

# Lecture 22 : Green's Functions I

Note Title

- Want to **diagonalize** the self-adj. op.  $\mathcal{L}$  arisen in the Sturm - Liouville theory.  $\mathcal{L}$  **Differential op.**
- If  $\mathcal{L}$  were a **compact** self-adj. op., then it's pretty close to a matrix, i.e., one can apply tools similar to those in linear algebra (e.g., eigenvalue decomposition, etc.)
- Unfortunately,  $\mathcal{L}$  is far from being compact! In fact,  $\mathcal{L}$  is **unbounded**!

Ex. Let  $\mathcal{L} = \frac{d^2}{dx^2}$  on  $[0,1]$  with  $D(\mathcal{L}) = \{f \in H^2(0,1) \mid f(0) = f(1) = 0\}$ .  
Then,  $\|\mathcal{L}\| := \sup_{f \in D(\mathcal{L})} \frac{\|\mathcal{L}f\|_2}{\|f\|_2}$

Take  $f_n = \sqrt{2} \sin n\pi x \in D(\mathcal{L})$ .  $\|f_n\|_2 = 1$ .

$\Rightarrow \mathcal{L}f_n = -(n\pi)^2 \sqrt{2} \sin n\pi x$ .  $\|\mathcal{L}f_n\|_2 = (n\pi)^2$ .

$\Rightarrow \|\mathcal{L}f_n\| / \|f_n\| = (n\pi)^2 \rightarrow \infty$ !

Hence  $\|\mathcal{L}\| = \infty$ , i.e., unbdd. //

- Therefore, we investigate  $\mathcal{L}^{-1}$  instead.  $\mathcal{L}^{-1}$  is an **integral op.**, and turns out to be **compact** in our case!
- We'll review some basic properties of compact op's later. But first, let's proceed with deriving  $\mathcal{L}^{-1}$ !

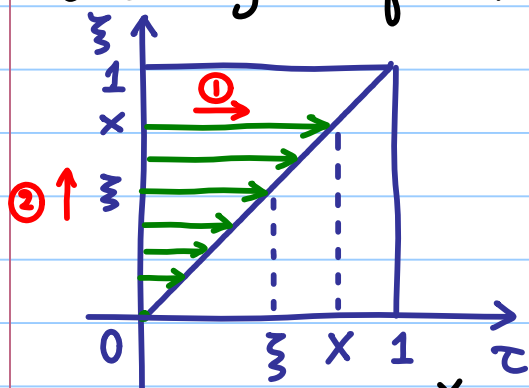
Consider an RSL:  $\mathcal{L}f = g$ , i.e.,  $(pf')' + qf = g$ , where  $D(\mathcal{L}) = \{f \in H^2(a,b) \mid \alpha f(a) + \alpha' f'(a) = 0, \beta f(b) + \beta' f'(b) = 0\}$ ,  $g \in L^2(a,b)$ . Want to do:  **$f = \mathcal{L}^{-1}g$** .

Let's look at the simplest case first, i.e.,  $\mathcal{L} = \frac{d^2}{dx^2}$  on  $[0,1]$  with the Dirichlet B.C.:  $f(0) = f(1) = 0$ .

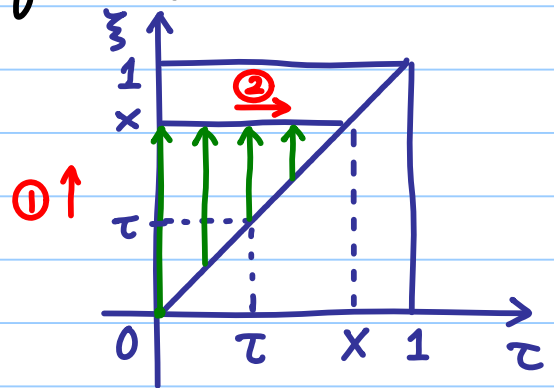
Integrate  $\mathcal{L}f = f'' = g$  twice to get

$$f(x) = \int_0^x \left( \int_0^\xi g(\tau) d\tau \right) d\xi + \underline{Ax} + \underline{B}. \quad \text{integration const's}$$

Let's swap the order of integration by considering the region of integration as follows:



$\equiv$



$$\begin{aligned} \text{So, } f(x) &= \int_0^x \left( \int_\tau^x g(\tau) d\xi \right) d\tau + Ax + B \\ &= \int_0^x (x - \tau) g(\tau) d\tau + Ax + B \end{aligned}$$

$\xrightarrow{\text{a fn of } \tau!}$

$$\text{Now, } f(0) = B = 0$$

$$f(1) = \int_0^1 (1 - \tau) g(\tau) d\tau + A = 0.$$

$$\begin{aligned} \Rightarrow f(x) &= \int_0^x (x - \tau) g(\tau) d\tau - x \int_0^1 (1 - \tau) g(\tau) d\tau \\ &= \int_0^x (x - \tau) g(\tau) d\tau - \left\{ \int_0^x x(1 - \tau) g(\tau) d\tau + \int_x^1 x(1 - \tau) g(\tau) d\tau \right\} \\ &= \int_0^x \tau(x - 1) g(\tau) d\tau + \int_x^1 x(\tau - 1) g(\tau) d\tau \\ &=: \int_0^1 k(x, \tau) g(\tau) d\tau =: \mathcal{K} g(x) \end{aligned}$$

$$\text{where } k(x, \tau) := \begin{cases} \tau(x - 1) & \text{if } 0 \leq \tau \leq x; \\ x(\tau - 1) & \text{if } x \leq \tau \leq 1. \end{cases}$$

$\mathcal{K}$  : an integral op.

$k(\cdot, \cdot)$  : the kernel fn of  $\mathcal{K}$ .

$\Rightarrow$  Mathematica fig. show here.

In this case,  $k(\cdot, \cdot)$  has a special name:

Green's fcn for  $\mathcal{L}$  (or the BVP associated w.  $\mathcal{L}$ )

Now, for a general case of RSL:  $\mathcal{L}f = g$ ,  $f \in D(\mathcal{L})$ , we use the method of variation of parameters due to Lagrange. First, let's define an extended op.:  
 $\mathcal{M} := \frac{d}{dx}(p \frac{d}{dx} \cdot) + q \cdot$ ,  $D(\mathcal{M}) = H^2(a, b) \supset D(\mathcal{L})$   
no explicit B.C.

Now suppose we can find two linearly indep. sol's  $u, v$  of the corresponding homogeneous eqn.  $\mathcal{M}f = 0$ . Then we look for a sol. of  $\mathcal{L}f = g$  of the form:

$$f = \varphi u + \psi v, \quad \exists \varphi, \psi \in C^1[a, b].$$

$$\Rightarrow f' = \varphi u' + \psi v' + \varphi' u + \psi' v$$

$$\text{Let's choose } \varphi, \psi \text{ s.t. } \varphi' u + \psi' v = 0 \quad \text{--- ①}$$

$$\Rightarrow f' = \varphi u' + \psi v'$$

$$\Rightarrow \mathcal{L}f = (pf')' + qf$$

$$= p' \varphi u' + p' \psi v' + p \varphi' u' + p \varphi u'' + p \psi' v' + p \psi v''$$

$$= \varphi' p u' + \varphi (p' u' + p u'' + q u) \leftarrow = \mathcal{M}u = 0 + q \varphi u + q \psi v$$

$$+ \psi' p v' + \psi (p' v' + p v'' + q v) \leftarrow = \mathcal{M}v = 0$$

$$= p(\varphi' u' + \psi' v') \quad \text{--- ②}$$

$$\text{①} \times p u' - \text{②} \times u \quad p(\cancel{\varphi' u' u} + \psi' u' v) - p(\cancel{\varphi' u' u} + \psi' u v') = -u g$$

$$\text{i.e., } \psi' p(uv' - vu') = u g \quad \text{--- ③}$$

By Lagrange's identity, we have

$$\underbrace{u \mathcal{M}v}_{=0} - \underbrace{v \mathcal{M}u}_{=0} = (p(uv' - vu'))' = 0.$$

So,  $p(uv' - vu') = \text{const.}$ , say,  $c$ .

$\Rightarrow$  ③ becomes  $c \psi' = u g$ .

Similarly, we can also get  $c \varphi' = -v g$ .

So, assuming  $c \neq 0$ , we can set

$$\varphi(x) = \frac{1}{c} \left( \int_x^b v(\tau) g(\tau) d\tau + \underline{A} \right) \rightarrow \text{Integration Const's}$$

$$\psi(x) = \frac{1}{c} \left( \int_a^x u(\tau) g(\tau) d\tau + \underline{B} \right)$$

as long as  $g \in C[a, b]$ ,  $\varphi, \psi \in C^1[a, b]$  and satisfy  $c\varphi' = -vg$ ,  $c\psi' = ug$ .

And in turn,  $\varphi'u + \psi'v = 0$  and  $f = \varphi u + \psi v$  is a sol. of  $Lf = g$ . Using the B.C., we expect  $A, B$  to be determined.

Yet,  $\exists$  two potential problems:

(a) Can we really assume  $c \neq 0$ ?

(b) Can we extend the result to  $g \in L^2[a, b]$  from  $g \in C[a, b]$ ?

We first deal with (a) and briefly discuss (b) later. (full discussion on (b) requires the knowledge of measure theory.)

Let's proceed!  $Mf = 0$  has nontrivial (i.e., nonzero)

sols  $f = u$ , s.t.  $\alpha u(a) + \alpha' u'(a) = 0$

$f = v$ , s.t.  $\beta v(b) + \beta' v'(b) = 0$

thanks to the Existence Thm for 2nd order ODEs.

Now set  $f(x) = \varphi(x)u(x) + \psi(x)v(x)$ ,  $f' = \varphi u' + \psi v'$

$$= \frac{1}{c} u(x) \left\{ \int_x^b v(\tau) g(\tau) d\tau + A \right\} + \frac{1}{c} v(x) \left\{ \int_a^x u(\tau) g(\tau) d\tau + B \right\}$$

By our derivation, we know  $Lf = g$ , but  $f$  must satisfy the B.C. at both ends.

$$f(a) = \frac{1}{c} u(a) \left\{ \int_a^b v(\tau) g(\tau) d\tau + A \right\} + \frac{1}{c} v(a) B$$

$$f'(a) = \varphi(a) u'(a) + \psi(a) v'(a)$$

$$= \frac{1}{c} u'(a) \left\{ \int_a^b v(\tau) g(\tau) d\tau + A \right\} + \frac{1}{c} v'(a) B$$

$$\text{So, } 0 = \alpha f(a) + \alpha' f'(a) = \frac{1}{c} \left\{ \int_a^b v(\tau) g(\tau) d\tau + A \right\} \underbrace{(\alpha u(a) + \alpha' u'(a))}_{=0} + \frac{B}{c} \underbrace{(\alpha v(a) + \alpha' v'(a))}_{\neq 0}$$

$\Rightarrow B=0$ . Similarly, we get  $A=0$ .

So, we now have :  $\varphi(x) = \frac{1}{c} \int_a^b v(\tau) g(\tau) d\tau$   
If  $f = \varphi u + \psi v$  with  $\begin{cases} \varphi(x) = \frac{1}{c} \int_a^x v(\tau) g(\tau) d\tau \\ \psi(x) = \frac{1}{c} \int_a^x u(\tau) g(\tau) d\tau \end{cases} \quad x \in [a, b]$

then  $f$  is a sol. of  $Lf = g$  satisfying the B.C.'s !

Now, we'll prove the following thm, which takes care of (a):

Thm Suppose that 0 is not an eigenval. of the RSL.

Then  $\forall g \in C[a, b]$ ,  $Lf = g$  (incl. B.C.'s) has the unique sol.  $f(x) = \int_a^b k(x, \tau) g(\tau) d\tau$

where  $k(x, \tau) := \begin{cases} \frac{1}{c} v(x) u(\tau) & \text{if } a \leq \tau \leq x \leq b \\ \frac{1}{c} u(x) v(\tau) & \text{if } a \leq x \leq \tau \leq b \end{cases}$

$u, v$  are non-zero real sol's of  $M_1 u = 0, M_2 v = 0$ ,  
 and  $c = p(uv' - vu') = \text{const.}$  =  $M + \text{B.C. at } a$   $M + \text{B.C. at } b$

Furthermore,  $f''$  exists and  $f'' \in C[a, b]$ . //

First, we prove:

Lemma Under the assumption of the above thm,

$$u v' - v u' \neq 0 \quad \forall x \in [a, b]. \quad =: W[u, v](x)$$

(Proof) Suppose  $u v' - v u' = \begin{vmatrix} u & v \\ u' & v' \end{vmatrix} = 0$  at  $\exists x_0 \in [a, b]$ .  
 Then  $\exists (\gamma, \delta) \neq (0, 0)$  s.t.

$$\begin{cases} \gamma u(x_0) + \delta v(x_0) = 0 \\ \gamma u'(x_0) + \delta v'(x_0) = 0 \end{cases} \leftarrow \begin{bmatrix} u(x_0) & v(x_0) \\ u'(x_0) & v'(x_0) \end{bmatrix} \begin{bmatrix} \gamma \\ \delta \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$\Rightarrow f = \gamma u + \delta v$  is a sol. of  $Mf = 0$  with  $\begin{cases} f(x_0) = 0 \\ f'(x_0) = 0 \end{cases}$ .

$\Rightarrow$  By the Fundamental Existence Thm for 2nd order ODEs,  $f(x) \equiv 0 \quad \forall x \in [a, b]$ .

$\Rightarrow \gamma u + \delta v \equiv 0$ , but  $(\gamma, \delta) \neq (0, 0)$

$\Leftrightarrow u, v$ : linearly dep. and  $u = -\frac{\delta}{\gamma} v$ .

$\Rightarrow \beta u(b) + \beta' u'(b) = 0$  since  $\beta v(b) + \beta' v'(b) = 0$ .

$\Rightarrow u$  satisfies  $\mathcal{L}u = 0$ ,  $u \neq 0$ .

$\Leftrightarrow u$ : an eigenfcn of  $\mathcal{L}$  corresp. to 0 eigenvalue, which contradicts with the assumption!  $\#$

(Proof of Thm)  $p > 0$  &  $uv' - vu' \neq 0, \quad \forall x \in [a, b]$  via Lemma.

$\Rightarrow c = p(uv' - vu') \neq 0$ .

Since 0 is not an eigval of  $\mathcal{L}$ ,  $\mathcal{L}f = g$  certainly has at most one sol. in  $D(\mathcal{L})$ . The foregoing calculations have already shown that  $f = \varphi u + \psi v$  is such a sol. It remains to check that  $f \in C^2[a, b]$ .

$u''$  exists since  $u$  is a sol. to  $M_1 f = 0$  (obvious!)

and  $u'' = -\frac{p'u'}{p} - \frac{f u}{p} \in C[a, b] \Rightarrow u \in C^2[a, b]$ .

Similarly,  $v \in C^2[a, b]$ .

Now,  $\varphi', \psi' \in C[a, b]$  because  $c\psi' = ug$ ,  $c\varphi' = -vg$ .

Since  $f' = \varphi u' + \psi v' \in C^1[a, b]$ , i.e.,  $f'' \in C[a, b]$ . ///