

Chapter 5

CE 3.

(a) $d=3$ basis: $(1, 0, 0, 0)$ $(0, 1, 0, 0)$ $(0, 0, 1, 0)$

(b) $d=3$ basis $(1, 0, 0, 1)$ $(0, 1, 0, 1)$ $(0, 0, 1, 0)$

(c) $d=2$ basis $(1, 0, 1, 1)$ $(0, 1, -1, 1)$

(d) $d=2$. $\begin{cases} X_4 = X_1 + X_2 & \textcircled{1} \\ X_3 = X_1 - X_2 & \textcircled{2} \\ X_3 + X_4 = 2X_1 & \textcircled{3} \end{cases}$ Adding $\textcircled{1}$ and $\textcircled{2}$ yields $\textcircled{3}$, so $\textcircled{3}$ is redundant.
Basis $(1, 0, 1, 1)$ $(0, 1, -1, 1)$

(e) $d=1$ basis $(1, 1, 1, 1)$

CE 4.

(a) $(\lambda, -1, -1)$, $(-1, \lambda, -1)$, $(-1, -1, \lambda)$ is linearly dependent if there exists C_1, C_2, C_3 (not all 0) such that

$$C_1(\lambda, -1, -1) + C_2(-1, \lambda, -1) + C_3(-1, -1, \lambda) = 0$$

$$(C_1\lambda - C_2 - C_3, -C_1 + \lambda C_2 - C_3, -C_1 - C_2 + \lambda C_3) = 0$$

$$\begin{cases} C_1\lambda - C_2 - C_3 = 0 \\ -C_1 + \lambda C_2 - C_3 = 0 \\ -C_1 - C_2 + \lambda C_3 = 0 \end{cases} \begin{matrix} \leftarrow \\ \otimes \\ \leftarrow \end{matrix} \begin{cases} (\lambda^2 - 1)C_2 - (\lambda + 1)C_3 = 0 \\ -C_1 + \lambda C_2 - C_3 = 0 \\ -(\lambda + 1)C_2 + (\lambda + 1)C_3 = 0 \end{cases} \begin{matrix} \textcircled{1} \\ \textcircled{2} \\ \textcircled{3} \end{matrix}$$

$$\Rightarrow \begin{cases} C_1 - \lambda C_2 + C_3 = 0 \\ (\lambda + 1)C_2 - (\lambda + 1)C_3 = 0 \\ (\lambda + 1)(\lambda - 1)C_2 - (\lambda + 1)C_3 = 0 \end{cases} \begin{matrix} \textcircled{1} \\ \textcircled{2} \\ \leftarrow \textcircled{3} \end{matrix} \begin{cases} C_1 - \lambda C_2 + C_3 = 0 \\ (\lambda + 1)C_2 - (\lambda + 1)C_3 = 0 \\ [(\lambda + 1)(\lambda - 1) - (\lambda + 1)]C_3 = 0 \end{cases}$$

$$\Rightarrow \begin{cases} C_1 - \lambda C_2 + C_3 = 0 \\ (\lambda + 1)C_2 - (\lambda + 1)C_3 = 0 \\ (\lambda + 1)(\lambda - 2)C_3 = 0 \end{cases}$$

This linear system has a nonzero solution if $(\lambda + 1)(\lambda - 2) = 0$.

Therefore, $\lambda = -1$ or 2 .

(b) $\sin^2(x)$, $\cos(2x)$, λ .

Let $C_1 \sin^2 x + C_2 \cos 2x + C_3 \lambda = 0$.

Remember $\sin^2 x = \frac{1 - \cos 2x}{2}$.

$$C_1 \frac{1 - \cos 2x}{2} + C_2 \cos 2x + C_3 \lambda = 0.$$

$$\left(\frac{C_1}{2} + C_3 \lambda\right) + \left(C_2 - \frac{C_1}{2}\right) \cos 2x = 0.$$

$$\text{Then: } \frac{C_1}{2} + \lambda C_3 = 0.$$

$$C_2 - \frac{C_1}{2} = 0.$$

There are 3 variables: C_1, C_2, C_3 and 2 equations. No matter what λ is, there are infinitely many nonzero solutions. $\{\sin^2 x, \cos 2x, \lambda\}$ is linearly dependent for any $\lambda \in \mathbb{R}$.

CE5.

$$(a) \dim V = 4 \quad \text{basis} \quad \begin{pmatrix} 1 \\ 0 \\ 0 \\ 0 \end{pmatrix} \begin{pmatrix} 0 \\ 1 \\ 0 \\ 0 \end{pmatrix} \begin{pmatrix} 0 \\ 0 \\ 1 \\ 0 \end{pmatrix} \begin{pmatrix} 0 \\ 0 \\ 0 \\ 1 \end{pmatrix}$$

(b). Three vectors can't span a 4 dimensional space.

$$\text{span}((1, 1, 0, 0), (0, 1, 1, 0), (0, 0, 1, 1)) \neq V.$$

$$\text{For example, } \begin{pmatrix} 1 \\ 1 \\ 1 \\ 0 \end{pmatrix} \notin \text{span}((1, 1, 0, 0), (0, 1, 1, 0), (0, 0, 1, 1))$$

$$\text{Let } \begin{pmatrix} 1 \\ 1 \\ 1 \\ 0 \end{pmatrix} = C_1 \begin{pmatrix} 1 \\ 0 \\ 0 \\ 0 \end{pmatrix} + C_2 \begin{pmatrix} 0 \\ 1 \\ 1 \\ 0 \end{pmatrix} + C_3 \begin{pmatrix} 0 \\ 0 \\ 1 \\ 1 \end{pmatrix}$$

$$C_1 = 1 \quad C_2 = 0 \quad C_3 = \text{both } 1 \text{ \& } 0 \text{ contradictory!}$$

Such C_1, C_2, C_3 doesn't exist.

$$(c). \quad C_1(1, -1, 0, 0) + C_2(0, 1, -1, 0) + C_3(0, 0, 1, -1) + C_4(-1, 0, 0, 1) = (0, 0, 0, 0)$$

$$\left\{ \begin{array}{l} C_1 \\ -C_1 + C_2 \\ -C_2 + C_3 \\ -C_3 + C_4 \end{array} \right. \begin{array}{l} -C_4 = 0 \\ = 0 \\ = 0 \\ = 0 \end{array} \left. \begin{array}{l} \\ \\ \\ \end{array} \right\}$$

$$\left\{ \begin{array}{l} C_1 \\ C_2 \\ -C_2 + C_3 \\ -C_3 + C_4 \end{array} \right. \begin{array}{l} -C_4 = 0 \\ -C_4 = 0 \\ = 0 \\ = 0 \end{array} \left. \begin{array}{l} \\ \\ \\ \end{array} \right\}$$

$$\left\{ \begin{array}{l} C_1 \\ C_2 \\ C_3 - C_4 \\ -C_3 + C_4 \end{array} \right. \begin{array}{l} -C_4 = 0 \\ -C_4 = 0 \\ = 0 \\ = 0 \end{array} \left. \begin{array}{l} \\ \\ \\ \end{array} \right\}$$

$$\begin{cases} c_1 - c_4 = 0 \\ c_2 - c_4 = 0 \\ c_3 - c_4 = 0 \\ 0 = 0 \end{cases}$$

Nonzero solution exists, These vectors are linearly dependent.

(d). Prove by contradiction.

If $\{v_1, v_2, v_3, v_4\}$ is linearly dependent, one vector must be the linear combination of other vectors. For instance, $v_4 = c_1 v_1 + c_2 v_2 + c_3 v_3$.

$$\text{Then } \text{span}\{v_1, v_2, v_3, v_4\} = \text{span}\{v_1, v_2, v_3\}$$

Three vectors can't span $\mathbb{R}^4$, so $\text{span}\{v_1, v_2, v_3\} \neq V$.

Contradiction!

(e). Let $U = \text{span}\{v_1, v_2\}$, which is 2 dimensional.

There exists a subspace W such that $\leftarrow$ Theorem 5.4.5.

$$\mathbb{R}^4 = U \oplus W.$$

$$\dim(\mathbb{R}^4) = \dim(U) + \dim(W). \text{ so } \dim(W) = 2.$$

Let $\{u, w\}$ be a basis of W , then $\{v_1, v_2, u, w\}$ is a basis of $\mathbb{R}^4$.

PWE. 3. There exists $c_1, c_2, \dots, c_n$ (not all 0) such that.

$$c_1(v_1 + w) + c_2(v_2 + w) + \dots + c_n(v_n + w) = 0.$$

$$c_1 v_1 + c_2 v_2 + \dots + c_n v_n + (c_1 + c_2 + \dots + c_n) w = 0.$$

Claim: $c_1 + c_2 + \dots + c_n \neq 0$, otherwise,

$$c_1 v_1 + c_2 v_2 + \dots + c_n v_n = 0.$$

Since $\{v_1, \dots, v_n\}$ is linearly independent, $c_1, c_2, \dots, c_n = 0$.

$$(C_1 + C_2 + \dots + C_n) \neq 0.$$

$$W = - \frac{C_1 V_1 + C_2 V_2 + \dots + C_n V_n}{C_1 + C_2 + \dots + C_n}.$$

$$\Rightarrow W \in \text{span} \{V_1, V_2, \dots, V_n\}.$$

PWE 4. Let $\{u_1, u_2, \dots, u_n\}$ be a basis of V .

$$U_1 = \text{span} \{u_1\}, U_2 = \text{span} \{u_2\}, \dots, U_n = \text{span} \{u_n\}.$$

$$\text{First. } V = U_1 + U_2 + \dots + U_n.$$

for every $v \in V$, there exists $\{c_1, \dots, c_n\}$ s.t.

$$v = c_1 u_1 + c_2 u_2 + \dots + c_n u_n.$$

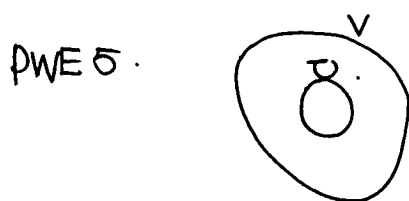
Second: $V = U_1 \oplus U_2 \oplus \dots \oplus U_n$, since $U_i \cap U_j = \{0\}$ for all i, j .

$$\text{Let } w = U_i \cap U_j.$$

$$\begin{aligned} \text{then } w &= c_i u_i \\ w &= c_j u_j \end{aligned} \Rightarrow c_i u_i - c_j u_j = 0.$$

$\{u_i, u_j\}$ is linearly independent, so $c_i = 0, c_j = 0$.

$$w = 0.$$



$$\text{Let } \dim(U) = \dim(V) = n.$$

Let $\{u_1, \dots, u_n\}$ be a basis of U .

Let $\{v_1, \dots, v_n\}$ be a basis of V .

Since $U \subseteq V$, According to the Basis Extension Theorem,

$\{u_1, \dots, u_n\}$ can be extended to a basis of V .

However, $n = \dim(V)$, $\{u_1, \dots, u_n\}$ is already a basis of V .

$$U = V.$$

PWE 6. $\dim(F_m[\mathbb{Z}]) = m+1$, since $\{1, z, z^2, \dots, z^m\}$ is a basis.

$$\text{Let } U = \{p(z) \in F_m[\mathbb{Z}] \mid p(2) = 0\}.$$

U is a subspace of $F_m[\mathbb{Z}]$.

What's the dimension of U ?

$$\text{Let } p(z) \in U \text{ and } p(z) = a_m z^m + a_{m-1} z^{m-1} + \dots + a_1 z + a_0.$$

$$p(2) = 0, \text{ then } a_m 2^m + a_{m-1} 2^{m-1} + \dots + 2a_1 + a_0 = 0$$

$$\Rightarrow a_0 = -a_m 2^m - a_{m-1} 2^{m-1} - \dots - 2a_1$$

$$p(z) = a_m (z^m - 2^m) + a_{m-1} (z^{m-1} - 2^{m-1}) + \dots + a_1 (z - 2)$$

$\{z^m - 2^m, z^{m-1} - 2^{m-1}, \dots, z - 2\}$ is a basis of U .

$$\dim U = m.$$

$m+1$ vectors in U must be linearly dependent, so $(p_0, p_1, \dots, p_m)$ is linearly dependent.

PWE 7. Prove by contradiction.

$$\text{If } U \cap V = \{0\}, \text{ Let } W = U \oplus V,$$

$$W \subseteq \mathbb{R}^9, \text{ but } \dim W = \dim U + \dim V = 5 + 5 = 10.$$

Contradiction!

Chapter 6 PWE 1

Let $\dim(U) = m$ and $\dim(V) = n$. $m \leq n$ since U is a subspace of V . Take a basis of U and let it be $\{u_1, u_2, \dots, u_m\}$. According to the Basis extension theorem, one can extend it to get a basis of V , which is $\{u_1, u_2, \dots, u_m, v_{m+1}, \dots, v_n\}$. Define the linear transformation on V such that, for $v \in V = c_1 u_1 + \dots + c_m u_m + c_{m+1} v_{m+1} + \dots + c_n v_n$,

$$T(v) = c_1 S(u_1) + \dots + c_m S(u_m).$$

- First, $T = S$ on U .
- Second, T is linear. For any $v_1 \in V = a_1 u_1 + \dots + a_m u_m + a_{m+1} v_{m+1} + \dots + a_n v_n$ and $v_2 \in V = b_1 u_1 + \dots + b_m u_m + b_{m+1} v_{m+1} + \dots + b_n v_n$,

$$T(v_1 + v_2) = (a_1 + b_1)S(u_1) + \dots + (a_m + b_m)S(u_m),$$

and

$$T(v_1) = a_1 S(u_1) + \dots + a_m S(u_m),$$

$$T(v_2) = b_1 S(u_1) + \dots + b_m S(u_m).$$

Hence, $T(v_1 + v_2) = T(v_1) + T(v_2)$. On the other hand,

$$T(\lambda v_1) = (\lambda a_1)S(u_1) + \dots + (\lambda a_m)S(u_m) = \lambda T(v_1).$$

Chapter 5 PWE 2.

Take $v \in V$, there exists $\{c_1, \dots, c_n\}$ s.t.

$$v = c_1 v_1 + c_2 v_2 + \dots + c_n v_n.$$

Want to prove there exists $\{b_1, \dots, b_n\}$ s.t.

$$v = b_1(v_1 - v_2) + b_2(v_2 - v_3) + b_3(v_3 - v_4) + \dots + b_{n-1}(v_{n-1} - v_n) + b_n v_n.$$

~~we get~~

$$= b_1 v_1 + (b_2 - b_1) v_2 + (b_3 - b_2) v_3 + \dots + (b_{n-1} - b_{n-2}) v_{n-1} + (b_n - b_{n-1}) v_n.$$

$$\begin{array}{lcl} \text{Let } b_1 & = c_1 & \\ -b_1 + b_2 & = c_2 & \\ -b_2 + b_3 & = c_3 & \\ & \vdots & \\ -b_{n-1} + b_n & = c_n & \end{array} \Rightarrow \begin{cases} b_1 = c_1 \\ b_2 = c_1 + c_2 \\ b_3 = c_1 + c_2 + c_3 \\ \vdots \\ b_n = c_1 + c_2 + c_3 + \dots + c_n. \end{cases}$$