Midterm 2

Math 22A, Fall 2019

Name: Solutions

Student ID:

You do not need to simplify numerical expressions for your final answers (e.g. you can write $3 - \frac{3}{4}$ instead of simplifying to $\frac{9}{4}$.)

$$\frac{\mathbf{v} \cdot \mathbf{w}}{||\mathbf{v}|| \, ||\mathbf{w}||} = \cos \theta$$

The formula for the projection matrix is

$$P = A(A^{T}A)^{-1}A^{T}$$
$$Pv = A(A^{T}A)^{-1}A^{T}v$$

When the projection is onto a line spanned by a single vector a, the projection matrix is

$$P_a = \frac{aa^T}{a^T a}$$
$$P_a v = \frac{aa^T}{a^T a} v = a \left(\frac{a^T v}{a^T a}\right)$$

Problem 1 (8 pts): Consider the subset S of \mathbb{R}^2 of vectors $\begin{bmatrix} x \\ y \end{bmatrix}$ such that $xy^2 = 0$.

(a) (3pts) Is S closed under scalar multiplication? Prove it is or give an example of a vector v in S and a scalar c such that cv is not in S.

If $\begin{bmatrix} x \\ y \end{bmatrix}$ is in $S = xy^2 = 0$ For any cin \mathbb{R} , $C\begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} cx \\ cy \end{bmatrix}$ satisfies $(cx)(cy)^2 = c^3xy^2 = c^3(0) = 0$ So $C\begin{bmatrix} x \\ y \end{bmatrix}$ is in S. Therefore S is closed under scalar multiplication

(b) (3pts) Is S closed under addition? Prove it is or give an example of vectors v_1, v_2 in S such that $v_1 + v_2$ is not in S.

S is not closed under addition
For example
$$\begin{bmatrix} 1\\0 \end{bmatrix}$$
 and $\begin{bmatrix} 0\\1 \end{bmatrix}$ are in S because
 $1 \cdot 0^2 = 0$ and $0 \cdot 1^2 = 0$
but $\begin{bmatrix} 1\\0 \end{bmatrix} + \begin{bmatrix} 0\\1 \end{bmatrix} = \begin{bmatrix} 1\\1 \end{bmatrix}$ is not in S because
 $1 \cdot 1^2 \neq 0$

(c) (2pts) Is S a subspace of \mathbb{R}^2 ?

Subspace



Problem 2 (8 pts):

1

$$U = \begin{bmatrix} -1 & 8 & 1 & 4 \\ 0 & 3 & 2 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

(a) (3pts) Write down 3 columns of U which are linearly independent.

$$\begin{bmatrix} -1 \\ 0 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 2 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 4 \\ 0 \\ 1 \\ 0 \end{bmatrix}$$

$$\left(\begin{array}{c} 0 R \\ 0 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 3 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 4 \\ 0 \\ 1 \\ 0 \end{bmatrix} \right)$$

$$\left(\begin{array}{c} 0 R \\ 0 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 3 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 4 \\ 0 \\ 1 \\ 0 \end{bmatrix} \right)$$

(b) (5pts) Give a proof that these 3 columns are linearly independent.

If
$$c_1 \begin{bmatrix} -1 \\ 0 \\ 0 \end{bmatrix} + c_2 \begin{bmatrix} 1 \\ 2 \\ 0 \end{bmatrix} + c_3 \begin{bmatrix} 9 \\ 0 \\ 0 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

then $\begin{bmatrix} -c_1 + c_2 + 4c_3 \\ 2c_2 \\ 0 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$ So $-c_1 + c_2 + 4c_3 = 0$
 $2c_2 = 0$
 $c_3 = 0$
 $c_3 = 0$
 $c_4 = c_2 + 4c_3 = 0$
 $c_5 = 0$
Therefore the only linear combination of $v_{1,1}v_{2,1}v_3$ giving $\vec{0}$
is when $c_1 = c_2 = c_3 = 0$
Thus $(v_{1,1}v_{2,1}v_3)$ one linearly independent.

Problem 3 (10 pts): Let

$$A = \left[\begin{array}{rr} -1 & 4\\ 2 & -8 \end{array} \right]$$

Find bases for the null space N(A) and the column space C(A). What is the nullity, $\dim(N(A))$? What is the rank $\dim(C(A))$?

$$\begin{bmatrix} -1 & 4 \\ 2 & -8 \end{bmatrix} \longrightarrow \begin{bmatrix} -1 & 4 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \qquad -x_1 + 4x_2 = 0$$

$$X_1 = 4x_2$$

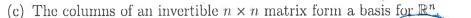
$$N(A) = \begin{cases} \begin{bmatrix} 4x_2 \\ x_2 \end{bmatrix} = \begin{cases} x_2 \begin{bmatrix} 4 \\ 1 \end{bmatrix} \\ x_2 \end{bmatrix} = \begin{cases} x_2 \begin{bmatrix} 4 \\ 1 \end{bmatrix} \\ x_2 \end{bmatrix} = \begin{cases} x_2 \begin{bmatrix} 4 \\ 1 \end{bmatrix} \\ x_2 \end{bmatrix} = \begin{cases} x_2 \begin{bmatrix} 4 \\ 1 \end{bmatrix} \\ x_2 \end{bmatrix} = \begin{cases} x_2 \begin{bmatrix} 4 \\ 1 \end{bmatrix} \\ x_2 \end{bmatrix} = \begin{cases} x_2 \begin{bmatrix} 4 \\ 1 \end{bmatrix} \\ x_2 \end{bmatrix} = \begin{cases} x_2 \begin{bmatrix} 4 \\ 1 \end{bmatrix} \\ x_2 \end{bmatrix} = \begin{cases} x_2 \begin{bmatrix} 4 \\ 1 \end{bmatrix} \\ x_2 \end{bmatrix} = \begin{cases} x_2 \begin{bmatrix} 4 \\ 1 \end{bmatrix} \\ x_2 \end{bmatrix} = \begin{cases} x_2 \begin{bmatrix} 4 \\ 1 \end{bmatrix} \\ x_2 \end{bmatrix} = \begin{cases} x_2 \begin{bmatrix} 4 \\ 1 \end{bmatrix} \\ x_2 \end{bmatrix} = \begin{cases} x_2 \begin{bmatrix} 4 \\ 1 \end{bmatrix} \\ x_2 \end{bmatrix} = \begin{cases} x_2 \begin{bmatrix} 4 \\ 2 \end{bmatrix} \\ x_2 \end{bmatrix} = \begin{cases} x_2 \begin{bmatrix} 4 \\ 2 \end{bmatrix} \\ x_2 \end{bmatrix} = \begin{cases} x_2 \begin{bmatrix} 4 \\ 2 \end{bmatrix} \\ x_2 \end{bmatrix} = \begin{cases} x_2 \begin{bmatrix} 4 \\ 2 \end{bmatrix} \\ x_2 \end{bmatrix} = \begin{cases} x_2 \begin{bmatrix} 4 \\ 2 \end{bmatrix} \\ x_2 \end{bmatrix} = \begin{cases} x_2 \begin{bmatrix} 4 \\ 2 \end{bmatrix} \\ x_2 \end{bmatrix} = \begin{cases} x_2 \begin{bmatrix} 4 \\ 2 \end{bmatrix} \\ x_2 \end{bmatrix} = \begin{cases} x_2 \begin{bmatrix} 4 \\ 2 \end{bmatrix} \\ x_2 \end{bmatrix} = \begin{cases} x_2 \begin{bmatrix} 4 \\ 2 \end{bmatrix} \\ x_2 \end{bmatrix} = \begin{cases} x_2 \begin{bmatrix} 4 \\ 2 \end{bmatrix} \\ x_2 \end{bmatrix} = \begin{cases} x_2 \begin{bmatrix} 4 \\ 2 \end{bmatrix} \\ x_2 \end{bmatrix} = \begin{cases} x_2 \begin{bmatrix} 4 \\ 2 \end{bmatrix} \\ x_2 \end{bmatrix} = \begin{cases} x_2 \begin{bmatrix} 4 \\ 2 \end{bmatrix} \\ x_2 \end{bmatrix} = \begin{cases} x_2 \begin{bmatrix} 4 \\ 2 \end{bmatrix} \\ x_2 \end{bmatrix} = \begin{cases} x_2 \begin{bmatrix} 4 \\ 2 \end{bmatrix} \\ x_2 \end{bmatrix} = \begin{cases} x_2 \begin{bmatrix} 4 \\ 2 \end{bmatrix} \\ x_2 \end{bmatrix} = \begin{cases} x_2 \begin{bmatrix} 4 \\ 2 \end{bmatrix} \\ x_2 \end{bmatrix} = \begin{cases} x_2 \begin{bmatrix} 4 \\ 2 \end{bmatrix} \\ x_2 \end{bmatrix} = \begin{cases} x_2 \begin{bmatrix} 4 \\ 2 \end{bmatrix} \\ x_2 \end{bmatrix} = \begin{cases} x_2 \begin{bmatrix} 4 \\ 2 \end{bmatrix} \\ x_2 \end{bmatrix} = \begin{cases} x_2 \begin{bmatrix} 4 \\ 2 \end{bmatrix} \\ x_2 \end{bmatrix} = \begin{cases} x_2 \begin{bmatrix} 4 \\ 2 \end{bmatrix} \\ x_2 \end{bmatrix} = \begin{cases} x_2 \begin{bmatrix} 4 \\ 2 \end{bmatrix} \\ x_2 \end{bmatrix} = \begin{cases} x_2 \begin{bmatrix} 4 \\ 2 \end{bmatrix} \\ x_2 \end{bmatrix} = \begin{cases} x_2 \begin{bmatrix} 4 \\ 2 \end{bmatrix} \\ x_2 \end{bmatrix} = \begin{cases} x_2 \begin{bmatrix} 4 \\ 2 \end{bmatrix} \\ x_2 \end{bmatrix} = \begin{cases} x_2 \begin{bmatrix} 4 \\ 2 \end{bmatrix} \\ x_2 \end{bmatrix} = \begin{cases} x_2 \begin{bmatrix} 4 \\ 2 \end{bmatrix} \\ x_2 \end{bmatrix} = \begin{cases} x_2 \begin{bmatrix} 4 \\ 2 \end{bmatrix} \\ x_2 \end{bmatrix} = \begin{cases} x_2 \begin{bmatrix} 4 \\ 2 \end{bmatrix} \\ x_2 \end{bmatrix} = \begin{cases} x_2 \begin{bmatrix} 4 \\ 2 \end{bmatrix} \\ x_2 \end{bmatrix} = \begin{cases} x_2 \begin{bmatrix} 4 \\ 2 \end{bmatrix} \\ x_2 \end{bmatrix} = \begin{cases} x_2 \begin{bmatrix} 4 \\ 2 \end{bmatrix} \\ x_2 \end{bmatrix} = \begin{cases} x_2 \begin{bmatrix} 4 \\ 2 \end{bmatrix} \\ x_2 \end{bmatrix} = \begin{cases} x_2 \begin{bmatrix} 4 \\ 2 \end{bmatrix} \\ x_2 \end{bmatrix} = \begin{cases} x_2 \begin{bmatrix} 4 \\ 2 \end{bmatrix} \\ x_2 \end{bmatrix} = \begin{cases} x_2 \begin{bmatrix} 4 \\ 2 \end{bmatrix} \\ x_2 \end{bmatrix} = \begin{cases} x_2 \begin{bmatrix} 4 \\ 2 \end{bmatrix} \\ x_2 \end{bmatrix} = \begin{cases} x_2 \begin{bmatrix} 4 \\ 2 \end{bmatrix} \\ x_2 \end{bmatrix} = \begin{cases} x_2 \begin{bmatrix} 4 \\ 2 \end{bmatrix} \\ x_2 \end{bmatrix} = \begin{cases} x_2 \begin{bmatrix} 4 \\ 2 \end{bmatrix} \\ x_2 \end{bmatrix} = \begin{cases} x_2 \begin{bmatrix} 4 \\ 2 \end{bmatrix} \\ x_2 \end{bmatrix} = \begin{cases} x_2 \begin{bmatrix} 4 \\ 2 \end{bmatrix} \\ x_2 \end{bmatrix} = \begin{cases} x_2 \end{bmatrix} \\ x_2 \end{bmatrix} = \begin{cases} x_2 \begin{bmatrix} x_2 \\ x_2 \end{bmatrix} = \begin{cases} x_2 \end{bmatrix} \\ x_2 \end{bmatrix} \\ x_2 \end{bmatrix} = \begin{cases} x_2 \end{bmatrix} \\ x_2 \end{bmatrix} \\ x_2 \end{bmatrix} = \begin{cases} x_2 \end{bmatrix} \\ x_2 \end{bmatrix} \\ x_2 \end{bmatrix} = \begin{cases} x_2 \end{bmatrix} \\ x_2 \end{bmatrix} \\ x_2 \end{bmatrix} = \begin{cases} x_2 \end{bmatrix} \\ x_2 \end{bmatrix}$$

{[4]} Basis for N(A) (4pts): _

Basis for
$$C(A)$$
 (4pts): $1 \begin{bmatrix} -1 & 2 \\ 2 & 2 \end{bmatrix}$
Nullity (1pt): $1 \\ Rank$ (1pt): $1 \\ Rank$

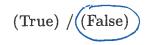
Problem 4 (8 pts): In each sentence, *circle the best choice* among the choices in parentheses.

- 1. Suppose v_1, v_2, \ldots, v_6 are vectors in \mathbb{R}^4 .
 - (a) Those six vectors (do) / (do not) / (might not) span \mathbb{R}^4 .
 - (b) Those six vectors (are) / ((are not)) / (might not be) linearly independent.
 - (c) Those six vectors (are) / (are not) / (might not be) a basis for \mathbb{R}^4 .
- 2. Choose true or false for the following statements.
 - (a) Every subspace contains the zero vector.
 - (b) A basis is a spanning set that is as large as possible.



- (d) A basis is a linearly independent set that is as large as possible. (True) (False)
- (e) A single nonzero vector v_1 by itself is linearly independent. (True)/ (False)





(False)

(False)

(True)

(True)

Problem 5 (8 pts):

1. (4 pts) If A is a 3×3 matrix with three column vectors c_1, c_2, c_3 which are orthogonal to each other such that $||c_1|| = 1$, $||c_2|| = 2$, and $||c_3|| = 3$, what is $A^T A$?

$$\begin{bmatrix} -c_1^{T} - -c_2^{T} - -c_2^{T$$

2. (4 pts) Calculate the projection $P_{\mathbf{v}}\mathbf{w}$ of the vector \mathbf{w} onto the line $L = \operatorname{Span}(\mathbf{w})$ where

$$v = \begin{bmatrix} 1 \\ -1 \\ 0 \\ -1 \end{bmatrix}, \quad w = \begin{bmatrix} 3 \\ 2 \\ -2 \\ 2 \end{bmatrix}$$

$$P_{v}w = \begin{bmatrix} 1 \\ -1 \\ 0 \\ -1 \end{bmatrix} \begin{bmatrix} 1 -1 & 0 & -1 \end{bmatrix} \begin{bmatrix} 3 \\ 2 \\ -2 \\ 2 \end{bmatrix} = \begin{bmatrix} 1 \\ -1 \\ 0 \\ -1 \end{bmatrix} \frac{\begin{bmatrix} -1 \end{bmatrix}}{\begin{bmatrix} -1 \end{bmatrix}}$$

$$\begin{bmatrix} 1 \\ 0 \\ -1 \end{bmatrix} \begin{bmatrix} -1 \end{bmatrix}$$

$$\begin{bmatrix} 1 \\ 0 \\ -1 \end{bmatrix} \begin{bmatrix} -1 \end{bmatrix}$$

$$\begin{bmatrix} -1 \end{bmatrix}$$

$$\begin{bmatrix} 1 \\ 0 \\ -1 \end{bmatrix} \begin{bmatrix} -1 \end{bmatrix}$$

$$= -\frac{1}{3} \begin{bmatrix} 1 \\ -1 \\ 0 \\ -1 \end{bmatrix}$$

$$v = \begin{bmatrix} -1 \\ 0 \\ -1 \end{bmatrix}$$

$$= -\frac{1}{3} \begin{bmatrix} 1 \\ -1 \\ 0 \\ -1 \end{bmatrix}$$

Problem 6 (8 pts): Find an orthonormal basis for the subspace

. .

$$U = \operatorname{Span} \left(\begin{bmatrix} 2\\0\\-2\\0\\1 \end{bmatrix}, \begin{bmatrix} 3\\1\\-1\\-1\\1 \end{bmatrix} \right)$$
$$\mathsf{v}_{\mathsf{l}} \qquad \mathsf{v}_{\mathsf{z}} \right)$$

$$\begin{aligned} \|V_{1}\| &= \sqrt{2^{2} + 0^{2} + (-2)^{2} + 0^{2} + (1)^{2}} &= \sqrt{q} = 3 \\ e_{1} &= \frac{1}{3} v_{1} = \begin{pmatrix} 2I_{3} \\ 0 \\ -\frac{1}{3} \\ 0 \\ \sqrt{3} \end{pmatrix} \\ \mathcal{U}_{2} &= V_{2} - P_{e_{1}} V_{2} &= \begin{pmatrix} 3 \\ -1 \\ -1 \\ 1 \\ 1 \end{pmatrix} - \frac{(e_{1} \cdot V_{2})}{2 + \frac{2}{3} + \frac{1}{3}} \begin{pmatrix} 2I_{3} \\ 0 \\ -\frac{2I_{3}}{3} \\ 0 \\ \sqrt{3} \end{pmatrix} = \begin{pmatrix} 3 \\ -1 \\ -1 \\ -1 \\ 1 \\ 1 \end{pmatrix} - \begin{pmatrix} 2 \\ 0 \\ -\frac{2}{0} \\ 0 \\ 1 \\ 1 \end{pmatrix} = \begin{pmatrix} 1 \\ 1 \\ -1 \\ 0 \\ 1 \\ 0 \end{pmatrix} \\ \\ \|U_{2}\| &= \sqrt{1^{2} + 1^{2} + 1^{2} + (-1)^{2} + 0^{2}} = \sqrt{4} = 2 \\ e_{2} &= \begin{pmatrix} V_{2} \\ V_{2} \\ V_{2} \\ -\frac{V_{2}}{0} \\ 0 \\ -\frac{2I_{3}}{0} \\ 0 \\ -\frac{2I_{3}}{0} \\ 0 \\ \frac{V_{3}}{3} \end{pmatrix} , \begin{bmatrix} V_{2} \\ V_{2} \\ V_{2} \\ V_{3} \\ 0 \\ \frac{V_{2}}{V_{3}} \\ 0 \\ \frac{V_{2}}{V_{3}} \\ 0 \\ \frac{V_{2}}{V_{2}} \\ \frac{V_{2}}{V_{2}} \\ 0 \\ \frac{V_{2}}{V_{3}} \\ 0 \\ \frac{V_{2}}{V_{3}} \\ 0 \\ \frac{V_{3}}{V_{3}} \end{pmatrix} , \end{aligned}$$

Problem 7 (8 pts):

(a) (4pts) Calculate the determinant of the matrix

$$A = \begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & 1 & 1 & 5 \\ 1 & 1 & 0 & 1 \\ 1 & 2 & 1 & 1 \end{bmatrix}$$

$$det A = det \begin{bmatrix} 1 & 1 & 1 & 1 \\ 0 & 0 & 0 & 4 \\ 0 & 0 & -1 & 0 \\ 0 & 1 & 0 & 0 \end{bmatrix} = -det \begin{bmatrix} 1 & 1 & 1 & 1 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & 4 \end{bmatrix}$$

$$= -1 \cdot 1 \cdot (-1) \cdot 4$$

$$= \underbrace{4}$$

(b) (4pts) Determine a value of k which ensures the following matrix has det(A) = 0:

$$A = \begin{bmatrix} 1 & 0 & 1 & 0 \\ 0 & 1 & 0 & 1 \\ 0 & 0 & 0 & 5 \\ 5 & 3 & k & 3 \end{bmatrix}$$

If (K=5) the first + third columns are the same
So the columns are linearly the dependent so

$$\frac{det(A) = 0}{det(A) = 0}$$

Or by considerations

$$det \begin{bmatrix} 1 & 0 & 1 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 & 5 \\ 5 & 3 & k & 3 \end{bmatrix} = det \begin{bmatrix} 1 & 0 & 1 & 0 \\ 0 & 1 & 0 & 1 \\ 0 & 0 & 0 & 5 \\ 0 & 0 & K-5 & 0 \end{bmatrix} = -det \begin{bmatrix} 1 & 0 & 10 \\ 0 & 1 & 0 & 1 \\ 0 & 0 & K-5 & 0 \\ 0 & 0 & 0 & 5 \end{bmatrix}$$

$$= -(K-5) \cdot 5$$

So $-5(K-5) = 0$ when $K=S$