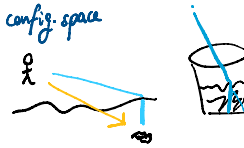


Lecture 2: Lagrangian Formalism *classical mechanics*

$$\Omega(a,b) := \{C^\infty\text{-maps } \gamma: [a,b] \rightarrow M\} \text{ config. space}$$

•  $S: \Omega \rightarrow \mathbb{R}$  action functional  
 $\gamma \mapsto S(\gamma)$



• In this context, we set  $M = \mathbb{R}^n$ ,  $TM = \mathbb{R}^n \times \mathbb{R}^n$  notation  
 and  $S(\gamma) = \int_a^b L(t, \gamma(t), \dot{\gamma}(t)) dt$  allowing  $\dot{\gamma}(t), \gamma^{(n)}(t)$  if fine  
 here the Lagrangian is:  $L: TM \times \mathbb{R} \rightarrow \mathbb{R}$ .

Q 2. Euler-Lagrange Eq's: set of them are  $\gamma$  which are critical for  $S(\gamma) = \int L$ .

$$\delta S(\gamma) = 0 \Leftrightarrow \left. \frac{d}{d\varepsilon} \right|_{\varepsilon=0} S(\gamma + \varepsilon \eta) = 0 \Leftrightarrow 0 = \left. \frac{d}{d\varepsilon} \right|_{\varepsilon=0} \int_a^b L(t, \gamma + \varepsilon \eta, \dot{\gamma} + \varepsilon \dot{\eta}) dt$$

Let's compute the  $\varepsilon$ -order of  $\int_a^b L(t, \gamma + \varepsilon \eta, \dot{\gamma} + \varepsilon \dot{\eta}) dt$ : we expand by Taylor

$$\int_a^b \left[ \partial_q L(t, \gamma + \varepsilon \eta, \dot{\gamma} + \varepsilon \dot{\eta}) \Big|_{\varepsilon=0} \cdot \eta + \partial_{\dot{q}} L(t, \gamma + \varepsilon \eta, \dot{\gamma} + \varepsilon \dot{\eta}) \Big|_{\varepsilon=0} \cdot \dot{\eta} \right] dt.$$

Now  $*$  = 0 iff  $\int_a^b \partial_q L(t, \gamma, \dot{\gamma}) \cdot \eta - \frac{d}{dt} \partial_{\dot{q}} L(t, \gamma, \dot{\gamma}) \cdot \eta dt + \left[ \partial_{\dot{q}} L \cdot \eta \right]_a^b = 0$

iff  $\int_a^b \left( \partial_q L - \frac{d}{dt} \partial_{\dot{q}} L \right) \cdot \eta dt = 0, \forall \eta$ .

now  $\rightarrow$  H.K.T  
 (K.T)  $\rightarrow$  The  $\partial_{\dot{q}} \cdot \dot{q} = \frac{d}{dt} \frac{\partial L}{\partial \dot{q}}$

The principle of least action states that allowed trajectories are MINIMA of  $S$ . (In general, are  $\text{crit}(S)$ ).

Skill to acquire: FIND CRITICAL POINTS OF A FUNCTIONAL  $S$



$\delta S(\gamma) := \left. \frac{d}{d\varepsilon} \right|_{\varepsilon=0} S(\gamma + \varepsilon \eta)$  is the "partial derivative" in the direction of  $\eta$ , where  $\eta \in \Omega$  with  $\eta$  fixed at endpoints. ( $\eta(a) = \eta(b) = 0$ )

Def: A point  $\gamma \in \Omega$  is critical if  $\delta S(\gamma) = 0$ , for all  $\eta$ .  
*is a diff. eq.*

Ex: In  $M = \mathbb{R}^n$ ,  $L(t, q, \dot{q}) = L(q, \dot{q}) = \frac{m}{2} \dot{q}^2 - V(q)$ .  
*kinetic energy*      *potential*

Hence  $\delta S(\gamma) = 0$  iff  $\partial_q L(\gamma) - \frac{d}{dt} \partial_{\dot{q}} L \equiv 0$ . (#)

Def: (#) are known as the Euler-Lagrange associated to the action  $S = \int L$ . (It is generally a 2nd ode.)

Ex:  $L(q, \dot{q}) = \frac{m}{2} \dot{q}^2 - V(q)$ , then (#) read  $\partial_q L = -\partial_q V = -\nabla V$ ,  $\partial_{\dot{q}} L = m \cdot \dot{q}$ ,  $\frac{d}{dt} \partial_{\dot{q}} L = m \cdot \ddot{q}$   
 $-\partial_q V - m \cdot \ddot{q} = 0$ , equivalently  $m \cdot \ddot{q} = -\nabla V \iff m \cdot \ddot{q} = F$ .

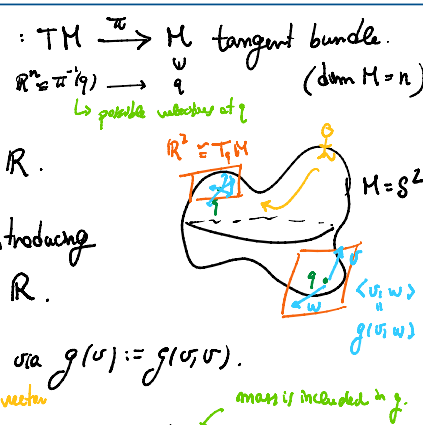
§ 3. General configuration spaces :  $TM \xrightarrow{\pi} M$  tangent bundle.

(1) • The potential term is just  $VEC(M)$ ,  
which gives  $V \circ \pi : TM \rightarrow \mathbb{R}$ .

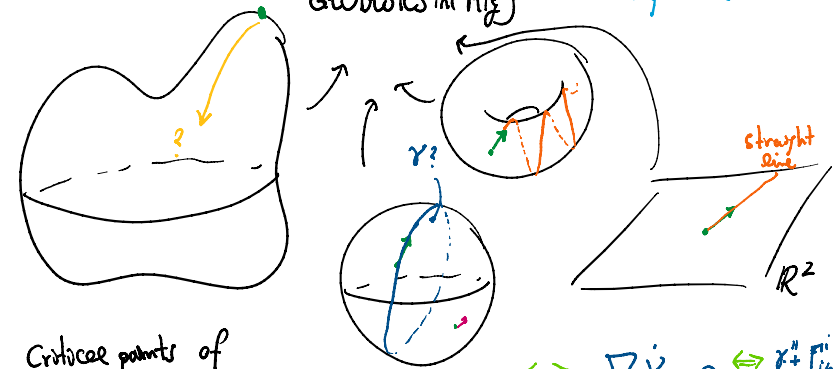
(2) • The kinetic term is generalized by introducing  
a metric  $g : TM \otimes TM \rightarrow \mathbb{R}$ .

From  $g$  we construct  $\mathcal{G} : TM \rightarrow \mathbb{R}$  via  $\mathcal{G}(v) := g(v, v)$ .

(3) • A Lagr.  $L : TM \rightarrow \mathbb{R}$  is typically  $L = \frac{1}{2} \mathcal{G} - V \circ \pi$ .



Ex: The case of  $(M, g)$  with zero potential. no force exerted to particles



Prop: Critical points of  $S(\gamma) = \int \frac{1}{2} g$  are geodesics paths.  $\iff \nabla_j \dot{\gamma} = 0 \iff \ddot{\gamma}^i + \Gamma_{jk}^i \dot{\gamma}^j \dot{\gamma}^k = 0$