

HW#3 G = matrix Lie group

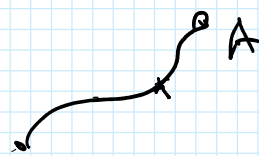
G_0 = (path) connected component of I

$A \in G_0 \Rightarrow$ there is a continuous path

$A(t)$ such that $\bullet A(t) \in G$ for all t

$\bullet A(0) = I$

$\bullet A(1) = A$



$B \in G_0 \Rightarrow$ path $B(t) \in G$ for all t

$B(0) = I, B(1) = B$

$A(t)B(t)$ = another path in G

$A(0)B(0) = I \cdot I = I$

$A(1)B(1) = AB$

} AB is connected to I by a path, $AB \in G_0$

Matrix exponential

Def X = any $n \times n$ matrix (real or complex)

$$e^X = I + X + \frac{X^2}{2!} + \frac{X^3}{3!} + \dots = \sum_{n=0}^{\infty} \frac{X^n}{n!}$$

Thm This is well defined, series converges for all X .

Proof: We define a norm on matrices (Hilbert-Schmidt)

$$\|A\| = \sqrt{\sum_{i,j} |a_{ij}|^2} = \sqrt{\text{Tr}(A^*A)}$$

One can check that $\|AB\| \leq \|A\| \cdot \|B\|$
 $\|A+B\| \leq \|A\| + \|B\|$

In particular, $\|X^n\| \leq \|X\|^n$

Since $\sum_{k=0}^{\infty} \frac{\|x\|^k}{k!}$ converges for all $\|x\|$,
 the series $\sum_{k=0}^{\infty} \frac{X^k}{k!}$ converges absolutely wrt
 this norm.

Note Converges uniformly on compact $\|X\| \leq K$
 So e^X is a continuous (and smooth) function of X .

Properties 1) $e^0 = I$

2) If X and Y commute then

$$e^{X+Y} = e^X e^Y$$

(false if X, Y do not commute)

3) e^X is invertible, $(e^X)^{-1} = e^{-X}$.

Proof: ① Clear

② Assume $XY = YX$, then we claim
 that $(X+Y)^n = \sum_{a=0}^n \binom{n}{a} X^a Y^{n-a}$

$(X+Y) \cdots (X+Y)$ and expand

$$e^{X+Y} = \sum_{n=0}^{\infty} \frac{(X+Y)^n}{n!} = \sum_{n=0}^{\infty} \sum_{a=0}^n \frac{1}{n!} \cdot \frac{n!}{a!(n-a)!} X^a Y^{n-a} =$$

$$e^{x+y} = \sum_{n=0}^{\infty} \frac{(x+y)^n}{n!} = \sum_{n=0}^{\infty} \sum_{a=0}^n \binom{n}{a} \frac{x^a y^{n-a}}{n!} = \sum_{a=0}^{\infty} \frac{x^a}{a!} \sum_{b=0}^{\infty} \frac{y^b}{b!}$$

③ $e^x \cdot e^{-x} = e^{x-x} = e^0 = I$ since $X, -X$ commute.

How to compute e^X in practice?

① Change a basis to transform X into Jordan normal form:

$$CXC^{-1} = \begin{pmatrix} \lambda_1 & & & 0 \\ & \ddots & & \\ & & \lambda_r & \\ 0 & & & \ddots \\ & & & & \lambda_s \end{pmatrix}$$

② If X is diagonal

$$X = \begin{pmatrix} \lambda_1 & & 0 \\ & \ddots & \\ 0 & & \lambda_n \end{pmatrix}$$

$$e^X = \begin{pmatrix} e^{\lambda_1} & & 0 \\ & \ddots & \\ 0 & & e^{\lambda_n} \end{pmatrix}$$

$$X^k = \begin{pmatrix} \lambda_1^k & & 0 \\ & \ddots & \\ 0 & & \lambda_n^k \end{pmatrix}$$

If X diagonalizable: $CXC^{-1} = \begin{pmatrix} \lambda_1 & & 0 \\ & \ddots & \\ 0 & & \lambda_n \end{pmatrix}$

$$X = C \begin{pmatrix} \lambda_1 & & 0 \\ & \ddots & \\ 0 & & \lambda_n \end{pmatrix} C^{-1}$$

$$\rightarrow e^X = C e^{\Lambda} C^{-1}$$

$$e^X = C^{-1} e^{\begin{pmatrix} \lambda_1 & & \\ & \ddots & \\ 0 & & \lambda_n \end{pmatrix}} C = C^{-1} \begin{pmatrix} e^{\lambda_1} & & \\ & \ddots & \\ 0 & & e^{\lambda_n} \end{pmatrix} C$$

③ How to compute exp of Jordan block?

$$X = \begin{pmatrix} \lambda & 1 & & \\ & \ddots & \ddots & \\ & & \ddots & 1 \\ 0 & & & \lambda \end{pmatrix} = \lambda \cdot I + N, \text{ where } N = \begin{pmatrix} 0 & 1 & & \\ & \ddots & \ddots & \\ & & \ddots & 1 \\ 0 & & & 0 \end{pmatrix}$$

Since $\lambda \cdot I$ and N commute, we can write

$$e^X = e^{\lambda \cdot I} \cdot e^N = e^\lambda \cdot e^N$$

$$N^2 = \begin{pmatrix} 0 & 0 & 1 & \\ & \ddots & \ddots & \\ & & \ddots & 1 \\ 0 & & & 0 \end{pmatrix}$$

$$N^3 = \begin{pmatrix} 0 & 0 & 0 & 1 \\ & \ddots & \ddots & \\ & & \ddots & 1 \\ 0 & & & 0 \end{pmatrix}$$

need to compute this

and so on

and $N^n = 0$

$$e^N = I + N + \frac{N^2}{2!} + \dots + \frac{N^{n-1}}{(n-1)!} = \begin{pmatrix} 1 & 1 & \frac{1}{2!} & \frac{1}{3!} & \dots \\ & \ddots & \ddots & \ddots & \\ & & \ddots & 1 & \\ 0 & & & & 1 \end{pmatrix}$$

Conclusion

$$\exp \begin{pmatrix} \lambda & 1 & & \\ & \ddots & \ddots & \\ & & \ddots & 1 \\ 0 & & & \lambda \end{pmatrix} = \begin{pmatrix} e^\lambda & e^\lambda & \frac{e^\lambda}{2!} & \dots & \frac{e^\lambda}{(n-1)!} \\ & e^\lambda & \frac{e^\lambda}{2!} & \dots & \frac{e^\lambda}{(n-2)!} \\ & & e^\lambda & \dots & \frac{e^\lambda}{(n-3)!} \\ & & & \ddots & e^\lambda \\ & & & & e^\lambda \end{pmatrix}$$

If we have several Jordan blocks we

If we have several Jordan blocks, we do it for each of them
 And conjugate back to the original basis.

Fact $\det(e^X) = e^{\text{tr}(X)}$

Proof Change the basis,

$$X = \begin{pmatrix} \lambda_1 & & * \\ & \ddots & \\ 0 & & \lambda_n \end{pmatrix} \quad e^X = \begin{pmatrix} e^{\lambda_1} & & * \\ & \ddots & \\ 0 & & e^{\lambda_n} \end{pmatrix}$$

$$\det e^X = e^{\lambda_1} \dots e^{\lambda_n} = e^{\lambda_1 + \dots + \lambda_n} = e^{\text{tr}(X)}$$

Cor If X is a real matrix then $\det(e^X) > 0$!

Ex: $X = (it)$ $e^X = (e^{it}) = (\cos t + i \sin t)$
 $t \in \mathbb{R}$

$$X = \begin{pmatrix} 0 & -t \\ t & 0 \end{pmatrix} = t \cdot \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix}$$

Exercise $e^X = \begin{pmatrix} \cos t & -\sin t \\ \sin t & \cos t \end{pmatrix}$
 (HW)

Consider the family of matrices

$$\Lambda(t) = e^{t \cdot X} \quad X = \text{fixed matrix } t \in \mathbb{R}$$

$$A(t) = e^{t \cdot X}, \quad X = \text{fixed matrix } t \in \mathbb{R}$$

Facts ① $A(t_1 + t_2) = A(t_1) \cdot A(t_2)$

$$A(-t) = A(t)^{-1}$$

$$A(0) = I$$

Proof $t_1 X$ and $t_2 X$ commute $\Rightarrow e^{(t_1 X + t_2 X)} = e^{t_1 X} e^{t_2 X}$
 \parallel
 $e^{(t_1 + t_2) X}$

② $\{A(t) : t \in \mathbb{R}\}$ is a subgroup of $GL(n)$!

It's called a one-parameter subgroup generated by X .

Warning! This subgroup is NOT necessarily closed, so not necessarily a matrix Lie group.

③ $\frac{d}{dt} A(t) = X A(t) = A(t) \cdot X$

$$A(t) = e^{tX} = \sum_{n=0}^{\infty} \frac{(tX)^n}{n!} = \sum_{n=0}^{\infty} \frac{t^n X^n}{n!}$$

We can differentiate this term by term:

$$\frac{d}{dt} A(t) = \sum_{n=0}^{\infty} \frac{n t^{n-1} X^n}{n!} = X \sum_{n=0}^{\infty} \frac{t^{n-1} X^{n-1}}{(n-1)!} = X e^{tX} = X A(t)$$