

# Answer Key

Math 022B

Final

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No Calculators allowed. Use the back of all the pages if needed.

- (1) (24pts) a)[6pts] Determine the interval in which a solution to the following Bernoulli equation is certain to exist:

$$y' + \frac{1}{t}y = \frac{1}{t^2}y^3, \quad y(1) = \sqrt{\frac{3}{2}}$$

- b)[6pts] Show that the substitution  $v = y^{-2}$  reduces the above equation into a linear equation

$$v' - \frac{2}{t}v = -\frac{2}{t^2}$$

- c)[12pts] Solve the equation in (b), then solve the initial value problem in (a).

Sol:

a) rewrite as  $y' = f(t,y) = -\frac{1}{t}y + \frac{1}{t^2}y^3$

By existence and uniqueness theorem, you need to find the interval, containing  $t=1$ , in which both  $f$  and  $\frac{\partial f}{\partial y}$  are continuous. Clearly  $t=0$  is the only discontinuous point, so  $(0, +\infty)$  is the interval

b)  $v = y^{-2} \Rightarrow y = \pm v^{-\frac{1}{2}} \Rightarrow y' = \pm(-\frac{1}{2})v^{-\frac{3}{2}} \cdot v'$  ← Note: Actually only "+" is possible by the initial data.  
 then  $\pm[(-\frac{1}{2})v^{-\frac{3}{2}}v' + \frac{1}{t}v^{-\frac{1}{2}}] = \frac{1}{t^2}(\pm v^{-\frac{1}{2}})^3$   
 the "+" sign will be cancelled, then multiply both sides by  $-2 \cdot v^{\frac{3}{2}}$   
 we get  $v' - \frac{2}{t}v = -\frac{2}{t^2}$

OR: you can follow the solution from HW#2, simply divide  $-\frac{1}{2}y^3$  on both sides of  $y' + \frac{1}{t}y = \frac{1}{t^2}y^3$ , recognising  $-2\frac{y'}{y^3} = v'$ , then we are done.

c) Integrating factor  $\mu(t) = e^{-\int \frac{2}{t} dt} = ce^{-2\ln t} = c \cdot t^{-2}$   
 choosing  $c=1$ , then  $(v \cdot \frac{1}{t^2})' = -2t^{-4}$

$$\Rightarrow \frac{v}{t^2} = \frac{2}{3}t^{-3} + C \Rightarrow \boxed{v = \frac{2}{3t} + Ct^2}$$

Initial value  $y(1) = \sqrt{\frac{3}{2}} \Rightarrow v(1) = (y(1))^{-2} = \frac{2}{3} \Rightarrow C=0 \Rightarrow v = \frac{2}{3t}$

So  $\boxed{y = +\sqrt{\frac{1}{v}} = \sqrt{\frac{3t}{2}}}$ . Note the "-" sign is not possible, since  $y(1) = \sqrt{\frac{3}{2}} > 0$

(2) (18pts) For  $-1 < a < 1$ , consider the ODE

$$y' = (1-y)(y^2 - a),$$

(a)[5pts] Find all equilibrium solutions in three different cases: (i)  $-1 < a < 0$ , (ii)  $a = 0$ , (iii)  $0 < a < 1$ .

(b)[10pts] Sketch the phase line and determine the stability of the equilibria you found in (a) in each case.

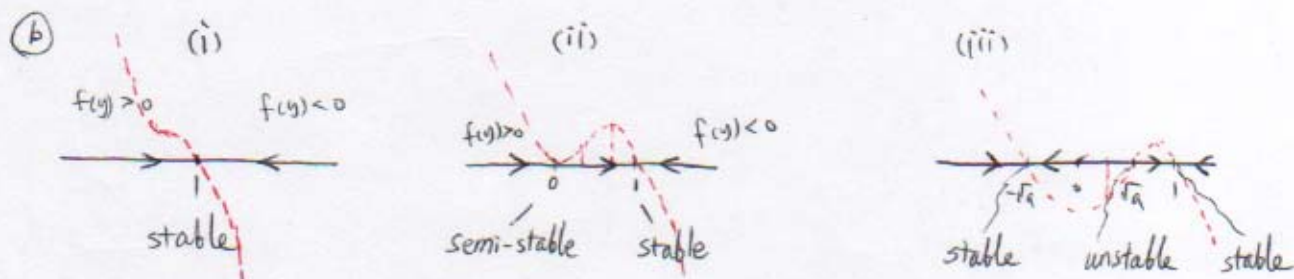
(c)[3pts] What is the asymptotical behavior of solution  $y(t)$  that satisfies the initial condition  $y(0) = 0$  in each case?

Sol:  $y' = f(y) = (1-y)(y^2 - a)$

(a) equilibrium solutions are the  $y^*$ 's such that  $f(y^*) = 0$

$$(1-y^*)(y^{*2} - a) = 0 \Rightarrow y^* = 1 \text{ or } y^{*2} = a$$

So in case (i)  $y^* = 1$  (ii)  $y^* = 1$  or  $y^* = 0$  (iii)  $y^* = 1$  or  $y^* = \pm\sqrt{a}$



Note: you don't need to draw the  $f(y)$  curve, but you can still tell the signs of  $f(y)$ , i.e.,  $y'$ , on each interval

(c) By the analysis we have in (b),  $y \rightarrow y^* = 1$  in case (i)  
 $y \equiv 0$  in case (ii) / since  $y^* = 0$  is an equil. sol.  
 $y \rightarrow \pm\sqrt{a}$  in case (iii)

(3) (20pts) a)[5pts] Show that the following differential equation is not exact:

$$dx + (x/y - \sin y)dy = 0$$

b)[15pts] It is shown that if  $(N_x - M_y)/M = Q(y)$ , then the differential equation  $M + Ny' = 0$  can be converted into an exact equation by multiplying an integrating factor  $\mu(y) = e^{\int Q(y)dy}$ . Use this fact to make the differential equation in a) exact and then solve it.

Sol: (a)  $M = 1$      $N = x/y - \sin y$

$$\text{Exactness} \Leftrightarrow \frac{\partial M}{\partial y} = \frac{\partial N}{\partial x} \quad / \text{OR} \quad M_y = N_x$$

$$\text{So } \frac{\partial M}{\partial y} = 0 \neq \frac{\partial N}{\partial x} = \frac{1}{y} \Rightarrow \text{Not exact}$$

(b) Here  $(N_x - M_y)/M = (\frac{1}{y} - 0)/1 = \frac{1}{y}$

$$\Rightarrow \text{we have } \mu(y) = e^{\int \frac{1}{y} dy} = c \cdot y$$

choose  $c=1$

then  $y dx + y(x/y - \sin y) dy = 0$  is exact.

i.e.  $y dx + (x - y \sin y) dy = 0$

So  $\tilde{M} = (\mu M) = y$  ,  $\tilde{N} = (\mu N) = x - y \sin y$

$$\tilde{M} = \phi_x \Rightarrow \phi(x, y) = \int \tilde{M} dx = \int y dx = xy + h(y)$$

We also need  $\phi_y = \tilde{N} \Rightarrow x + h'(y) = x - y \sin y$

$$\Rightarrow h'(y) = -y \sin y \Rightarrow h(y) = -\int y \sin y dy$$

$$\begin{aligned} \text{Hence } \phi(x, y) &= xy + y \cos y - \sin y + C \\ &= y \cos y - \int \cos y dy \\ &= y \cos y - \sin y + C \end{aligned}$$

i.e. the general (implicit) solution

is  $xy + y \cos y - \sin y = C$

- (4) (28pts) a)[10pts] Find the appropriate form of a particular solution to the following differential equation and do not solve.

$$y'' - 2y' + 5y = te^{-t} + e^t \cos 2t + 3t$$

- b)[18pts] Verify that  $\{y_1 = 1+t, y_2 = e^t\}$  form a set of fundamental solutions to the homogeneous equation corresponding to

$$ty'' - (1+t)y' + y = t^2 e^t, t > 0.$$

Then use the method of variation of parameters to find a particular solution to the non-homogeneous equation.

Sol: (a) check the roots of the characteristic equation first:

$$r^2 - 2r + 5 = 0 \Rightarrow r = 1 \pm 2i \Rightarrow y_c = e^t (C_1 \cos 2t + C_2 \sin 2t) \text{ for homogeneous eqn.}$$

$$g_1 = te^{-t} \rightarrow Y_1 = (A_0 t + A_1) e^{-t}$$

$$g_2 = e^t \cos 2t \rightarrow Y_2 = t(A_2 \cos 2t + A_3 \sin 2t) e^t$$

$$g_3 = 3t \rightarrow Y_3 = A_4 t + A_5$$

Note: you only need to multiply  $t$  in  $Y_2$  since  $e^t \cos 2t$  is a sol to the homogeneous equation.

So the appropriate form of a particular sol

$$\text{is } Y(t) = (A_0 t + A_1) e^{-t} + t(A_2 \cos 2t + A_3 \sin 2t) e^t + A_4 t + A_5$$

- (b)  $y_1 = 1+t \Rightarrow y_1' = 1, y_1'' = 0 \Rightarrow t \cdot 0 - (1+t) \cdot 1 + (1+t) = 0$   
 $y_2 = e^t \Rightarrow y_2' = y_2'' = e^t \Rightarrow e^t (t - (1+t) + 1) = 0$  }  $\Rightarrow y_1, y_2$  are solutions of the homogeneous eqn.

Further,  $W(y_1, y_2) = \begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix} = y_1 y_2' - y_1' y_2 = (1+t)e^t - e^t = t \cdot e^t \neq 0$ , since  $t > 0$ .

Hence  $\{y_1, y_2\}$  form a set of fundamental solutions to  $ty'' - (1+t)y' + y = 0$

Then let  $y(t) = (1+t)u_1(t) + e^t u_2(t)$

rewrite the non-homogeneous eqn as  $y'' - (1 + \frac{1}{t})y' + \frac{1}{t}y = te^t$

$$\text{then } \begin{cases} u_1' \cdot (1+t) + u_2' \cdot e^t = 0 & \textcircled{1} \\ u_1' \cdot 1 + u_2' \cdot e^t = t \cdot e^t & \textcircled{2} \end{cases}$$

$$\textcircled{1} - \textcircled{2} \Rightarrow u_1' = -e^t, \text{ so } u_1 = -(1+t)e^t + c_1$$

$$\Rightarrow u_1 = -e^t + c_1, \quad u_2 = t + \frac{t^2}{2} + c_2$$

$$\Rightarrow y(t) = (1+t)(-e^t + c_1) + (t + \frac{t^2}{2} + c_2)e^t = (\frac{t^2}{2} - 1)e^t + c_1(1+t) + c_2 e^t$$

$$\Rightarrow \boxed{Y(t) = (\frac{t^2}{2} - 1)e^t} \text{ is a particular solution.}$$

(5) (15pts) (a)[9pts] Find the general solution of  $2y'' + y' = 0$ .

(b)[6pts] Show that the solution approaches some constant as  $t \rightarrow \infty$  and find the value of that constant when the solution satisfies  $y(0) = 1$ ,  $y'(0) = 1$ .

sol: Characteristic eqn:  $2r^2 + r = 0 \Rightarrow r = 0$  or  $r = -\frac{1}{2}$

①

$\Rightarrow$  general sol.  $y(t) = C_1 + C_2 e^{-\frac{1}{2}t}$

②

$e^{-\frac{1}{2}t} \rightarrow 0$  as  $t \rightarrow \infty$ .  $\therefore$   $y(t) \rightarrow C_1$

$$\begin{cases} y(0) = C_1 + C_2 = 1 \\ y'(0) = -\frac{1}{2}C_2 = 1 \end{cases} \Rightarrow C_1 = 3$$

(6) (24pts) Use the Laplace transform to solve the initial value problem:

$$y^{(4)} - y = 0, \quad y(0) = 1, y'(0) = 1, y''(0) = 1, y'''(0) = 0.$$

(Hint: write your  $\mathcal{L}\{y\}(s)$  into partial fractions and use  $\mathcal{L}\{\cosh(at)\} = \frac{s}{s^2 - a^2}$ ,  $s > |a|$ ,  $\mathcal{L}\{\sinh(at)\} = \frac{a}{s^2 - a^2}$ ,  $s > |a|$ ,  $\mathcal{L}\{\sin(at)\} = \frac{a}{s^2 + a^2}$ ,  $s > 0$  to find the inverse transform)

Sol:  $\mathcal{L}\{y^{(4)}\} - \mathcal{L}\{y\} = 0$

$$\Rightarrow s^4 \mathcal{L}\{y\} - s^3 y(0) - s^2 y'(0) - s y''(0) - y'''(0) - \mathcal{L}\{y\} = 0$$

$$\Rightarrow (s^4 - 1) \mathcal{L}\{y\} = s^3 + s^2 + s$$

$$\Rightarrow \mathcal{L}\{y\} = \frac{s^3 + s^2 + s}{s^4 - 1} = \frac{s(s^2 + 1) + s^2}{(s^2 + 1)(s^2 - 1)} = \frac{s}{s^2 - 1} + \frac{1}{2} \left( \frac{1}{s^2 + 1} + \frac{1}{s^2 - 1} \right)$$

So  $y = \cosh t + \frac{1}{2}(\sinh t + \sin t)$

(7) (19pts) Solve the following initial value problem and describe the behavior of your solution as  $t \rightarrow \infty$ :

$$\mathbf{X}' = \begin{pmatrix} 1 & -5 \\ 1 & -3 \end{pmatrix} \mathbf{X}, \quad \mathbf{X}(0) = \begin{pmatrix} 1 \\ 1 \end{pmatrix}.$$

Sol:  $A = \begin{pmatrix} 1 & -5 \\ 1 & -3 \end{pmatrix} \quad \det(A - \lambda I) = 0 \Rightarrow \begin{vmatrix} 1-\lambda & -5 \\ 1 & -3-\lambda \end{vmatrix} = 0$

$$\Rightarrow \lambda^2 + 2\lambda + 2 = 0 \Rightarrow \lambda = -1 \pm i$$

For  $\lambda = -1 + i$ ,  $\begin{pmatrix} 2-i & -5 \\ 1 & -2-i \end{pmatrix} \begin{pmatrix} \xi_1 \\ \xi_2 \end{pmatrix} = 0 \Rightarrow \xi_1 = (2+i)\xi_2$

$$\Rightarrow \vec{\xi}_1 = \begin{pmatrix} 2+i \\ 1 \end{pmatrix} \Rightarrow \vec{\xi}_1 e^{\lambda t} = \begin{pmatrix} 2+i \\ 1 \end{pmatrix} e^{(-1+i)t} \text{ is a solution.}$$

From:  $\begin{pmatrix} 2+i \\ 1 \end{pmatrix} e^{(-1+i)t} = \begin{pmatrix} 2+i \\ 1 \end{pmatrix} e^{-t} (\cos t + i \sin t)$

$$= e^{-t} \begin{pmatrix} (2+i)(\cos t + i \sin t) \\ \cos t + i \sin t \end{pmatrix}$$

$$= e^{-t} \left[ \begin{pmatrix} 2\cos t - \sin t \\ \cos t \end{pmatrix} + i \begin{pmatrix} \cos t + 2\sin t \\ \sin t \end{pmatrix} \right]$$

We get the (real) general solution:

$$\vec{X}(t) = e^{-t} \left[ C_1 \begin{pmatrix} 2\cos t - \sin t \\ \cos t \end{pmatrix} + C_2 \begin{pmatrix} \cos t + 2\sin t \\ \sin t \end{pmatrix} \right]$$

$$\vec{X}(0) = \begin{pmatrix} 1 \\ 1 \end{pmatrix} \Rightarrow C_1 \begin{pmatrix} 2 \\ 1 \end{pmatrix} + C_2 \begin{pmatrix} 1 \\ 0 \end{pmatrix} = \begin{pmatrix} 1 \\ 1 \end{pmatrix} \Rightarrow \begin{cases} C_1 = 1 \\ C_2 = -1 \end{cases}$$

$$\text{So } \vec{X}(t) = e^{-t} \left[ \begin{pmatrix} 2\cos t - \sin t \\ \cos t \end{pmatrix} - \begin{pmatrix} \cos t + 2\sin t \\ \sin t \end{pmatrix} \right] = \boxed{e^{-t} \begin{pmatrix} \cos t - 3\sin t \\ \cos t - \sin t \end{pmatrix}}$$

We can see that  $\lim_{t \rightarrow \infty} \vec{X}(t) = \vec{0}$ . Both  $x_1(t)$  and  $x_2(t)$  oscillate

near  $y=0$  and approach  $y=0$

(8) (24pts) a)[18pts] Find the general solution of the following system of equations:

$$\mathbf{X}' = \begin{pmatrix} 0 & 1 & 1 \\ 1 & 0 & 1 \\ 1 & 1 & 0 \end{pmatrix} \mathbf{X}$$

b)[6pts] For a  $3 \times 3$  matrix  $\mathbf{A}$ , if you have found an eigenvalue  $r$  with algebraic multiplicity 2, and there's only one eigenvector  $\vec{\xi}$  associated with it, then what is the equation that the generalized eigenvector  $\vec{\eta}$  should satisfy?

Sol:  $\textcircled{a}$   $\mathbf{A} = \begin{pmatrix} 0 & 1 & 1 \\ 1 & 0 & 1 \\ 1 & 1 & 0 \end{pmatrix}$   $\det(\mathbf{A} - \lambda \mathbf{I}) = 0 \Rightarrow \begin{vmatrix} -\lambda & 1 & 1 \\ 1 & -\lambda & 1 \\ 1 & 1 & -\lambda \end{vmatrix} = 0$

$$\Rightarrow (-\lambda)^3 + 1 + 1 - 3(-\lambda) = 0 \Rightarrow \lambda^3 - 3\lambda - 2 = 0$$

$$\Rightarrow \lambda_1 = 2, \lambda_{2,3} = -1$$

For  $\lambda_1 = 2$   $\begin{pmatrix} -2 & 1 & 1 \\ 1 & -2 & 1 \\ 1 & 1 & -2 \end{pmatrix} \begin{pmatrix} \xi_1 \\ \xi_2 \\ \xi_3 \end{pmatrix} = 0 \Rightarrow \xi_1 = \xi_2 = \xi_3 \Rightarrow \vec{\xi}_1 = \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}$

For  $\lambda_{2,3} = -1$   $\begin{pmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \\ 1 & 1 & 1 \end{pmatrix} \begin{pmatrix} \xi_1 \\ \xi_2 \\ \xi_3 \end{pmatrix} = 0 \Rightarrow \xi_1 + \xi_2 + \xi_3 = 0 \Rightarrow \begin{cases} \vec{\xi}_2 = \begin{pmatrix} +1 \\ 0 \\ -1 \end{pmatrix} \\ \vec{\xi}_3 = \begin{pmatrix} +1 \\ -1 \\ 0 \end{pmatrix} \end{cases}$

$\Rightarrow$  general solution:  $\vec{X}(t) = C_1 \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} e^{2t} + C_2 \begin{pmatrix} 1 \\ 0 \\ -1 \end{pmatrix} e^{-t} + C_3 \begin{pmatrix} 1 \\ -1 \\ 0 \end{pmatrix} e^{-t}$

$\textcircled{b}$  let  $\vec{x} = \vec{\xi} t e^{rt} + \vec{\eta} e^{rt}$ , then  $\vec{\eta}$  is the generalized eigenvector

Substitute into  $\vec{x}' = \mathbf{A} \vec{x} \Rightarrow \begin{cases} (\mathbf{A} - r\mathbf{I}) \vec{\xi} = 0 \\ (\mathbf{A} - r\mathbf{I}) \vec{\eta} = \vec{\xi} \end{cases}$

So  $\boxed{(\mathbf{A} - r\mathbf{I}) \vec{\eta} = \vec{\xi}}$  or  $\boxed{(\mathbf{A} - r\mathbf{I})^2 \vec{\eta} = 0}$

- (9) (28pts) Consider the following non-homogeneous system of first order differential equation

$$\mathbf{X}' = \begin{pmatrix} 2 & -1 \\ 3 & -2 \end{pmatrix} \mathbf{X} + \begin{pmatrix} e^t \\ t \end{pmatrix}$$

a)[18pts] Find the general solution to the homogeneous equation and sketch the phase portrait.

b)[4pts] If you are supposed to find a particular solution of the non-homogeneous system by method of undetermined coefficient, what is the correct form of the particular solution that you should assume?

c)[6pts] To find a particular solution of the non-homogeneous system by method of variation of parameters, we start with assuming  $\mathbf{X}(t) = \Psi(t)\mathbf{u}(t)$ , where  $\Psi(t)$  is the fundamental matrix of the homogeneous system and  $\mathbf{u}(t)$  is unknown. Find  $\Psi(t)$  and derive the equations that  $\mathbf{u}(t)$  should satisfy. You don't have to solve them.

Sol: @  $A = \begin{pmatrix} 2 & -1 \\ 3 & -2 \end{pmatrix}$   $\det(A - \lambda I) = 0 \Rightarrow \begin{vmatrix} 2-\lambda & -1 \\ 3 & -2-\lambda \end{vmatrix} = 0$

$$\Rightarrow \lambda^2 - 1 = 0 \Rightarrow \lambda_1 = 1, \lambda_2 = -1$$

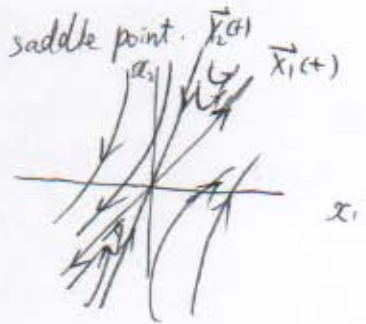
For  $\lambda_1 = 1$   $\begin{pmatrix} 1 & -1 \\ 3 & -3 \end{pmatrix} \begin{pmatrix} \xi_1 \\ \xi_2 \end{pmatrix} = 0 \Rightarrow \xi_1 = \xi_2 \Rightarrow \vec{\xi}_1 = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$

For  $\lambda_2 = -1$   $\begin{pmatrix} 3 & -1 \\ 3 & -1 \end{pmatrix} \begin{pmatrix} \xi_1 \\ \xi_2 \end{pmatrix} = 0 \Rightarrow 3\xi_1 = \xi_2 \Rightarrow \vec{\xi}_2 = \begin{pmatrix} 1 \\ 3 \end{pmatrix}$

$$\Rightarrow \boxed{\vec{X}(t) = c_1 \begin{pmatrix} 1 \\ 1 \end{pmatrix} e^t + c_2 \begin{pmatrix} 1 \\ 3 \end{pmatrix} e^{-t}}$$

Origin is a saddle point.  $\vec{X}_1(t)$   $\vec{X}_2(t)$

phase portrait:



(b)  $\vec{g}(t) = \begin{pmatrix} e^t \\ t \end{pmatrix} = e^t \begin{pmatrix} 1 \\ 0 \end{pmatrix} + t \begin{pmatrix} 0 \\ 1 \end{pmatrix}$

$\Rightarrow$  The correct form of a particular sol is

$$\boxed{\vec{X}(t) = \vec{a} t e^t + \vec{b} e^t + \vec{c} t + \vec{d}}$$

Note: We need this form because  $\vec{k} e^t$  is a solution of the homogeneous system.

(c)  $\Psi(t) = \begin{pmatrix} \vec{x}_1 & \vec{x}_2 \end{pmatrix} = \begin{pmatrix} e^t & e^{-t} \\ e^t & 3e^{-t} \end{pmatrix}$

$$\vec{X}(t) = \Psi \vec{u} \Rightarrow \vec{X}' = \Psi' \cdot \vec{u} + \Psi \cdot \vec{u}' = A \Psi \vec{u} + \vec{g}$$

$\Psi' = A \Psi$  by property of the fundamental matrix so  $\Psi \cdot \vec{u}' = \vec{g}$

In this particular case:  $\begin{vmatrix} e^t & e^{-t} \\ e^t & 3e^{-t} \end{vmatrix} \begin{pmatrix} u_1' \\ u_2' \end{pmatrix} = \begin{pmatrix} e^t \\ t \end{pmatrix}$