $T$ , then (for small displacements) the motion of the string is an extremum of the action

$$S(u) = \int_{t_0}^{t_1} \int_a^b \left( \frac{1}{2} \rho u_t^2 - \frac{1}{2} T u_x^2 \right) dx dt.$$

Derive the Euler-Lagrange equation for  $u(x, t)$ .

**Solution.**

- For every  $\phi \in C_c^\infty((a, b) \times (t_0, t_1))$ , we have

$$\frac{d}{d\epsilon} S(u + \epsilon\phi)|_{\epsilon=0} = \int_{t_0}^{t_1} \int_a^b (\rho u_t \phi_t - T u_x \phi_x) dx dt.$$

- Integrating by parts and using the fact that  $\phi = 0$  at  $x = a, b$  and  $t = t_0, t_1$ , we get that

$$\frac{d}{d\epsilon} S(u + \epsilon\phi)|_{\epsilon=0} = \int_{t_0}^{t_1} \int_a^b (-\rho u_{tt} + T u_{xx}) \phi dx dt.$$

- The fundamental lemma of the calculus of variations then implies that a smooth extremal  $u$  of  $S$  satisfies the wave equation

$$\rho u_{tt} = T u_{xx}.$$

4. The ( $n$ -dimensional) area of a surface  $y = u(x)$  over a region  $\Omega \subset \mathbb{R}^n$  is given by

$$J(u) = \int_{\Omega} \sqrt{1 + |\nabla u|^2} dx.$$

Find the Euler-Lagrange equation (called the minimal surface equation) that is satisfied by a smooth extremum of this functional.

**Solution.**

- Using the divergence theorem, we find for every  $\phi \in C_c^\infty(\Omega)$  that

$$\begin{aligned} \frac{d}{d\epsilon} J(u + \epsilon\phi)|_{\epsilon=0} &= \frac{d}{d\epsilon} \int_{\Omega} \sqrt{1 + |\nabla u + \epsilon\nabla\phi|^2} dx \Big|_{\epsilon=0} \\ &= \int_{\Omega} \frac{1}{2\sqrt{1 + |\nabla u|^2}} \frac{d}{d\epsilon} |\nabla u + \epsilon\nabla\phi|^2 \Big|_{\epsilon=0} dx \\ &= \int_{\Omega} \frac{\nabla u \cdot \nabla\phi}{\sqrt{1 + |\nabla u|^2}} dx \\ &= - \int_{\Omega} \nabla \cdot \left( \frac{\nabla u}{\sqrt{1 + |\nabla u|^2}} \right) \phi dx. \end{aligned}$$

- The Euler-Lagrange equation for smooth extremals of  $J$  is therefore

$$\nabla \cdot \left( \frac{\nabla u}{\sqrt{1 + |\nabla u|^2}} \right) = 0$$

- Using the summation convention, we can write this equation in component form as

$$\left( \frac{u_{x_i}}{\sqrt{1 + u_{x_j}u_{x_j}}} \right)_{x_i} = 0.$$

5. Let  $X = \{u \in C^1([-1, 1]) : u(-1) = -1, u(1) = 1\}$ , where  $C^1([a, b])$  denotes the space of continuously differentiable functions on  $[a, b]$ . Define  $J : X \rightarrow \mathbb{R}$  by

$$J(u) = \int_{-1}^1 x^4 (u')^2 dx.$$

(a) Show that

$$\inf_{u \in X} J(u) = 0,$$

but  $J(u) > 0$  for every  $u \in X$  (so  $J$  does not attain its infimum on  $X$ ).

(b) What happens when you try to solve the Euler-Lagrange equation for extremals of  $J$ ?

**Solution.**

- We have  $J(u) \geq 0$  for every  $u \in X$ , so  $\inf J(u) \geq 0$ .
- To make  $J(u)$  as small as possible, we want to make  $u'$  small except near  $x = 0$ , where  $u'$  can be large.
- In order to do this, let  $f : \mathbb{R} \rightarrow \mathbb{R}$  be any continuously differentiable, odd function such that  $f(x) \rightarrow 1$  as  $x \rightarrow \infty$  and

$$\int_0^\infty x^4 f'(x)^2 dx = C < \infty.$$

For example, we could choose  $f(x) = \tanh x$ .

- If we were to include piecewise smooth functions in  $X$ , or functions in a Sobolev space such as  $H^1(-1, 1)$ , we could instead take

$$f(x) = \begin{cases} -1 & \text{if } -\infty < x \leq -1, \\ x & \text{if } -1 < x < 1, \\ 1 & \text{if } 1 \leq x < \infty. \end{cases}$$

- For  $\epsilon > 0$ , define

$$u^\epsilon(x) = \frac{f(x/\epsilon)}{f(1/\epsilon)}.$$

Then  $u^\epsilon(-1) = -1$  and  $u^\epsilon(1) = 1$  so  $u^\epsilon \in X$ .

- Making the change of variables  $x = \epsilon t$ , we have

$$\begin{aligned} J(u^\epsilon) &= \frac{2}{\epsilon^2 f(1/\epsilon)^2} \int_0^1 x^4 \left[ f' \left( \frac{x}{\epsilon} \right) \right]^2 dx \\ &= \frac{2\epsilon^3}{f(1/\epsilon)^2} \int_0^{1/\epsilon} t^4 f'(t)^2 dt \\ &\leq \frac{2C\epsilon^3}{f(1/\epsilon)^2}. \end{aligned}$$

It follows that  $J(u^\epsilon) \rightarrow 0$  as  $\epsilon \rightarrow 0^+$ , so

$$\inf_{u \in X} J(u) = 0.$$

- If  $J(u) = 0$  and  $u \in C^1([-1, 1])$ , then  $x^4(u')^2 = 0$ , so  $u'(x) = 0$  except at  $x = 0$ , and then  $u'(0) = 0$  by continuity. It follows that  $u = \text{constant}$ , but no constant function satisfies both boundary conditions for functions in  $X$ , so  $J(u) > 0$  for every  $u \in X$ .
- (b) The Euler-Lagrange equation for  $J(u)$  is

$$-2(x^4 u')' = 0.$$

Integrating this ODE once, we get that  $x^4 u' = c$ , where  $c$  is a constant of integration. Integrating again, we get that

$$u(x) = c_1 + \frac{c_2}{x^3}$$

where  $c_1, c_2$  are constants of integration.

- The boundary conditions imply that  $c_1 - c_2 = -1$ ,  $c_1 + c_2 = 1$ , so  $c_1 = 0$ ,  $c_2 = 1$ .
- The solution of the Euler-Lagrange equation is  $u(x) = 1/x^3$ , which is singular at  $x = 0$ , so there is no smooth solution.

**Remark.** The Lagrangian for  $J(u)$  is  $F(x, u') = x^4(u')^2$ . When  $x \neq 0$ , the Lagrangian is a strictly convex function of  $u'$  (with  $F_{u'u'} = 2x^4 > 0$ ), but strict convexity is lost at  $x = 0$ . The nonexistence of a minimizer of  $J(u)$  is associated with this loss of strict convexity.