STRUCTURE OF THE TENSOR PRODUCT SEMIGROUP

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To the memory of S. S. Chern

Abstract. We study the structure of semigroup $Tens(G)$ consisting of triples of fundamental weights (λ, μ, ν) of a complex reductive Lie group G such that

$$(V_\lambda \otimes V_\mu \otimes V_\nu)^G \neq 0.$$

We prove two general structural results for $Tens(G)$ and give an explicit computation of $Tens(G)$ for $G = Sp(4, \mathbb{C})$.

1. Introduction

Suppose that G is a complex reductive Lie group. Finite-dimensional irreducible representations V_λ of G are parameterized by their highest weights $\lambda \in \Delta \cap L$, where Δ is the positive Weyl chamber, L is the character lattice of a maximal (split) torus in G. One of the basic questions of the representation theory is to decompose tensor products $V_\lambda \otimes V_\mu$ into sums of irreducible representations. Accordingly, we define the set

$$Tens(G) := \{(\lambda, \mu, \nu) \in (\Delta \cap L)^3 : (V_\lambda \otimes V_\mu \otimes V_\nu)^G \neq 0\}.$$

For simply-connected Lie groups with the root system R we will write $Tens(R)$ instead of $Tens(G)$. It was known for a long time, see for example [12], Theorem 9.8, that the set $Tens(G)$ forms a semigroup with respect to the addition. The goal of this paper is to provide more specific structural theorems for $Tens(G)$ and to make an explicit computation of $Tens(Sp(4, \mathbb{C}))$.

Theorem 1.1. *For each group G as above, the set $Tens(G)$ is a finite union of elementary subsets of L^3.*

Here an *elementary subset* is a subset given by a finite system of linear inequalities (with integer coefficients) and congruences. Thus, to "describe" $Tens(G)$ one would have to find these inequalities and congruences. The above theorem is an analogue of a theorem by C. Laskowski [17], who proved a similar statement for the structure constants of spherical Hecke rings.

Our next theorem provides a glimpse of what these inequalities and congruences might look like. In [2] and [10] there have been defined a finite-sided homogeneous polyhedral cone $\mathcal{P}(G) = D_3(G/K) \subset \Delta^3$ (where K is a maximal compact subgroup of G), given by the inequalities of the form:

$$\langle \varpi_i, w_1\lambda \rangle + \langle \varpi_i, w_2\mu \rangle + \langle \varpi_i, w_3\nu \rangle \leq 0,$$

Date: July 15, 2005.

where ϖ_i are the fundamental weights of R and w_i are certain elements of the Weyl group of G determined by the "Schubert calculus". It is known (see for instance [12]) that

$$Tens(G) \subset \mathcal{P}(G) \cap \{(\lambda, \mu, \nu) \in L^3 : \lambda + \mu + \nu \in Q(R)\},$$

where $Q(R)$ is the root lattice.

Theorem 1.2. *There exists a vector $\sigma \in \mathcal{P}(G)$ such that*

$$(\mathcal{P}(G) + \sigma) \cap Tens(G) = (\mathcal{P}(G) + \sigma) \cap \{(\lambda, \mu, \nu) \in L^3 : \lambda + \mu + \nu \in Q(R)\}.$$

In other words, inside of the translated cone $\mathcal{P}(G) + \sigma$ the *necessary* conditions on (λ, μ, ν) to belong to $Tens(G)$ are also *sufficient*. Observe that the intersection $\{(\lambda, \mu, \nu) \in L^3 : \lambda + \mu + \nu \in Q(R)\} \cap (\mathcal{P}(G) + \sigma)$ is an elementary subset of the lattice L^3. The length of the vector σ can be explicitly estimated. In section 4 we make such an estimate in the case when $R = B_\ell$; the same methods work for other root systems.

In section 5 we will compute the semigroup $Tens = Tens(G)$ for the group $G = Sp(4, \mathbb{C})$ and show that this set is *not* an elementary set itself. Below $P(R) = L$ is the weight lattice of G and ϖ_2 is the longest fundamental weight. We let

$$\Lambda := \{(\lambda, \mu, \nu) \in L^3 : \lambda + \mu + \nu \in Q(R)\}.$$

We first write the description of $Tens$ in English and then translate this description into decomposition of $Tens$ into elementary subsets:

Theorem 1.3. $(\lambda, \mu, \nu) \in \mathcal{P}(G) \cap \Lambda$ *belongs to $Tens$ if and only if one of the following is satisfied:*

1. *At least two of the vectors λ, μ, ν are not multiples of ϖ_2.*
2. *If two of the vectors λ, μ, ν are multiples of ϖ_2 then $\lambda + \mu + \nu \in 2P(R)$.*

We now express $Tens$ as the union of elementary subsets. In what follows, $\mathbb{N} = \{0, 1, 2, ...\}$. Let

$$E_1 = \{(\lambda, \mu, \nu) \in L^3 : \lambda + \mu + \nu \in 2P(R), \lambda \in \mathbb{N}\varpi_2, \mu \in \mathbb{N}\varpi_2\} \cap \mathcal{P}(G),$$

$$E_2 = \{(\lambda, \mu, \nu) \in L^3 : \lambda + \mu + \nu \in 2P(R), \lambda \in \mathbb{N}\varpi_2, \nu \in \mathbb{N}\varpi_2\} \cap \mathcal{P}(G),$$

$$E_3 = \{(\lambda, \mu, \nu) \in L^3 : \lambda + \mu + \nu \in 2P(R), \nu \in \mathbb{N}\varpi_2, \mu \in \mathbb{N}\varpi_2\} \cap \mathcal{P}(G),$$

$$E_1' = \{(\lambda, \mu, \nu) \in \Lambda : \lambda \notin \mathbb{N}\varpi_2, \mu \notin \mathbb{N}\varpi_2\} \cap \mathcal{P}(G),$$

$$E_2' = \{(\lambda, \mu, \nu) \in \Lambda : \lambda \notin \mathbb{N}\varpi_2, \nu \notin \mathbb{N}\varpi_2\} \cap \mathcal{P}(G),$$

$$E_3' = \{(\lambda, \mu, \nu) \in \Lambda : \mu \notin \mathbb{N}\varpi_2, \nu \notin \mathbb{N}\varpi_2\} \cap \mathcal{P}(G).$$

Then

$$Tens = \bigcup_{i=1}^{3} E_i \cup \bigcup_{i=1}^{3} E_i'.$$

We refer the reader to [10, 16] (see also section 2.3 of this paper) for the explicit computation of the polyhedron $\mathcal{P}(Sp(4, \mathbb{C}))$ and polyhedra $\mathcal{P}(G)$ for complex semisimple Lie group of rank ≤ 3.

We note that prior to the present paper, the complete description of the semigroup $Tens(G)$ was known only for the groups of type A_n. In this case the Saturation Theorem of Knutson and Tao [15] implies that

$$Tens(G) = \mathcal{P}(G) \cap \{(\lambda, \mu, \nu) \in L^3 : \lambda + \mu + \nu \in Q(R)\}.$$

Acknowledgements. During the work on this paper the first author was supported by the NSF grant DMS-04-05180; part of this work was done when the first author was visiting the Max Plank Institute for Mathematics in Bonn. The second author was supported by the NSF grant DMS-04-05606. The authors gratefully acknowledge support of these institutions.

The possibility of Theorem 1.2 was suggested by J. Bernstein in a conversation at Oberwolfach. T. Haines and S. Kumar have told us about about Theorem 4.6. The authors are grateful to J. Bernstein, T. Haines, S. Kumar and C. Laskowski for these and other useful conversations. The second author would like to acknowledge how exciting it was to learn Chern-Weil theory and the theory of Chern-Simons invariants first-hand when he was a graduate student in Berkeley in the early seventies.

2. Review of the path model for the representation theory of complex reductive Lie groups

2.1. **Root systems and Coxeter complexes.** Let V be a finite-dimensional Euclidean vector space and $R \subset V$ be a root system in V. Then the collection of coroots $R^\vee$ determines a root system in V^*. Using the metric on V we will be identifying R and $R^\vee$ with root systems in V. Thus we will think of both R and $R^\vee$ as linear functionals on V. Given R we define the *affine Coxeter group* $W_{aff} := W_{R^\vee,aff}$ as the group generated by reflections in the *walls*

$$H = \{x \in V : \alpha(x) = t\}, \alpha \in R^\vee, t \in \mathbb{Z}.$$

We let $W = W_{R^\vee,sph} = W_{R,sph}$ denote the linear part of $W_{R,aff}$, which is the same as the stabilizer of the origin in $W_{R^\vee,aff}$. The group W is the Weyl group of the root system R (and $R^\vee$).

Remark 2.1. *In the context of the representation theory of a complex semisimple Lie group G, the space V equals $X^*(T) \otimes \mathbb{R}$, where T is a maximal torus in G. Thus $R \subset V$ and the walls in V are given by the coroot system $R^\vee$.*

A *Weyl chamber* Δ is a fundamental domain for the finite reflection group W, it is bounded by certain walls passing through the origin. Given a vector $v \in \Delta$ we let $v^* \in \Delta$ denote the *contragredient vector* $v^* = w_0(-v)$, where $w_0 \in W$ is the longest element, i.e. the element which carries $-\Delta$ to Δ.

The group W_{aff} acts by isometries on the Euclidean space V. Let A denote the affine space underlying V. The pair (A, W_{aff}) is called a *Euclidean Coxeter complex*. Let $\mathcal{W}$ denote the union of all walls. Then the closures of connected components of $A \setminus \mathcal{W}$ are called *alcoves*. If R is irreducible and spans V then alcoves are simplicies and therefore (A, W_{aff}) has natural structure of a simplicial complex.

Each alcove is a fundamental domain for the action $W_{aff} \curvearrowright A$. Pick an alcove a and call it a fundamental alcove. We have a natural projection $\theta : A \to a$ sending

each point $v \in A$ to the inique intersection point $\theta(v) \in W_{aff} \cdot v \cap a$. The image $\theta(v)$ is called the *type* of v.

Special verticies of the complex (A, W_{aff}) are points whose stabilizer in W_{aff} is isomorphic to W_{sph}. The weight group $P(R)$ acts simply transitively on the set of special verticies.

Let $h : A \to A$ be a dilation of A, i.e. an affine map of the form $x \mapsto kx+b$, where $b \in V$, $k > 0$. The number k is the *conformal factor* of h. We define $Dil(A, W_{aff})$ to be the semigroup of dilations h of A such that

$$hW_{aff}h^{-1} \subset W_{aff}.$$

Then each $h \in Dil(A, W_{aff})$ sends verticies of (A, W_{aff}) to verticies of (A, W_{aff}), walls to walls, etc.

2.2. **Chains.** Let $R \subset V$ be a root system in a Euclidean vector space V, W be the Weyl group of R. We pick a Weyl chamber Δ for W, this determines the set of positive roots R_+ and the set of the simple roots Φ in R, as well as positive and simple coroots. The following notion of *chains* and the *partial order* $\geq$ *on* $V \setminus \{0\}$ was introduced by P. Littelmann in [18].

Definition 2.2. *A* W–chain *in* V *is a finite sequence* $(\eta_0, ..., \eta_m)$ *of nonzero vectors in* V *so that for each* $i = 1, ..., m$ *there exists a positive coroot* $\beta_i \in R^\vee$ *so that the corresponding reflection* $\tau_i := \tau_{\beta_i} \in W$ *satisfies*

1. $\tau_i(\eta_{i-1}) = \eta_i$.
2. $\beta_i(\eta_{i-1}) < 0$.

Then $\eta \geq_W \nu$ if there exists a chain from η to ν. Most of the time we will abbreviate $\geq_W$ to $\geq$. We say that a chain

$$\eta'_0 \geq ...\eta'_i \geq ... \geq \eta'_n$$

is a *refinement* of the chain

$$\eta_0 \geq ... \geq \eta_i \geq ... \geq \eta_k$$

if $\eta_0 = \eta'_0, \eta'_n = \eta_k$ and

$$\{\eta_0, ..., \eta_k\} \subset \{\eta'_0, ..., \eta'_n\}.$$

A chain which does not admit a proper refinement is called *maximal*.

Define a (nontransitive) relation $\sim = \sim_W$ on $V \setminus \{0\}$ by

$$\mu \sim_W \nu \iff$$

$$\mu, \nu \text{ belong to the same Weyl chamber of } W.$$

We write $\lambda \gtrsim \xi$ if there exist μ, ν so that

$$\lambda \geq \mu \sim \nu \geq \xi.$$

Accordingly, we define *generalized chains* as sequences of nonzero vectors in V:

$$\eta_0 \gtrsim \eta_1 \gtrsim ... \gtrsim \eta_m.$$

2.3. **Buildings.** Our discussion of buildings follows [14]. We refer the reader to [5], [19], [20] for the more combinatorial discussion.

Fix a spherical or Euclidean (discrete) Coxeter complex (A, W), where A is a Euclidean space E or a unit sphere S and $W = W_{aff}$ or $W = W_{sph}$ is a discrete Euclidean or a spherical Coxeter group acting on A.

A metric space Z is called *geodesic* if every pair of points x, y in Z can be connected by a geodesic segment $\overline{xy}$.

Let Z be a metric space. A *geometric structure* on Z *modeled on* (A, W) consists of an atlas of isometric embeddings $\varphi : A \hookrightarrow Z$ satisfying the following compatibility condition: For any two charts φ_1 and φ_2, the transition map $\varphi_2^{-1} \circ \varphi_1$ is the restriction of an isometry in W. The charts and their images, $\varphi(A) = a \subset Z$, are called *apartments*. We will sometimes refer to A as the *model apartment*. We will require that there are *plenty of apartments* in the sense that any two points in Z lie in a common apartment. All W-invariant notions introduced for the Coxeter complex (A, W), such as rank, walls, singular subspaces, chambers etc., carry over to geometries modeled on (A, W). If $a, a' \subset X$ are alcoves (in the Euclidean case) or chambers (in the spherical case) then there exists an apartment $A' \subset X$ containing $a \cup a'$: Just take regular points $x \in a, x' \in a'$ and an apartment A' passing through x and x'.

A geodesic metric space Z is said to be a $CAT(0)$-space (resp, $CAT(1)$-space) if *geodesic triangles in Z are "thinner" than geodesic triangles in* $\mathbb{R}^2$ (resp. in the unit sphere S^2). We refer the reader to [1] for the precise definition.

Definition 2.3. *A Euclidean (resp. spherical) building is a $CAT(0)$-space (resp. $CAT(1)$-space) modeled on a Euclidean (resp. spherical) Coxeter complex.*

A building is called *thick* if every wall is an intersection of apartments. A non-thick building can always be equipped with a natural structure of a thick building by reducing the Coxeter group.

Let $\mathbb{K}$ be a local field with a (discrete) valuation ν and valuation ring $\mathcal{O}$. Given a split reductive algebraic group $\underline{G}$ over $\mathbb{Z}$, and a nonarchimedian Lie group $G = \underline{G}(\mathbb{K})$ we can associate with it a Euclidean building (a Bruhat-Tits building) $X = X_G$. We refer the reader to [6], [12] and [20] for more detailed discussion of the properties of X. Here we only recall that:

1. X is thick and locally compact.

2. X is modeled on a Euclidean Coxeter complex (A, W_{aff}) whose dimension equals the rank of $\underline{G}$, and the root system is isomorphic to the root system of $\underline{G}$.

3. X contains a special vertex o whose stabilizer in G is $\underline{G}(\mathcal{O})$.

Example 2.4. *Let X be a (discrete) Euclidean building, consider the* spaces of directions $\Sigma_x X$. *We will think of this space as the space of germs of non-constant geodesic segments $\overline{xy} \subset X$. As a polysimplicial complex $\Sigma_x X$ is just the link of the point $x \in X$. The space of directions has the structure of a spherical building modeled on (S, W_{sph}), which is thick if and only if x is a special vertex of X, see* [14]. *The same applies in the case when X is a spherical building.*

Let (A, W_{aff}) be a Euclidean Coxeter complex and pick a Weyl chamber $\Delta \subset A$.

Given a pair of points $x, y \in A$ we define their Δ-distance $d_\Delta(x, y)$ by taking the vector $v := y - x$ and applying to it an element $w \in W_{sph}$ such that $u := w(v) \in \Delta$. Then $d_\Delta(x, y) := u$.

Suppose that X is a Euclidean building modeled on (A, W_{aff}). We define a Δ-distance in X as follows. For a pair of points $x, y \in X$ pick an apartment $\phi : A \to A' \subset X$ such that A' contains x, y. Then set

$$d_\Delta(x, y) := d_\Delta(\phi^{-1}(x), \phi^{-1}(y)).$$

It is easy to see that this distance is independent of the choice of ϕ. A similar definition applies if $X = G/K$ is a nonpositively curved symmetric space, where A is a maximal flat in X and $W_{sph} \curvearrowright A$ is the Weyl group of G.

Generalized triangle inequalities. Suppose that X is a nonpositively curved symmetric space or a Euclidean building as above. Define the set

$$D_3(X) := \{(\lambda, \mu, \nu) \in \Delta^3 : \exists \text{ a geodesic triangle } [x, y, z] \subset X \text{ with}$$
$$d_\Delta(x, y) = \lambda, d_\Delta(y, z) = \mu, d_\Delta(z, x) = \nu\}.$$

It is proven in [10, 11] that $D_3(X)$ is a convex homogeneous polyhedral cone which depends only on the pair (A, W_{sph}) and nothing else, therefore we will frequently use the notation $\mathcal{P}(G)$ for $D_3(G/K)$, where G is a reductive Lie group with a maximal compact subgroup K. In the case when G is a complex semisimple Lie group, the inequalities defining this polyhedron have the form

1. Stability inequalities $\psi_j(\lambda, \mu, \nu) \geq 0$:

$$-\langle \varpi_i, w_1\lambda\rangle - \langle \varpi_i, w_2\mu\rangle - \langle \varpi_i, w_3\nu\rangle \geq 0,$$

where ϖ_i are the fundamental weights of R and w_i are certain elements of the Weyl group of G.

2. Chamber inequalities $\psi_k(\lambda, \mu, \nu) \geq 0$:

$$\alpha^\vee(\lambda) \geq 0, \alpha^\vee(\mu) \geq 0, \alpha^\vee(\nu) \geq 0,$$

where α are simple roots in R.

In [10] the polyhedra $D_3(G)$ were computed for all complex semisimple Lie groups G of rank 2. Below we provide the explicit set of *stability inequalities* for this polyhedron in the case $G = Sp(4, \mathbb{C})$.

The Weyl chamber Δ is given by

$$\Delta = \{(x, y) : x \geq y \geq 0\}.$$

We will omit these inequalities from the list of inequalities defining $\mathcal{P}(G)$ and will list only the *stability inequalities*. Instead of the notation (λ, μ, ν) for elements of Δ^3, we will use the more symmetric notation $(\lambda_1, \lambda_2, \lambda_3)$, where $\lambda_i = (x_i, y_i), i = 1, 2, 3$.

The system of stability inequalities defining $\mathcal{P}(Sp(4, \mathbb{C}))$ breaks into two subsystems (since $Sp(4, \mathbb{C})$ has rank 2). The first subsystem is given by

$$x_i \leq x_j + x_k, \quad \{i, j, k\} = \{1, 2, 3\}$$
$$y_i \leq y_j + x_k, \quad \{i, j, k\} = \{1, 2, 3\}.$$

In order to describe the second subsystem we set

$$S = x_1 + y_1 + x_2 + y_2 + x_3 + y_3.$$

The second subsystem is then given by

$$x_i + y_j \leq S/2, \quad 1 \leq i, j \leq 3.$$

2.4. **LS paths and their generalizations.** Suppose that (A, W_{aff}) is a Euclidean Coxeter complex. Given a point $x \in A$ let W_x denote the stabilizer of x in W_{aff}. For a vector v in V define the path π_v by the formula:

$$\pi_v(t) = tv, \quad t \in [0, 1].$$

In what follows we will assume that all paths are (re)parameterized to have constant speed and domain $I := [0, 1]$.

Given two paths p_1, p_2 in A, we define their *concatenation* $p = p_1 * p_2$ by

$$p(t) = \begin{cases} p_1(t), & t \in [0, 1], \\ p_1(1) - p_2(0) + p_2(t), & t \in [1, 2]. \end{cases}$$

Suppose that $p : I \to A$ is a path and $J = [a, b]$ is nondegenerate subinterval in $I = [0, 1]$. We will use the notation $p\big|_J$ to denote the restriction of p to $[a, b]$

If p is a PL path in A which is the concatenation

$$\overline{x_1 x_2} * ... * \overline{x_n x_{n+1}}$$

of geodesic segments, then the Δ-length of p, denoted $\text{length}_\Delta(p)$, is the sum

$$\sum_{i=1}^{n} d_\Delta(x_i, x_{i+1}).$$

Given a PL path p in A we use the notation $p'_\pm(t) \in T_{p(t)}(A)$ to denote the derivatives of p at t from the left and from the right.

We say that a path $p : [0, 1] \to A$ is a *billiard path* if for each $t \in [0, 1]$,

$$p'_-(t) \in W_{p(t)} p'_+(t).$$

If $p := p_1 * ... * p_m$ is a concatenation of billiard paths then we set

$$\underline{\text{length}}_\Delta(p) := (\text{length}_\Delta(p_1), ..., \text{length}_\Delta(p_m)).$$

Definition 2.5. *A PL path $p : [0, 1] \to A$ in A is said to be an LS path with respect to the root system R if:*

1. $p(0), p(1) \in P(R)$.
2. *For each $t \in [0, 1]$ we have*

$$p'_-(t) \geq_{W_{p(t)}} p'_+(t)$$

3. *There is a $W_{p(t)}$–chain from $p'_-(t)$ to $p'_+(t)$ which is maximal as a W-chain when we regard $p'_-(t)$ and $p'_+(t)$ as vectors in V.*

Remark 2.6. *This definition is a slight generalization of the Littelmann's definition in* [18], *where it is assumed that $p(0) = 0$.*

Note that each LS path is necessarily a billiard path. Let $t_i, i = 1, ..., n$, denote the *break-points* of p, i.e. such that p is not geodesic at t. We then obtain a chain

$$p'(0) \geq p'_+(t_1) \geq ... \geq p'_+(t_{n-1}) \geq p'(1).$$

Using property (3) we extend this chain to a maximal W-chain

$$\eta_0 = p'(0) \geq ... \geq \eta_m = p'(1).$$

Then the translated path $p - p(0)$ is the concatenation of the geodesic paths

$$\pi_{a_i \eta_i}, a_i \geq 0, i = 1, ..., n.$$

We also need a generalization of the concept of an LS path described below:

Definition 2.7 ([13]). *Suppose that $p_1, ..., p_m : [0,1] \to A$ are LS paths. Their concatenation $p_1 * ... * p_m$ is called a generalized LS path if for each $i = 1, ..., m-1$ we have:*

$$(p'_i)_-(1) \gtrsim (p'_i)_+(0).$$

We will use the notation $LS(R)$ and $LS_1(R)$ to denote the sets of LS paths and generalized LS paths with respect to the root system R. In fact, in this paper we will be using only (generalized) LS paths $p = p_1 * ... * p_m$ such that

$$\underline{\text{length}}_\Delta(p) = (n_1 \varpi_1, ..., n_m \varpi_m), n_i \in \mathbb{N},$$

where ϖ_i are fundamental weights of R.

2.5. **The path model.** The following theorem is a version of Littelmann's rule for decomposing tensor products:

Theorem 2.8 ([13], Corollary 5.22). *The tensor product $V_\lambda \otimes V_\mu$ contains V_ν as a subrepresentation if and only if there exists a generalized LS path p with $p(0) = \lambda, p(1) = \nu$ so that*

1.

$$\underline{\text{length}}_\Delta(p) = (\mu_1, ..., \mu_m),$$

2.

$$\mu_i \in \mathbb{N}\varpi_i, \forall i = 1, ..., m,$$

3.

$$\sum_{i=1}^m \mu_i = \mu$$

4. p is contained in Δ.

The following lemma easily follows from the above theorem, one can also derive it directly from the definition of a generalized LS path:

Lemma 2.9. *If p is a generalized LS path then*

$$p(0) - p(1) - \text{length}_\Delta(p) \in Q(R).$$

2.6. **The saturation theorem.** In this section we discuss the *Saturation Theorem* proven in [13].

Recall that in [12] we have defined two constants k_R and k_w associated with the root system R. The *saturation constant* k_R is defined by the property that it is the least integer $k \geq 1$ such that for each vertex v of the Euclidean Coxeter complex $(A, W_{R,aff})$ we have:

$$kv \in P(R),$$

i.e. is a special vertex. The constant k_w is the least integer $k \geq 1$ with the following property:

Suppose that F is a face of $(A, W_{R,aff})$ invariant under an isometry of A and let v denote the barycenter of F. Then kv is a special vertex.

We have proven in [12] that for the root systems B_ℓ and C_ℓ we have:

$$k_R = k_w = 2.$$

In particular, k_R and k_w do not change if we replace R with $R^\vee$.

Let $\underline{G}$ be a reductive algebraic group over $\mathbb{Z}$; set $G = \underline{G}(\mathbb{C})$. For a nonarchimedian local field $\mathbb{K}$ (e.g. $\mathbb{K} = \mathbb{Q}_p$) we let X denote the Bruhat-Tits building associated with $\underline{G}^\vee(\mathbb{K})$, where $\underline{G}^\vee$ is the Langlands' dual of $\underline{G}$.

Theorem 2.10. *1. Suppose that $\sigma = (\lambda, \mu, \nu) \in P(R)^3 \cap \mathcal{P}(G)$ is such that $\lambda + \mu + \nu \in Q(R)$. Then*

$$k_R^2 \cdot \sigma \in Tens(G).$$

2. Suppose that $\sigma = (\lambda, \mu, \nu) \in P(R)^3 \cap \mathcal{P}(G)$. Then

$$k_R k_w \cdot \sigma \in Tens(G).$$

Proof: The first assertion is the *Saturation Theorem* 1.8 of [13]. We prove the second assertion.

Then, since $\sigma \in \mathcal{P}(G) = D_3(X)$, there exists a geodesic triangle $[z, x, y]$ in X with the Δ-side lengths (λ, μ, ν) (see [11]). According to Theorem 7.16 of [12], there exists a geodesic triangle $[z', x', y'] \subset X$ whose verticies are special verticies of X and whose Δ-side lengths are $(\lambda', \mu', \nu') := (k_w\lambda, k_w\mu, k_w\nu)$. Therefore, by Part 2 of Theorem 1.8 in [13],

$$k_R(\lambda', \mu', \nu') \in Tens(G). \quad \square$$

In section 5 we will need the following improvement of Theorem 2.10 in the case of the root system $R = B_2 \cong C_2$.

Theorem 2.11. *Suppose that G has the root system $R \cong B_2$, $\sigma = (\lambda, \mu, \nu) \in P(R)^3 \cap \mathcal{P}(G)$ and $\lambda + \mu + \nu \in Q(R)$. Then:*

1.

$$2 \cdot \sigma \in Tens(G).$$

2. Moreover, there exists a generalized LS path $p \in LS_1(R)$ contained in Δ, connecting 2λ to $2\nu = 2\nu^*$, so that $\underline{\text{length}}_\Delta(p) = (2\mu_1, 2\mu_2)$, $\mu_1 + \mu_2 = \mu$, $\mu_i \in \mathbb{N}\varpi_i$ and all breakpoints of p, with possible exception of ones occurring on the boundary of Δ, are special verticies.

Proof: The first assertion follows from the second. The proof of the second assertion is a variation on the proof of the Saturation Theorem 1.8 given in [13] so here we will give only a sketch and refer the reader to [13] for the details.

Let X be the Euclidean building as above. Then the assumptions that $\sigma = (\lambda, \mu, \nu) \in P(R)^3 \cap \mathcal{P}(G)$ and $\lambda + \mu + \nu \in Q(R)$ imply that there exists a geodesic triangle $[\tilde{x}, \tilde{y}, \tilde{z}] \subset X$ whose verticies are verticies of X and whose Δ–side-lengths are μ, ν, λ, see [12, Corollary 7.12, Part 1]. We let $\tilde{A} \subset X$ denote an apartment containing the segment $\overline{\tilde{x}\tilde{y}}$ and let $\tilde{\Delta} \subset \tilde{A}$ denote a translate of a Weyl chamber in $\tilde{A}$, so that the tip of $\tilde{\Delta}$ is at $\tilde{x}$, and $\overline{\tilde{x}\tilde{y}} \subset \tilde{\Delta}$. We identify the fundamental weights ϖ_1, ϖ_2 with vectors in $\tilde{A}$ so that $\mu = m_1\mu_1 + m_2\mu_2$, where μ_i are multiples of ϖ_i, $i = 1, 2$. We then replace the segment $\overline{\tilde{x}\tilde{y}}$ with the concatenation

$$\tilde{p} = \pi_{\mu_1} * \pi_{\mu_2} \subset \tilde{\Delta}$$

The path $\tilde{p}$ connects $\tilde{x}$ to $\tilde{y}$.

Lemma 2.12. *Let $h : A \to A$ be a dilation by 2 which fixes a special vertex. Then the path $\tilde{p}$ crosses walls of $\tilde{A}$ transversally only at points v such that $h(v)$ are special verticies.*

Proof: To simplify the notation we identify the apartment $\tilde{A}$ with the model apartment (A, W_{aff}). Suppose first that $\tilde{x}$ is a special vertex. Since $\mu_1 \in P(R)$, the end-point of the path π_{μ_1} is also a special vertex. Thus the paths π_{μ_1}, π_{μ_2} (and therefore $\tilde{p}$) are entirely contained in the 1-dimensional skeleton of the simplicial complex (A, W_{aff}). Therefore these paths cross walls transversally only at the verticies of this complex. However $k_R = 2$ for $R = C_2$ means that for each vertex $v \in (A, W_{aff})$, its image under dilation $h(v)$ is a special vertex. Hence the claim follows in this case.

Suppose that $\tilde{x}$ is not a special vertex. Nevertheless, this point is a vertex of an alcove $a \subset (A, W_{aff})$. The break-point $\tilde{u}$ of the path $\tilde{p}$ is also a vertex of (A, W_{aff}) which has the same type as $\tilde{x}$. Consider now a pair of points $u \in a, s \in A$ which are nonspecial verticies so that the geodesic segment $J = \overline{us} \subset (A, W_{aff})$ is parallel to an element of $W \cdot \varpi_1$ or $W \cdot \varpi_2$. Then for each point v of transversal intersection of J with walls of (A, W_{aff}) we have:

- Either the type $\theta(v)$ of v is a vertex of a, in the case when J is parallel to an element of $W \cdot \varpi_2$,
- Or the type $\theta(v)$ equals $\frac{1}{2}\varpi_2$, in the case when J is parallel to an element of $W \cdot \varpi_1$, see Figure 1.

In either case, $h(v)$ is again a special vertex of (A, W_{aff}). □

Remark 2.13. *The direct generalization of Lemma 2.12 fails in the case of the root system B_3 where the path $\tilde{p}$ is the concatenation of three geodesic segments parallel to the fundamental weights.*

Recall that in [13] we have defined a family of projections $f = Fold_{z,k,\Delta} : X \to \Delta$, where $\Delta \subset A$ is a Weyl chamber with tip at o. Here $k \in \mathbb{N}$, z is a vertex in A. The mapping f is the composition of three maps:

1. A retraction $Fold_{a,A} : X \to A$ with respect to an alcove a containing z.

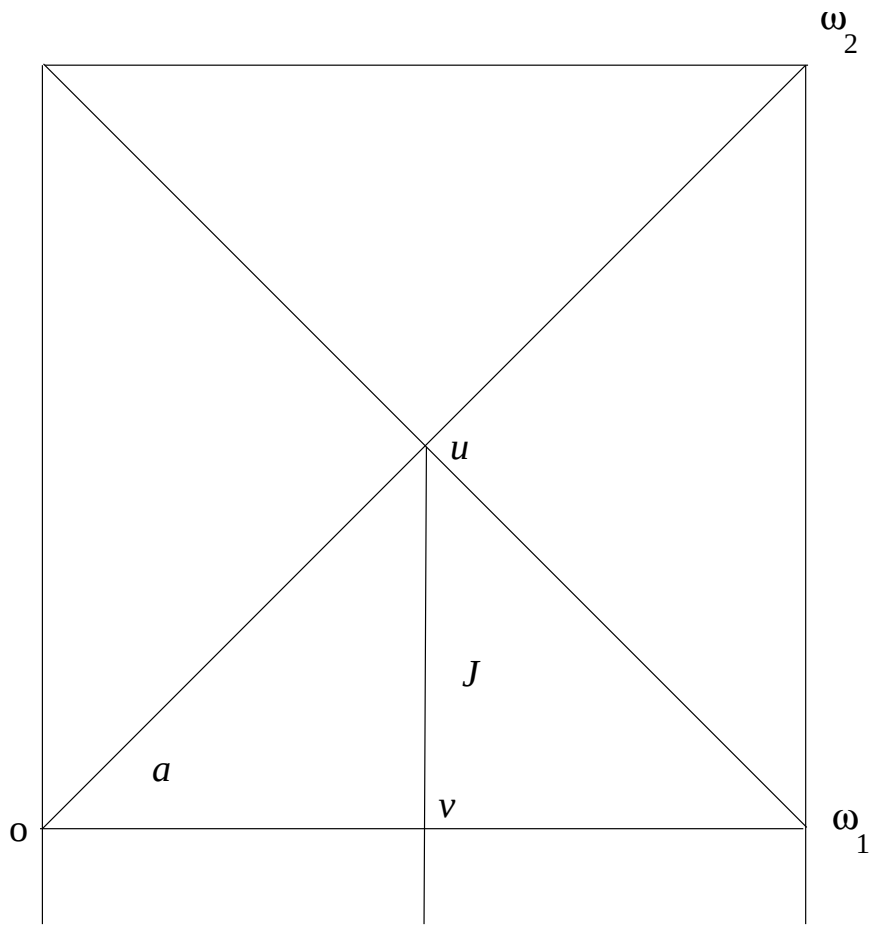

FIGURE 1.

2. Dilation $h : A \to A$ by k so that $h(z) = o$.
3. Projection $\mathbb{P}_\Delta : A \to \Delta$.

Then

$$f = \mathbb{P}_\Delta \circ h \circ Fold_{a,A}.$$

Consider the path

$$p := Fold_{z,2,\Delta}(\tilde{p}),$$

where $z := \tilde{z}$. It was shown in [13] that the path p is in $LS_1(R)$ and

$$\underline{\text{length}}_\Delta(p) = 2\,\underline{\text{length}}_\Delta(\tilde{p}) = 2(\mu_1, \mu_2).$$

It is clear that p is contained in Δ and that this path connects $x := f(\tilde{x})$ to $y := f(\tilde{y})$ where $\overrightarrow{ox} = 2\lambda, \overrightarrow{oy} = 2\nu$. Observation 2.12 implies that all break-points of the path $q := h \circ Fold_{a,A}(\tilde{p})$ are special verticies of A. Their images under the projection $\mathbb{P}_\Delta$ are also special. The projection $\mathbb{P}_\Delta$ may introduce new break-points in the path p (i.e. break-points which are not projections of break-points of q). However such points necessarily belong to the walls of Δ. □

Remark 2.14. *It is proven in Proposition 8.34 of* [12] *that in Part 1 of Theorem 2.11, the assumption that $\lambda + \mu + \nu \in Q(R)$ can be omitted. Theorem 5.3 proven in section 5.4 of the present paper, provides an alternative proof of this result.*

3. Decomposition of $Tens(G)$ into elementary subsets

Definition 3.1. *Call a subset $E \subset \mathbb{Z}^n$* elementary *if it is defined via a finite system of (non-strict, possibly inhomogeneous) linear inequalities with rational coefficients and congruences, i.e. equations of the form $h(x) \in \mathbb{Z}$, where h is a rational linear function.*

Note that each system of congruence conditions on x is equivalent to the requirement that x belongs to a coset of a subgroup in $\mathbb{Z}^n$. By adding a linear equation to the system of inequalities, we can reduce a system of congruence conditions on x to the requirement that $x \in L + z$, where L is a sublattice in $\mathbb{Z}^n$ (i.e. a rank n subgroup) and z is a certain element of $\mathbb{Z}^n$.

The next proposition follows for instance from [7, Theorem 1] (we are grateful to C. Laskowski for this reference), but we give an elementary proof for the sake of completeness.

Proposition 3.2. *If $E \subset \mathbb{Z}^n$ is an elementary subset then its projection to $\mathbb{Z}^{n-1}$ is a finite union of elementary subsets.*

Proof: We let (x, a) denote coordinates in $\mathbb{Z}^n$ so that x is the coordinate in $\mathbb{Z}^{n-1}$. Suppose that the elementary set E is given by the linear inequalities

$$F(x, a) \in (\mathbb{R}_+)^m$$

and congruences $(x, a) \in L$, where L is a translate of a sublattice in $\mathbb{Z}^n$. Therefore, up to changing coordinates via an integer translation, L is a sublattice in $\mathbb{Z}^n$. Since L has finite index in $\mathbb{Z}^n$, there exists an integer κ so that $\kappa \cdot \mathbb{Z}^n \subset L$; therefore L is a union of finitely many cosets

$$L_i := z_i + \kappa \cdot \mathbb{Z}^n.$$

By restricting to the cosets L_i and making the linear changes of variables $(x, a) \to (x, a) - z_i$, we reduce the proof to the case when L has the form $\kappa \cdot \mathbb{Z}^n$, which we assume from now on.

Let $\tilde{P}$ denote the convex polyhedron $\{(x, a) : F(x, a) \in (\mathbb{R}_+)^m\}$. Let P denote the projection of $\tilde{P}$ to $\mathbb{R}^{m-1}$ under the map $p : (x, a) \mapsto x$; this set is again a convex polyhedron. Then we can subdivide P into a finite union of convex polyhedra P_i (each given by a linear system of inequalities with rational coefficients) such that for each i the set $p^{-1}(P_i) \cap \tilde{P}$ is given by the two inequalities

$$g_i(x) \le a \le f_i(x)$$

where g_i, f_i are linear functions with rational coefficients. From now on we fix i and set $f := f_i, g := g_i$: We will show that $p(E) \cap P_i$ is a finite union of elementary sets.

Observe that the restriction of f/κ to $\kappa \cdot \mathbb{Z}^{n-1}$ takes only finitely many values (mod $\mathbb{Z}$)

$$t_j \in [0, 1), j = 1, ..., J.$$

Let Λ_j denote the coset in $\kappa\mathbb{Z}^{n-1}$ such that the value of f/κ on Λ_j equals t_j mod $\mathbb{Z}$. Let $[f(x)/\kappa]$ denote the integer part. Then the condition that there exists $a \in \kappa\mathbb{Z}$ such that

$$g(x) \le a \le f(x)$$

is equivalent to

$$g(x)/\kappa \leq [f(x)/\kappa]$$

i.e.

$$g(x)/\kappa \leq f(x)/\kappa - t_j, x \in \Lambda_j.$$

Therefore the projection of $E \cap p^{-1}(P_i)$ to P_i equals

$$E_{ij} = \bigcup_{j=1}^{J} \{x \in P_i \cap \Lambda_j : g(x) \leq f(x) - \kappa t_j\}.$$

It is clear that each E_{ij} is an elementary set. □

Our next goal is to show that the semigroup $Tens := Tens(G)$ is a finite union of elementary sets, where G is a complex reductive Lie group. Let $L = X^*(T)$ denote the cocharacter lattice of a maximal torus $T \subset G$. We let $\varpi_1, ..., \varpi_\ell$ denote the fundamental weights of G, $\Pi := W \cdot \{\varpi_1, ..., \varpi_\ell\}$, where W is the Weyl group of G. Let $\alpha_1, ..., \alpha_\ell$ denote the simple roots in R. Let $\alpha_i^\vee$ denote the coroots.

For each $\eta \in \Pi$ let $\iota(\eta)$ denote the number i such that $\eta \in W \cdot \varpi_i$. Let Σ denote the set of *generalized chains* σ in Π, i.e. sequences

$$\eta_0 \gtrsim \eta_1 \gtrsim ... \gtrsim \eta_m$$

of elements of Π so that

$$\iota(\eta_0) \leq \iota(\eta_1) \leq ... \leq \iota(\eta_m).$$

Let Σ_{max} denote the collection of *maximal* generalized chains as above, i.e. chains of maximal length from η_0 to η_m.

Let $\lambda, \mu, \nu \in \Delta \cap L$ be dominant characters,

$$\mu = \sum_{i=1}^{\ell} n_i \varpi_i.$$

We consider broken geodesic paths $\pi : [0, 1] \to V = P(R) \otimes \mathbb{R}$ modeled on the chain σ as above, with $p(0) = 0$, i.e. concatenations of paths

$$\pi_{a_i \eta_i}, i = 0, ..., m,$$

where $a_i \in \frac{1}{k_R^2}\mathbb{Z}$, $a_i \geq 0$. We require that

$$\underline{\text{length}}_\Delta(\pi) = (n_1 \varpi_1, ..., n_\ell \varpi_\ell).$$

This means that

$$a_1 + ... + a_{J_1} = n_1, a_{J_1+1} + ... + a_{J_2+2} = n_2, ...$$

We define the partial sums

$$S_r = \sum_{j=1}^{r} a_j \eta_j$$

for $1 \leq r \leq m$. Observe that $\iota(\eta_r) = \iota(\eta_{r+1})$ if nd only if there exists a reflection $\tau_r = \tau_{\alpha_r^\vee}$ which carries η_r to η_{r+1}. Then the path π is a generalized LS path if and only if the following condition is satisfied:

For each r such that $\iota(\eta_r) = \iota(\eta_{r+1})$ we have

$$\alpha_r^\vee(S_r) = \sum_{j=1}^{r} a_j \alpha_r^\vee(\eta_j) \in \mathbb{Z}.$$

Note that these conditions imply that if $\iota(\eta_r) \neq \iota(\eta_{r+1})$ then S_r is necessarily a special vertex, i.e. all coroots take integer values at this point.

Since $\alpha_r^\vee(\eta_j) \in \mathbb{Z}$ for all r, j, it follows that the above integrality condition is a *congruence* condition on the m-tuple $a = (a_0, ..., a_m)$.

According to Theorem 2.8, we have: $(\lambda, \mu, \nu) \in Tens(G)$ if and only if there exists a generalized LS path π as above so that:

(1) $\lambda + \pi(1) = \nu^*$.

(2) The entire path $\lambda + \pi(t)$ is contained in the positive chamber Δ, i.e. for each simple coroot $\alpha^\vee$ and each partial sum

$$S_r = \sum_{j=1}^{r} a_j \eta_j$$

we have:

$$\alpha^\vee(\lambda + S_r) \geq 0.$$

Let $\lambda = \sum_{i=1}^{\ell} m_i \varpi_i$, $\nu = \sum_{i=1}^{\ell} k_i \varpi_i$. Set

$$x := (m_1, ..., m_\ell, n_1, ..., n_\ell, k_1, ..., k_\ell).$$

Note that the condition (1) is a linear equation with integer coefficients on the vector a and the condition (2) has the form of a system of linear inequalities with integer coefficients. Therefore for each generalized chain σ as above, the set

$$E_\sigma := \{(x, a) : \lambda + p(1) = \gamma^*, \alpha^\vee(\lambda + S_r) \geq 0, \forall \alpha \in \Phi, \text{and } \alpha_r^\vee(S_r) \in \mathbb{Z}, r = 0, ..., m-1\}$$

is an elementary set.

Remark 3.3. *Instead of using path model in the above argument one can use the polytopal model from* [3].

Consider the projection $p(E_\sigma)$ of E_σ to the x-coordinate. By applying Proposition 3.2 inductively we conclude that $p(E_\sigma)$ is a finite union of elementary sets. Therefore the union

$$Tens(G) = \bigcup_{\sigma \in \Sigma_{max}} p(E_\sigma)$$

is also a finite union of elementary sets.

Thus we have proved the following analogue of Laskowski's theorem in [17]:

Theorem 3.4. *The semigroup $Tens(G)$ is a finite union of elementary sets.*

4. Deep subcone

The goal of this section is to show that deep inside of the cone $D_3 = \mathcal{P}(G)$ there is a subcone of the form $D_3 + \sigma$ (for some $\sigma \in D_3$), such that

$$(D_3 + \sigma) \cap \Lambda \subset Tens(G).$$

We will also present an explicit computation of this subcone for the root system B_ℓ. In what follows we normalize the roots so that the Euclidean norm of each coroot is either 1 or 2.

Given an irreducible representation V_λ let $Weight(V_\lambda) \subset P(R)$ denote the set of weights of V_λ. Define the set

$$S_3(G)^{1,2} := \{(\lambda, \mu, \nu) \in \Delta^3 : \lambda \gg \mu, \nu^* = \lambda + \beta, \text{for some } \beta \in Weight(V_\mu)\}$$

Here $\lambda \gg \mu$ iff $\lambda + \beta \in \Delta$ for all $\beta \in Weight(V_\mu)$.

Below we give a more explicit description of the above subset $S_3(G)^{1,2}$ in terms of linear inequalities and congruences.

We will be using the following notation: If $C \subset V$ is a convex subset then $\lambda \geq_C \mu$ iff $\mu - \lambda \in C$. We use the notation Δ^* for the convex cone *dual to* Δ, i.e.

$$\Delta^* = \{v \in V : v \cdot u \geq 0, \forall u \in V\}.$$

Define the lattice

$$\Lambda = \{(\mu, \nu, \lambda) : \mu, \nu, \lambda \in L, \lambda + \mu + \nu \in Q(R)\},$$

where $L = X^*(T)$. We let $C^{1,2}$ be convex polyhedral cone in Δ^3 given by the following inequalities:

1.
$$w\mu^* \leq_\Delta \lambda, \quad \forall w \in W.$$

2.
$$w\nu^* \leq_{\Delta^*} w\lambda + \mu, \quad \forall w \in W.$$

Proposition 4.1.

$$S_3(G)^{1,2} = C^{1,2} \cap \Lambda.$$

Proof:

Lemma 4.2.

$$\lambda \gg \mu \iff w\mu^* \leq_\Delta \lambda, \quad \forall w \in W.$$

Proof: First let's check that if $\lambda + w\mu \in \Delta$ for all $w \in W$ then

$$\lambda + \beta \in \Delta, \forall \beta \in Weight(V_\mu).$$

Indeed, let $\beta \in Weight(V_\mu)$. We write β as a convex combination of extreme weights $\{w\mu, w \in W\}$:

$$\beta = \sum_{w \in W} t_w(w\mu), \sum_{w \in W} t_w = 1, 0 \leq t_w \leq 1.$$

Then

$$\lambda + \beta = \lambda + \sum_{w \in W} t_w(w\mu) = \sum_{w \in W} t_w\lambda + \sum_{w \in W} t_w(w\mu) = \sum_{w \in W} t_w(\lambda + w\mu).$$

By assumption, $\lambda + w\mu \in \Delta$. Since Δ is convex, $\lambda + \beta \in \Delta$ as well. Therefore

$$\lambda \gg \mu \iff \lambda + w\mu \geq_\Delta 0, \forall w \in W \iff \lambda + ww_0\mu \geq_\Delta 0, \forall w \in W,$$

where $w_0 \in W$ is the longest element.

$$\lambda + ww_0\mu \geq_\Delta 0 \iff ww_0(-\mu) \leq_\Delta \lambda \iff w\mu^* \leq_\Delta \lambda,$$

since $\mu^* = w_0(-\mu)$. □

We refer the reader to [9] for the proof of the following:

Lemma 4.3. *For a dominant weight μ and a weight β we have*

$$\beta \in Weight(V_\mu) \iff w\beta \leq_{\Delta^*} \mu, \ \forall w \in W, \ \textit{and } \mu - \beta \in Q(R).$$

Lemma 4.4. *Let λ, μ, ν be dominant weights. Then*

$$\nu^* = \lambda + \beta, \ \textit{for some } \beta \in Weight(V_\mu)$$

if and only if

$$w\nu^* \leq_{\Delta^*} w\lambda + \mu, \ \textit{and } \mu - \nu^* + \lambda \in Q(R).$$

Proof:

$$\nu^* - \lambda \in Weight(V_\mu) \iff w(\nu^* - \lambda) \leq_{\Delta^*} \mu, \forall w \in W, \text{ and } \mu - (\nu^* - \lambda) \in Q(R).$$

□

It remains to prove

Lemma 4.5.

$$\mu - \nu^* + \lambda \in Q(R) \iff \mu + \nu + \lambda \in Q(R).$$

Proof: It suffices to prove that $\mu - \nu^* + \lambda - (\mu + \nu + \lambda) \in Q(R)$, equivalently,

$$\nu + \nu^* = \nu - w_0\nu \in Q(R).$$

However for each $\nu \in P(R), w \in W$ we have $w\nu \in Weight(V_\nu)$, therefore

$$\nu - w\nu \in Q(R),$$

by Lemma 4.3. □

This concludes the proof of Proposition 4.1. □

The following result is standard, we are grateful to T. Haines and S. Kumar for pointing out this result to us and explaining the proofs:

Theorem 4.6. *The subset $S_3(X)^{1,2}$ is contained in $Tens(G)$.*

Proof: We will present the proof of this result using Littelmann's path model.

We need the following

Lemma 4.7. *Suppose that p is an LS path of Δ-length μ. Then the path p is entirely contained in the convex hull of the W-orbit $S := W(\mu)$.*

Proof: By definition of an LS path, for each $t \in [0,1]$ there exist $t_i \geq 0$ and $\nu_i \in W\mu$ such that

$$t = t_1 + ... + t_j$$

and

$$p(t) = t_1\nu_1 + ... + t_j\nu_j.$$

Therefore, since $t \in [0,1]$, and the convex hull of S contains the origin, the subconvex combination $p(t)$ is contained in the convex hull of S. □

Suppose now that $\sigma = (\lambda, \mu, \nu) \in S_3(X)^{1,2}$. Then $\nu^* = \lambda + \beta$ for some weight vector β of the representation V_μ. Then, according to [18], there exists an LS path p of the Δ-length μ such that $p(0) = 0, p(1) = \beta$. By the above Lemma, the path p is entirely contained in the convex hull of $W\mu$. Consider the path $q(t) := \lambda + p(t)$. We claim that this path is entirely contained in Δ. Indeed,

$$q(t) \in \lambda + Hull(W\mu).$$

Since $\lambda \gg \mu$, for each vector $\gamma \in W \cdot \mu$, we have:

$$\lambda + \gamma \in \Delta.$$

Thus $\lambda + Hull(W\mu) \subset \Delta$. On the other hand, $q(1) = \lambda + \beta = \nu^*$. Therefore, according to Theorem 2.8, $(\lambda, \mu, \nu) \in Tens(G)$. □

We next observe that the cone $C^{1,2}$ has nonempty interior. Indeed, first choose $\mu \in Int(\Delta)$. Then take $\lambda \in \Delta$ such that

$$d(\lambda, \partial\Delta) > |\mu|.$$

Finally, pick ν^* sufficiently close to λ so that

$$|\lambda - \nu^*| < d(\mu, \partial\Delta^*).$$

Any triple (λ, μ, ν) chosen like this satisfies the strict inequalities

$$w\mu^* <_\Delta \lambda, \quad \forall w \in W, \tag{1}$$

$$w\nu^* <_{\Delta^*} w\lambda + \mu, \quad \forall w \in W. \tag{2}$$

and therefore belongs to the interior of $C^{1,2}$. Our next goal is to apply the above observations to show that the cone $\mathcal{P}(G)$ contains a subcone $\sigma + \mathcal{P}(G)$ such that

$$\sigma + \mathcal{P}(G) \cap \Lambda = Tens(G) \cap \Lambda.$$

Since $C^{1,2}$ is a homogeneous cone with nonempty interior, it contains metric balls $B(\sigma_0, R)$ of arbitrarily large radius R. Let $k := k_R k_w$. Choose R larger than the diameter of a fundamental domain F for the lattice $k \cdot P(R)$. (Here F is a certain fundamental parallelepiped containing the origin.) Without loss of generality we assume that the ball $B(\sigma_0, R)$ is centered at a point $\sigma_0 \in k \cdot P(R)$.

Suppose now that $\tau \in \Lambda \cap D_3(X)$. Then there exists a point $\sigma \in k \cdot P(R)$ such that $\tau \in F + \sigma$. Let $\kappa := \sigma - \sigma_0$. Since

$$F + \sigma = (F + \sigma_0) + \kappa,$$

there exists a point $\tau_0 \in F + \sigma_0$ such that $\tau = \tau_0 + \kappa$.

Note that $k \cdot P(R) \subset Q(R)$, since the index $|P(R) : Q(R)|$ divides $k_R k_w$, see [12], Table 11. Therefore

$$\sigma_0 \in k \cdot P(R)^3 \subset \Lambda$$

and hence $\tau_0 = \tau - \kappa = \tau - \sigma + \sigma_0 \in \Lambda$. Since $diam(F) \leq R$, $F + \sigma_0$ is contained in $B(\sigma_0, R) \subset C^{1,2}$. Therefore, by Theorem 4.6, $\tau_0 \in F + \sigma_0 \subset C^{1,2} \subset Tens(G)$. By the triangle inequality, if

$$d(\tau, \partial D_3(X)) \geq |\sigma_0| + diam(F),$$

then $\kappa = \sigma - \sigma_0$ belongs to $\mathcal{P}(G)$. On the other hand, since $\sigma, \sigma_0 \in k \cdot P(R)$, it follows that $\kappa \in k \cdot P(R)$ and therefore, by the saturation theorem,

$$\kappa \in Tens(G).$$

Therefore, since $\tau_0 \in Tens(G)$ and $Tens(G)$ is a semigroup, it follows that

$$\tau = \tau_0 + \kappa$$

also belongs to $Tens(G)$. Hence we have proven

Theorem 4.8. *Suppose that $\tau \in \mathcal{P}(G) \cap \Lambda$ is such that $d(\tau, \partial\mathcal{P}(G)) \geq |\sigma_0| + diam(F)$. Then $\tau \in Tens(G)$.*

Next, the linear inequalities defining $\mathcal{P}(G)$ have the form

$$\psi_j(x) \geq 0,$$

where either $|\psi_j| \leq 2$ (in the case of the inequalities $\psi_j \geq 0$ defining the chamber Δ) or $|\psi_j| = \sqrt{3}|\varpi_{i_j}|$ for a certain fundamental weight ϖ_{i_j} (in the case of the stability inequalities). Here we are using the Euclidean norm of linear functionals. Set $m := \max_i |\varpi_i|$ and note that, because of our normalization of the lengths of the coroots, $m \geq 2$. Therefore,

$$\max_j |\psi_j| = m.$$

Suppose that $\tau - \kappa \in \partial\mathcal{P}(G)$. Then there exists some ψ_j such that $\psi_j(\tau - \kappa) = 0$, i.e.

$$|\psi_j(\tau)| = |\psi_j(\kappa)| \leq |\psi_j| \cdot |\kappa| \leq m|\kappa|$$

and $|\kappa| \geq |\psi_j(\tau)|/m$. Thus, if

$$\psi_j(\tau) \geq m(|\sigma_0| + diam(F)), \forall j,$$

then $d(\tau, \partial\mathcal{P}(G)) \geq |\sigma_0| + diam(F)$. Therefore, if we define an inhomogeneous subcone $\mathcal{P}'(G)$ in $\mathcal{P}(G)$ by the linear inequalities

$$\psi_j(\tau) \geq m(|\sigma_0| + diam(F)), \forall j,$$

we obtain:

Corollary 4.9. *The intersection $\mathcal{P}'(G) \cap \Lambda$ is contained in $Tens(G)$.*

Below we make an explicit computation for the root system $R = B_\ell$ (i.e. when $G = Sp(2\ell, \mathbb{C})$). We use the Bourbaki coordinates [4], to describe this root system. Since for this root system $w_0 = -1$, it follows that $\lambda = \lambda^*$ for each $\lambda \in \Delta$. We let $\{\epsilon_i\}$ denote the standard orthonormal basis in V. Then for each i, $\varpi_i = \sum_{j=1}^{i} \epsilon_i$. Moreover, the simple roots are $\alpha_i = \epsilon_{i-1} - \epsilon_i$, $i < \ell$ and $\alpha_\ell = \epsilon_\ell$. The positive chamber Δ is given by the inequalities $\alpha_i \cdot v \geq 0, i = 1, ..., \ell$.

Theorem 4.10. *Suppose that $R = B_\ell$ ($\ell \geq 2$), and $\tau \in \Lambda$ is such that for each linear functional ψ which appears in the system of stability inequalities and chamber inequalities we have:*

$$\psi(\tau) \geq 2\ell^2(\ell+1)(4\ell+5) + 6\ell. \tag{3}$$

Then $\tau \in Tens(Sp(2\ell, \mathbb{C}))$.

Proof: We will use the notation from the proof of Theorem 4.8. In order for τ to be in $Tens(Sp(2\ell, \mathbb{C}))$ we need two things:

$$\sigma_0 + F \subset C^{1,2} \tag{4}$$

and

$$\kappa = \tau - \tau_0 \in \mathcal{P}(G), \quad \forall \tau_0 \in F + \sigma_0. \tag{5}$$

We simplify the discussion by observing that in the case of the root system B_ℓ we have $k = k_R = k_w = k_G = 2$ (using the notation of [12]), which means that instead of working with the lattice Λ we can work with the lattice L^3, where $L = P(R^\vee)$:

According to Part 2 of Theorem 2.10, for each $\sigma \in L^3 \cap \mathcal{P}(G)$, the vector $k^2\sigma$ belongs to $Tens(G)$.

The lattice L is just the integer lattice in $\mathbb{R}^\ell$ (using Bourbaki coordinates). Therefore we choose the fundamental domain F for the sublattice $(4L)^3$ to be the cube whose edges have length 4 and which is centered at the origin.

The condition (5) would follow from:

$$\psi_j(\tau) \geq \psi_j(\tau_0)$$

which in turn is implied by

$$\psi_j(\tau) \geq \psi_j(\sigma_0) + \max_{f \in F}\{\psi_j(f)\}. \tag{6}$$

Remark 4.11. *$M = \max_{j, f \in F}\{\psi_j(f)\}$ equals the maximum of all ψ_j's on the set of points in V^3 with coordinates $\in \{0, \pm 1, \pm 2\}$. Here $V = P(R) \otimes \mathbb{R}$*

In what follows we will use the norm

$$\|(v_1, ..., v_\ell)\| = \sum_{i=1}^{\ell} |v_i|$$

for vectors $v \in V$.

For the linear functionals ψ_j which come from the stability inequalities, the maximum

$$\max_{f \in F} \psi_j(f)$$

does not exceed $6\|\varpi_\ell\| = 6\ell$. If the inequality $\psi_j \geq 0$ is one of the chamber inequalities, then $\psi_j(f) \leq 4 \leq 6\ell$ for all $f \in F$. Thus $M \leq 6\ell$.

Hence for the root system B_ℓ to guarantee (6) (and hence (5)) it suffices to require that

$$\psi_j(\tau) \geq \psi_j(\sigma_0) + 6\ell, \forall j. \tag{7}$$

To get an explicit estimate we have to choose an appropriate $\sigma_0 = (\lambda_0, \mu_0, \nu_0)$. Set

$$\mu_0 := (4\ell, ..., 8, 4),$$

$a := 4\ell + 8, s := 8\ell + 4$ and

$$\nu_0 = \lambda_0 := (a + (\ell - 1)s, ..., a + 2s, a + s, a).$$

Clearly $\lambda_0, \mu_0, \nu_0 \in \Delta \cap 4P(R)$.

Observe that

$$\|\mu_0\| = 2\ell(\ell + 1),$$

$$\|\lambda_0\| = \|\nu_0\| = a\ell + s\frac{\ell(\ell - 1)}{2} = \ell(a + \frac{s\ell - s}{2}) = \ell(4\ell^2 + 2\ell + 6) \leq 4\ell(\ell + 1)^2.$$

Therefore for each linear functional ψ of the form

$$\psi(\lambda, \mu, \nu) = w_1\lambda \cdot \varpi_i + w_2\mu \cdot \varpi_i + w_3\nu \cdot \varpi_i$$

we obtain:

$$|\psi(\sigma_0)| \leq |\varpi_i|(\|\lambda_0\| + \|\mu_0\| + \|\nu_0\|) \leq \ell(8\ell(\ell + 1)^2 + 2\ell(\ell + 1)) = 2\ell^2(\ell + 1)(4\ell + 5).$$

Therefore (7) follows from

$$\psi(\tau) \geq 2\ell^2(\ell + 1)(4\ell + 5) + 6\ell, \forall \psi. \tag{8}$$

We now consider the condition (4), i.e. that each

$$(\lambda, \mu, \nu) = \sigma_0 + f, f \in F,$$

satisfies

$$w\mu \leq_\Delta \lambda, \forall w \in W, \tag{9}$$

and

$$w\nu \leq_{\Delta^*} w\lambda + \mu, \forall w \in W. \tag{10}$$

Let ϕ_{ij} denote the linear functionals of the form

$$\phi_{ij}(\lambda, \mu, \nu) = \alpha_i \cdot (\lambda - w_j\mu)$$

where α_i is a simple root and $w_j \in W$.

Let η_{ij} denote the linear functionals of the form

$$\eta_{ij}(\lambda, \mu, \nu) = \varpi_i \cdot (w_j\lambda + \mu - w_j\nu), w_j \in W.$$

Then to guarantee (9) and (10) we need:

$$\phi_{ij}(\sigma_0) \geq \phi_{ij}(f), \forall f \in F, \tag{11}$$

and

$$\eta_{ij}(\sigma_0) \geq \eta_{ij}(f), \forall f \in F \tag{12}$$

respectively.

We first consider (12) since it is simpler. Since $\nu_0 = \lambda_0$, the inequality (12) reads as

$$\varpi_i \cdot \mu_0 \geq \eta_{ij}(f), \forall f \in F.$$

The right hand side of this inequality is $\leq 6i$, while the left hand-side equals

$$2(\ell + i)(\ell + 1 - i).$$

It is clear that for $1 \leq i \leq \ell$ and each $\ell \geq 2$ we have:

$$2(\ell + i)(\ell + 1 - i) \geq 2(\ell^2 - i^2) + 2(\ell + 1)(\ell + i) \geq 6(\ell + i) \geq 6i.$$

This takes care of the condition (12).

Now consider (11). First note that $\phi_{ij}(f) \leq 8$ for all i, j and $f \in F$. Next, for all $w \in W$ we have

$$\alpha_i \cdot (w\mu_0) \leq 8\ell - 4$$

for each $i = 1, ..., \ell - 1$ and

$$\alpha_\ell \cdot (w\mu_0) \leq 4\ell.$$

On the other hand,

$$\phi_{ij}(\sigma_0) = \alpha_i \cdot (\lambda_0 - w_j\mu_0) = \alpha_i \cdot \lambda_0 - \alpha_i \cdot (w_j\mu_0).$$

We have:

$$\alpha_i \cdot \lambda_0 = s, \forall i < \ell$$

and

$$\alpha_\ell \cdot \lambda_0 = a.$$

Therefore for $i = 1, ..., \ell - 1$,

$$\phi_{ij}(\sigma_0) - \phi_{ij}(f) \geq s - 8\ell + 4 - 8 = (8\ell + 4) - 8\ell - 4 = 0$$

and for $i = \ell$

$$\phi_{ij}(\sigma_0) - \phi_{ij}(f) \geq a - (4\ell + 8) = (4\ell + 8) - (4\ell + 8) = 0.$$

Therefore the condition (11) holds. Hence the inequality (8) implies that $\tau \in Tens(Sp(2\ell, \mathbb{C}))$. □

Conjecture 4.12. *Suppose that G is a complex semisimple Lie group, S is a stratum in the boundary of the cone $\mathcal{P}(G)$ which contains a point (λ, μ, ν) such that all the vectors λ, μ, ν are regular. Then there exists a subcone $S + \sigma \subset S$ such that*

$$S + \sigma \cap \Lambda = (S + \sigma) \cap Tens(G)$$

5. Computation of the semigroup $Tens(Sp(4, \mathbb{C}))$

Let V be $\mathbb{R}^2$ with the coordinates x, y and Euclidean metric. Let A denote the underlying affine space. Let $R := C_2 \subset V$ and $R^\vee = B_2 \subset V^* = V$ be root systems with the sets of simple roots equal to $\{\alpha_1(x, y) = x - y, \alpha_2(x, y) = y\}$ and $\{\alpha_1^\vee(x, y) = x - y, \alpha_2^\vee(x, y) = 2y\}$ respectively. The fundamental weights of C_2 are $\varpi_1 = (1, 0), \varpi_2 = (1, 1)$; the root lattice is

$$Q(R) = \{(x, y) \in \mathbb{Z}^2 : x + y \in 2\mathbb{Z}\}$$

and the weight lattice is $P(R) = \mathbb{Z}^2$.

Let $W_{aff} := W_{R^\vee,aff}, W^\vee_{aff} := W_{R,aff}$ denote the affine Weyl groups acting on A corresponding to the root systems R and $R^\vee$ respectively. Note that $W_{aff} \subset W^\vee_{aff}$ is a subgroup of index 2, so that all verticies of (A, W_{aff}) are special verticies of $(A, W^\vee_{aff})$. The root lattice $Q(R)$ equals the translation subgroup of W_{aff} and the weight lattice $P(R)$ is the normalizer of W_{aff} in the group of Euclidean translations of A.

Our goal is to compute the semigroup $Tens = Tens(R)$, for $R = C_2$. We know (from [12]) that each triple $\sigma = (\lambda, \mu, \nu) \in Tens$ satisfies:

1. $\sigma \in D_3 := D_3(C_2)$.
2. $\sigma \in P(R)^3$.
3. $\lambda + \mu + \nu \in Q(R)$.

It was shown in [12] that these conditions are necessary but not sufficient for σ to be in $Tens$. The goal of this chapter to find *necessary and sufficient conditions.*

We start by observing that since $\lambda + \mu + \nu \in Q(R)$, it follows that at least one of the vectors λ, μ, ν belongs to $Q(R)$.

Convention 5.1. *Throughout the rest of the paper we will assume that $\mu \in Q(R)$.*

Notation 5.2. *We break the vector μ as $\mu = \mu_1 + \mu_2$, where $\mu_i = n_i \varpi_i$,*

$$\mu_1 = (n_1, 0), \mu_2 = (n_2, n_2), \mu = (n_1 + n_2, n_2).$$

Since $\mu, \mu_2 \in Q(R)$, it follows that $\mu_1 \in Q(R)$ as well, i.e. n_1 is even.

Theorem 5.3. *Suppose that $\sigma \in D_3(R) \cap P(R)^3$ is such that $\lambda + \mu + \nu \in Q(R)$. Then $\sigma \notin Tens$ if and only if two of the three vectors λ, μ, ν belong to $\mathbb{N}\varpi_2$ and $\lambda + \mu + \nu \notin 2P(R)$.*

Proof: The proof of this theorem occupies the rest of this chapter. Our strategy is to analyze the geometry of generalized LS paths with respect to the root system $2R$ and show that all such paths (subject to the condition on λ, μ, ν described in the above theorem) can be transformed to generalized LS paths with respect to the root system R. We first do this in the case of *singular* paths $p_i \in LS(2R)$ with $\text{length}_\Delta(p_i) \in \mathbb{N}\varpi_i$ (section 5.2) and then use the results to deal with the general $LS_1(2R)$ paths $p = p_1 * p_2$ (section 5.3). We are able to carry out this approach largely thanks to the fact that the root system C_2 is rather small and there are not that many chains formed by elements of $W \cdot \varpi_i, i = 1, 2$. This allows us to describe the paths in $LS_1(2R)$ rather explicitely. A large supply of $LS_1(2R)$ paths is given by the Saturation Theorem 2.11 which is another key tool in the proof.

To get an idea how the proof of Theorem 5.3 might proceed, consider the case when $\lambda, \mu, \nu \in Q(R)$ (i.e. the problem of decomposing tensor products of representations of $PSp(4, \mathbb{C})$). Then $\lambda, \mu, \nu \in 2P(R^\vee)$ and, according to Proposition 8.34 of [12],

$$(\lambda, \mu, \nu) \in Tens(R^\vee).$$

Therefore there exists a path $p \in LS_1(R^\vee)$ contained in Δ connecting λ to ν and having

$$\underline{\text{length}}_\Delta(p) = (\mu_1, \mu_2).$$

If we are lucky, all break-points of p occur at special verticies of $(A, W_{aff}^{\vee})$ (compare Theorem 2.11), hence they are at the verticies of (A, W_{aff}), see Corollary 5.10. The key then is to replace p with a new $LS_1(R^{\vee})$ path $\hat{p}$ contained in Δ whose break-points occur at the special verticies of (A, W_{aff}), the crucial lemmas proving this are Lemmas 5.13, 5.14. This would imply that $\hat{p}$ is an $LS_1(R)$ path and $(\lambda, \mu, \nu) \in Tens(R)$.

5.1. **Analysis of the $LS_1(R)$ paths.** In this section we describe generalized LS paths p with respect to the root system R. Recall that every such path is a concatenation

$$p = p_1 * p_2, \quad \text{length}_{\Delta}(p_i) \in \mathbb{N}\varpi_i, i = 1, 2,$$

where each p_i is an LS path. Let τ_i denote the reflections in the walls $\{\alpha_i = 0\}$, $i = 1, 2$.

Suppose that p is a PL path in A parameterized with the constant speed. We say that t (or $p(t)$) is a *break-point* of p, if p is not geodesic at t.

Definition 5.4. *We will call a break-point $p(t)$* a turning point *if the vectors $p'_-(t)$, $p'_+(t)$ are linearly independent and* a point of backtracking *if $p'_-(t) = -p'_+(t)$.*

Note that for $\eta \in V$, each chain in $W\eta$ can be extended to a chain which starts in $-\Delta$ and ends in Δ. We leave the proof of the following lemma to the reader:

Lemma 5.5. *Suppose that $\eta \in \{\varpi_1, \varpi_2\}$. Then every maximal chain in $W(\eta)$ has to be of the form:*

$$\eta_0, \eta_1 = \tau_1(\eta_0), \eta_2 = \tau_2(\eta_1), \ldots.$$

or

$$\eta_0, \eta_1 = \tau_2(\eta_0), \eta_2 = \tau_1(\eta_1), \ldots.$$

By combining these observations, we see that each chain in $W(\varpi_1)$ is a subchain of:

$$\eta_1 = -\varpi_1, \eta_2 = \tau_2(\eta_1), \eta_3 = \tau_1(\eta_2), \eta_4 = \tau_2(\eta_3) = \varpi_1$$

and each chain in $W(\varpi_2)$ is a subchain of:

$$\eta_1 = -\varpi_2, \eta_2 = \tau_1(\eta_1), \eta_3 = \tau_2(\eta_2), \eta_4 = \tau_1(\eta_3) = \varpi_2.$$

Accordingly, each $LS(R)$ path p with $\text{length}_{\Delta}(p) \in \mathbb{N}\varpi_1$ has the shape as in Figure 2 and each $LS(R)$ path with $\text{length}_{\Delta}(p) \in \mathbb{N}\varpi_2$ has the shape as in Figure 3. (Some of the geodesic segments in p described in these figures could have zero length.)

Lemma 5.6. *Suppose p is an LS path with respect to $2R$ so that $p(0)$ is a special vertex of (A, W_{aff}), $\text{length}_{\Delta}(p) = \mu \in \mathbb{N} \cdot \varpi_1$ and all breaks of p are at the verticies of (A, W_{aff}). Then:*

1. *p has breaks only at the special verticies of (A, W_{aff})*
2. *p_1 is an LS path with respect to R.*
3. *If $\mu \in 2\mathbb{N}\varpi_1$, then $p_1(0) - p_1(1) \in Q(R)$.*

Proof: 1. Observe that our assumptions imply that the path p_1 has edges parallel to the coordinate axes and it is entirely contained in the 1-skeleton of the simplicial complex (A, W_{aff}). Let v be a non-special vertex of (A, W_{aff}). Then v is disjoint

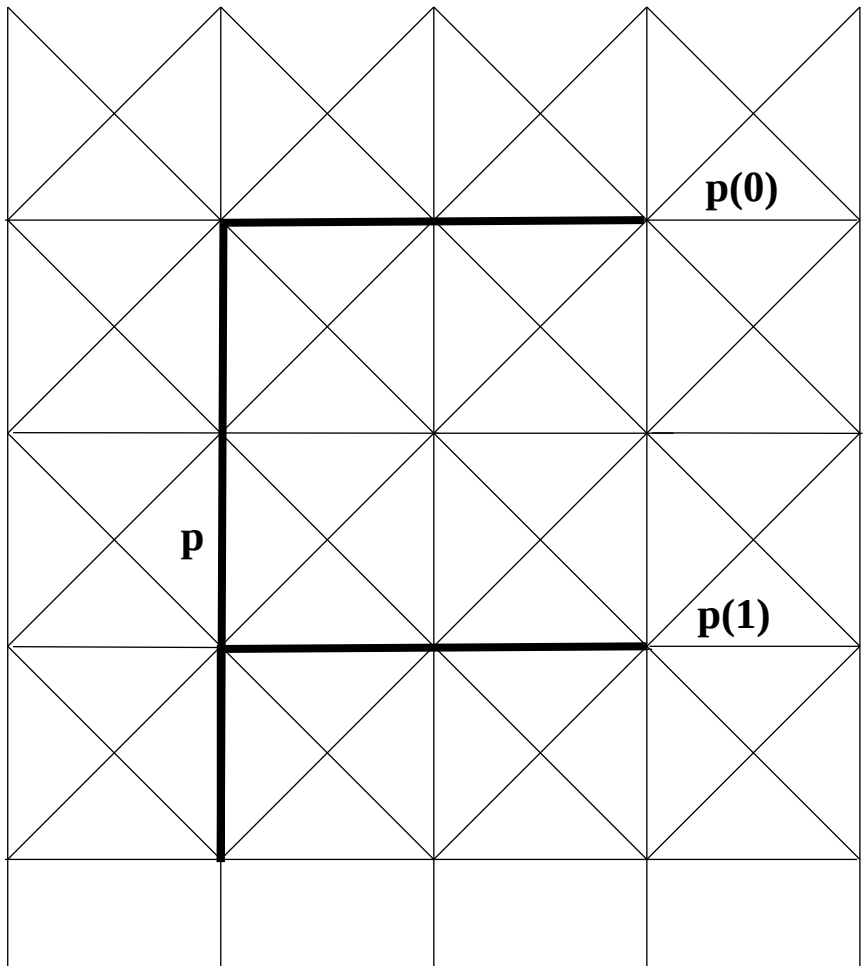

FIGURE 2.

from all the edges of (A, W_{aff}) parallel to the coordinate axes. Therefore the path p_1 is disjoint from the set of nonspecial verticies.

2. Suppose that $v = p(t)$ is a break-point of p. Since v is a special vertex of (A, W_{aff}), the chain condition in the definition of an LS path (with respect to R) at v follows from the chain condition with respect to $2R$.

3. Since $p \in LS(R)$, it follows from Lemma 2.9 that

$$p_1(0) - p_1(1) - \mu \in Q(R).$$

Since $\mu \in 2\mathbb{N} \cdot \varpi_1 \subset Q(R)$, the last assertion of Lemma follows. □

Corollary 5.7. *Suppose that p is an $LS(R)$–path with* $\mathrm{length}_\Delta(p) \in \mathbb{N}\varpi_1$. *Then p has breaks only at the special verticies of (A, W_{aff}).*

Lemma 5.8. *Suppose that $p = p_1 * p_2 \in LS_1(R)$. Then p can have at most one break-point which is not a special vertex of (A, W_{aff}); such a point is a point of backtracking of the sub-path p_2.*

Proof: By the previous lemma, the path p_1 can have breaks only at the special verticies of (A, W_{aff}). Consider the path p_2. Suppose that a break-point $p(t)$ is a *turning point*

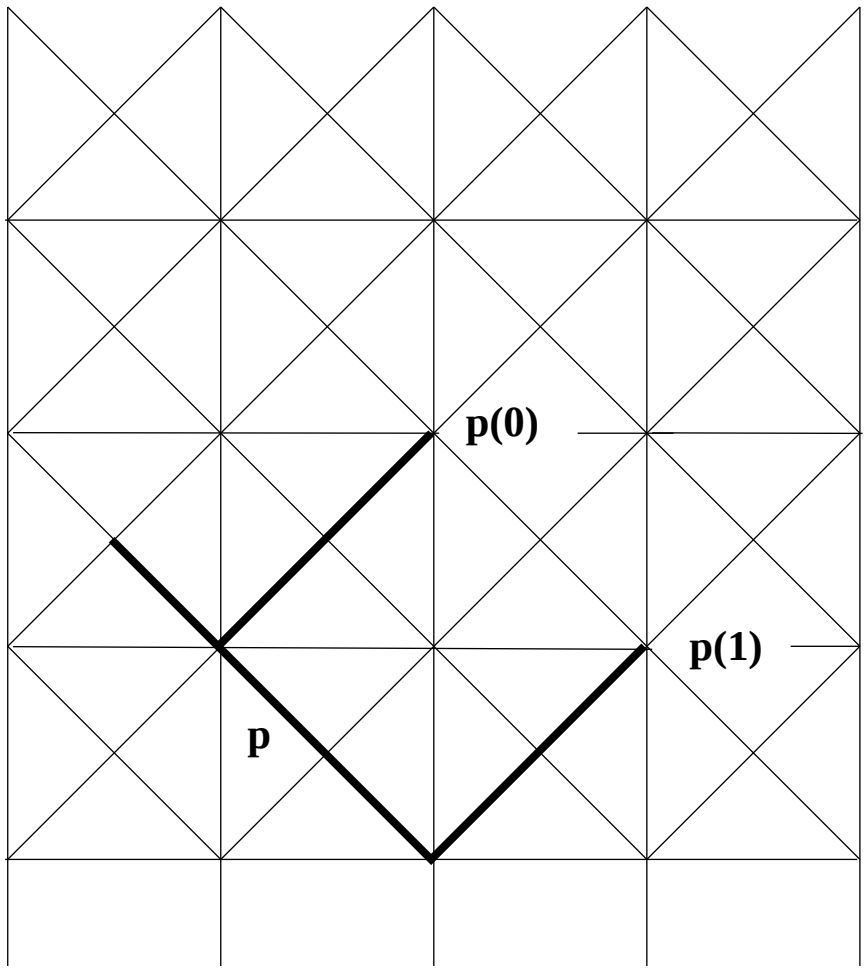

FIGURE 3.

of p; let $\tau \in W_{aff}$ denote the reflection fixing $p(t)$ which sends $p'_-(t)$ to $p'_+(t)$. The vectors $p'_-(t)$, $p'_+(t) \in T_{p(t)}A$ are tangent to the walls H_-, H_+ of (A, W_{aff}) which are parallel to the lines $\{x = y\}, \{x = -y\}$. The linear part of τ permutes H_-, H_+, hence τ is the reflection in a wall which is either vertical or horizontal. Therefore $p(t)$ is a special vertex of (A, W_{aff}).

Hence, if a break-point p is non-special, then the path p has to backtrack at this point. On the other hand, our analysis of the shapes of LS paths shows that there could be at most one point where p_2 backtracks. □

We now analyze the points of backtracking.

Lemma 5.9. *Suppose that $p = p_2 : [0, 1] \to V$ belongs to $LS(R)$, $\mathrm{length}_\Delta(p) \in \mathbb{N}\varpi_2$, $p(t_1)$ is a backtracking point of p which belongs to the wall $\{x = y\}$, and $p(0)$ or $p(1)$ belongs to $Q(R)$. Then $p(t_1)$ is a special vertex of (A, W_{aff}).*

Proof: Suppose that the break-point $p(t_1) = (x_1, x_1)$ is not special. Consider the line

$$\ell = \{x + y = 2x_1\}.$$

Observe that the line ℓ contains no verticies of $Q(R)$ since $2x_1$ is an odd number, while for each $(x, y) \in Q(R)$, the sum $x + y$ is even. Suppose that $p(0) \in Q(R)$. Then $p(0) \notin \ell$ and hence there exists a geodesic subsegment $\overline{p(0)p(t_2)}$ in p which is orthogonal to ℓ so that $p(t_2) = (x_2, y_2) \in \ell$ is a turning point of p. However such segment clearly cannot contain points in $Q(R)$ since its points (x, y) satisfy the equation

$$x - y = x_2 - y_2 \notin 2\mathbb{Z}.$$

Contradiction. □

As a corollary we obtain:

Corollary 5.10. *Suppose that $\sigma = (\lambda, \mu, \nu) \in Q(R)^3 \cap D_3$ and $\lambda + \mu + \nu \in 2P(R)$. Then there exists a path $p \in LS_1(R^\vee)$ contained in Δ such that:*

1. *$p(0) = \lambda, p(1) = \nu$.*
2. *All break-points of p are verticies of (A, W_{aff}).*

Proof: Note that $Q(R) = 2P(R^\vee)$. We now apply the results established above to the root system $R^\vee$; note that this interchanges the roles of short and long fundamental weights, e.g. the wall $\{x = y\}$ contains the short fundamental weight of $R^\vee$.

Then, according to the saturation theorem 2.11, $\sigma \in Tens(R^\vee)$. Moreover, there exists a path $p \subset \Delta$ connecting λ to ν such that:

1. $\underline{\text{length}}_\Delta(p) = (\mu_1, \mu_2) \in 2P(R^\vee) \times 2P(R^\vee)$.
2. $p \in LS_1(R^\vee)$ is a generalized LS path with respect to $R^\vee$.

Accordingly, the path p is the concatenation $p = p_1 * p_2$ of two $LS(R^\vee)$–paths $p_i : [0, 1] \to V$. Consider the break-points of the path p. According to Corollary 5.7, all break-points of p_2 are special verticies of $(A, W^\vee_{aff})$. All break-points of p_1 are special verticies of $(A, W^\vee_{aff})$ except possibly for a point $p_2(t_1)$ of backtracking which occurs on a wall of Δ, where the path p_1 intersects $\partial\Delta$ orthogonally (see Theorem 2.11 and Lemma 5.8). On the other hand, the end-point $\lambda = p_1(0)$ of the path p_1 belongs to $2P(R^\vee) \subset Q(R^\vee)$. Therefore, it follows from Lemma 5.9 (applied to the root system $R^\vee$ rather than R) that $p_1(t_1)$ has to be a special vertex of $(A, W^\vee_{aff})$.

Thus all break-points of p occur in special verticies of $(A, W^\vee_{aff})$. Since $P(R^\vee)$ is the set of verticies of (A, W_{aff}), all break-points of p are verticies of (A, W_{aff}). □

5.2. **Analysis of the $LS(R^\vee)$ paths with singular Δ-length.** In Corollary 5.10 we have established that for a large class of triples $(\lambda, \mu, \nu) \in D_3$, there exists an $LS_1(R^\vee)$ path p with $\underline{\text{length}}_\Delta(p) = \mu$ connecting λ to ν, so that all break-points of p are verticies of (A, W_{aff}).

We now analyze LS paths with respect to $R^\vee$ whose break-points are verticies of (A, W_{aff}). Such paths necessarily belong to $LS(2R)$. Throughout this section we assume that $p : [0, 1] \to V$ is a PL path in Δ so that:

- $\text{length}_\Delta(p) = \mu \in \mathbb{N}\varpi_2$.
- $\lambda := p(0), \nu := p(1) \in P(R)$, $\lambda - \nu \in Q(R)$.
- All break-points of p are verticies of (A, W_{aff}).
- $p \in LS(R^\vee)$.

Unlike the paths p with $\text{length}_\Delta(p) \in \mathbb{N}\varpi_1$, the above paths p do not have to belong to $LS(R)$. However, after analyzing these paths, we show that in "most cases" they can be replaced with a new $LS(R)$ path $\hat{p}$ while keeping the same end-points and the Δ-length.

If the path p is not an LS path with respect to R then it has a break-point which is not a special vertex of (A, W_{aff}).

Definition 5.11. *Suppose that $v = p(t)$ is a break-point of a PL path p. We call the break-point x* illegal *if it violates the axioms of an LS path (with respect to R).*

Accordingly, we will refer to an illegal break-point which is a turning/backtracking point as an *illegal turn/backtrack.*

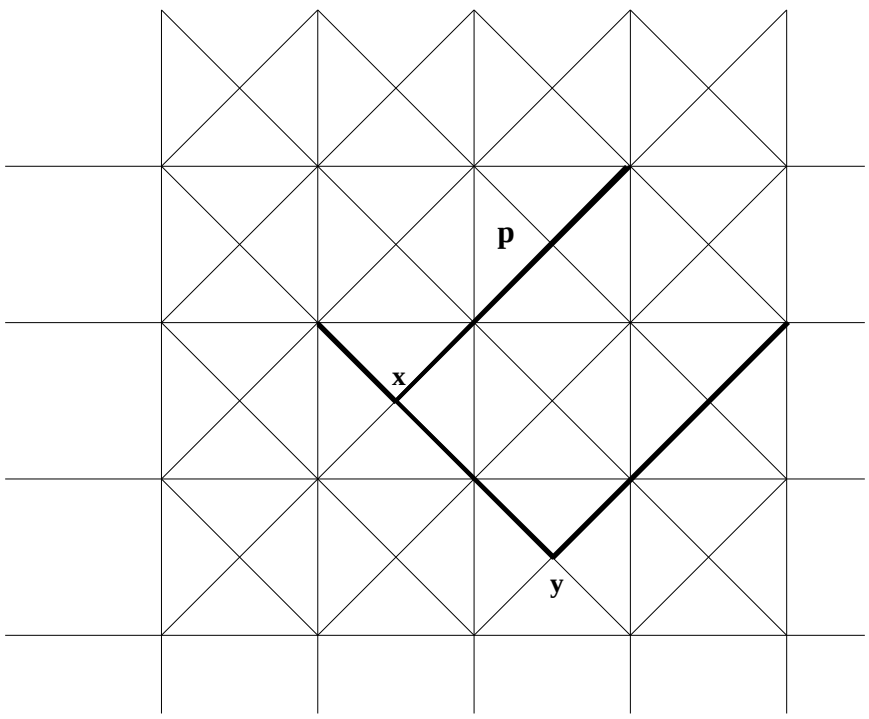

FIGURE 4. *Points x, y are illegal breaks.*

Lemma 5.12. *1. Either p has no illegal breaks or it has 2 illegal turns at $t_1 < t_2$ or one illegal backtrack.*

2. In the case of two illegal turns at $t_1, t_2 \in [0, 1]$, up to the reversal of orientation, the path p has the shape described in the Figure 4.

Proof: We first consider the backtracks of p. If p has a backtrack at t and $p'_+(t) \notin \Delta$ then

$$w(p'_-(t)) = p'_+(t)$$

where $w \in W^\vee_{aff}$ is a reflection fixing the vertex $p(t)$ and whose linear part is τ_1. Since τ_1 is a simple reflection, it follows that the chain

$$(p'_-(t), p'_+(t))$$

is necessarily maximal (see Lemma 3.15 in [13]) and therefore the backtrack at t is *legal*. Moreover, the reflection w also belongs to W_{aff}. Thus, if p has an illegal backtrack at a point t then $p'_-(t) \in -\Delta, p'_+(t) \in \Delta$. Therefore p has no other breaks in this case and we are done. Hence we assume that p has no illegal backtracks.

Let $t_i \in [0,1], i = 1, ..., m$ denote the illegal turns of p. We set $t_0^+ := 0$, $t_{m+1}^- := 1$. For each t_i define $[t_i^-, t_i^+] \subset [0,1]$ to be the smallest subinterval containing t_i such that $p(t_i^-), p(t_i^+)$ are special verticies of (A, W_{aff}). Then the assumption that for each i the point $p(t_i)$ is an illegal turn implies that

$$p(t_i^+) - p(t_i^-) \notin Q(R). \tag{13}$$

On the other hand, the restriction of p to each subinterval $[t_i^+, t_{i+1}^-]$ is an LS path, therefore

$$p(t_i^+) - p(t_{i+1}^-) \in Q(R)$$

(see Lemma 2.9). Thus

$$p(0) - p(t_1^-) + p(t_1^+) - p(t_2^-) + ... - p(t_m^-) + p(t_m^+) - p(1) \in Q(R)$$

and since $p(0) - p(1) \in Q(R)$, the latter is equivalent to:

$$(-p(t_1^-) + p(t_1^+)) + ... + (-p(t_m^-) + p(t_m^+)) \in Q(R).$$

Thus, since $Q(R)$ has index 2 in $P(R)$, it follows from (13) that p has to have an even number of illegal turns. Since the length of the longest chain in $W \cdot \varpi_2$ is 4, the number of illegal turns is ≤ 3, hence it is either 0 or 2. This proves the first assertion of Lemma.

Suppose that p has illegal turns at t_1 and t_2, where $t_1 < t_2$. Then, analogously to the case of an illegal backtrack,

$$p'_-(t_1) \in -\Delta, \quad p'_+(t_2) \in \Delta.$$

Therefore $p\big|_{[0,t_1]}, p\big|_{[t_2,1]}$ are geodesic paths. Moreover, since the length of the longest chain in $W \cdot \varpi_2$ is 4, the path p can have at most one (necessarily legal) break-point on the open interval (t_1, t_2). Therefore the path p has the shape as in Figure 4. □

Let p be a path as above. Let $x_1 = p(t_1), x_2 = p(t_2)$ denote the first and the last illegal breaks of p (possibly $t_1 = t_2$). Then both breaks occur at nonspecial verticies. According to the above lemma, either $t_1 = t_2$ and p has an illegal backtrack at this point or both breaks are illegal turns. Let $t_0 < t_1$ and $t_3 > t_2$ be the largest and smallest values of t such that $p(t) \in P(R)$. Our goal is to show that, with one exception, one can always modify the path p on the interval (t_0, t_3) (preserving its Δ-length) so that the new path is an $LS(R)$–path.

Lemma 5.13. *Suppose that $p(0) \notin \mathbb{N}\varpi_2$ and the image of p is contained in Δ. Then there exists a path $q : [t_0, t_3] \to V$ such that:*

1. *The concatenation*

$$\hat{p} := p\big|_{[0,t_0]} * q * p\big|_{[t_3,1]}$$

is an $LS(R)$ path contained in Δ.

2. $\text{length}_\Delta(\hat{p}) = \text{length}_\Delta(p)$.

Proof: There are two cases to consider:

Case 1. The path p restricted to the open interval (t_1, t_2) is not geodesic. In particular, $t_1 \neq t_2$ and both illegal breaks are illegal turns. Then we use the modification described in Figure 5. It is clear that the new path $\hat{p}$ always satisfies the requirements of Lemma.

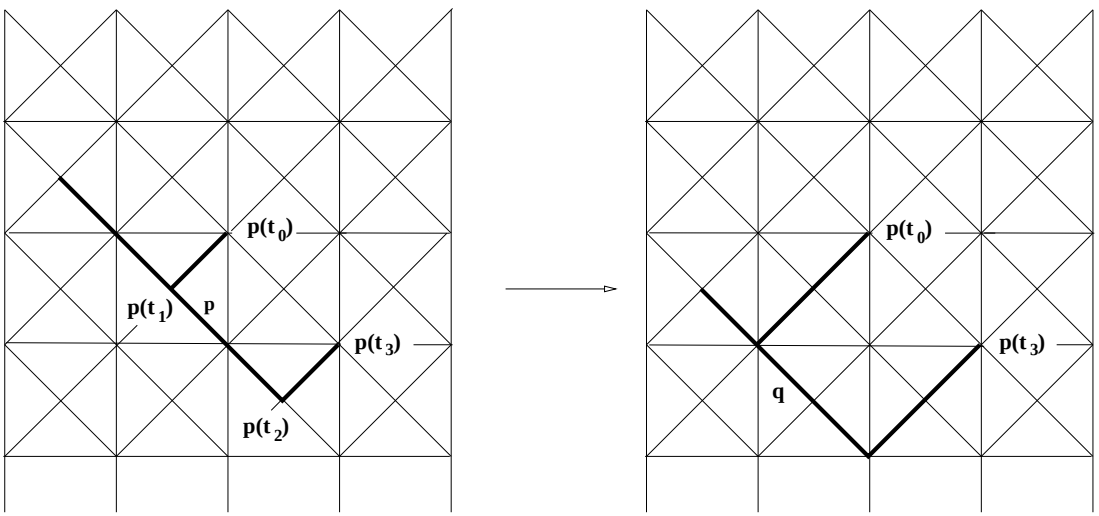

FIGURE 5. *Points $p(t_1), p(t_2)$ are illegal breaks of p.*

Case 2. The path $p\big|_{(t_1,t_2)}$ is a (possibly constant) geodesic. Then we use the modification described in Figure 6 by introducing an extra break τ between t_1 and t_2.

It is clear that the new path $\hat{p}$ is an LS path, it has the same Δ-length as p. However $\hat{p}$ is not necessarily contained in Δ: The point $q(\tau)$ could be outside of Δ. This happens if and only if the point $p(t_1)$ lies on the wall $\{x = y\}$ of Δ. In this case however $p(0) \in \{x = y\}$ as well which contradicts our hypothesis. $\square$

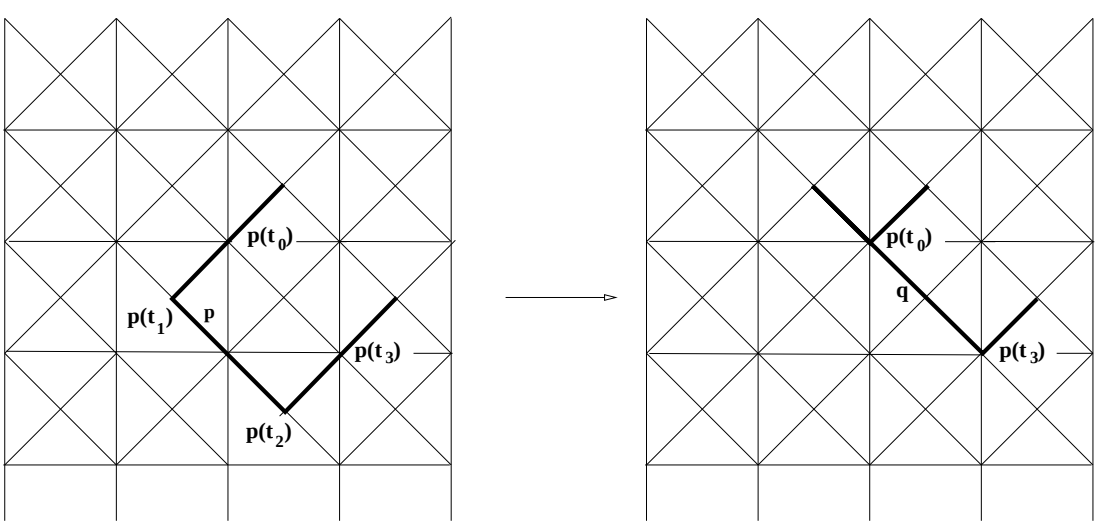

FIGURE 6. *Points $p(t_1), p(t_2)$ are illegal breaks of p.*

We now analyze in detail the exceptional case when $\lambda := p(0)$ lies on the wall $\{x = y\}$, i.e. λ belongs to $\mathbb{N}\varpi_2$. Then the path p has exactly two turns or one backtrack and all breaks are illegal.

Lemma 5.14. *Under the above conditions we have:*

$$\lambda + \mu + \nu \notin 2P(R).$$

Proof: Let p have breaks at $t_1 \leq t_2$. Set $u := p(t_1), v := p(t_2)$. Then

$$u = \lambda - (l + \frac{1}{2})\varpi_2, v = \nu - (m + \frac{1}{2})\varpi_2,$$

$$\mu = \tau_2((l + \frac{1}{2})\varpi_2 + (v - u) + (m + \frac{1}{2})\varpi_2),$$

where $l, m \in \mathbb{Z}$ and $\tau_2(x, y) = (x, -y)$. Note that $\mu - \tau_2(\mu) \in 2P(R)$. Therefore, modulo $2P(R)$ we have:

$$\lambda + \nu + \mu = \lambda + \nu + (l + \frac{1}{2})\varpi_2 + (v - u) + (m + \frac{1}{2})\varpi_2 = 2\nu + (2l + 1)\varpi_2.$$

Hence $\lambda + \mu + \nu$ does not belong to $2P(R)$. □

Lemma 5.15. *If $\lambda = n\varpi_2$ and $(\lambda, \mu, \nu) \in Tens(R)$ then $\lambda + \mu + \nu \in 2P(R)$.*

Proof: Suppose that $(\lambda, \mu, \nu) \in Tens(R)$. Then there exists an LS path q with $\text{length}_\Delta(q) = \mu$, $q(0) = \lambda, q(1) = \nu$, so that q is entirely contained in Δ. This path is either geodesic or has one or two turns, or one backtrack. See Figure 7. We consider the "generic case" when q has two turns at the points $u = q(t_1), v = q(t_2)$, $t_1 < t_2$. Then, analogously to the proof of the previous lemma,

$$\mu = (l + s + m)\varpi_2,$$

$$\nu = \lambda - l\varpi_2 + s\tau_2(\varpi_2) + m\varpi_2,$$

where $u = \lambda - l\varpi_2, v = \nu - m\varpi_2$ and $l, s, m \in \mathbb{N}$. Since $\varpi_2 \in P(R)$ and $\tau_2(\varpi_2) - \varpi_2 \in 2P(R)$, we obtain:

$$\nu \equiv \lambda + l\varpi_2 + s\varpi_2 + m\varpi_2 \ (\bmod\ 2P(R)),$$

i.e.

$$\nu \equiv \lambda + \mu \ (\bmod\ 2P(R)).$$

Therefore

$$\lambda + \mu + \nu \equiv 2\nu \equiv 0 \ (\bmod\ 2P(R)). \quad \square$$

We summarize the above results in the following:

Proposition 5.16. *Suppose that $\mu \in \mathbb{N}\varpi_2$ and p is an LS path with respect to $2R$ such that p is contained in Δ, $p(0) = \lambda, p(1) = \nu \in P(R)$, $\text{length}_\Delta(p) = \mu$ and all breaks of p are at verticies of (A, W_{aff}). Then:*

1. $(\lambda, \mu, \nu) \notin Tens(R)$ if and only if either $\lambda \in \mathbb{N}\varpi_2$ or $\nu \in \mathbb{N}\varpi_2$ and

$$\lambda + \mu + \nu \notin 2P(R).$$

2. Unless $p'(0) \in -\Delta, p'(1) \in \Delta$, the path p is also an LS path with respect to the root system R.

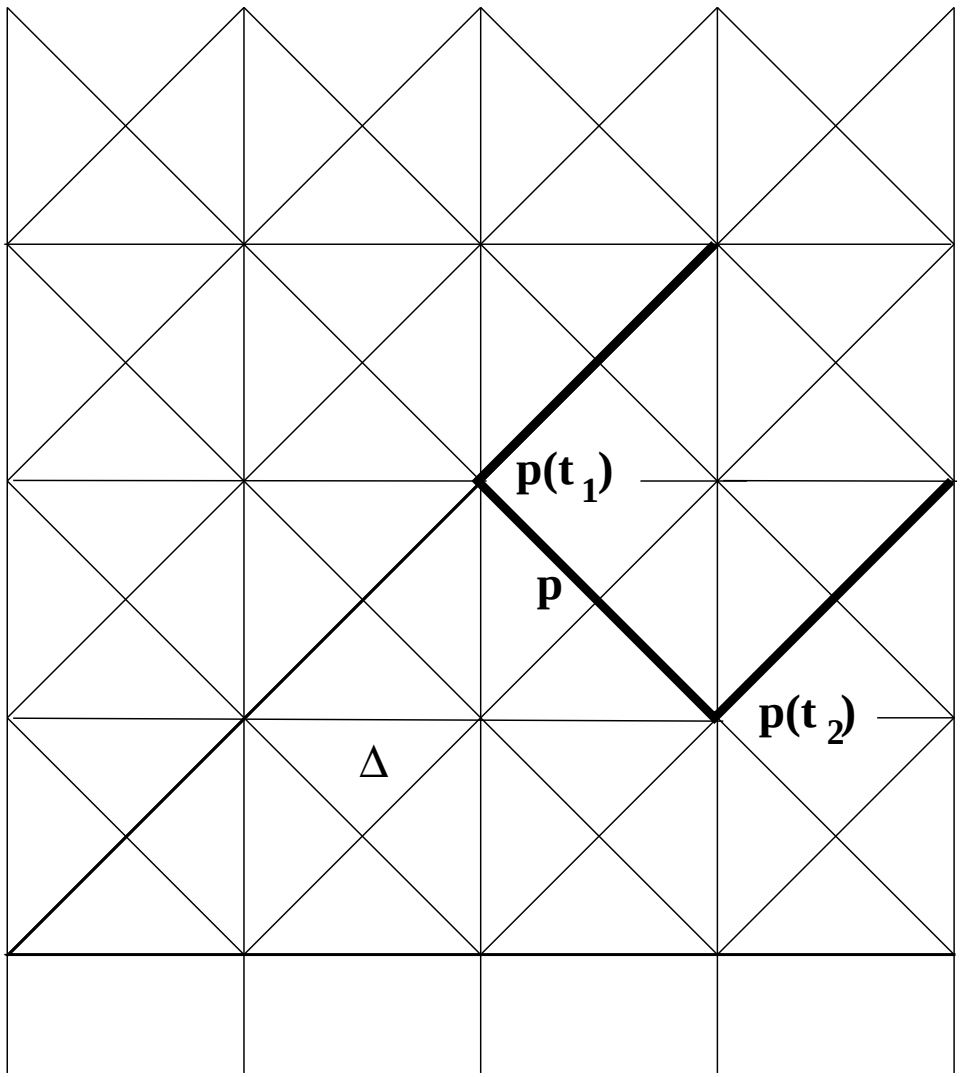

FIGURE 7.

3. Unless λ or $\nu \in \mathbb{N}\varpi_2$, and $\lambda + \mu + \nu \notin 2P(R)$, there exists a path $\hat{p}$ contained in Δ (of Δ–length μ) which is an LS path with respect to the root system R, so that $\hat{p}(0) = p(0), \hat{p}(1) = p(1)$.

5.3. **Analysis of $LS_1(R^\vee)$ paths.** In the previous section we proved that for "most" singular $LS(2R)$ paths $p_i \subset \Delta$ (with $\text{length}_\Delta(p_i) \in \mathbb{N}\varpi_i$), whose break-points are verticies of (A, W_{aff}), we can replace p_i with a new path $\hat{p}_i$ which has the same Δ-length, same end-points and is still contained in Δ (Proposition 5.16). The goal of this section is to prove a similar statement for paths $p = p_1 * p_2 \in LS_1(2R)$. The naive idea would be to replace each p_i with $\hat{p}_i$ using Proposition 5.16 and then take $\hat{p} := \hat{p}_1 * \hat{p}_2$. The are two issues however which have to be addressed:

(1) It might happen that the path p_2 is "exceptional" from the point of view of Proposition 5.17, i.e. $p_2(0) \in \{x = y\}$.

(2) We have to ensure that at the concatenation point between $\hat{p}_1$ and $\hat{p}_2$ the new path satisfies the axiom of an $LS_1(R)$ path.

It turns out that the issue (1) is trickier to handle: We cannot use Proposition 5.16 directly and are forced first to change the 'concatenation point" (Figure 9) and move it away from the wall $\{x = y\}$.

The main result of this section is the following proposition:

Proposition 5.17. *Suppose that $\sigma = (\lambda, \mu, \nu) \in P(R)^3$ is such that:*

1. $\lambda, \nu \notin \mathbb{N}\varpi_2$.

2. There exists a path $p \in LS_1(2R)$ from λ to ν, which is contained in Δ, all whose break-points are verticies of (A, W_{aff}) and so that

$$\underline{\text{length}}_\Delta(p) = (\mu_1, \mu_2), \mu = \mu_1 + \mu_2.$$

Then $\sigma \in Tens(R)$.

Proof: We start by analyzing the path p. Our goal is to replace it with a a new path which is in $LS_1(R)$ and which still satisfies condition 2.

Set $\delta := p_1(1)$. According to Lemma 5.6, the path p_1 is an LS path with respect to R. In particular, $\delta \in P(R)$. On the other hand, if $p_2'(0)$ does not belong to $-\Delta$, then, according to the second part of Proposition 5.16, the path p_2 is an LS path with respect to R. Hence $p = p_1 * p_2$ belongs to $LS_1(R)$, since the vertex δ is special and the generalized chain condition at this point (with respect to R) follows from the generalized chain condition at this point (with respect to $2R$).

We now consider the case $p_2'(0) \in -\Delta$. Observe that, since δ is a special vertex, for each $\eta \in -\Delta$ and every $w \in W$,

$$\eta \geq w(\eta),$$

it follows that for every $LS(R)$-path q_2, the concatenation

$$p_1 * q_2$$

belongs to $LS_1(R)$.

Case 1. $p_1(1) \notin \{x = y\}$. Then, according to Part 3 of Proposition 5.16, there exists an $LS(R)$–path q_2 (entirely contained in Δ) starting at δ, ending at ν, with $\text{length}_\Delta(q_2) = \mu_2$. Hence the concatenation $\hat{p} := p_1 * q_2$ is a generalized LS path with respect to the root system R, $\hat{p}$ is contained in Δ, and therefore $(\lambda, \mu, \nu) \in Tens(R)$.

Case 2. $p_1(1) \in \{x = y\}$. Since $p_2'(0) \in -\Delta$, then $p_1'(1) \in \mathbb{R}_- \times \mathbb{R}_-$. Since $\delta = p_1(1)$ belongs to the wall $\{x = y\}$ and p_1 is contained in Δ, it follows that $p_1'(1) \in -\Delta$. Hence p_1 is a geodesic path and the entire path p has the shape as in Figure 8.

We let $t_1 \in [0, 1]$ be such that $\delta = p(t_1)$ is the concatenation point, let $t_0 < t_1$ be the maximal value of t such that $p(t)$ is a special vertex. Let $t_2 > t_1$ be the first value of t where $p(t)$ is not geodesic, $t_3 > t_2$ be the first value of t such that $p(t_2)$ is a (special) vertex. We now replace the restriction $p\big|_{[t_0,t_3]}$ with the new path $\tilde{p} : [t_0, t_3] \to V$ described in Figure 9. Observe that $p(t_3) \notin \partial\Delta$, for otherwise the path p_2 has exactly one illegal turn which contradicts Lemma 5.12. Therefore the path $\tilde{p}$ is contained in Δ.

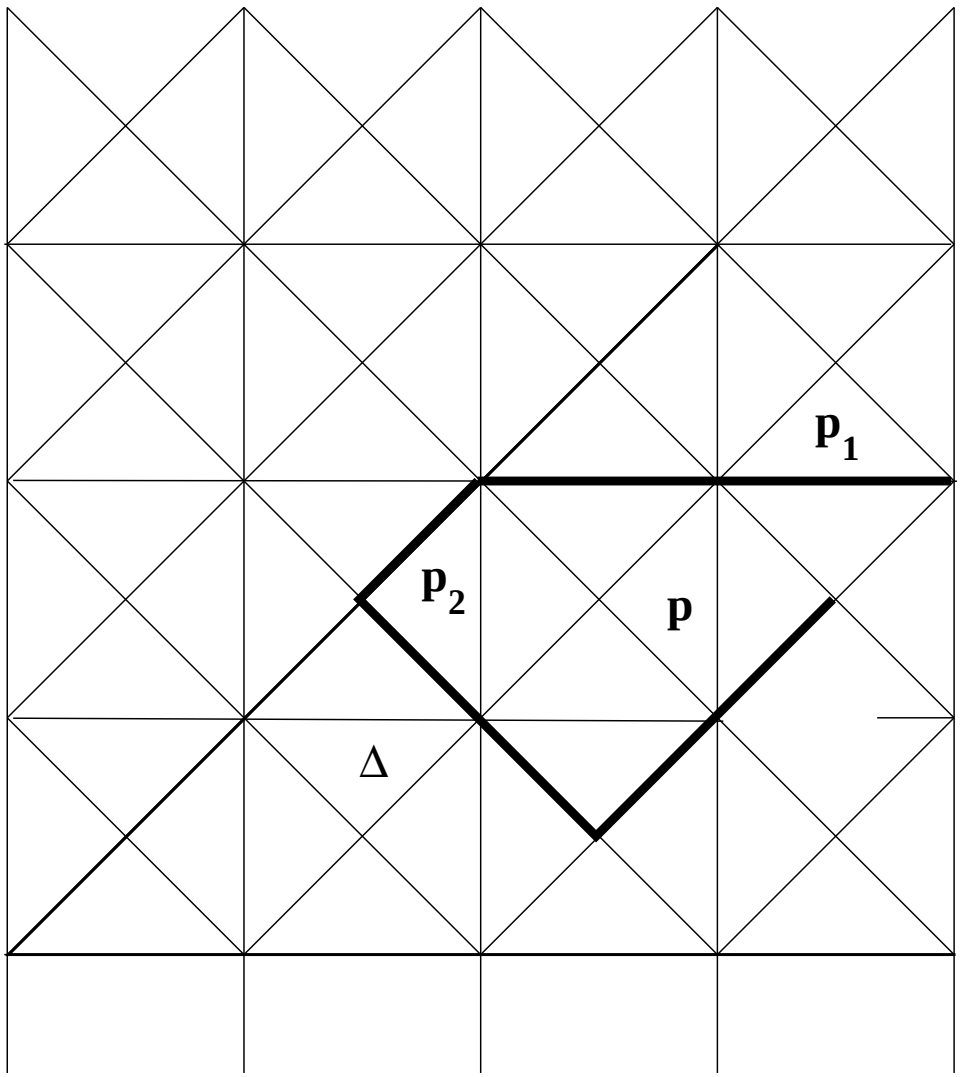

FIGURE 8.

Moreover, $\tilde{p}(t_0) = p(t_0), \tilde{p}(t_3) = p(t_3)$,

$$\underline{\text{length}}_{\Delta}(\tilde{p}) = \underline{\text{length}}_{\Delta}(p\big|_{[t_0,t_3]})$$

Thus we define the path

$$q := p\big|_{[0,t_0]} * \tilde{p}[t_0, t_3] * p\big|_{[t_3,1]}.$$

Note that the new path has a (legal) turn at the point $\tilde{p}(t_3)$ and in addition, two (illegal) simple turns. Therefore $q = q_1 * q_2$ is still not a generalized LS path. However it has the property that its concatenation point $\tilde{\delta} = q(t_1)$ is not on the wall $\{x = y\}$. Thus we have reduced the argument to Case 1 and hence $\sigma \in Tens(R)$.

This concludes the proof of Proposition 5.17. □

Corollary 5.18. *Suppose that $\sigma = (\lambda, \mu, \nu) \in Q(R)^3 \cap D_3$ and $\lambda + \mu + \nu \in 2P(R)$. Then $\sigma \in Tens(R)$.*

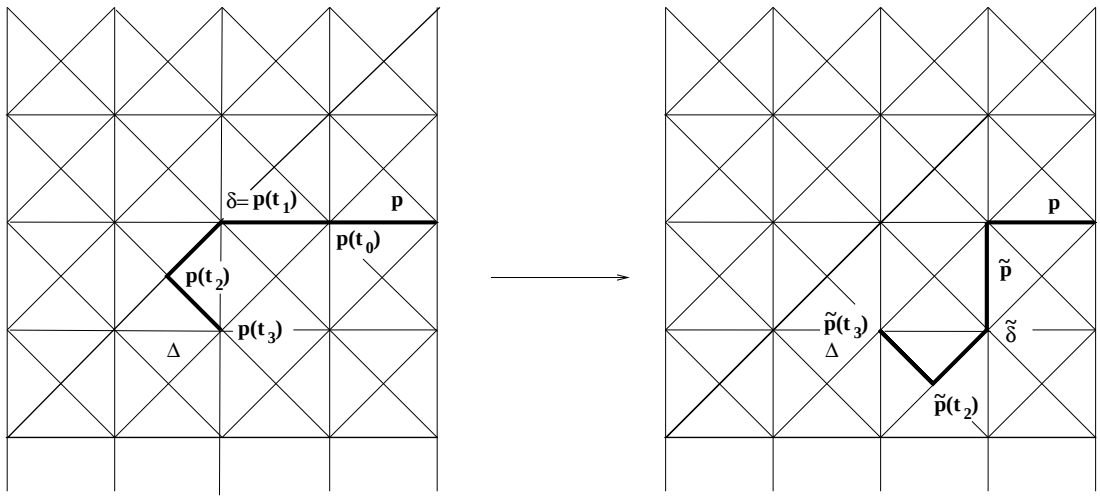

FIGURE 9.

Proof: If all three vectors λ, μ, ν do not belong to $\mathbb{N}\varpi_2$ then the assertion follows immediately from the combination of Corollary 5.10 and Proposition 5.17. If one of these vectors belongs to $\mathbb{N}\varpi_2$ (by permuting λ, μ, ν we can assume that this vector is μ), then we use Corollary 5.10 and Proposition 5.16. □

5.4. **Proof of Theorem 5.3.** Our final goal is to eliminate the assumption that $\lambda, \mu, \nu \in Q(R)$ in Corollary 5.18. Recall that $(\lambda, \mu, \nu) \in D_3 \cap (P(R))^3$, $\lambda+\mu+\nu \in Q(R)$ and either at most one of the vectors λ, μ, ν belongs to $\mathbb{N}\varpi_2$ or $\lambda + \mu + \nu \in 2P(R)$. If one of the vectors λ, μ, ν belongs to $\mathbb{N}\varpi_2$, we can assume (by relabelling) that this vector is μ. (Note that $\varpi_2 \in Q(R)$ which makes this relabelling consistent with our convention 5.1.)

Observe that $\lambda, \mu, \nu \in P(R) = Q(R^\vee)$, $\lambda + \mu + \nu \in Q(R) = 2P(R^\vee)$. Therefore, since the root systems B_2 and C_2 are isomorphic, we can apply Corollary 5.18 to the triple (λ, μ, ν) *with respect to the coroot system* $R^\vee$ and conclude that the triple (λ, μ, ν) belongs to $Tens(R^\vee)$.

Hence there exists a generalized LS path p in Δ with respect to the root system $R^\vee$, connecting λ to μ and having

$$\underline{\text{length}}_\Delta(p) = (\mu_1, \mu_2).$$

This path is a concatenation $p = p_1 * p_2$ of $LS(R^\vee)$ paths p_1, p_2, the edges of the path p_1 are parallel to the x and y axes.

Remark 5.19. *Strictly speaking, since in the root system $R^\vee$ the long and the short roots are reversed, according to our notation 5.2, we would have to use the concatenation $p_2 * p_1$ rather than $p_1 * p_2$. However reversing the roles of λ and ν eliminates this problem.*

Lemma 5.20. *The breaks of p occur only at special verticies of the Coxeter complex $(A, W^\vee_{aff})$.*

Proof: Observe that our analysis of generalized LS paths (see Lemma 5.8 applied to the root system $R^\vee$) shows that the break-points of p occur only at special verticies

of $(A, W^\vee_{aff})$ with the sole exception of a single break of the sub-path p_1 which can occur at a nonspecial vertex $p(t_1)$, and where p *backtracks* and has germ parallel to the y axis.

We claim that this is impossible. Let $[t_0, t_2]$ be the smallest interval containing t_1 such that $p(t_0) = p(t_1) \in P(R^\vee)$. We then replace the path p with the path $\tilde{p}$ by *eliminating this backtracking*:

$$\tilde{p} = p\Big|_{[0,t_0]} * p\Big|_{[t_1,1]}.$$

Then

$$\tilde{\mu} := \mathrm{length}_\Delta(\tilde{p}) = \mathrm{length}_\Delta(p) - \varpi_1.$$

It is clear that the new path $\tilde{p}$ is a generalized LS path with respect to the root system $R^\vee$ and moreover its breaks occur only at the special verticies of $(A, W^\vee_{aff})$, i.e. at verticies of (A, W_{aff}). We are now in position to apply Proposition 5.17 (with respect to the root system R).

1. Either $(\lambda, \tilde{\mu}, \nu) \in Tens(R)$,
2. Or two of the vectors λ, μ, ν belong to $\mathbb{N}\varpi_2$.

In Case 1, since $(\lambda, \tilde{\mu}, \nu) \in Tens(R)$, it follows that

$$\lambda + \mu + \nu - \varpi_1 = \lambda + \tilde{\mu} + \nu \in Q(R).$$

However $\lambda + \mu + \nu \in Q(R)$ (by the assumption in Theorem 5.3) and $\varpi_1 \notin Q(R)$. Contradiction.

In Case 2, as it was observed in the beginning of this section, we can assume that $\mu \in \mathbb{N}\varpi_2$. Then the path p cannot contain a subsegment parallel to the y-axis, i.e. the above backtracking in the path p is impossible. □

Corollary 5.21. *There exists a path p in Δ, connecting λ to ν, which is a generalized LS path with respect to $R^\vee$ all whose breaks are at verticies of (A, W_{aff}) and such that* $\underline{\mathrm{length}}_\Delta(p) = (\mu_1, \mu_2)$.

We now can finish the proof of Theorem 5.3. Consider a path p in Δ as in Corollary 5.21. The breaks in this path occur only in verticies of (A, W_{aff}). Suppose that at most one of the vectors λ, μ, ν belongs to $\mathbb{N}\varpi_2$. Then, according to Proposition 5.17, $\sigma \in Tens(R)$.

Consider the exceptional case, say, $\lambda, \mu \in \mathbb{N}\varpi_2$. Then, according to the hypothesis of Theorem 5.3, $\lambda + \mu + \nu \in 2P(R)$. Therefore we can apply Proposition 5.16 and $\sigma \in Tens(R)$. □

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