MAT 280: Harmonic Analysis on Graphs \& Networks Lecture 3: Baiscs of Graph Theory: Graph Laplacians

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## Outline

(1) Basic Definitions in Graph Theory
(2) Matrices Associated with a Graph
(3) Why Graph Laplacians?

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## (2) Matrices Associated with a Graph

## (3) Why Graph Laplacians?

## Basic Definitions

- A graph $G$ consists of a set of vertices (or nodes) $V$ and a set of edges $E$ connecting some pairs of vertices in $V$. We write $G=(V, E)$.
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- For any two vertices in $V$, if $\exists$ a path connecting them, then such a graph $G$ is said to be connected. In the case of a digraph, it is said to be strongly connected.
- $d(x, y):=\inf _{c \in \mathscr{P}(x, y)} \ell(c)$ is called the graph distance between $x$ and $y$.
- $\operatorname{diam}(G):=\sup _{x, y \in V} d(x, y)$ is called the diameter of $G$. Note that $\operatorname{diam}(G)<\infty \Longleftrightarrow G$ is finite.


## Basic Definitions ...

- We say two graphs are isomorphic if $\exists$ a one-to-one correspondence between the vertex sets such that if two vertices are joined by an edge in one graph, the corresponding vertices are also joined by an edge in the other graph.



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- If all the vertices of a graph has the same degree, the graph is called regular. Hence, $K_{n}$ is regular.


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- A polygon is a finite connected graph that is regular of degree 2. $P_{n}=$ a polygon with $n$ vertices.

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- The complete bipartite graph $K_{n, m}$ has $n+m$ vertices $a_{1}, \ldots, a_{n}$, $b_{1}, \ldots, b_{m}$, and all $n m$ pairs $\left(a_{i}, b_{j}\right)$ as edges. An example: $K_{2,3}$ :



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## Matrices Associated with a Graph

- The adjacency matrix $A=A(G)=\left(a_{i j}\right) \in \mathbb{R}^{n \times n}, n=|V|$, for an unweighted graph $G$ consists of the following entries:

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a_{i j}:=\left\{\begin{array}{lc}
1 & \text { if } v_{i} \sim v_{j} ; \\
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- Another typical way to define its entries is based on the similarity of information at $v_{i}$ and $v_{j}$ :

$$
a_{i j}:=\exp \left(-\operatorname{dist}\left(v_{i}, v_{j}\right)^{2} / \epsilon^{2}\right)
$$

where dist is an appropriate distance measure (i.e., metric) defined in $V$, and $\epsilon>0$ is an appropriate scale parameter. This leads to a weighted graph. We will discuss later more about the weighted graphs, how to determine weights, and how to construct a graph from given datasets in general.

## Matrices Associated with a Graph ...

- The degree matrix $D=D(G)=\operatorname{diag}\left(d_{1}, \ldots, d_{n}\right) \in \mathbb{R}^{n \times n}$ is a diagonal matrix whose entries are:

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d_{i}:=d\left(\nu_{i}\right)=d_{\nu_{i}}=\sum_{j=1}^{n} a_{i j}
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p_{i j}:=a_{i j} / d_{i} \quad \text { if } d_{i} \neq 0
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- $A^{\top}=A, P^{\top} \neq P, P=D^{-1} A$.


## Matrices Associated with a Graph ...

- Let $G$ be an undirected graph. Then, we can define several Laplacian matrices of $G$ :

$$
\begin{array}{rlr}
L(G) & :=D-A & \text { Unnormalized } \\
L_{\mathrm{rw}}(G) & :=I_{n}-D^{-1} A=I_{n}-P=D^{-1} L & \text { Normalized } \\
L_{\mathrm{sym}}(G) & :=I_{n}-D^{-\frac{1}{2}} A D^{-\frac{1}{2}}=D^{-\frac{1}{2}} L D^{-\frac{1}{2}} & \text { Symmetrically-Normalized }
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- Graph Laplacians can also be defined for directed graphs, which I want to cover later in this course.


## Functions Defined on a Graph

$$
\begin{aligned}
C(V) & :=\{\text { all functions defined on } V\} \\
C_{0}(V) & :=\{f \in C(V) \mid \operatorname{supp} f \text { is a finite subset of } V\} \\
\operatorname{supp} f & :=\{u \in V \mid f(u) \neq 0\} \\
\mathscr{L}^{2}(V) & :=\{f \in C(V) \mid\|f\|:=\sqrt{\langle f, f\rangle}<\infty\} \\
\langle f, g\rangle & :=\sum_{u \in V} d(u) f(u) g(u) .
\end{aligned}
$$

Lemma

$$
\begin{gathered}
\langle P f, g\rangle=\langle f, P g\rangle \quad \forall f, g \in \mathscr{L}^{2}(V) ; \\
\|P f\| \leq\|f\| \quad \forall f \in \mathscr{L}^{2}(V) .
\end{gathered}
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- Let $f \in \mathscr{L}^{2}(V)$. Then

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L f\left(v_{i}\right)=d_{i} f\left(v_{i}\right)-\sum_{j=1}^{n} a_{i j} f\left(v_{j}\right)=\sum_{j=1}^{n} a_{i j}\left(f\left(v_{i}\right)-f\left(v_{j}\right)\right) .
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L_{\mathrm{rw}} f\left(\nu_{i}\right)=f\left(v_{i}\right)-\sum_{j=1}^{n} p_{i j} f\left(v_{j}\right)=\frac{1}{d_{i}} \sum_{j=1}^{n} a_{i j}\left(f\left(v_{i}\right)-f\left(v_{j}\right)\right) . \\
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- Note that these definitions of the graph Laplacian corresponds to $-\Delta$ in $\mathbb{R}^{d}$, i.e., they are nonnegative operators (or positive semi-definite matrices).


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- A function $f \in C(V)$ is called harmonic if

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- One can also generalize various analytic concepts such as Green's functions, Green's identity, analytic functions, Cauchy-Riemann equations, ..., to the graph setting!


## Derivatives and Green's Identity

Let $C(\boldsymbol{E}):=\{\varphi$ defined on $\boldsymbol{E} \mid \varphi(\bar{e})=-\varphi(e), e \in \boldsymbol{E}\}$. For $f \in C(V)$, define the derivative $d f \in C(\boldsymbol{E})$ of $f$ as

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Theorem (The discrete version of Green's first identity, Dodziuk 1984)

$$
\forall f_{1}, f_{2} \in C_{0}(V),\left\langle d f_{1}, d f_{2}\right\rangle=\left\langle L_{\mathrm{rw}} f_{1}, f_{2}\right\rangle=\sum_{u \in V} L f_{1}(u) f_{2}(u) .
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$$
d f(e)=d f([x, y]):=f(y)-f(x) .
$$

Theorem (The discrete version of Green's first identity, Dodziuk 1984)

$$
\forall f_{1}, f_{2} \in C_{0}(V),\left\langle d f_{1}, d f_{2}\right\rangle=\left\langle L_{\mathrm{rw}} f_{1}, f_{2}\right\rangle=\sum_{u \in V} L f_{1}(u) f_{2}(u) .
$$

## Corollary

$L, L_{\mathrm{rw}}$, and $L_{\mathrm{sym}}$ are nonnegative operators, e.g.,

$$
\left\langle L_{\mathrm{rw}} f, f\right\rangle=\sum_{u \in V} L f(u) f(u)=\langle d f, d f\rangle \geq 0 .
$$

## The Minimum Principle

Theorem (The discrete version of the minimum principle)
Let $f \in C(V)$ be superharmonic at $x \in V$. If $f(x) \leq \min _{y \sim x} f(y)$, then $f(z)=f(x), \forall z \sim x$.

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Proof. From the superharmonicity of $f$ at $x \in V$, we have

$$
\frac{1}{d_{x}} \sum_{y \sim x} a_{x y} f(y) \leq f(x)
$$

On the other hand, from the condition of this theorem, we have

$$
\frac{1}{d_{x}} \sum_{y \sim x} a_{x y} f(y) \geq \frac{1}{d_{x}} \sum_{y \sim x} a_{x y} f(x)=f(x) .
$$

Hence, we must have $\frac{1}{d_{x}} \sum_{y \sim x} a_{x y} f(y)=f(x)$. But this can happen only if $f(z)=f(x), \forall z \sim x$.

## Outline

## (1) Basic Definitions in Graph Theory

(2) Matrices Associated with a Graph
(3) Why Graph Laplacians?

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- Hence, the eigenfunction expansion of data measured at the vertices using the eigenfunctions (in fact, eigenvectors) of a graph Laplacian corresponds to Fourier (or spectral) analysis of the data on that graph.
- They also play a useful role to understand a graph (e.g., the discrete nodal domain theorem useful for grouping vertices; see Bıyıkoğlu, Leydold, \& Stadler, LNM, Springer, 2007)


## Why Graph Laplacians?

- Furthermore, the eigenvalues of $L(G)$ reflect various intrinsic geometric and topological information about the graph including
- diameter (the maximum distance over all pairs of vertices) - mean distance.
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## A Simple Yet Important Example: A Path Graph



The eigenvectors of this matrix are exactly the DCT Type // basis vectors (used for the JPEG standard) while those of the symmetrically-normalized Graph Laplacian matrix $L_{\text {sym }}=D^{-\frac{1}{2}} L D^{-\frac{1}{2}}$ are the DCT Type I basis! (See G. Strang: "The discrete cosine transform," SIAM Review, vol. 41, pp. 135-147, 1999).

- $\lambda_{k}=2-2 \cos (\pi k / n)=4 \sin ^{2}(\pi k / 2 n), k=0: n-1$.
- $\boldsymbol{\phi}_{k}(\ell)=a_{k ; n} \cos \left(\pi k\left(\ell+\frac{1}{2}\right) / n\right), k, \ell=0: n-1 ; a_{k ; n}$ is a const. s.t. $\left\|\boldsymbol{\phi}_{k}\right\|_{2}=1$.
- In this simple case, $\lambda$ (eigenvalue) is a monotonic function w.r.t. the frequency, which is the eigenvalue index $k$. For a general graph, however, the notion of frequency is not well defined.

