

Section 6.1: Inner Products

**Definition.** An **inner product** on a real vector space  $V$  is a function that associates a real number  $\langle \mathbf{u}, \mathbf{v} \rangle$  with each pair of vectors in  $V$  in such a way that the following axioms are satisfied for all vectors  $\mathbf{u}, \mathbf{v}, \mathbf{w}$  in  $V$  and all scalars  $k$ .

1.  $\langle \mathbf{u}, \mathbf{v} \rangle = \langle \mathbf{v}, \mathbf{u} \rangle$  (**symmetry axiom**)
2.  $\langle \mathbf{u} + \mathbf{v}, \mathbf{w} \rangle = \langle \mathbf{u}, \mathbf{w} \rangle + \langle \mathbf{v}, \mathbf{w} \rangle$  (**additivity axiom**)
3.  $\langle k\mathbf{u}, \mathbf{v} \rangle = k\langle \mathbf{u}, \mathbf{v} \rangle$  (**homogeneity axiom**)
4.  $\langle \mathbf{v}, \mathbf{v} \rangle \geq 0$  and  $\langle \mathbf{v}, \mathbf{v} \rangle = 0$  if and only if  $\mathbf{v} = \mathbf{0}$  (**positivity axiom**)

A real vector space with an inner product is called a **real inner product space**.

**Definition.** If  $V$  is a real inner product space, then the **norm** (or **length**) of a vector  $\mathbf{v}$  in  $V$  is defined by  $\|\mathbf{v}\| = \sqrt{\langle \mathbf{v}, \mathbf{v} \rangle}$ . The **distance** between two vectors is defined by  $d(\mathbf{u}, \mathbf{v}) = \|\mathbf{u} - \mathbf{v}\| = \sqrt{\langle \mathbf{u} - \mathbf{v}, \mathbf{u} - \mathbf{v} \rangle}$ . A vector of norm 1 is called a **unit vector**.

**Theorem.** If  $\mathbf{u}$  and  $\mathbf{v}$  are vectors in a real inner product space  $V$ , and if  $k$  is a scalar, then:

- (a)  $\|\mathbf{v}\| \geq 0$  with equality if and only if  $\mathbf{v} = \mathbf{0}$
- (b)  $\|k\mathbf{v}\| = |k| \|\mathbf{v}\|$
- (c)  $d(\mathbf{u}, \mathbf{v}) = d(\mathbf{v}, \mathbf{u})$
- (d)  $d(\mathbf{u}, \mathbf{v}) \geq 0$  with equality if and only if  $\mathbf{u} = \mathbf{v}$

- $\langle \mathbf{u}, \mathbf{v} \rangle = w_1u_1v_1 + w_2u_2v_2 + \dots + w_nu_nv_n$
- $\langle \mathbf{u}, \mathbf{v} \rangle = A\mathbf{u} \cdot A\mathbf{v}$
- $\langle \mathbf{u}, \mathbf{v} \rangle = \mathbf{v}^T A^T A \mathbf{u}$
- $\langle U, V \rangle = \text{tr}(U^T V)$

**Theorem.** If  $\mathbf{u}, \mathbf{v}$ , and  $\mathbf{w}$  are vectors in a real inner product space  $V$ , and if  $k$  is a scalar, then:

- (a)  $\langle \mathbf{0}, \mathbf{v} \rangle = \langle \mathbf{v}, \mathbf{0} \rangle = 0$
- (b)  $\langle \mathbf{u}, \mathbf{v} + \mathbf{w} \rangle = \langle \mathbf{u}, \mathbf{v} \rangle + \langle \mathbf{u}, \mathbf{w} \rangle$
- (c)  $\langle \mathbf{u}, \mathbf{v} - \mathbf{w} \rangle = \langle \mathbf{u}, \mathbf{v} \rangle - \langle \mathbf{u}, \mathbf{w} \rangle$
- (d)  $\langle \mathbf{u} - \mathbf{v}, \mathbf{w} \rangle = \langle \mathbf{u}, \mathbf{w} \rangle - \langle \mathbf{v}, \mathbf{w} \rangle$
- (e)  $k\langle \mathbf{u}, \mathbf{v} \rangle = \langle \mathbf{u}, k\mathbf{v} \rangle$

Section 6.2: Angle and Orthogonality in Inner Product Spaces

**Theorem. Cauchy-Schwarz Inequality:** If  $\mathbf{u}$  and  $\mathbf{v}$  are vectors in a real inner product space  $V$ , then  $|\langle \mathbf{u}, \mathbf{v} \rangle| \leq \|\mathbf{u}\| \|\mathbf{v}\|$ .

- $\langle \mathbf{u}, \mathbf{v} \rangle^2 \leq \langle \mathbf{u}, \mathbf{u} \rangle \langle \mathbf{v}, \mathbf{v} \rangle$
- $\langle \mathbf{u}, \mathbf{v} \rangle^2 \leq \|\mathbf{u}\|^2 \|\mathbf{v}\|^2$
- $\theta = \cos^{-1}[\langle \mathbf{u}, \mathbf{v} \rangle / (\|\mathbf{u}\| \|\mathbf{v}\|)]$

**Theorem.** If  $\mathbf{u}, \mathbf{v}$  and  $\mathbf{w}$  are vectors in a real inner product space  $V$ , and if  $k$  is any scalar, then:

- (a)  $\|\mathbf{u} + \mathbf{v}\| \leq \|\mathbf{u}\| + \|\mathbf{v}\|$  (**Triangle Inequality for Vectors**)
- (b)  $d(\mathbf{u}, \mathbf{v}) \leq d(\mathbf{u}, \mathbf{w}) + d(\mathbf{w}, \mathbf{v})$  (**Triangle Inequality for Distances**)

**Definition.** Two vectors  $\mathbf{u}$  and  $\mathbf{v}$  in an inner product space are called **orthogonal** if  $\langle \mathbf{u}, \mathbf{v} \rangle = 0$ .

**Theorem. Generalized Theorem of Pythagoras.**

If  $\mathbf{u}$  and  $\mathbf{v}$  are orthogonal vectors in an inner product space, then  $\|\mathbf{u} + \mathbf{v}\|^2 = \|\mathbf{u}\|^2 + \|\mathbf{v}\|^2$

**Definition.** If  $W$  is a subspace of an inner product space  $V$ , then the set of all vectors in  $V$  that are orthogonal to every vector in  $W$  is called the **orthogonal complement** of  $W$  and is denoted by the symbol  $W^\perp$ .

**Theorem.** If  $W$  is a subspace of an inner product space  $V$ , then:

- (a)  $W^\perp$  is a subspace of  $V$
- (b)  $W \cap W^\perp = \{\mathbf{0}\}$

**Theorem.** If  $W$  is a subspace of a finite-dimensional inner product space  $V$ , then the orthogonal complement of  $W^\perp$  is  $W$ ; that is,  $(W^\perp)^\perp = W$ .

Section 6.3: Gram-Schmidt Process: QR-Decomposition

**Definition.** A set of two or more vectors in a real inner product space is said to be **orthogonal** if all pairs of distinct vectors in the set are orthogonal. An orthogonal set in which each vector has norm 1 is said to be **orthonormal**.

**Theorem.** If  $S = \{\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_n\}$  is an orthogonal set of nonzero vectors in an inner product space, then  $S$  is linearly independent.

**Theorem.** (a) If  $S = \{\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_n\}$  is an orthogonal basis for an inner product space  $V$ , and if  $\mathbf{u}$  is any vector in  $V$ , then  $\mathbf{u} = [\langle \mathbf{u}, \mathbf{v}_1 \rangle / \|\mathbf{v}_1\|^2] \mathbf{v}_1 + [\langle \mathbf{u}, \mathbf{v}_2 \rangle / \|\mathbf{v}_2\|^2] \mathbf{v}_2 + \dots + [\langle \mathbf{u}, \mathbf{v}_n \rangle / \|\mathbf{v}_n\|^2] \mathbf{v}_n$

(b) If  $S = \{\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_n\}$  is an orthonormal basis for an inner product space  $V$ , and if  $\mathbf{u}$  is any vector in  $V$ , then  $\mathbf{u} = \langle \mathbf{u}, \mathbf{v}_1 \rangle \mathbf{v}_1 + \langle \mathbf{u}, \mathbf{v}_2 \rangle \mathbf{v}_2 + \dots + \langle \mathbf{u}, \mathbf{v}_n \rangle \mathbf{v}_n$

**Theorem. Projection Theorem:** If  $W$  is a finite-dimensional subspace of an inner product space  $V$ , then every vector  $\mathbf{u}$  in  $V$  can be expressed in exactly one way as  $\mathbf{u} = \mathbf{w}_1 + \mathbf{w}_2$  where  $\mathbf{w}_1$  is in  $W$  and  $\mathbf{w}_2$  is in  $W^\perp$ .

•  $\mathbf{u} = \text{proj}_W \mathbf{u} + \text{proj}_{W^\perp} \mathbf{u} = \text{proj}_W \mathbf{u} + (\mathbf{u} - \text{proj}_W \mathbf{u})$

**Theorem.** Let  $W$  be a finite-dimensional subspace of an inner product space  $V$ .

(a) If  $\{\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_r\}$  is an orthogonal basis for  $W$ , and  $\mathbf{u}$  is any vector in  $V$ , then  $\text{proj}_W \mathbf{u} = [\langle \mathbf{u}, \mathbf{v}_1 \rangle / \|\mathbf{v}_1\|^2] \mathbf{v}_1 + [\langle \mathbf{u}, \mathbf{v}_2 \rangle / \|\mathbf{v}_2\|^2] \mathbf{v}_2 + \dots + [\langle \mathbf{u}, \mathbf{v}_r \rangle / \|\mathbf{v}_r\|^2] \mathbf{v}_r$ .

(b) If  $\{\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_r\}$  is an orthonormal basis for  $W$ , and  $\mathbf{u}$  is any vector in  $V$ , then  $\text{proj}_W \mathbf{u} = \langle \mathbf{u}, \mathbf{v}_1 \rangle \mathbf{v}_1 + \langle \mathbf{u}, \mathbf{v}_2 \rangle \mathbf{v}_2 + \dots + \langle \mathbf{u}, \mathbf{v}_r \rangle \mathbf{v}_r$ .

**Theorem.** Every nonzero finite-dimensional inner product space has an orthonormal basis.

• **The Gram-Schmidt Process:** To convert a basis  $\{\mathbf{u}_1, \mathbf{u}_2, \dots, \mathbf{u}_r\}$  into an orthogonal basis  $\{\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_r\}$ , perform the following computations:

**Step 1:**  $\mathbf{v}_1 = \mathbf{u}_1$

**Step 2:**  $\mathbf{v}_2 = \mathbf{u}_2 - [\langle \mathbf{u}_2, \mathbf{v}_1 \rangle / \|\mathbf{v}_1\|^2] \mathbf{v}_1$

**Step 3:**  $\mathbf{v}_3 = \mathbf{u}_3 - [\langle \mathbf{u}_3, \mathbf{v}_1 \rangle / \|\mathbf{v}_1\|^2] \mathbf{v}_1 - [\langle \mathbf{u}_3, \mathbf{v}_2 \rangle / \|\mathbf{v}_2\|^2] \mathbf{v}_2$

**Step 4:**  $\mathbf{v}_4 = \mathbf{u}_4 - [\langle \mathbf{u}_4, \mathbf{v}_1 \rangle / \|\mathbf{v}_1\|^2] \mathbf{v}_1 - [\langle \mathbf{u}_4, \mathbf{v}_2 \rangle / \|\mathbf{v}_2\|^2] \mathbf{v}_2 - [\langle \mathbf{u}_4, \mathbf{v}_3 \rangle / \|\mathbf{v}_3\|^2] \mathbf{v}_3$

⋮

(continue for  $r$  steps)

**Optional Step:** To convert the orthogonal basis into an orthonormal basis  $\{\mathbf{q}_1, \mathbf{q}_2, \dots, \mathbf{q}_r\}$ , normalize the orthogonal basis vectors.

**Theorem.** If  $W$  is a finite-dimensional inner product space, then:

(a) Every orthogonal set of nonzero vectors in  $W$  can be enlarged to an orthogonal basis for  $W$ .

(b) Every orthonormal set in  $W$  can be enlarged to an orthonormal basis for  $W$ .

• **Problem:** If  $A$  is an  $m \times n$  matrix with linearly independent column vectors, and if  $Q$  is the matrix that results by applying the Gram-Schmidt process to the column vectors of  $A$ , what relationship, if any, exists between  $A$  and  $Q$ ?

**Theorem. QR-Decomposition:** If  $A$  is an  $m \times n$  matrix with linearly independent column vectors, then  $A$  can be factored as  $A = QR$  where  $Q$  is an  $m \times n$  matrix with orthonormal column vectors, and  $R$  is an  $n \times n$  invertible upper triangular matrix.

#### Section 6.4: Best Approximation; Least Squares

• **Least Squares Problem:** Given a linear system  $A\mathbf{x} = \mathbf{b}$  of  $m$  equations in  $n$  unknowns, find a vector  $\mathbf{x}$  that minimizes  $\|\mathbf{b} - A\mathbf{x}\|$  with respect to the Euclidean inner product on  $\mathbf{R}^m$ . We call such an  $\mathbf{x}$  a **least squares solution** of the system, we call  $\mathbf{b} - A\mathbf{x}$  the **least squares error vector**, and we call  $\|\mathbf{b} - A\mathbf{x}\|$  the **least squares error**.

**Theorem. Best Approximation Theorem:** If  $W$  is a finite-dimensional subspace of an inner product space  $V$ , and if  $\mathbf{b}$  is a vector in  $V$ , then  $\text{proj}_W \mathbf{b}$  is the **best approximation** to  $\mathbf{b}$  from  $W$  in the sense that  $\|\mathbf{b} - \text{proj}_W \mathbf{b}\| < \|\mathbf{b} - \mathbf{w}\|$  for every vector  $\mathbf{w}$  in  $W$  that is different from  $\text{proj}_W \mathbf{b}$ .

**Theorem.** For every linear system  $A\mathbf{x} = \mathbf{b}$ , the associated normal system  $A^T A \mathbf{x} = A^T \mathbf{b}$  is consistent, and all solutions of the normal system are least squares solutions of  $A\mathbf{x} = \mathbf{b}$ . Moreover, if  $W$  is the column space of  $A$ , and  $\mathbf{x}$  is any least squares solution of  $A\mathbf{x} = \mathbf{b}$ , then the orthogonal projection of  $\mathbf{b}$  on  $W$  is  $\text{proj}_W \mathbf{b} = A\mathbf{x}$ .

**Theorem.** If  $A$  is an  $m \times n$  matrix, then the following are equivalent:

(a)  $A$  has linearly independent column vectors.

(b)  $A^T A$  is invertible.

**Theorem.** If  $A$  is an  $m \times n$  matrix with linearly independent column vectors, then for every  $m \times 1$  matrix  $\mathbf{b}$ , the linear system  $A\mathbf{x} = \mathbf{b}$  has a unique least squares solution. This solution is given by  $\mathbf{x} = (A^T A)^{-1} A^T \mathbf{b}$ . Moreover, if  $W$  is the column space of  $A$ , then the orthogonal projection of  $\mathbf{b}$  on  $W$  is  $\text{proj}_W \mathbf{b} = A\mathbf{x} = A(A^T A)^{-1} A^T \mathbf{b}$ .

**Theorem.** If  $A$  is an  $m \times n$  matrix with linearly independent column vectors, and if  $A = QR$  is a QR-decomposition of  $A$ , then for each  $\mathbf{b}$  in  $\mathbf{R}^m$  the system  $A\mathbf{x} = \mathbf{b}$  has a unique least squares solution given by  $\mathbf{x} = R^{-1} Q^T \mathbf{b}$ .

**Definition.** If  $W$  is a subspace of  $\mathbf{R}^m$ , then the transformation  $P: \mathbf{R}^m \rightarrow W$  that maps each vector  $\mathbf{x}$  in  $\mathbf{R}^m$  into its orthogonal projection  $\text{proj}_W \mathbf{x}$  in  $W$  is called the **orthogonal projection of  $\mathbf{R}^m$  on  $W$** .

•  $[P] = A(A^T A)^{-1} A^T$

**Theorem. Equivalent Statements:** If  $A$  is an  $n \times n$  matrix, then the following statements are equivalent:

(a)  $A$  is invertible

(b)  $A\mathbf{x} = \mathbf{0}$  has only the trivial solution

(c) the reduced row-echelon form of  $A$  is  $I_n$

(d)  $A$  is expressible as a product of elementary matrices

(e)  $A\mathbf{x} = \mathbf{b}$  is consistent for every  $n \times 1$  matrix  $\mathbf{b}$

(f)  $A\mathbf{x} = \mathbf{b}$  has exactly one solution for every  $n \times 1$  matrix  $\mathbf{b}$

(g)  $\det(A) \neq 0$

(h) The column vectors of  $A$  are linearly independent.

- (i) The row vectors of  $A$  are linearly independent.
- (j) The column vectors of  $A$  span  $\mathbf{R}^n$ .
- (k) The row vectors of  $A$  span  $\mathbf{R}^n$ .
- (l) The column vectors of  $A$  form a basis for  $\mathbf{R}^n$ .
- (m) The row vectors of  $A$  form a basis for  $\mathbf{R}^n$ .
- (n)  $A$  has rank  $n$
- (o)  $A$  has nullity 0
- (p) The orthogonal complement of the null space of  $A$  is  $\mathbf{R}^n$ .
- (q) The orthogonal complement of the row space of  $A$  is  $\mathbf{0}$ .
- (r) The range of  $T_A$  is  $\mathbf{R}^n$
- (s)  $T_A$  is one-to-one.
- (t)  $\lambda = 0$  is not an eigenvalue of  $A$ .
- (u)  $A^T A$  is invertible