

$$U(n) = SU(n) \times U(1)$$

↑
homeomorphic as top-spaces

Not isomorphic as groups!!

$$SU(n) \longrightarrow U(n) \xrightarrow{\det} U(1)$$

↑ Ker(det) ↙ group homomorphism

have a section $\sigma: U(1) \rightarrow U(n)$

$$\alpha \longmapsto \begin{pmatrix} \alpha & & 0 \\ & \ddots & \\ 0 & & 1 \end{pmatrix}$$

But this section does not commute with $SU(n)$!

So: we have a continuous map

$$SU(n) \times U(1) : (A, \alpha) \longrightarrow A \begin{pmatrix} \alpha & & 0 \\ & \ddots & \\ 0 & & 1 \end{pmatrix}$$

this is a homeomorphism

$$A = B \cdot \begin{pmatrix} \det B^{-1} & & 0 \\ & \ddots & \\ 0 & & 1 \end{pmatrix} \longleftarrow B$$

$$\alpha = \det B$$

Not a group homomorphism since A does not commute with $\begin{pmatrix} \alpha & & 0 \\ & \ddots & \\ 0 & & 1 \end{pmatrix}$

Exercise Prove that $U(n)$ and $SU(n) \times U(1)$ are not isomorphic as groups. Hint: compute $Z(U(n)) \leftarrow$ center
 $Z(SU(n) \times U(1)) = Z(SU(n)) \times U(1)$

Recall important lemma:

$\lambda_i \neq \lambda_j; \begin{pmatrix} \lambda_i & & 0 \\ & \ddots & \\ 0 & & \lambda_j \end{pmatrix}$ commutes with $M \Rightarrow M$ is diagonal.

anything in $Z(U(n))$ or $Z(SU(n))$ is diagonal

$$\text{check } Z(U(n)) = \left\{ \begin{pmatrix} \lambda & & 0 \\ & \ddots & \\ 0 & & 1 \end{pmatrix} : |\lambda| = 1 \right\} = U(1)$$

check $Z(U(n)) = \left\{ \begin{pmatrix} \lambda & & 0 \\ & \ddots & \\ 0 & & \lambda \end{pmatrix}, |\lambda| = 1 \right\} = U(1)$

$Z(SO(n)) = \left\{ \begin{pmatrix} \lambda & & 0 \\ & \ddots & \\ 0 & & \lambda \end{pmatrix}, |\lambda| = 1, \lambda^n = 1 \right\} = \left\{ \begin{matrix} n\text{-th} \\ \text{roots of } 1 \end{matrix} \right\}$

Examples of Lie algebras

① $G = GL_n$ $Lie(G) = gl_n = \{ \text{all } n \times n \text{ matrices} \}$

$\dim gl_n(\mathbb{R}) = n^2$ $\dim_{\mathbb{R}} gl_n(\mathbb{C}) = 2n^2$

② $G = SL_n$ $Lie(G) = sl_n = \{ X : \text{Tr } X = 0 \}$

$\dim sl_n(\mathbb{R}) = n^2 - 1$

③ $G = O(n)$ $Lie(G) = \left\{ \begin{matrix} X : X + X^T = 0 \\ \text{skew-symmetric} \\ \text{matrices} \end{matrix} \right\}$ see last Friday lec.

$\dim = \frac{n^2 - n}{2}$

$$\begin{pmatrix} 0 & & & \\ & \ddots & & \\ & & x_{ij} & \\ & & -x_{ij} & \\ & & & \ddots & \\ & & & & 0 \end{pmatrix}$$

$G = SO(n)$

$Lie(G) = \left\{ \begin{matrix} X : X + X^T = 0 \\ \text{Tr}(X) = 0 \end{matrix} \right\}$

$O(n) = SO(n)$.

holds automatically since 0's on diagonal.

Ex $SO(3) = \begin{pmatrix} 0 & x & y \\ -x & 0 & z \\ -y & -z & 0 \end{pmatrix}$ $\dim = 3$

basis $\begin{pmatrix} 0 & 1 & 0 \\ x & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}, \begin{pmatrix} 0 & 0 & 1 \\ 0 & 0 & 0 \\ -1 & 0 & 0 \end{pmatrix}, \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & -1 & 0 \end{pmatrix}$.

HW4: compute $[,]$ in this basis.

④ $G = U(n)$ $Lie(G) = u(n) = \{ X : X^* + X = 0 \}$

④ $G = U(n)$ $\text{Lie}(G) = u(n) = \left\{ X : \begin{array}{l} X^* + X = 0 \\ \text{or} \\ X^T + X = 0 \end{array} \right\}$ "Hermitian skew symmetric"

$$\begin{pmatrix} ia_1 & & & \\ & ia_2 & & \\ & & \ddots & \\ -\bar{x}_{ij} & & & \\ & & & ia_n \end{pmatrix}$$

On diagonal, $\bar{x} + x = 0$
 $x = ia \quad a \in \mathbb{R}$

Upper-triangular part determines the lower-triangular one.

$\dim = n + d \cdot \frac{n^2 - n}{2} = n^2$
 (diagonal) (upper-trian)

$\text{Lie}(SU(n)) = su(n) = \left\{ X : \begin{array}{l} X^* + X = 0 \\ \text{Tr}(X) = 0 \end{array} \right\}$
 additional condition $a_1 + \dots + a_n = 0$

$\dim su(n) = n^2 - 1$

⑤ $T =$ (abelian) group of diagonal invertible matrices = $\begin{pmatrix} d_1 & & \\ & \ddots & \\ 0 & & d_n \end{pmatrix}$
 algebraic torus $d_i \neq 0$ for all i

Over $\mathbb{R} : (\mathbb{R}^*)^n$

Over $\mathbb{C} : (\mathbb{C}^*)^n \supset U(1)^n = (\mathbb{S}^1)^n$ n -dim torus.

$\text{Lie}(T) = \{ \text{all diagonal matrices} \}$

$\dim = n$

$X, Y \in \text{Lie}(T) \Rightarrow XY - YX = 0$

abelian Lie algebra $[,] = 0$.

Know $A(t) = e^{tX}$ diagonal for all t
 $\frac{d}{dt} A(t)$ diagonal $\Rightarrow X$ diagonal.

⑥ $B =$ (Borel) subgroup of upper-triangular invertible matrices = $\begin{pmatrix} d_1 & & * \\ & \ddots & \\ 0 & & d_n \end{pmatrix}$

① $\mathbb{B} = (\text{Block})$ subgroup of upper-triangular invertible matrices $\begin{pmatrix} * & & \\ 0 & \ddots & \\ & & d_n \end{pmatrix}$

$$\text{Lie}(\mathbb{B}) = \begin{pmatrix} x_1 & & * \\ & \ddots & \\ 0 & & x_n \end{pmatrix} \quad \dim = n + \frac{n^2 - n}{2} = \frac{n^2 + n}{2}$$

Thm $G = \text{matrix Lie group} \Rightarrow G$ is a smooth manifold.

$$\dim G = \dim \text{Lie}(G) \quad \text{Lie}(G) \simeq \mathbb{T}_{\mathbb{I}} G$$

as a manifold
as a vector space

identity matrix

Proof: Friday.

How to prove that $O(n) = \{A: A^T A = I\}$ is a smooth mfd?

Recall \mathbb{R}^N , equations $F_1(x_1, \dots, x_N) = \dots = F_k(x_1, \dots, x_N) = 0$

Implicit Function Theorem: $J = \begin{pmatrix} \frac{\partial F_1}{\partial x_j} \\ \vdots \\ \frac{\partial F_k}{\partial x_j} \end{pmatrix}$ Jacobi matrix

If $\text{Rank}(J) = k$ for all points of

$$M = \{F_1 = \dots = F_k = 0\}$$

then M is a smooth manifold of $\dim = N - k$.

$$\textcircled{1} F(x + \delta x) = F(x) + \sum \frac{\partial F}{\partial x_i} \cdot \delta x_i + \dots \quad \left\{ \right.$$

Can use it to get all partial derivatives.

Eqn: $A^T A = I$, replace A by $A + \delta A$

$$(A + \delta A)^T \cdot (A + \delta A) = A^T A + \underbrace{A^T \cdot \delta A + (\delta A)^T A}_{J \cdot \delta A} + \text{higher order}$$

$J = \text{Jacobi matrix}$.

$J = \text{Jacobi matrix}$. $v \cdot \delta A$

$$J \cdot \delta A = 0 \iff A^T \delta A + (\delta A)^T A = 0. \quad (**)$$

$N = n^2$ ambient space $k = \# \text{ equations} = \frac{n^2 + n}{2}$

Want to prove $\text{Rank}(J) = \frac{n^2 + n}{2}$

$$\iff \dim \{ \delta A : J \cdot \delta A = 0 \} = N - k = \frac{n^2 - n}{2}.$$

space of solutions of (**)
for fixed $A \in O(n)$.

② Solve (**) at $A = I$ first!

$$\delta A + (\delta A)^T = 0 = \text{Lie}(O(n)), \dim = \frac{n^2 - n}{2} \text{ correct.}$$

$\Rightarrow \text{Rank}(J)$ at $A = I$ is maximal

by Implicit Function Thm we can choose a neighborhood of $I \simeq$ open subset of $\mathbb{R}^{\frac{n^2 - n}{2}}$.

Key idea: To get a neighborhood of A , translate the neighborhood of I by (left) multiplication by A .