

MAT 22A Problem Set 6 Solutions

1. Find the complete solution to

$$\begin{bmatrix} 1 & 3 & 1 & 2 \\ 2 & 6 & 4 & 8 \\ 0 & 0 & 2 & 4 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \\ t \end{bmatrix} = \begin{bmatrix} -3 \\ -4 \\ 2 \end{bmatrix}.$$

Write the complete solution as  $\mathbf{x} = \mathbf{x}_p + \mathbf{x}_n$ .

*Solution.*

First we row reduce the augmented matrix

$$\begin{array}{c} \left[ \begin{array}{cccc|c} 1 & 3 & 1 & 2 & -3 \\ 2 & 6 & 4 & 8 & -4 \\ 0 & 0 & 2 & 4 & 2 \end{array} \right] \begin{array}{l} r_2 - 2r_1 \\ \end{array} = \left[ \begin{array}{cccc|c} 1 & 3 & 1 & 2 & -3 \\ 0 & 0 & 2 & 4 & 2 \\ 0 & 0 & 2 & 4 & 2 \end{array} \right] \begin{array}{l} r_1 - \frac{1}{2}r_2 \\ r_3 - r_2 \end{array} \\ = \left[ \begin{array}{cccc|c} 1 & 3 & 0 & 0 & -4 \\ 0 & 0 & 2 & 4 & 2 \\ 0 & 0 & 0 & 0 & 0 \end{array} \right] \frac{1}{2} \\ = \left[ \begin{array}{cccc|c} 1 & 3 & 0 & 0 & -4 \\ 0 & 0 & 1 & 2 & 1 \\ 0 & 0 & 0 & 0 & 0 \end{array} \right]. \end{array}$$

We see that  $\mathbf{x}_p = \begin{bmatrix} -4 \\ 0 \\ 1 \\ 0 \end{bmatrix}$  and  $\mathbf{x}_n = \begin{bmatrix} -3x_2 \\ x_2 \\ -2x_4 \\ x_4 \end{bmatrix} = x_2 \begin{bmatrix} -3 \\ 1 \\ 0 \\ 0 \end{bmatrix} + x_4 \begin{bmatrix} 0 \\ 0 \\ -2 \\ 1 \end{bmatrix}$ . Thus,

the complete solution is

$$\mathbf{x} = \begin{bmatrix} -4 \\ 0 \\ 1 \\ 0 \end{bmatrix} + x_2 \begin{bmatrix} -3 \\ 1 \\ 0 \\ 0 \end{bmatrix} + x_4 \begin{bmatrix} 0 \\ 0 \\ -2 \\ 1 \end{bmatrix}.$$

□

2. Give an example of a matrix  $A$  for each of the four possibilities for linear equations depending on the rank  $r$ . Show that the matrix has the corresponding number of solutions.

*Solution.*

Let  $A$  be an  $m \times n$  matrix, and  $\text{rank}(A) = r$ .

(a) If  $r = m = n$ ,  $A$  is an invertible matrix, so  $A\mathbf{x} = \mathbf{b}$  has only one solution. For example, consider  $A = I$ .

(b) If  $r = m < n$ , we can consider the matrix  $\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix}$ . Then

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix} \mathbf{x} = \mathbf{b}$$

has infinitely many solutions of the form  $\mathbf{x} = \begin{bmatrix} b_1 \\ b_2 \\ 0 \end{bmatrix} + x_3 \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$ .

(c) If  $r = n < m$ , we can consider the matrix  $\begin{bmatrix} 1 & 0 \\ 0 & 1 \\ 0 & 0 \end{bmatrix}$ . Then

$$\begin{bmatrix} 1 & 0 \\ 0 & 1 \\ 0 & 0 \end{bmatrix} \mathbf{x} = \mathbf{b}$$

has solution  $\mathbf{x} = \begin{bmatrix} b_1 \\ b_2 \end{bmatrix}$  if  $b_3 = 0$ . If  $b_3 \neq 0$ , then the system has no solution.

(d) If  $r < m$  and  $r < n$ , we can consider the matrix  $\begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$ . Then

$$\begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix} \mathbf{x} = \mathbf{b}$$

has infinitely many solutions of the form  $\mathbf{x} = \begin{bmatrix} b_1 \\ b_2 \\ 0 \\ 0 \end{bmatrix} + x_3 \begin{bmatrix} 0 \\ 0 \\ 1 \\ 0 \end{bmatrix} + x_4 \begin{bmatrix} 0 \\ 0 \\ 0 \\ 1 \end{bmatrix}$  if  $b_3 = 0$ . If  $b_3 \neq 0$ , then the system has no solution.

□

3. Find a basis for the column space and nullspace of  $A$ . What is the dimension of the nullspace and columnspace? What is the rank of  $A$ ?

$$A = \begin{bmatrix} 1 & 1 & 0 \\ 1 & 3 & 1 \\ 3 & 1 & -1 \end{bmatrix}.$$

*Solution.*

First, we find rref( $A$ ).

$$\begin{aligned} \left[ \begin{array}{ccc} 1 & 1 & 0 \\ 1 & 3 & 1 \\ 3 & 1 & -1 \end{array} \right] \begin{array}{l} r_2 - r_1 \\ r_3 - 3r_1 \end{array} &= \left[ \begin{array}{ccc} 1 & 1 & 0 \\ 0 & 2 & 1 \\ 0 & -2 & -1 \end{array} \right] \begin{array}{l} r_1 - \frac{1}{2}r_2 \\ r_3 + r_2 \end{array} \\ &= \left[ \begin{array}{ccc} 1 & 0 & -\frac{1}{2} \\ 0 & 2 & 1 \\ 0 & 0 & 0 \end{array} \right] \frac{1}{2}r_2 \\ &= \left[ \begin{array}{ccc} 1 & 0 & -\frac{1}{2} \\ 0 & 1 & \frac{1}{2} \\ 0 & 0 & 0 \end{array} \right] \end{aligned}$$

We see that a basis of the column space is given by the first two columns

of  $A$ . Then  $\begin{bmatrix} 1 \\ 1 \\ 3 \end{bmatrix}, \begin{bmatrix} 1 \\ 3 \\ 1 \end{bmatrix}$  form a basis of the column space of  $A$ . For the

nullspace, we solve  $A\mathbf{x} = \mathbf{0}$ , so  $\mathbf{x} = \begin{bmatrix} \frac{1}{2}x_3 \\ -\frac{1}{2}x_3 \\ x_3 \end{bmatrix}$ , so  $\begin{bmatrix} \frac{1}{2} \\ -\frac{1}{2} \\ 1 \end{bmatrix}$  forms a basis of  $N(A)$ . We see that the column space is 2-dimensional and  $N(A)$  is 1-dimensional. The rank of  $A$  is the dimension of the column space (=dimension of the row space = number of pivots), so  $\text{rank}(A) = 2$ .  $\square$

4. Suppose  $\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3$  are linearly independent.

- (a) Let  $\mathbf{v}_1 = \mathbf{u}_2 - \mathbf{u}_3$ ,  $\mathbf{v}_2 = \mathbf{u}_1 - \mathbf{u}_3$ , and  $\mathbf{v}_3 = \mathbf{u}_1 - \mathbf{u}_2$ . Determine whether  $\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3$  are linearly independent.
- (b) Let  $\mathbf{v}_1 = \mathbf{u}_2 + \mathbf{u}_3$ ,  $\mathbf{v}_2 = \mathbf{u}_1 + \mathbf{u}_3$ , and  $\mathbf{v}_3 = \mathbf{u}_1 + \mathbf{u}_2$ . Determine whether  $\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3$  are linearly independent.

*Solution.*

- (a)  $\mathbf{v}_1, \mathbf{v}_2$ , and  $\mathbf{v}_3$  are linearly independent if

$$c_1\mathbf{v}_1 + c_2\mathbf{v}_2 + c_3\mathbf{v}_3 = \mathbf{0}$$

requires  $c_1 = c_2 = c_3 = 0$ . We see that

$$\begin{aligned} \mathbf{0} &= c_1\mathbf{v}_1 + c_2\mathbf{v}_2 + c_3\mathbf{v}_3 \\ &= c_1(\mathbf{u}_2 - \mathbf{u}_3) + c_2(\mathbf{u}_1 - \mathbf{u}_3) + c_3(\mathbf{u}_1 - \mathbf{u}_2) \\ &= (c_2 + c_3)\mathbf{u}_1 + (c_1 - c_3)\mathbf{u}_2 + (-c_1 - c_2)\mathbf{u}_3. \end{aligned}$$

Since  $\mathbf{u}_1, \mathbf{u}_2$ , and  $\mathbf{u}_3$  are linearly independent, so

$$c_2 + c_3 = 0$$

$$c_1 - c_3 = 0$$

$$-c_1 - c_2 = 0$$

and we have that  $c_2 = -c_3$ ,  $c_1 = c_3$  and  $c_2 = -c_1$ . Letting  $c_1 = 1$ , we see that  $c_2 = -1$ , and  $c_3 = 1$ . Then, we see that

$$\mathbf{v}_1 - \mathbf{v}_2 + \mathbf{v}_3 = \mathbf{0}$$

so  $\mathbf{v}_1$ ,  $\mathbf{v}_2$ , and  $\mathbf{v}_3$  are not linearly independent.

(b) Again,  $\mathbf{v}_1$ ,  $\mathbf{v}_2$ , and  $\mathbf{v}_3$  are linearly independent if

$$c_1\mathbf{v}_1 + c_2\mathbf{v}_2 + c_3\mathbf{v}_3 = \mathbf{0}$$

requires  $c_1 = c_2 = c_3 = 0$ . We see that

$$\begin{aligned} \mathbf{0} &= c_1\mathbf{v}_1 + c_2\mathbf{v}_2 + c_3\mathbf{v}_3 \\ &= c_1(\mathbf{u}_2 + \mathbf{u}_3) + c_2(\mathbf{u}_1 + \mathbf{u}_3) + c_3(\mathbf{u}_1 + \mathbf{u}_2) \\ &= (c_2 + c_3)\mathbf{u}_1 + (c_1 + c_3)\mathbf{u}_2 + (c_1 + c_2)\mathbf{u}_3. \end{aligned}$$

Since  $\mathbf{u}_1$ ,  $\mathbf{u}_2$  and  $\mathbf{u}_3$  are linearly independent,

$$c_2 + c_3 = 0$$

$$c_1 + c_3 = 0$$

$$c_1 + c_2 = 0$$

So  $c_2 = -c_3$ ,  $c_1 = -c_3$  and  $c_1 = -c_2$ . Then we must have that  $c_2 = c_1$  from the first two relations and so  $c_1 = -c_1$ . Then  $c_1 = 0$ , so  $c_2 = 0$  and  $c_3 = 0$ . Thus,  $\mathbf{v}_1$ ,  $\mathbf{v}_2$ , and  $\mathbf{v}_3$  are linearly independent.

□