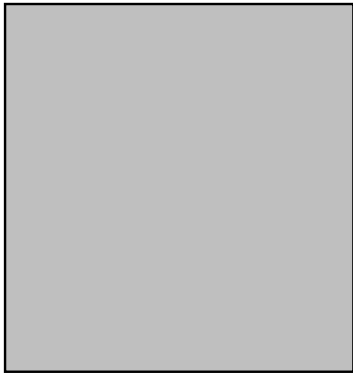
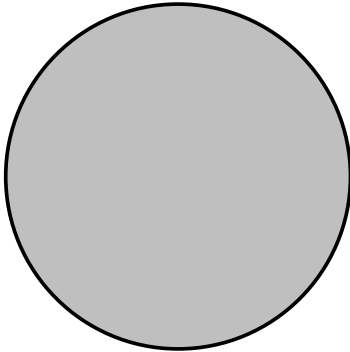
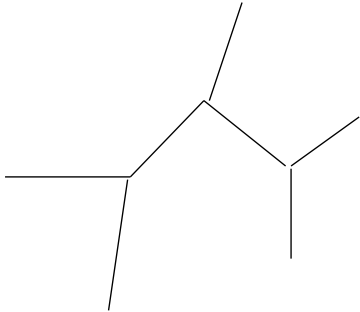


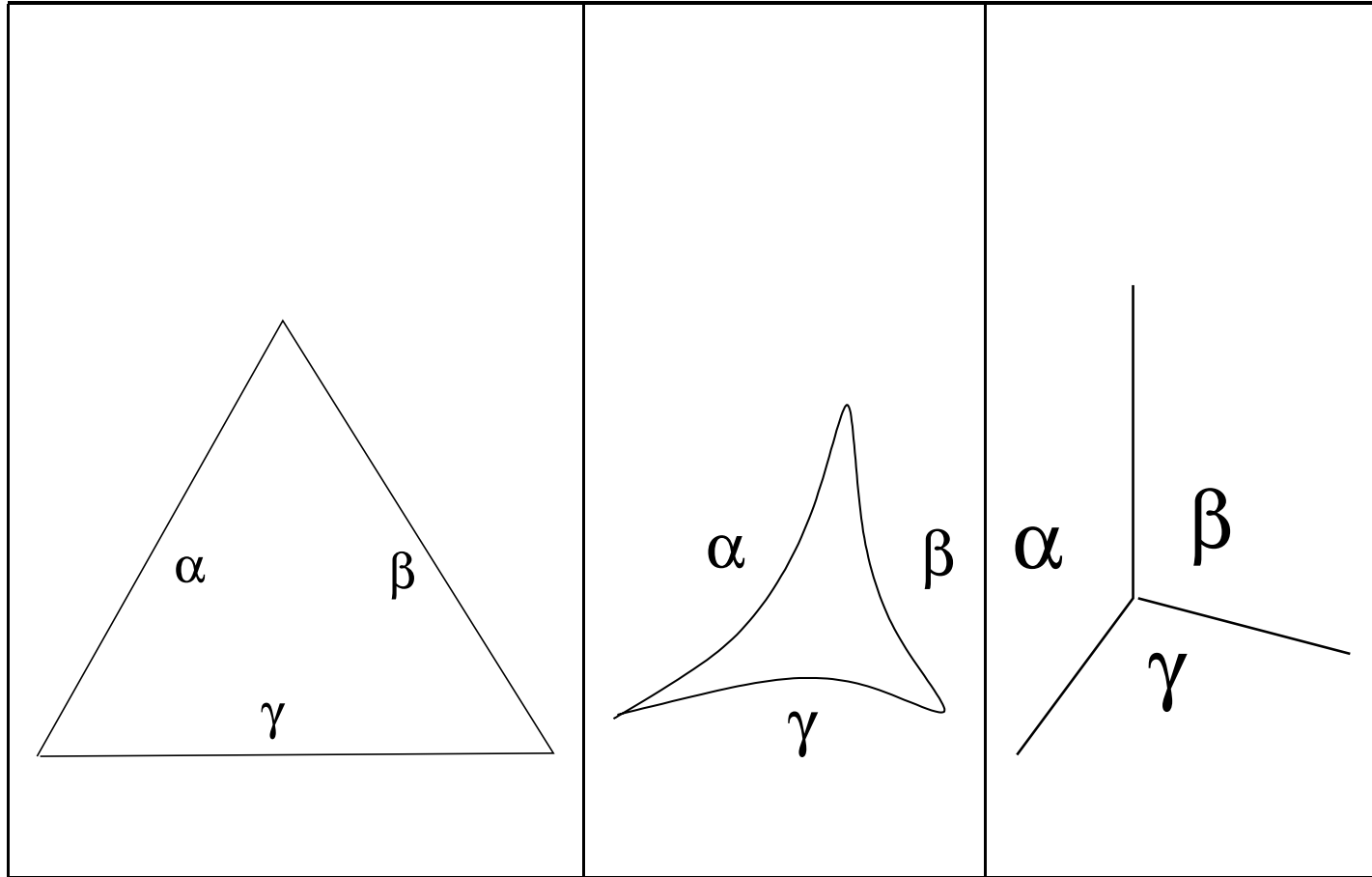
Generalized triangle inequalities and their applications

Misha Kapovich
with Bernhard Leeb and John Millson

GEOMETRY

	\mathbb{R}^2	\mathbb{H}^2	Tree
Rank 1			
Spaces:			
Distances:	\mathbb{R}_+	\mathbb{R}_+	\mathbb{R}_+

Triangles



Triangle inequalities: $\gamma \leq \alpha + \beta$.

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Example 2: $X = \mathbb{H}^2$, positive-definite symmetric 2×2 matrices of unit determinant.

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Example 2: $X = \mathbb{H}^3$, $X' = \mathbb{R}^3$, $\text{Aut}(X') = O(3) \ltimes \mathbb{R}^3$.

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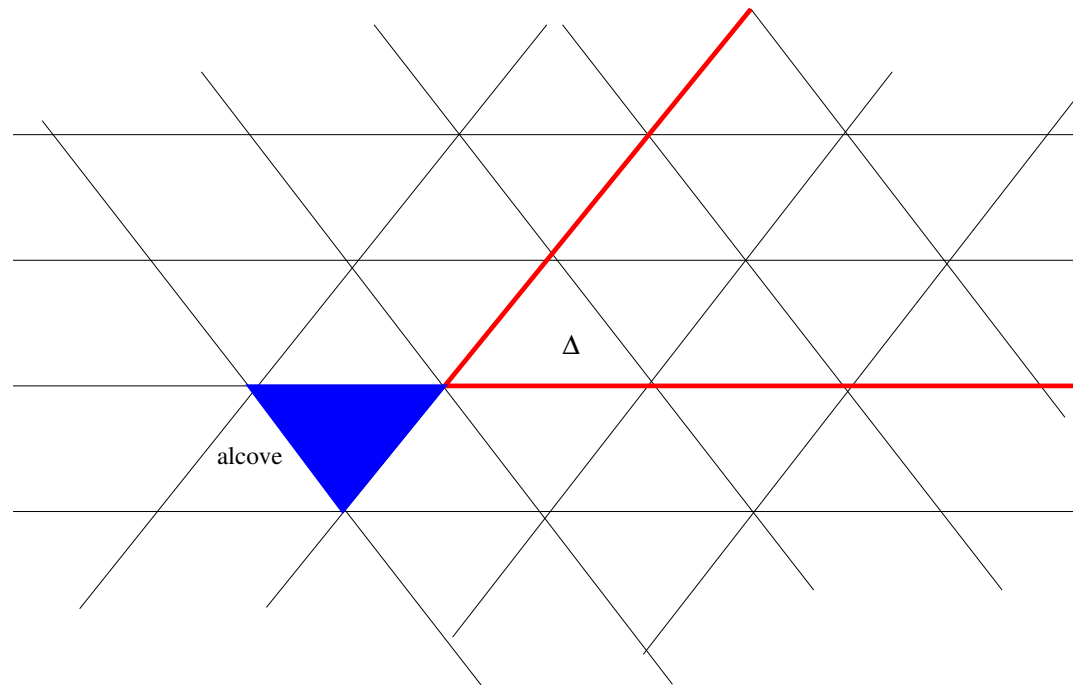
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2. Every two points belong to an **apartment**, an isometrically embedded copy of the Euclidean m -space A . The number m is called the **rank** of X .
3. The way the apartments are **glued together** is governed by a finite reflection group W (**Weyl group**) operating on A isometrically.

Apartments

Fundamental domain Δ of W is called a **Weyl chamber**.

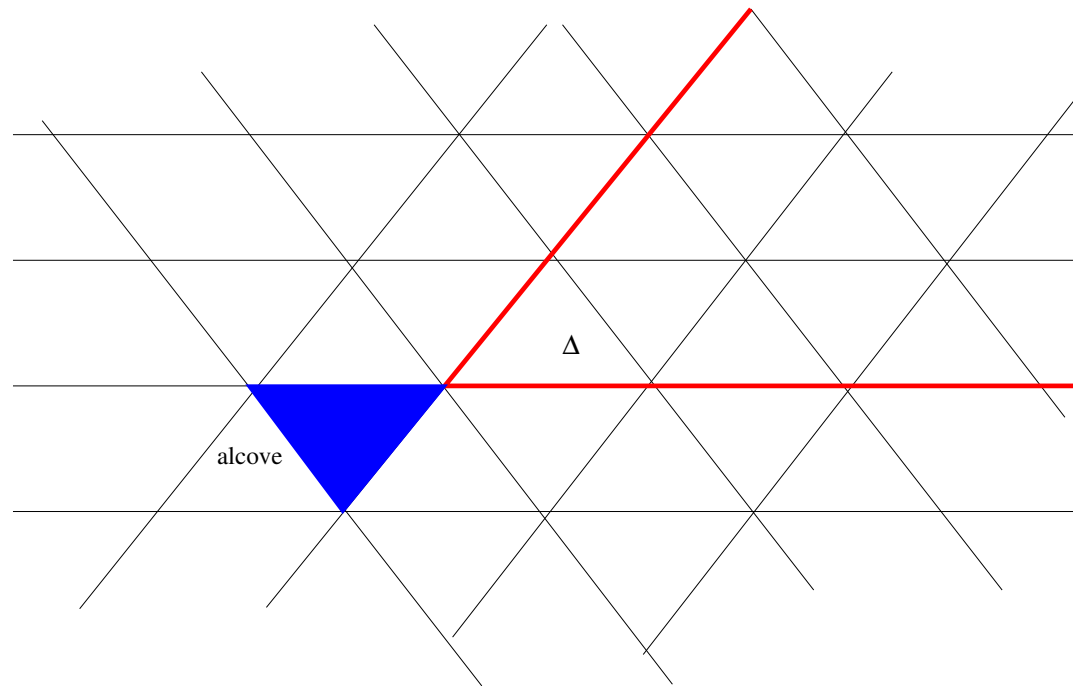
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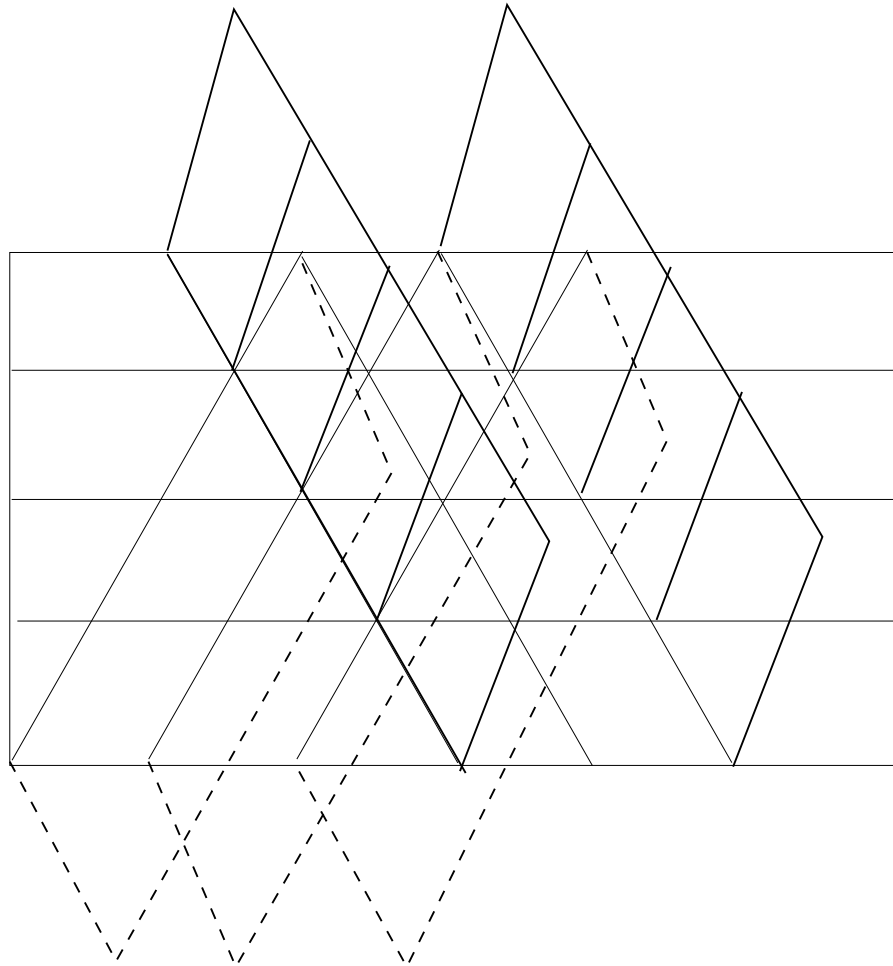
Fundamental domain Δ of W is called a **Weyl chamber**.



Example: $X = \mathbb{H}^2$ or a tree. Apartments are lines.
Chambers are rays. $W = \mathbb{Z}/2$

Buildings

A lame attempt to draw a rank 2 Euclidean building.



Δ -valued distance function

Definition. Let $x, y \in A$. Consider the vector \overrightarrow{xy} with tail at the origin=tip of Δ , then apply an element $w \in W$ to move this vector to the chamber Δ .

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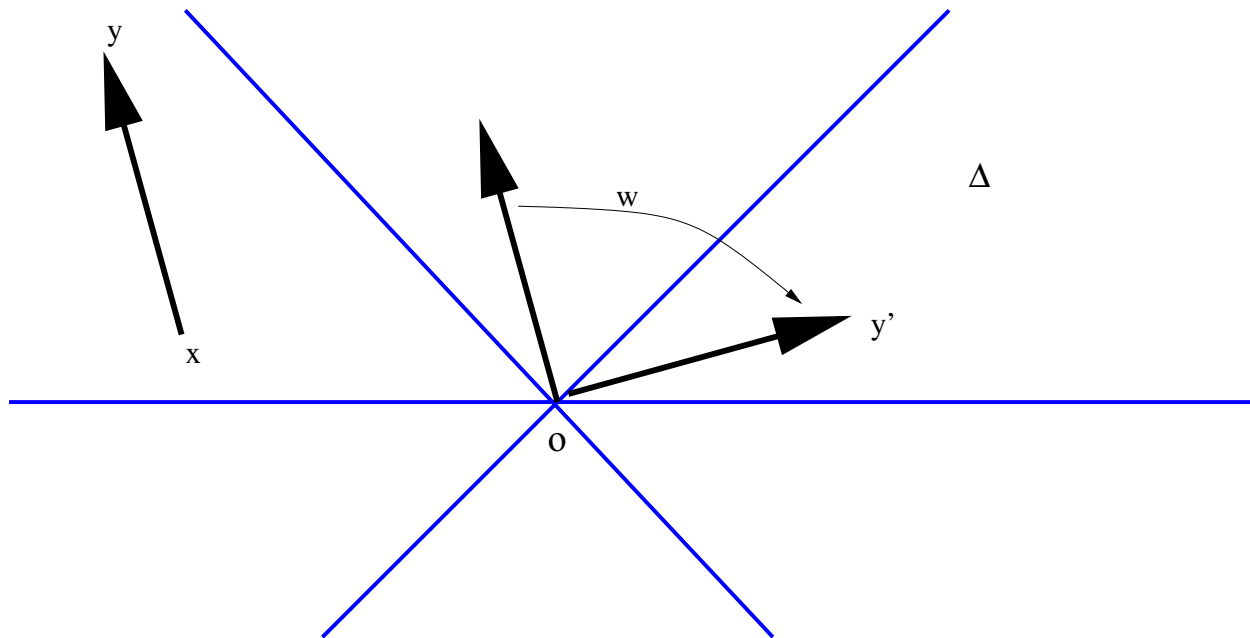
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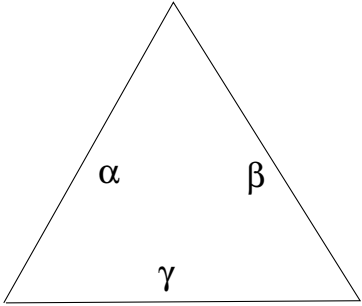
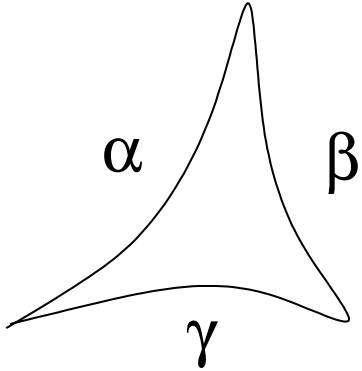
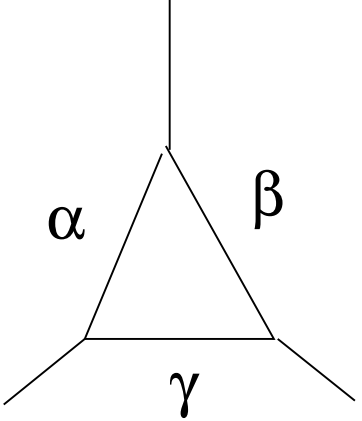
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Example 3. $X = \mathit{Sym}_m$, symmetric space. Then $d(1, x)$ is the set of singular values of x arranged in the descending order.

Summary

<i>Spaces :</i>	$\mathfrak{p} = T_oX$	$X = G/K$	building
Automorphisms:	$\mathfrak{p} \rtimes K$	G	G_p
Δ -Distances:	Δ	Δ	Δ
Triangles:			

In the case of symmetric and infinitesimal symmetric spaces,

$d_{\Delta}(x, y)$ is a complete congruence invariant of $[x, y]$.

Generalized Triangle Inequalities

Define $D_3(X) = \{(\alpha, \beta, \gamma) \in \Delta^3 : \text{there exists a triangle in } X \text{ with the side-lengths } \alpha, \beta, \gamma\}$.

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More generally:

2. $w\alpha \leq_{\Delta^*} w\beta + \gamma, \forall w \in W$

and permutations of α, β, γ . In rank 2 case this is enough.

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Schubert calculus: computation of the cohomology rings $H^*(G/P, \mathbb{Z})$, where P is a maximal parabolic subgroup.

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P2. Singular values of a product. Give necessary and sufficient conditions on α, β and γ in order that there exist matrices A, B and C in $GL(m, \mathbb{R})$ the logarithms of whose singular values are α, β and γ , respectively, so that

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The matrix $\text{Diag}(p^{-\lambda_1}, \dots, p^{-\lambda_m})$ is called **Smith normal form** of A .

The integers $\lambda_1 \geq \dots \geq \lambda_m$ are called **invariant factors** of A . ($-\log_p$ of the diagonal entries.)

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m -tuples of integers $\alpha = (\lambda_1 \geq \dots \geq \lambda_m)$ parameterize irreducible representations V_α of $GL(m, \mathbb{C})$; α is the **highest weight** of V_α .

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Below $\alpha, \beta, \gamma \in \Delta \cap \mathbb{Z}^m$ are dominant weights of $SL(m, \mathbb{C})$:

2 discrete problems

P3. Invariant factors of a product. Give necessary and sufficient conditions on the integer vectors α , β and γ in order that there exist matrices A , B and C in $GL(m, \mathbb{Q}_p)$ with invariant factors α , β and γ , respectively, so that

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Generalization to other groups

The above algebra problems make sense for other (reductive) Lie groups G , like $Sp(m)$, $O(m)$. So we have problem $P1, P2, P3, P4$ for groups $G(\mathbb{C}), G(\mathbb{R}), G(\mathbb{Q}_p)$ (e.g. $O(m, \mathbb{C}), Sp(m, \mathbb{Q}_p)$).

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Let $Sol(P_i, G)$ denote the solution set of the problem P_i for the group G .

It turns out that there is an “obvious” condition that solutions of P_3, P_4 have to satisfy:

$$\delta = \alpha + \beta + \gamma \in Q(R^\vee), Q(R),$$

the **coroot** and **root** lattices respectively.

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So far we have discussed problems, it is time to talk about the answers!

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Therefore

$$D_3(X) = \text{Sol}(P2, G), \text{ for a symmetric space } X = G/K,$$

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$$o, g_1(o), g_1g_2(o), g_1g_2g_3(o).$$

Then $g_1g_2g_3 = 1$ corresponds to the triangle in X , with Δ -side lengths $\alpha = d_{\Delta}(o, g_1(o))$, $\beta = d_{\Delta}(o, g_2(o))$, etc.

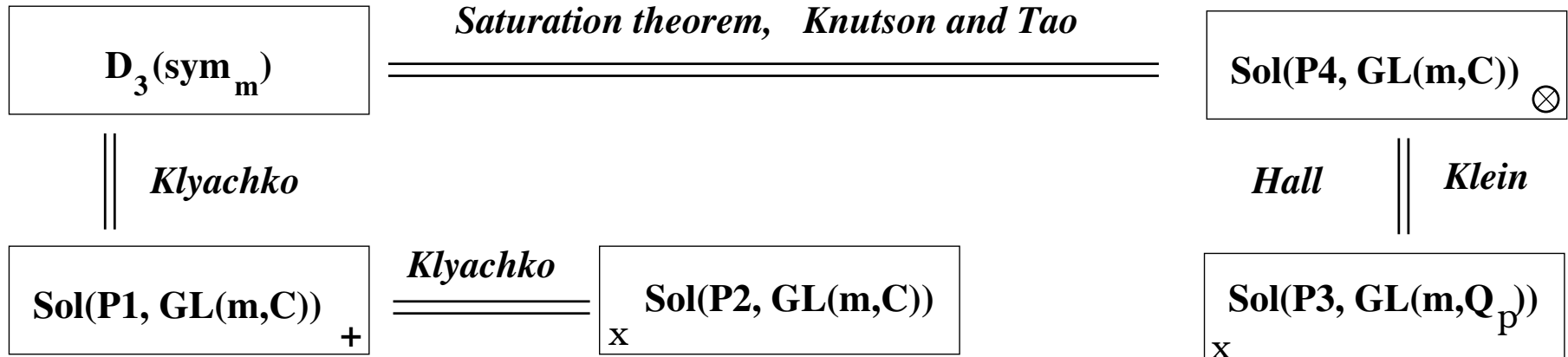
Therefore

$$D_3(X) = \text{Sol}(P2, G), \text{ for a symmetric space } X = G/K,$$

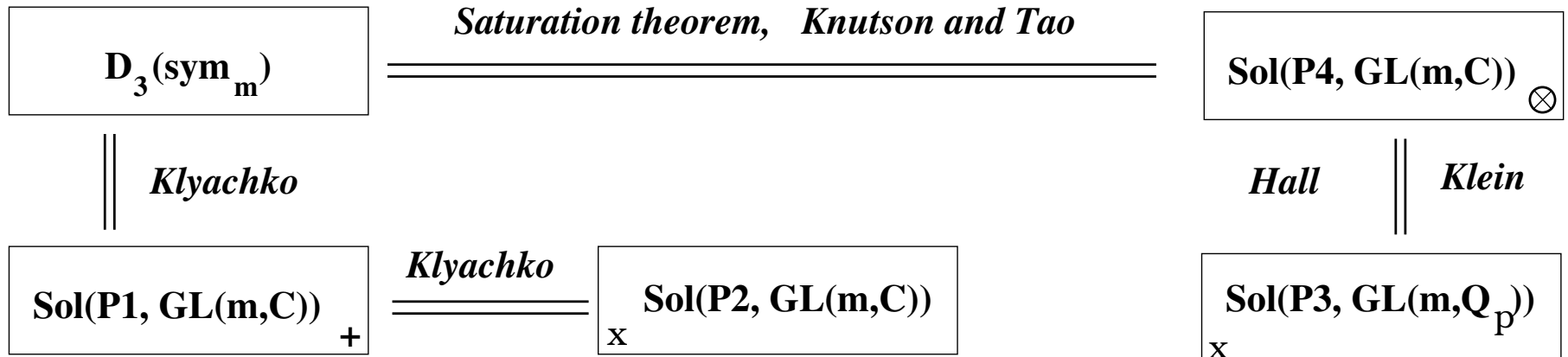
$$D_3(X') = \text{Sol}(P1, G),$$

for the infinitesimal symmetric space $X' = T_oX$.

GL(m) case



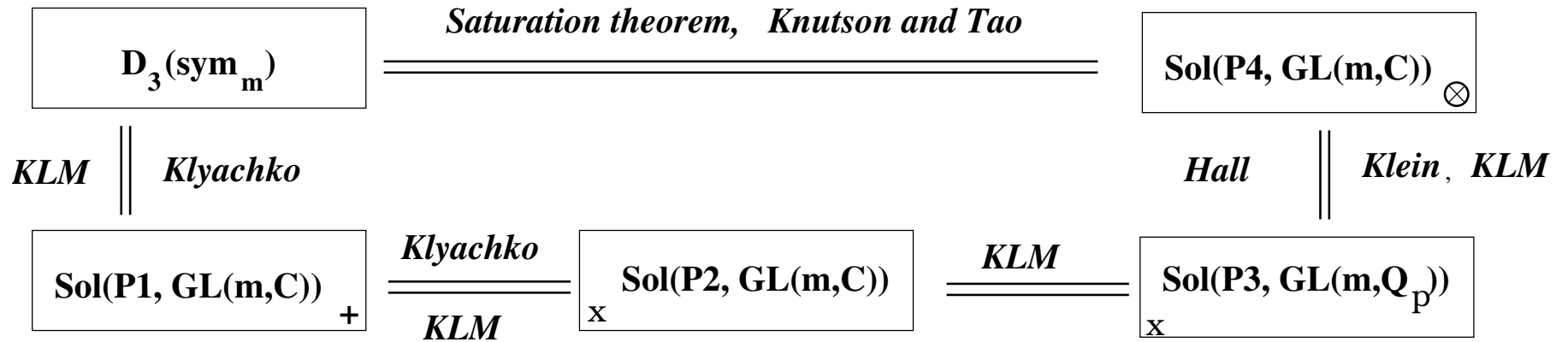
GL(m) case



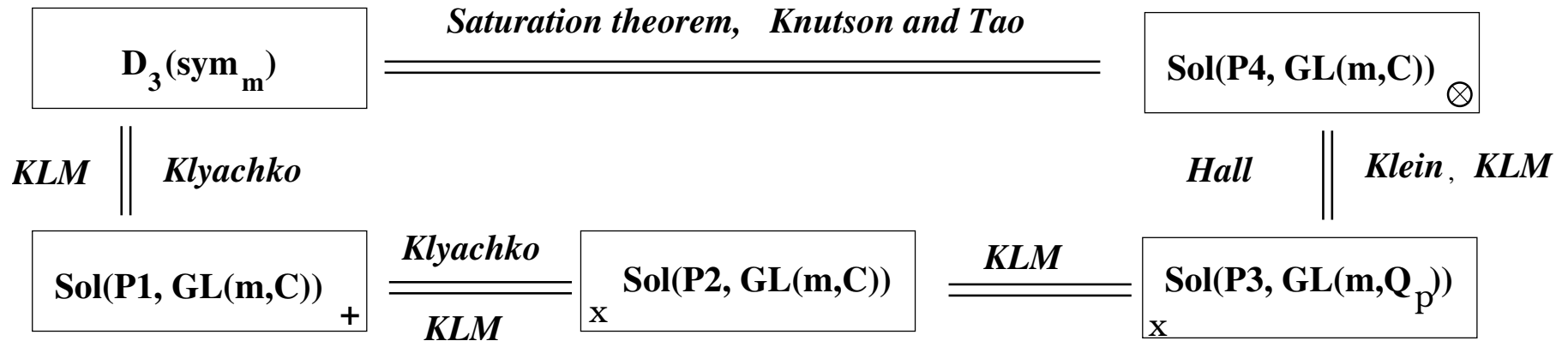
Recall that $Sol(P3)$, $Sol(P4)$ are contained in certain lattices. Namely:

$$\alpha, \beta, \gamma \in L, \alpha + \beta + \gamma \in Q(R^\vee).$$

GL(m) case



GL(m) case

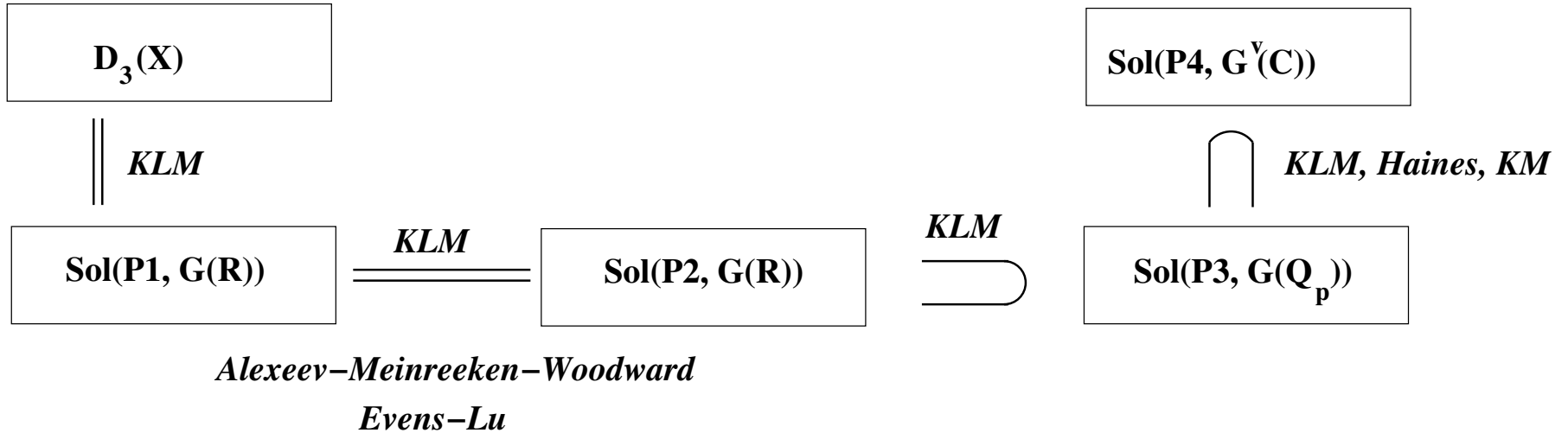


Knutson—Tao, Hall and Klein— combinatorics.

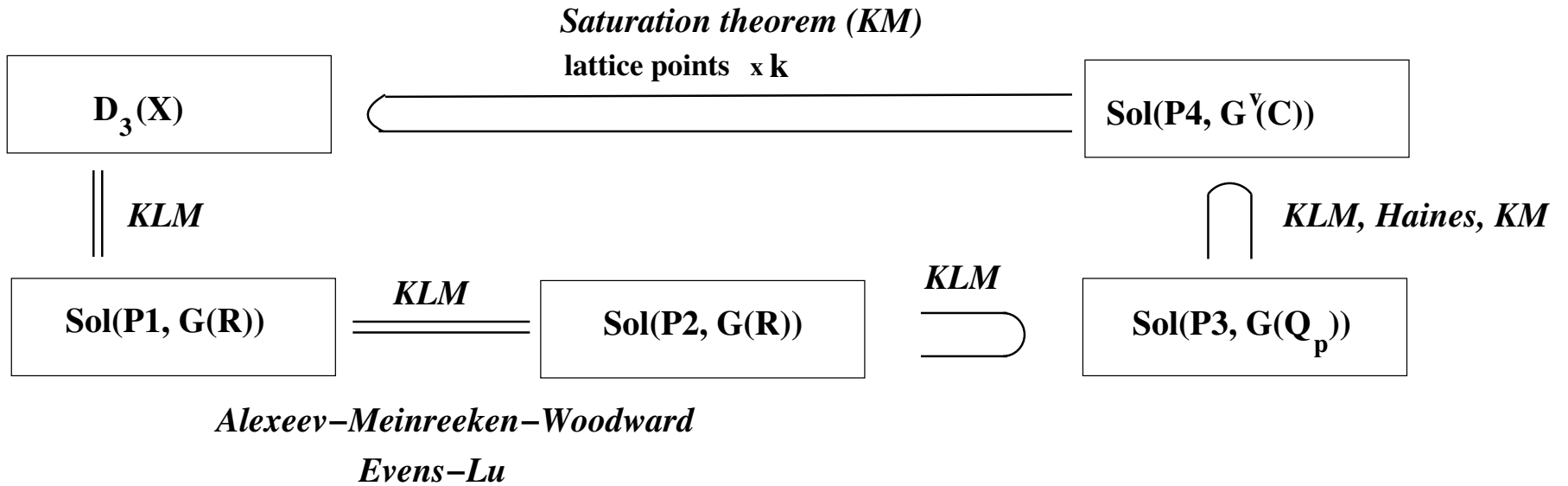
KLM $P4 \subset P3$ — Satake correspondence (a kind of Fourier transform).

$P2 = P3$ — geometry.

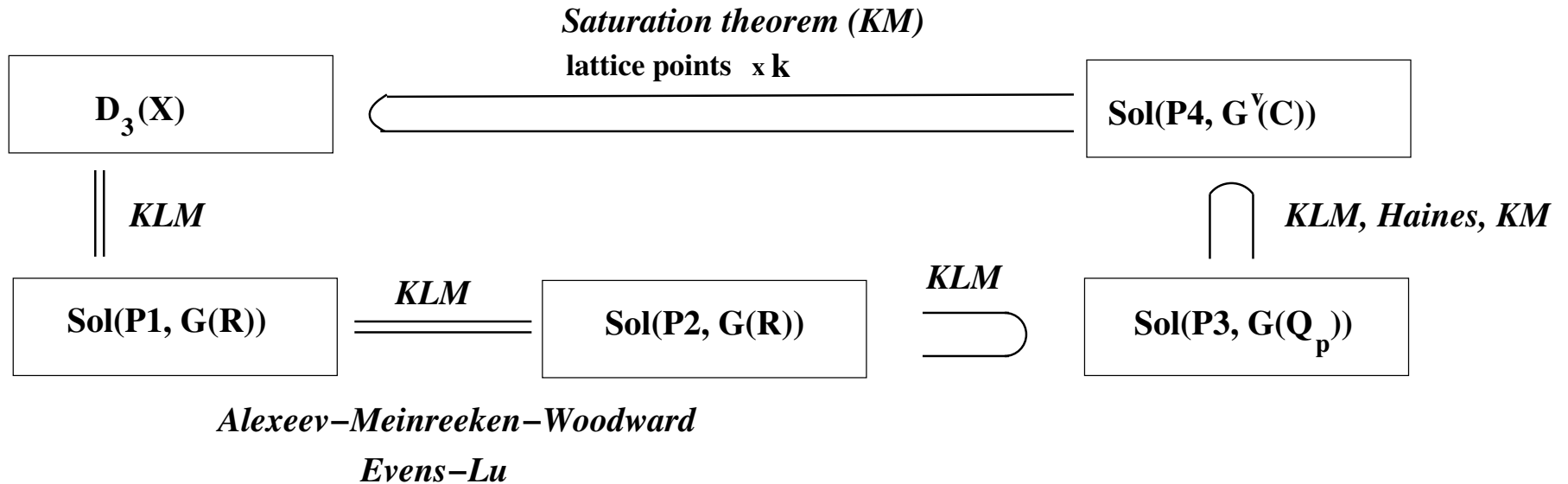
General case



General case



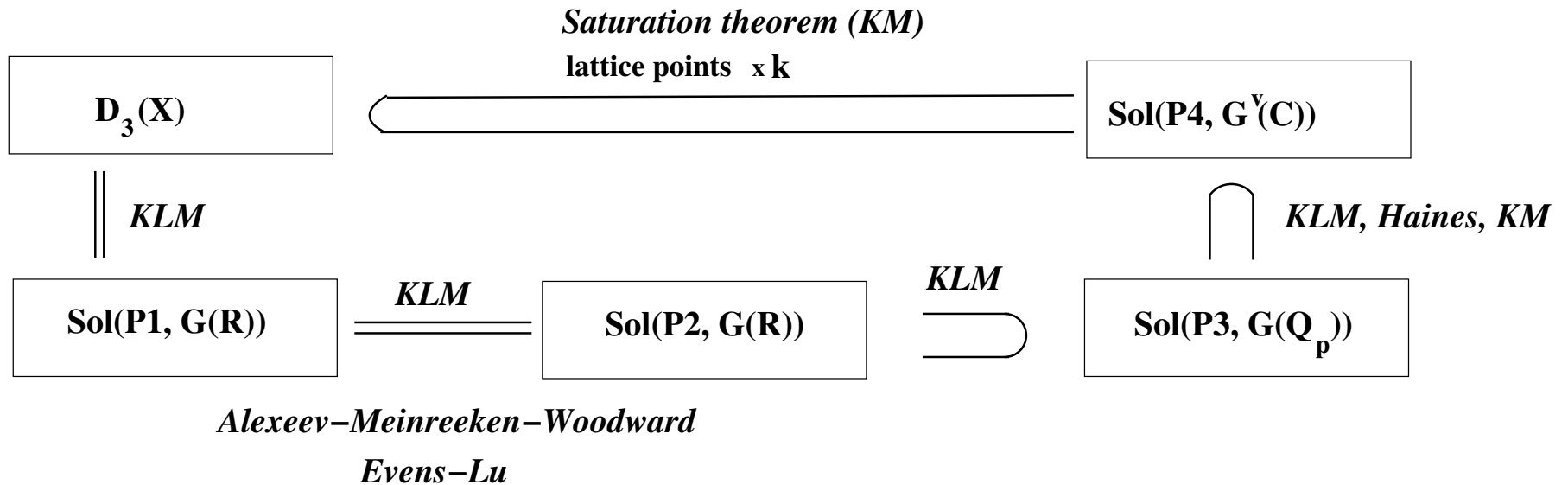
General case



The number k is the *saturation constant*, depends only on the group G . For $GL(m)$, $k = 1!$

The current values of k are described on the next slide.

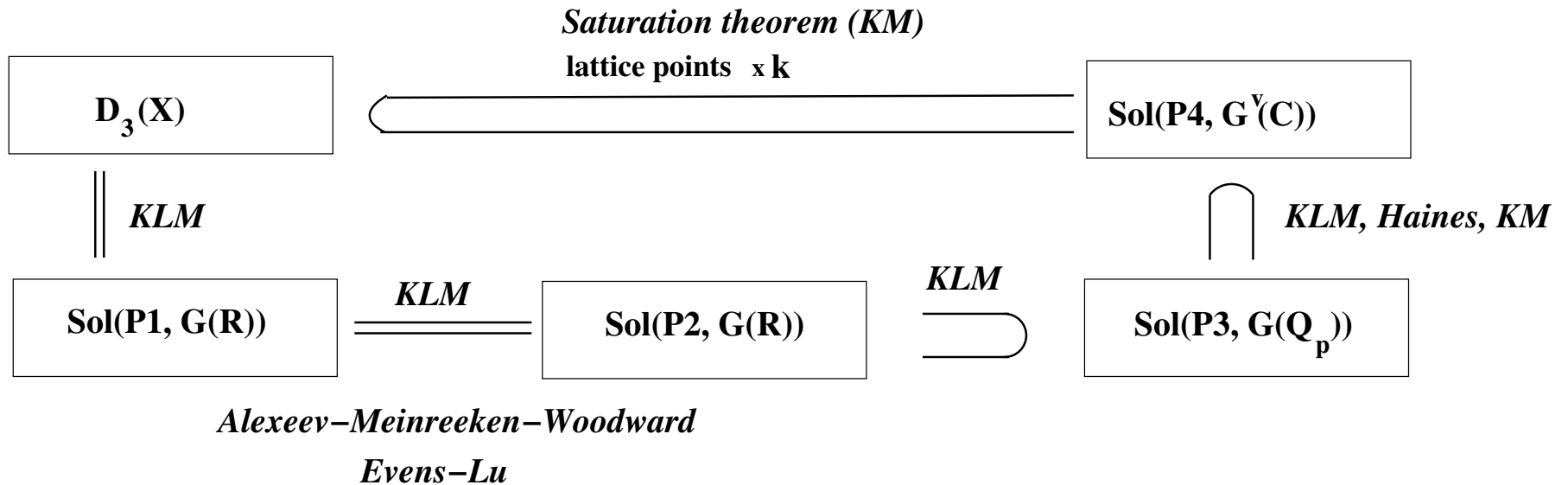
General case



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General case



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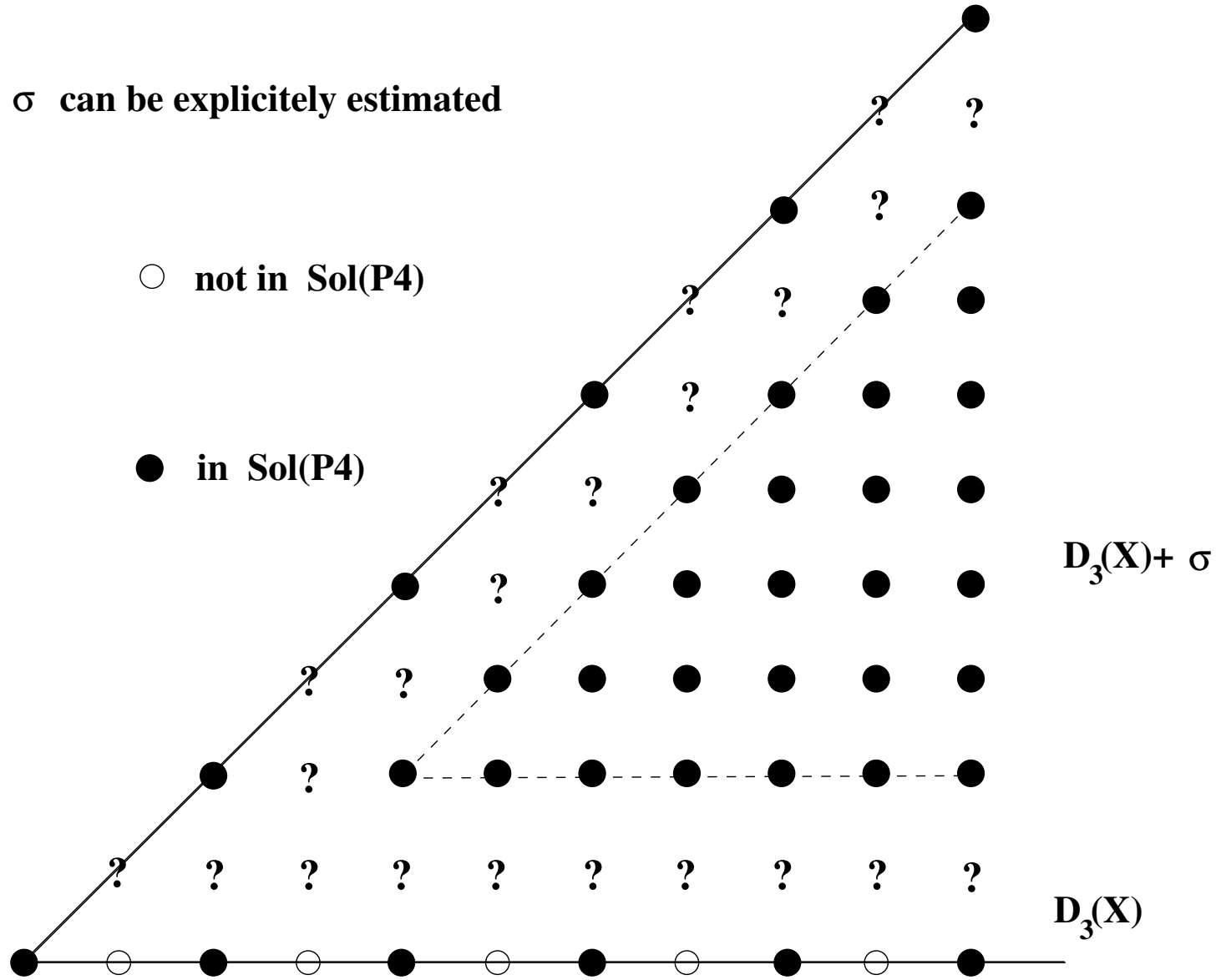
Conjecture: One can take $k = 1$ in the simply laced and $k = 2$ in the non-simply laced case.

Picture of $Sol(P4)$

σ can be explicitly estimated

○ not in $Sol(P4)$

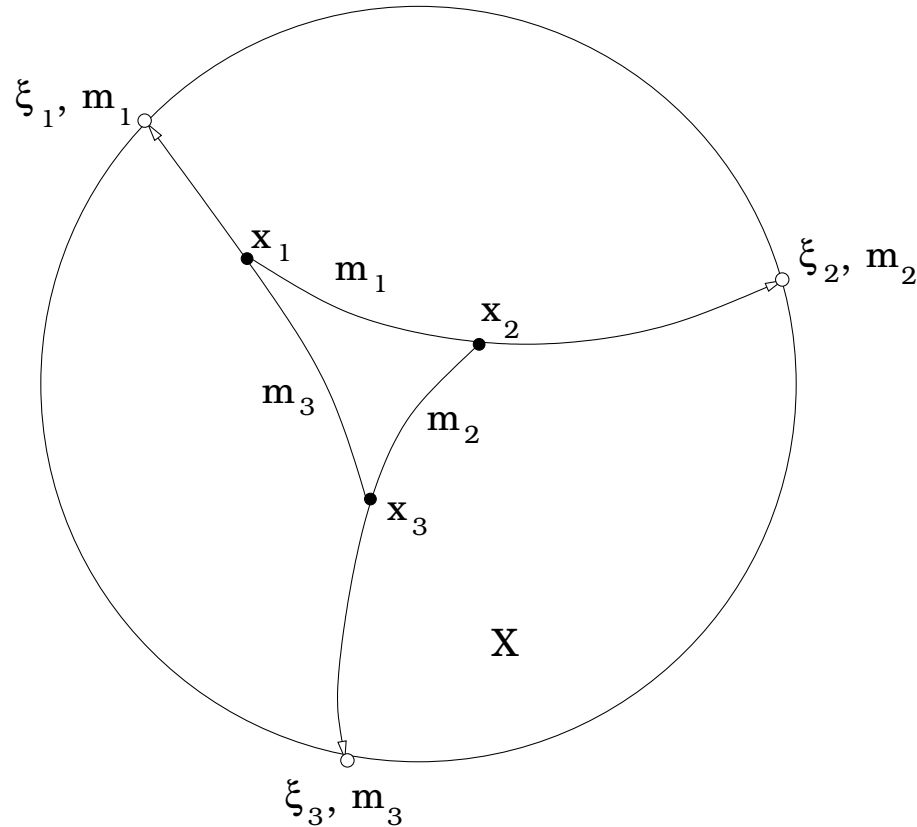
● in $Sol(P4)$



Current saturation factors k :

Root system R	Group G	k
A_m	$SL(m + 1), GL(m + 1)$	1
B_m	$SO(2m + 1), Spin(2m + 1)$	2
C_m	$Sp(2m), PSp(2m)$	2
D_m	$Spin(2m), SO(2m)$	2
G_2	G	2
F_4	G	12
E_6	G	6
E_7	G	12
E_8	G	60

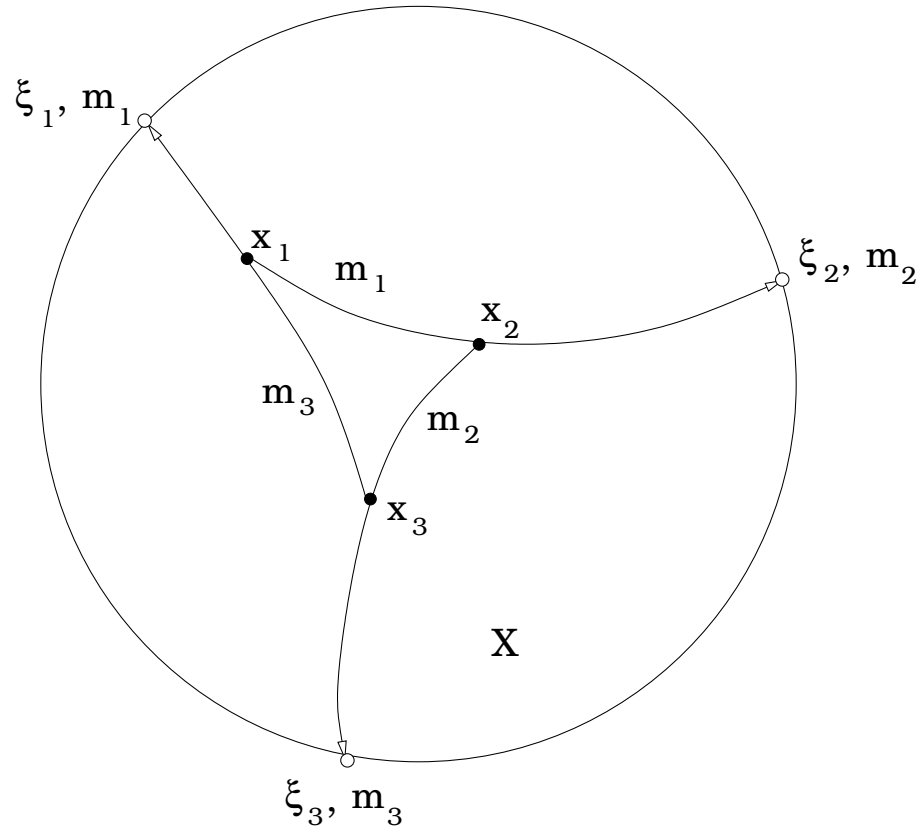
Gauss map



Gauss: Triangles \longrightarrow weighted configurations at infinity.

$$[x_1, x_2, x_3] \longrightarrow ((\xi_1, m_1), (\xi_2, m_2), (\xi_3, m_3))$$

Gauss map



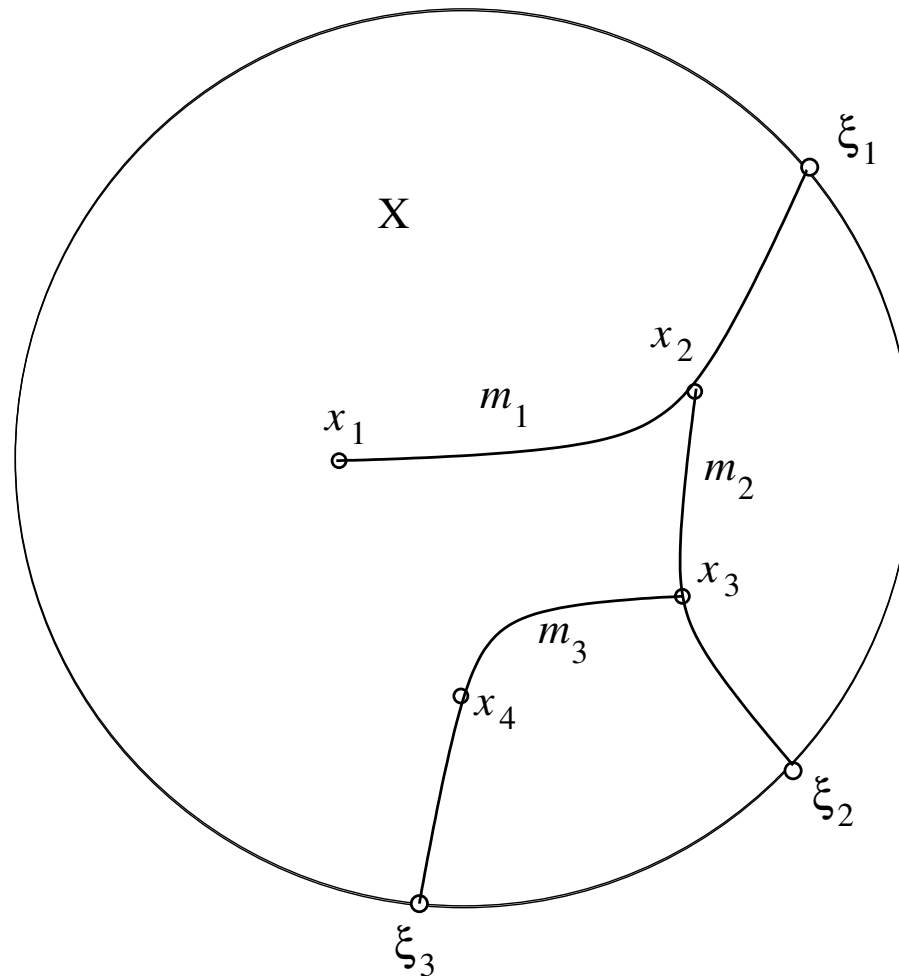
Gauss: Triangles \longrightarrow weighted configurations at infinity.

$$[x_1, x_2, x_3] \longrightarrow ((\xi_1, m_1), (\xi_2, m_2), (\xi_3, m_3))$$

We would like to invert this map.

Fixed point problem

A fixed point problem for the map $\Phi : x_1 \rightarrow x_4$. Existence \iff the weighted configuration at infinity is *nice semistable*.



Proof that D_3 depends on W only

How to transport triangles from one symmetric space (building) to another.

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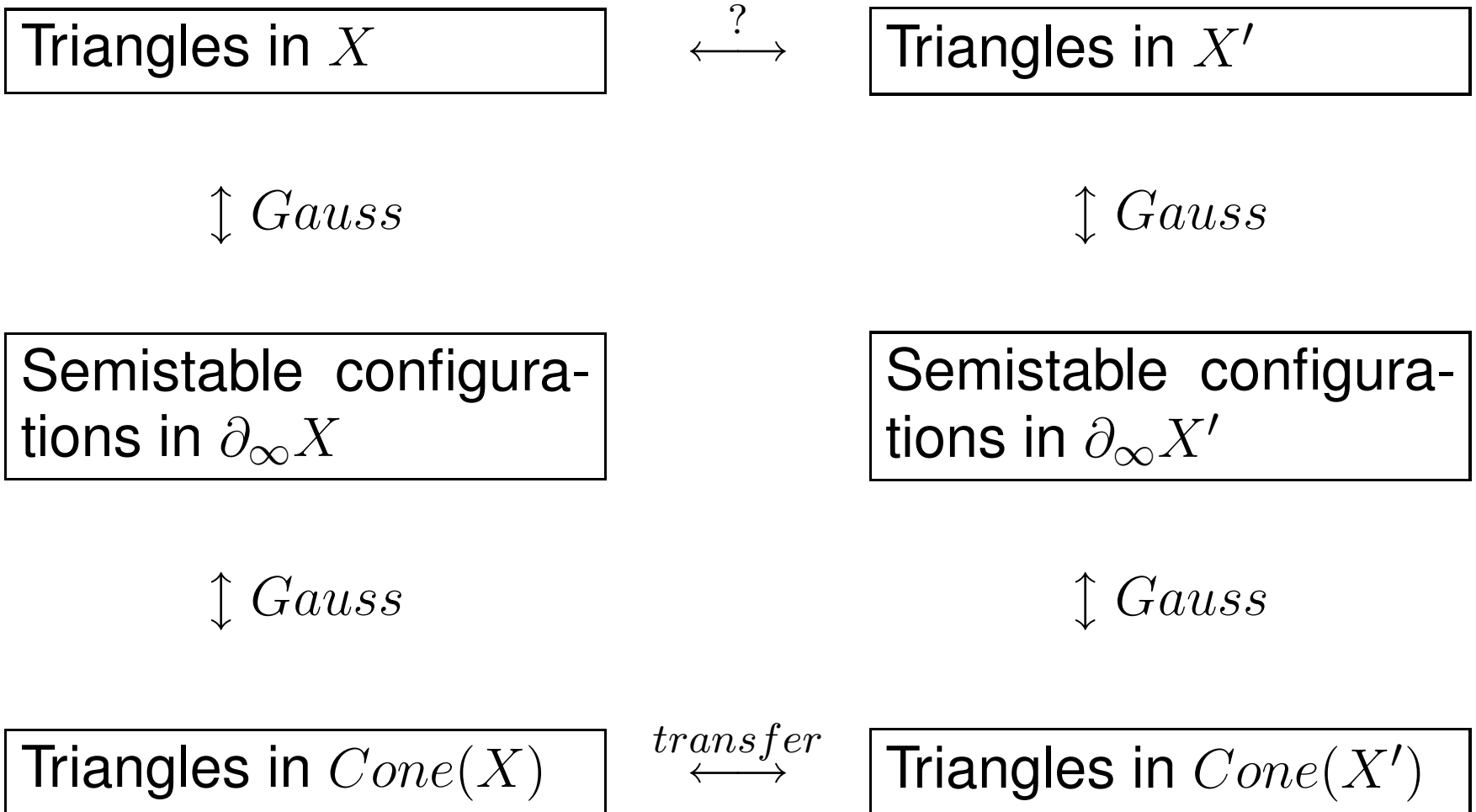
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Let X and X' have the same (finite) Weyl group.

Proof that D_3 depends on W only



References

1. M. Kapovich, B. Leeb, J. J. Millson, *Convex functions on symmetric spaces, side lengths of polygons and the stability inequalities for weighted configurations at infinity*, Preprint, 2004.
2. M. Kapovich, J. J. Millson and B. Leeb, *Polygons in buildings and their side-lengths*, Preprint, 2004.
3. M. Kapovich, J. J. Millson and B. Leeb, *Polygons in symmetric spaces and buildings with applications to algebra*, Preprint, 2004.
4. M. Kapovich, J. J. Millson, *A path model for geodesics in Euclidean buildings and its applications to the representation theory*, Preprint, 2004.