

Root systems

\mathfrak{g} = Lie algebra

① Killing form on \mathfrak{g}
 $(X, Y) = \text{Tr}(\text{ad}_X \text{ad}_Y)$

Recall:
 adjoint representation
 $\text{ad}_X: \mathfrak{g} \rightarrow \mathfrak{g}$
 $\text{ad}_X(Z) = [X, Z]$

Fact: For $\mathfrak{sl}_n, \mathfrak{so}_n, \mathfrak{sp}_n$ etc
 $(X, Y) = \text{factor} \cdot \text{Tr}(XY)$

Key definition \mathfrak{g} is semisimple if $(,)$ is nondegenerate

Fact If \mathfrak{g} is semisimple then the center of \mathfrak{g} is trivial (center = $\{X \text{ such that } [X, Z] = 0 \text{ for all } Z\}$)

Proof If X is in the center of \mathfrak{g} then $\text{ad}_X = 0$
 $\Rightarrow (X, Y) = 0$ for all Y , contradiction \square

We will identify $\mathfrak{g} \cong \mathfrak{g}^*$ via the Killing form.

Ex \mathfrak{sl}_2 $E = \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}$ $F = \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix}$ $H = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$

$(E, F) = (F, E) = 1$ $(H, H) = 2$ and all other $(,) = 0$
 \parallel \parallel
 $\text{Tr}(EF)$ $\text{Tr}(H^2)$

Goal: understand the structure of semisimple Lie algebras.

② Key example: \mathfrak{sl}_3

Basis: $H_1 = \begin{pmatrix} 1 & & \\ & -1 & \\ & & 0 \end{pmatrix}$ $H_2 = \begin{pmatrix} 0 & & \\ & 1 & \\ & & -1 \end{pmatrix} \leftarrow \text{diagonal}$

ans: $H_1 = \begin{pmatrix} -1 & \\ & 0 \end{pmatrix}$ $H_2 = \begin{pmatrix} & 1 \\ & -1 \end{pmatrix}$ ← diagonal

$E_1 = \begin{pmatrix} 0 & 1 \\ & 0 \end{pmatrix}$ $E_2 = \begin{pmatrix} & 0 & 1 \\ & 0 & 0 \end{pmatrix}$ $E_{12} = \begin{pmatrix} 0 & 0 & 1 \\ & 0 & 0 \\ & & 0 \end{pmatrix} = [E_1, E_2]$ ← upper triangular

$F_1 = \begin{pmatrix} 0 & & \\ 1 & 0 & \\ & & 0 \end{pmatrix}$ $F_2 = \begin{pmatrix} 0 & & \\ & 0 & \\ & & 1 & 0 \end{pmatrix}$ $F_{12} = \begin{pmatrix} 0 & & \\ & 0 & 0 \\ 1 & 0 & 0 \end{pmatrix} = -[F_1, F_2]$ ← lower triangular

Some relations

- $[H_1, H_2] = 0$, so H_1, H_2 span a commutative 2d Lie subalgebra (Cartan subalgebra)

• $[H_1, E_1] = 2E_1$ $[H_1, E_2] = -E_2$ (check it!)

$[H_2, E_1] = -E_1$ $[H_2, E_2] = 2E_2$

- H_1, E_1, F_1 span a copy of \mathfrak{sl}_2 inside \mathfrak{sl}_3 !

H_2, E_2, F_2 span a copy of \mathfrak{sl}_2

$H_1 + H_2 = \begin{pmatrix} 1 & & \\ & 0 & \\ & & -1 \end{pmatrix}$, E_{12}, F_{12} span a copy of \mathfrak{sl}_2 .

③ Def of = semisimple Lie algebra.

A Cartan subalgebra $\mathfrak{h} \subset \mathfrak{g}$ is a maximal subspace such that:

- $[X_1, X_2] = 0$ for $X_1, X_2 \in \mathfrak{h}$ (commutative)

- ad_X is diagonalizable on \mathfrak{g} for

all $x \in \mathfrak{h}$.

Fact Cartan subalgebras exist.

$$\underline{\text{Ex}} \quad \mathfrak{g} = \mathfrak{sl}_2 \quad \mathfrak{h} = \langle H \rangle \quad \begin{aligned} \text{ad}_H(E) &= [H, E] = 2E \\ \text{ad}_H(H) &= 0 \quad \text{ad}_H(F) = [H, F] = -2F \end{aligned}$$

So E, F, H are eigenvectors for ad_H .
and ad_H is diagonalizable.

$$\underline{\text{Ex}} \quad \mathfrak{g} = \mathfrak{sl}_3 \quad \mathfrak{h} = \langle H_1, H_2 \rangle$$

$$\text{ad}_{H_1}(H_1) = \text{ad}_{H_1}(H_2) = 0$$

$$\text{ad}_{H_1}(E_1) = 2E_1, \quad \text{ad}_{H_1}(E_2) = [H_1, E_2] = -E_2$$

$$\text{ad}_{H_1}(E_{12}) = E_{12}$$

$$\text{ad}_{H_1}(F_1) = -2F_1, \quad \text{ad}_{H_1}(F_2) = F_2$$

$$\text{ad}_{H_1}(F_{12}) = -F_{12}.$$

So: ad_{H_1} is diagonalizable in our basis!

Similarly ad_{H_2} is diagonalizable in our basis.

④ Very important lemma.

Suppose A_1, \dots, A_k are diagonalizable operators
in a f. dim vector space V .

If $[A_i, A_j] = 0$ for all i, j then there
is a common eigenbasis in V for all A_i .

Basis v_1, \dots, v_n , $A_j v_m = \lambda_{jm} v_m$ for all j, m

Proof: First, diagonalize A_1 , let λ be some eigenvalue for A_1 . Consider the eigenspace $V_\lambda = \{v : A_1 v = \lambda v\}$. We claim that $A_2 \dots A_k$ preserve V_λ . Indeed, if $v \in V_\lambda$, $A_1(A_j v) = A_j(A_1 v) = A_j(\lambda v) = \lambda A_j v$ so $A_j v$ is also in V_λ . Then we can diagonalize A_2 on V_λ , and continue by induction. \square

⑤ As a consequence of Very Important Lemma, we can diagonalize ad_X for all $X \in \mathfrak{h}$ simultaneously.

Ex \mathfrak{sl}_3 $[H_1, E_1] = 2E_1$, $[H_2, E_1] = -E_1$

$X \in \mathfrak{h}$ $X = aH_1 + bH_2$ for some a, b

$$\text{ad}_X(E_1) = [X, E_1] = [aH_1 + bH_2, E_1] = a \cdot 2E_1 + b(-E_1) = (2a - b)E_1.$$

So E_1 is an eigenvector for any element X in the Cartan subalgebra, but the eigenvalue depends on X .

In fact, the eigenvalue is a linear functional (for fixed eigenvector) on \mathfrak{h} !

Observe $\boxed{\text{ad}_X(E_1) = (X, H_1) E_1}$ so in this case the eigenvalue of X is given by (X, H_1) .

Proof Both sides are linear in X , so need to check for $X = H_1$, or $X = H_2$.

$$\text{ad}_{H_1}(E_1) = 2E_1 \quad \text{ad}_{H_2}(E_1) = -E_1$$

$$(H_1, H_1) = 2 \quad (H_1, H_2) = -1.$$

Similarly, $\text{ad}_X(E_2) = (X, H_2)E_2$

$$\text{ad}_X(E_{12}) = (X, H_1 + H_2)E_{12}$$

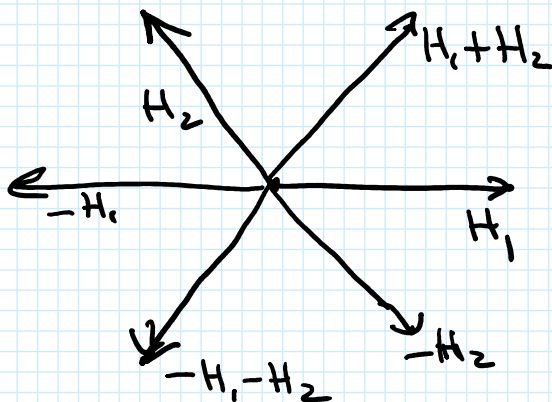
Picture: draw $\eta = \text{Span}(H_1, H_2)$ as 2d vector space w. Killing form

length $(H_1) = \sqrt{2}$ since $(H_1, H_1) = 2$

length (H_2)

$$(H_1, H_2) = \sqrt{2} \cdot \sqrt{2} \cdot \cos(\varphi) = -1$$

$$\cos(\varphi) = -\frac{1}{2} \quad \varphi = \frac{2\pi}{3}$$



Claim By the above, this picture contains all the information about ad_X for X in Cartan subalgebra.