Basics of Analytic Signals

Naoki Saito

Professor of Department of Mathematics University of California, Davis

February 24, 2016

saito@math.ucdavis.edu (UC Davis)

Analytic Signals

02/24/2016 1 / 10

- Many natural and man-made signals exhibit *time-varying frequencies* (e.g., chirps, FM radio waves).
- Characterization and analysis of such a signal, u(t), based on instantaneous amplitude a(t), instantaneous phase φ(t), and instantaneous frequency ω(t) := φ'(t), are very important:

 $u(t) = a(t)\cos\phi(t).$

- Many natural and man-made signals exhibit *time-varying frequencies* (e.g., chirps, FM radio waves).
- Characterization and analysis of such a signal, u(t), based on *instantaneous amplitude* a(t), *instantaneous phase* $\phi(t)$, and *instantaneous frequency* $\omega(t) := \phi'(t)$, are very important:

 $u(t)=a(t)\cos\phi(t).$

- It is convenient to use a complexified version of the signal whose real part is a given real-valued signal u(t).
- Given *u*(*t*), however, there are infinitely many ways to define the instantaneous amplitude and phase (IAP) pairs so that

 $u(t) = a(t)\cos\phi(t).$

• This is due to the arbitrariness of the complexified version of u, i.e.,

 $f(t) = u(t) + \mathrm{i}v(t)$

where v(t) is an arbitrary real-valued signal; yet this yields the IAP representation of u(t) via

$$a(t) = \sqrt{u^2(t) + v^2(t)}, \quad \phi(t) = \arctan \frac{v(t)}{u(t)}.$$

• The *instantaneous frequency* is defined as

$$\omega(t) := \frac{\mathrm{d}\phi}{\mathrm{d}t} = \frac{u(t)v'(t) - u'(t)v(t)}{u^2(t) + v^2(t)}$$

saito@math.ucdavis.edu (UC Davis)

Analytic Signals

- It is convenient to use a complexified version of the signal whose real part is a given real-valued signal u(t).
- Given *u*(*t*), however, there are infinitely many ways to define the instantaneous amplitude and phase (IAP) pairs so that

 $u(t) = a(t)\cos\phi(t).$

• This is due to the arbitrariness of the complexified version of u, i.e., f(t) = u(t) + iv(t)

where v(t) is an arbitrary real-valued signal; yet this yields the IAP representation of u(t) via

$$a(t) = \sqrt{u^2(t) + v^2(t)}, \quad \phi(t) = \arctan \frac{v(t)}{u(t)}.$$

• The *instantaneous frequency* is defined as

$$\omega(t) := \frac{\mathrm{d}\phi}{\mathrm{d}t} = \frac{u(t)v'(t) - u'(t)v(t)}{u^2(t) + v^2(t)}$$

saito@math.ucdavis.edu (UC Davis)

Analytic Signals

- It is convenient to use a complexified version of the signal whose real part is a given real-valued signal u(t).
- Given *u*(*t*), however, there are infinitely many ways to define the instantaneous amplitude and phase (IAP) pairs so that

 $u(t) = a(t)\cos\phi(t).$

• This is due to the arbitrariness of the complexified version of u, i.e.,

$$f(t) = u(t) + \mathrm{i}v(t)$$

where v(t) is an arbitrary real-valued signal; yet this yields the IAP representation of u(t) via

$$a(t) = \sqrt{u^2(t) + v^2(t)}, \quad \phi(t) = \arctan \frac{v(t)}{u(t)}.$$

• The *instantaneous frequency* is defined as

$$\omega(t) := \frac{\mathrm{d}\phi}{\mathrm{d}t} = \frac{u(t)v'(t) - u'(t)v(t)}{u^2(t) + v^2(t)}$$

- It is convenient to use a complexified version of the signal whose real part is a given real-valued signal u(t).
- Given *u*(*t*), however, there are infinitely many ways to define the instantaneous amplitude and phase (IAP) pairs so that

 $u(t) = a(t)\cos\phi(t).$

• This is due to the arbitrariness of the complexified version of u, i.e.,

$$f(t) = u(t) + \mathrm{i}v(t)$$

where v(t) is an arbitrary real-valued signal; yet this yields the IAP representation of u(t) via

$$a(t) = \sqrt{u^2(t) + v^2(t)}, \quad \phi(t) = \arctan \frac{v(t)}{u(t)}.$$

• The *instantaneous frequency* is defined as

$$\omega(t) := \frac{\mathrm{d}\phi}{\mathrm{d}t} = \frac{u(t)v'(t) - u'(t)v(t)}{u^2(t) + v^2(t)}$$

- Gabor (1946) proposed to use the *the Hilbert transform* of u(t) as v(t), and called the complex-valued f(t) an *analytic signal*.
- Vakman (1972) proved that v(t) must be of the Hilbert transform of u(t) if we impose some a priori physical assumptions:
 - v(t) must be derived from u(t).
 - Amplitude continuity: a small change in $u \rightarrow$ a small change in a(t).
 - Phase independence of scale: if cu(t), $c \in \mathbb{R}$ arbitrary scalar, then the phase does not change from that of u(t) and its amplitude becomes c times that of u(t).
 - Harmonic correspondence: if $u(t) = a_0 \cos(\omega_0 t + \phi_0)$, then $a(t) \equiv a_0$, $\phi(t) \equiv \omega_0 t + \phi_0$.

- Gabor (1946) proposed to use the *the Hilbert transform* of u(t) as v(t), and called the complex-valued f(t) an *analytic signal*.
- Vakman (1972) proved that v(t) must be of the Hilbert transform of u(t) if we impose some a priori physical assumptions:
 - **1** v(t) must be derived from u(t).
 - ② Amplitude continuity: a small change in $u \Longrightarrow$ a small change in a(t).
 - **③** Phase independence of scale: if cu(t), $c \in \mathbb{R}$ arbitrary scalar, then the phase does not change from that of u(t) and its amplitude becomes c times that of u(t).
 - I Harmonic correspondence: if $u(t) = a_0 \cos(\omega_0 t + \phi_0)$, then $a(t) \equiv a_0$, $\phi(t) \equiv \omega_0 t + \phi_0$.

A D > A A P >

- Gabor (1946) proposed to use the *the Hilbert transform* of u(t) as v(t), and called the complex-valued f(t) an *analytic signal*.
- Vakman (1972) proved that v(t) must be of the Hilbert transform of u(t) if we impose some a priori physical assumptions:
 - **1** v(t) must be derived from u(t).
 - a mplitude continuity: a small change in u ⇒ a small change in a(t).
 Phase independence of scale: if cu(t), c ∈ R arbitrary scalar, then the phase does not change from that of u(t) and its amplitude becomes c times that of u(t).
 - I Harmonic correspondence: if $u(t) = a_0 \cos(\omega_0 t + \phi_0)$, then $a(t) \equiv a_0$, $\phi(t) \equiv \omega_0 t + \phi_0$.

Image: Image:

- Gabor (1946) proposed to use the *the Hilbert transform* of u(t) as v(t), and called the complex-valued f(t) an *analytic signal*.
- Vakman (1972) proved that v(t) must be of the Hilbert transform of u(t) if we impose some a priori physical assumptions:
 - **1** v(t) must be derived from u(t).
 - 2 Amplitude continuity: a small change in $u \Longrightarrow$ a small change in a(t).
 - 3 Phase independence of scale: if cu(t), $c \in \mathbb{R}$ arbitrary scalar, then the phase does not change from that of u(t) and its amplitude becomes c times that of u(t).
 - I Harmonic correspondence: if $u(t) = a_0 \cos(\omega_0 t + \phi_0)$, then $a(t) \equiv a_0$, $\phi(t) \equiv \omega_0 t + \phi_0$.

A D > A A P >

- Gabor (1946) proposed to use the *the Hilbert transform* of u(t) as v(t), and called the complex-valued f(t) an *analytic signal*.
- Vakman (1972) proved that v(t) must be of the Hilbert transform of u(t) if we impose some a priori physical assumptions:
 - **1** v(t) must be derived from u(t).
 - 2 Amplitude continuity: a small change in $u \Longrightarrow$ a small change in a(t).
 - **③** Phase independence of scale: if cu(t), $c \in \mathbb{R}$ arbitrary scalar, then the phase does not change from that of u(t) and its amplitude becomes c times that of u(t).
 - B Harmonic correspondence: if $u(t) = a_0 \cos(\omega_0 t + \phi_0)$, then $a(t) \equiv a_0$, $\phi(t) \equiv \omega_0 t + \phi_0$.

- Gabor (1946) proposed to use the *the Hilbert transform* of u(t) as v(t), and called the complex-valued f(t) an *analytic signal*.
- Vakman (1972) proved that v(t) must be of the Hilbert transform of u(t) if we impose some a priori physical assumptions:
 - **1** v(t) must be derived from u(t).
 - 2 Amplitude continuity: a small change in $u \Longrightarrow$ a small change in a(t).
 - **③** Phase independence of scale: if cu(t), $c \in \mathbb{R}$ arbitrary scalar, then the phase does not change from that of u(t) and its amplitude becomes c times that of u(t).
 - **4** Harmonic correspondence: if $u(t) = a_0 \cos(\omega_0 t + \phi_0)$, then $a(t) \equiv a_0$, $\phi(t) \equiv \omega_0 t + \phi_0$.

- For simplicity, we assume that our signals are 2π -periodic in $\theta \in [-\pi, \pi)$.
- Hence, we work on the unit circle and unit disk \mathbb{D} in $\mathbb{C} = \mathbb{R}^2$.
- Note that the signals over R = (-∞,∞) can be treated similarly by considering the real axis and the upper half plane of C.
- The analytic signal of a given signal $u(\theta) \in \mathbb{R}$ is often and simply obtained via the *Hilbert transform*:

$$f(\theta) = u(\theta) + i\mathcal{H}u(\theta), \quad \mathcal{H}u(\theta) := \frac{1}{2\pi} \operatorname{pv} \int_{-\pi}^{\pi} u(\tau) \cot \frac{\theta - \tau}{2} d\tau.$$

Note that

$$u(\theta) = \frac{a_0}{2} + \sum_{k \ge 1} (a_k \cos k\theta + b_k \sin k\theta) \Rightarrow \mathcal{H}u(\theta) = \sum_{k \ge 1} (a_k \sin k\theta - b_k \cos k\theta).$$

• Furthermore,

$$f(\theta) = \frac{a_0}{2} + \sum_{k \ge 1} (a_k - \mathrm{i}b_k) \mathrm{e}^{\mathrm{i}k\theta}.$$

- For simplicity, we assume that our signals are 2π -periodic in $\theta \in [-\pi, \pi)$.
- Hence, we work on the unit circle and unit disk \mathbb{D} in $\mathbb{C} = \mathbb{R}^2$.
- Note that the signals over R = (-∞,∞) can be treated similarly by considering the real axis and the upper half plane of C.
- The analytic signal of a given signal $u(\theta) \in \mathbb{R}$ is often and simply obtained via the *Hilbert transform*:

$$f(\theta) = u(\theta) + i\mathcal{H}u(\theta), \quad \mathcal{H}u(\theta) := \frac{1}{2\pi} \operatorname{pv} \int_{-\pi}^{\pi} u(\tau) \cot \frac{\theta - \tau}{2} d\tau.$$

Note that

 $u(\theta) = \frac{a_0}{2} + \sum_{k \ge 1} (a_k \cos k\theta + b_k \sin k\theta) \Rightarrow \mathcal{H}u(\theta) = \sum_{k \ge 1} (a_k \sin k\theta - b_k \cos k\theta).$

• Furthermore,

$$f(\theta) = \frac{a_0}{2} + \sum_{k \ge 1} (a_k - \mathrm{i}b_k) \mathrm{e}^{\mathrm{i}k\theta}.$$

- For simplicity, we assume that our signals are 2π -periodic in $\theta \in [-\pi, \pi)$.
- Hence, we work on the unit circle and unit disk \mathbb{D} in $\mathbb{C} = \mathbb{R}^2$.
- Note that the signals over R = (-∞,∞) can be treated similarly by considering the real axis and the upper half plane of C.
- The analytic signal of a given signal u(θ) ∈ ℝ is often and simply obtained via the *Hilbert transform*:

$$f(\theta) = u(\theta) + i\mathcal{H}u(\theta), \quad \mathcal{H}u(\theta) := \frac{1}{2\pi} \operatorname{pv} \int_{-\pi}^{\pi} u(\tau) \cot \frac{\theta - \tau}{2} d\tau.$$

Note that

 $u(\theta) = \frac{a_0}{2} + \sum_{k \ge 1} (a_k \cos k\theta + b_k \sin k\theta) \Rightarrow \mathcal{H}u(\theta) = \sum_{k \ge 1} (a_k \sin k\theta - b_k \cos k\theta).$

• Furthermore,

$$f(\theta) = \frac{a_0}{2} + \sum_{k \ge 1} (a_k - \mathrm{i}b_k) \mathrm{e}^{\mathrm{i}k\theta}.$$

- For simplicity, we assume that our signals are 2π -periodic in $\theta \in [-\pi, \pi)$.
- Hence, we work on the unit circle and unit disk \mathbb{D} in $\mathbb{C} = \mathbb{R}^2$.
- Note that the signals over R = (-∞,∞) can be treated similarly by considering the real axis and the upper half plane of C.
- The analytic signal of a given signal $u(\theta) \in \mathbb{R}$ is often and simply obtained via the *Hilbert transform*:

$$f(\theta) = u(\theta) + i\mathcal{H}u(\theta), \quad \mathcal{H}u(\theta) := \frac{1}{2\pi} \operatorname{pv} \int_{-\pi}^{\pi} u(\tau) \cot \frac{\theta - \tau}{2} d\tau.$$

Note that

 $u(\theta) = \frac{a_0}{2} + \sum_{k \ge 1} (a_k \cos k\theta + b_k \sin k\theta) \Rightarrow \mathcal{H}u(\theta) = \sum_{k \ge 1} (a_k \sin k\theta - b_k \cos k\theta).$

Furthermore,

$$f(\theta) = \frac{a_0}{2} + \sum_{k \ge 1} (a_k - \mathrm{i}b_k) \mathrm{e}^{\mathrm{i}k\theta}.$$

- For simplicity, we assume that our signals are 2π -periodic in $\theta \in [-\pi, \pi)$.
- Hence, we work on the unit circle and unit disk \mathbb{D} in $\mathbb{C} = \mathbb{R}^2$.
- Note that the signals over R = (-∞,∞) can be treated similarly by considering the real axis and the upper half plane of C.
- The analytic signal of a given signal $u(\theta) \in \mathbb{R}$ is often and simply obtained via the *Hilbert transform*:

$$f(\theta) = u(\theta) + i\mathcal{H}u(\theta), \quad \mathcal{H}u(\theta) := \frac{1}{2\pi} \operatorname{pv} \int_{-\pi}^{\pi} u(\tau) \cot \frac{\theta - \tau}{2} d\tau.$$

Note that

$$u(\theta) = \frac{a_0}{2} + \sum_{k \ge 1} (a_k \cos k\theta + b_k \sin k\theta) \Rightarrow \mathcal{H}u(\theta) = \sum_{k \ge 1} (a_k \sin k\theta - b_k \cos k\theta).$$

Furthermore,

$$f(\theta) = \frac{a_0}{2} + \sum_{k \ge 1} (a_k - \mathrm{i}b_k) \mathrm{e}^{\mathrm{i}k\theta}.$$

- For simplicity, we assume that our signals are 2π -periodic in $\theta \in [-\pi, \pi)$.
- Hence, we work on the unit circle and unit disk \mathbb{D} in $\mathbb{C} = \mathbb{R}^2$.
- Note that the signals over R = (-∞,∞) can be treated similarly by considering the real axis and the upper half plane of C.
- The analytic signal of a given signal $u(\theta) \in \mathbb{R}$ is often and simply obtained via the *Hilbert transform*:

$$f(\theta) = u(\theta) + i\mathcal{H}u(\theta), \quad \mathcal{H}u(\theta) := \frac{1}{2\pi} \operatorname{pv} \int_{-\pi}^{\pi} u(\tau) \cot \frac{\theta - \tau}{2} d\tau.$$

Note that

$$u(\theta) = \frac{a_0}{2} + \sum_{k \ge 1} (a_k \cos k\theta + b_k \sin k\theta) \Rightarrow \mathcal{H}u(\theta) = \sum_{k \ge 1} (a_k \sin k\theta - b_k \cos k\theta).$$

Furthermore,

$$f(\theta) = \frac{a_0}{2} + \sum_{k \ge 1} (a_k - \mathrm{i}b_k) \mathrm{e}^{\mathrm{i}k\theta}.$$

We can gain a deeper insight by viewing this as *the boundary value* of an *analytic function* F(z) where

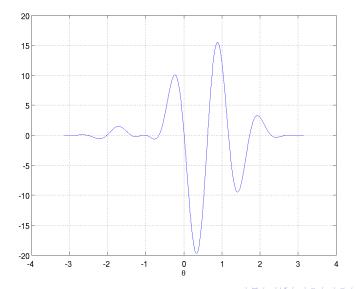
$$F(z) := U(z) + i\widetilde{U}(z), \quad z \in \mathbb{D},$$

where

$$\begin{split} U(z) &= U\left(r\mathrm{e}^{\mathrm{i}\theta}\right) = P_r * u(\theta) = \frac{1}{2\pi} \int_{-\pi}^{\pi} \frac{1 - r^2}{1 - 2r\cos(\theta - \tau) + r^2} u(\tau) \,\mathrm{d}\tau, \\ \widetilde{U}(z) &= \widetilde{U}\left(r\mathrm{e}^{\mathrm{i}\theta}\right) = Q_r * u(\theta) = \frac{1}{2\pi} \int_{-\pi}^{\pi} \frac{2r\sin(\theta - \tau)}{1 - 2r\cos(\theta - \tau) + r^2} u(\tau) \,\mathrm{d}\tau. \end{split}$$

In other words, the original signal $u(\theta) = U(e^{i\theta})$ is the boundary value of the harmonic function U on $\partial \mathbb{D}$, which is constructed by the Poisson integral. \tilde{U} and $Q_r(\theta)$ are referred to as the conjugate harmonic function and the conjugate Poisson kernel, respectively.

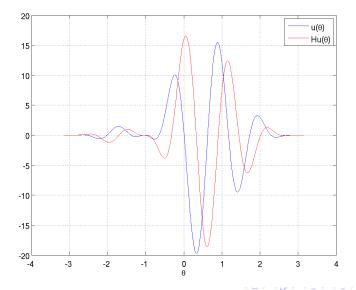
Analytic Signal ... An Example: $u(\theta)$



saito@math.ucdavis.edu (UC Davis)

02/24/2016 7 / 10

Analytic Signal ... An Example: $u(\theta)$ and $\mathcal{H}u(\theta)$

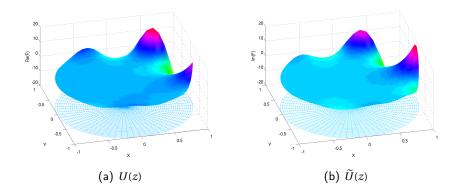


saito@math.ucdavis.edu (UC Davis)

Analytic Signals

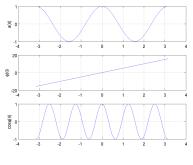
02/24/2016 8 / 10

Analytic Signal . . . An Example: U(z) and $\widetilde{U}(z)$



Even if we use the analytic signal, its IAP representation is not unique as shown by Cohen, Loughlin, and Vakman (1999):

- $f(\theta) = a(\theta)e^{i\phi(\theta)}$, where $a(\theta) = u(\theta)\cos\phi(\theta) + v(\theta)\sin\phi(\theta)$ may be negative though $\phi(\theta)$ is continuous;
- $f(\theta) = |a(\theta)| e^{i(\phi(\theta) + \pi \alpha(\theta))}$, where $\alpha(\theta)$ is an appropriate phase function, which may be discontinuous.



(a) Continuous phase

Even if we use the analytic signal, its IAP representation is not unique as shown by Cohen, Loughlin, and Vakman (1999):

- $f(\theta) = a(\theta)e^{i\phi(\theta)}$, where $a(\theta) = u(\theta)\cos\phi(\theta) + v(\theta)\sin\phi(\theta)$ may be negative though $\phi(\theta)$ is continuous;
- $f(\theta) = |a(\theta)| e^{i(\phi(\theta) + \pi \alpha(\theta))}$, where $\alpha(\theta)$ is an appropriate phase function, which may be discontinuous.

