Math 17C, Spring 2011. May 11, 2011.

MIDTERM EXAM 2

NAME(print in CAPITAL letters, first name first):	KEY	
NAME(sign):		
ID#:		

Instructions: Each of the 4 problems has equal worth. Read each question carefully and answer it in the space provided. YOU MUST SHOW ALL YOUR WORK TO RECEIVE FULL CREDIT. Clarity of your solutions may be a factor when determining credit. Calculators, books or notes are not allowed.

Make sure that you have a total of 5 pages (including this one) with 4 problems.

1	
2	
3	
4	
TOTAL	

$$c_1 e^{\alpha t} \begin{bmatrix} u_1 \cos(\beta t) - v_1 \sin(\beta t) \\ u_2 \cos(\beta t) - v_2 \sin(\beta t) \end{bmatrix} + c_2 e^{\alpha t} \begin{bmatrix} u_1 \sin(\beta t) + v_1 \cos(\beta t) \\ u_2 \sin(\beta t) + v_2 \cos(\beta t) \end{bmatrix}$$

1. The bounded region D in the plane lies in the first quadrant $(x \ge 0, y \ge 0)$ and is bounded by the graphs of y = 2x and $y = x^2$. Compute the volume of the spatial region above D and under the surface z = 6xy.

$$y = x^{2}$$

Volume = $\int_{0}^{2} dx \int_{0}^{2} dx \int_{0}^{$

- 2. The position (x_1, x_2) of a particle at time t is given by $x_1 = t^2 + 1$, $x_2 = t^3 9t^2 + 24t 96$. Assume that time is nonegative, i.e., $t \ge 0$.
- (a) Determine the speed and the unit vector in the direction of motion at time t = 1.

$$\frac{dx_1}{dt} = 2t$$

$$\frac{dx_2}{dt} = 3t^2 - 18t + 24$$

$$\frac{dx_2}{dt} = \begin{bmatrix} 2 \\ 9 \end{bmatrix}$$

$$8 + 2t = \sqrt{4 + 81} = \sqrt{85}$$

$$\frac{2}{8} = \left[\frac{2}{185} \right]$$

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(b) At which times $t \ge 0$ is the direction of motion horizontal (i.e., in the x_1 -direction)? What are the locations of the particle at these times (note: $96 = 4 \cdot 24 = 2 \cdot 48$)?

$$\frac{dx_{2}}{dt} = 0$$

$$\frac{dx$$

(c) Does the particle ever return to a previous position?

No:
$$\frac{dx_1}{dt} > 0$$
 so the particle always moves to the right (x₁ always moreases), &

3. Consider the linear system

$$\frac{dx_1}{dt} = x_1 - 4x_2$$

$$\frac{dx_2}{dt} = x_1 + x_2$$

(a) Find the general solution of this system.

$$A = \begin{bmatrix} 1 & -4 \\ 1 & 1 \end{bmatrix} \quad \text{dist} (A - \lambda I) = (I - \lambda)^{2} + 4$$

$$= \lambda^{2} - 2\lambda + 5$$

$$\lambda = \frac{2 \pm \sqrt{-16}}{2} = 1 \pm 2i$$

$$\lambda_{1} = 1 + 2i$$

$$\begin{bmatrix} -2i & -4 \\ 1 & -2i \end{bmatrix} \begin{bmatrix} 3i \\ 3i \end{bmatrix} = 0 \quad \text{for } i = 1$$

$$\begin{bmatrix} 2i \\ 3i \end{bmatrix} = \begin{bmatrix} 2ii \\ 3$$

(b) Find the solution that is at the point (4,1) at time t=0 and sketch is trajectory.

$$2c_{1} = 4, c_{2} = 2$$

$$2c_{2} = 4, c_{2} = 2$$

$$c_{1} = 1$$

$$c_{1} = 1$$

$$c_{1} = 1$$

$$c_{2} = 4$$

$$c_{2} = 4$$

$$c_{3} = 2$$

$$c_{4} = 4$$

$$c_{2} = 4$$

$$c_{3} = 4$$

$$c_{4} = 4$$

$$c_{5} = 4$$

$$c_{5} = 4$$

$$c_{6} = 4$$

$$c_{6} = 4$$

$$c_{6} = 4$$

$$c_{6} = 4$$

$$c_{7} = 4$$

$$c_{7$$

(c) Find, classify, and discuss the stability of the only fixed fixed point of this system.

4. Consider the nonlinear system

$$\frac{dx_1}{dt} = -x_1 + 2x_2$$

$$\frac{dx_2}{dt} = 2x_1 - x_2^2 + 5$$

Find, classify, and discuss the stability of all of its fixed points. (You may use $\sqrt{11^2 - 24} \approx 9.85$.)

$$-X_{1} + 2X_{2} = 0 X_{1} = 2X_{2}$$

$$-X_{2} + 5 = 0 X_{2} - 4X_{2} - 5 = 0$$

$$(X_{2} + 4)(X_{2} - 5) = 0$$

$$+1 \times 2$$

$$-2 \times 2$$

$$-2 \times 2$$

$$(-2,-1)$$

$$A = \begin{bmatrix} -1 & 2 \\ 2 & 2 \end{bmatrix}$$

$$(-1-\lambda)(2-\lambda)-4=0$$

 $(\lambda^2-\lambda-6=0)$
 $(\lambda-3)(\lambda+2)=0$ $\lambda=3,-2$
Saddle (unstable)

$$A = \begin{bmatrix} -1 & 2 \\ 2 & -10 \end{bmatrix}$$

$$(-1-\lambda) (-10-\lambda) - 4=0$$

$$\lambda^{2} + 11\lambda + 6 = 0$$

$$\lambda = \frac{-11 \pm \sqrt{11^{2} - 24}}{2}$$

$$= \frac{-11 \pm 9.85}{2} \text{ both } < 0$$

stable unde