

Structural stability of meandering-hyperbolic group actions

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Abstract

In his 1985 paper Sullivan sketched a proof of his structural stability theorem for group actions satisfying certain expansion-hyperbolicity axioms. In this paper we relax Sullivan's axioms and introduce a notion of *meandering hyperbolicity* for group actions on general metric spaces. This generalization is substantial enough to encompass actions of certain non-hyperbolic groups, such as actions of *uniform lattices* in semisimple Lie groups on flag manifolds. At the same time, our notion is sufficiently robust and we prove that meandering-hyperbolic actions are still structurally stable. We also prove some basic results on meandering-hyperbolic actions and give other examples of such actions.

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1 Introduction

In [Sul85, §9. Theorem II] Sullivan stated his structural stability theorem for group actions satisfying certain expansion-hyperbolicity axioms in the C^1 -setting. Its main application was to the stability for convex-cocompact Kleinian groups, but this particular result of Sullivan appears to have been unknown outside of the communities working in Kleinian groups and holomorphic dynamics.

The history of stability for convex-cocompact (and, more generally, geometrically finite) Kleinian groups goes back to the pioneering work of Marden [Mar74] (in the case of subgroups of $\mathrm{PSL}(2, \mathbb{C})$). It appears that the first proof of stability of geometrically finite subgroups of $\mathrm{Isom}(\mathbb{H}^n)$ (the isometry group of the hyperbolic n -space) was given by Bowditch in [Bow98], although many arguments are already contained in [CEG87]. Bowditch in his paper also credits this result to P. Tukia. A generalization of the Sullivan's stability theorem for subgroups of $\mathrm{Isom}(\mathbb{H}^n)$, proving the existence of a quasiconformal conjugation on the entire sphere at infinity, was given by Izeki [Ize00].

After Sullivan’s paper [Sul85], a proof of stability for convex-cocompact subgroups of rank one semisimple Lie groups was given by Corlette [Cor90]. Corlette’s proof also goes through in the setting of C^1 -stability as it was observed by Yue [Yue96]. Unlike the proofs of Sullivan and Bowditch, however, Corlette’s proof is based on an application of Anosov flows; the same tool is used in the subsequent proofs of stability of *Anosov subgroups* of higher rank semisimple Lie groups.

The notion of Anosov subgroups was introduced by Labourie [Lab06] as a natural analogue of convex-cocompact groups, and the theory was further developed by Guichard and Wienhard [GW12] to include all word-hyperbolic groups. Subsequently, Kapovich, Leeb and Porti [KLP17] provided new characterizations of Anosov subgroups investigating their properties from many different perspectives. In particular, they gave an alternative proof of stability of Anosov subgroups in [KLP14] using coarse-geometric ideas which is quite different from the arguments of Sullivan, Bowditch and Corlette–Labourie–Guichard–Wienhard.

Recently, a notion of convex-cocompactness for discrete subgroups of $\mathrm{PGL}(n, \mathbb{R})$ was studied by Danciger, Guéritaud and Kassel in [DGK17, Definition 1.11]. While every Anosov subgroup is word-hyperbolic, convex-cocompact subgroups of $\mathrm{PGL}(n, \mathbb{R})$ in their definition are not necessarily word-hyperbolic. Nevertheless, stability in the sense of linear deformations was established for such groups in [DGK17, Theorem 1.17(D)].

In this paper we propose a new notion of *meandering hyperbolicity* of group actions on general metric spaces, which still implies the structural stability in the sense of Sullivan even though the groups need *not* be word-hyperbolic. This notion is an extension of the expansion-hyperbolicity axioms given by Sullivan and is satisfied by Anosov actions of word-hyperbolic groups on flag manifolds. We establish some basic properties of meandering-hyperbolic actions and explore various examples of such actions, most unexpected among which are actions of *uniform lattices* in semisimple Lie groups on flag manifolds. Other interesting examples include actions of word-hyperbolic groups with invariant subsets non-homeomorphic to Gromov boundaries.

Before describing our results in more detail, let us first summarize the contents of Sullivan’s paper [Sul85] in order to see the context in which his structural stability theorem appears. Let $\Gamma < \mathrm{PSL}(2, \mathbb{C})$ be a finitely generated, non-solvable, non-rigid, non-relatively-compact and torsion-free group of conformal transformations of the Riemann sphere $P^1(\mathbb{C})$. Sullivan showed that the following are equivalent:

- (1) the subgroup $\Gamma < \mathrm{PSL}(2, \mathbb{C})$ is convex-cocompact;
- (2) the Γ -action on the limit set $\Lambda \subset P^1(\mathbb{C})$ satisfies the expansion-hyperbolicity axioms;
- (3) this action is structurally stable in the sense of C^1 -dynamics;
- (4) the subgroup $\Gamma < \mathrm{PSL}(2, \mathbb{C})$ is algebraically stable.

Here $\Gamma < \mathrm{PSL}(2, \mathbb{C})$ is said to be *structurally stable in the sense of C^1 -dynamics* if, for every representation $\rho : \Gamma \rightarrow \rho(\Gamma) = \Gamma' < \mathrm{Diff}^1(P^1(\mathbb{C}))$ sufficiently close to the identity embedding, there exists a Γ' -invariant compact subset $\Lambda' \subset P^1(\mathbb{C})$ along with an equivariant homeomorphism $\phi : \Lambda \rightarrow \Lambda'$ also close to the identity embedding. It is said to be *algebraically stable* if all representations $\Gamma \rightarrow \mathrm{PSL}(2, \mathbb{C})$ sufficiently close to the identity embedding are injective.

Without defining the expansion-hyperbolicity axioms for now, we note that the implication $(4 \Rightarrow 1)$ is the main result (Theorem A) of the paper [Sul85]. The implications $(1 \Rightarrow 2)$ and $(2 \Rightarrow 3)$ are his Theorems I and II, respectively, and $(3 \Rightarrow 4)$ is immediate. For groups with torsion the implication $(4 \Rightarrow 1)$ is false (see Example 7.12) but other implications still hold. For the rest of the paper we will allow groups with torsion.

It is Sullivan’s Theorem II that we refer to as Sullivan’s structural stability theorem in the present paper. In fact, its statement is more general than the implication $(2 \Rightarrow 3)$ above.

Theorem ([Sul85, Theorem II]). *Consider a group action $\Gamma \rightarrow \text{Diff}^1(M)$ on a Riemannian manifold M with a compact invariant subset $\Lambda \subset M$. If the action satisfies the expansion-hyperbolicity axioms, then it is structurally stable in the sense of C^1 -dynamics.*

We generalize this theorem as follows. We adopt Sullivan’s remark that the theorem generalizes to actions on metric spaces. Thus we consider a continuous action of a finitely generated group Γ on a metric space M with an invariant compact subset $\Lambda \subset M$, no point of which is isolated in M ; the subset Λ plays the role of a “limit set” of Γ . We denote such an action by

$$\Gamma \rightarrow \text{Homeo}(M; \Lambda),$$

topologize the set of such actions accordingly, and talk about structural stability *in the sense of Lipschitz dynamics* (see Section 3.4). In this broader context we refer to Sullivan’s original expansion-hyperbolicity axioms as S-hyperbolicity (with the letter S standing for Sullivan). See Definitions 3.4 and 3.25. After generalizing S-hyperbolicity to what we call *meandering hyperbolicity* (Definition 3.26) we prove:

1.1 Theorem (Theorem 3.32(1)). *If an action $\Gamma \rightarrow \text{Homeo}(M; \Lambda)$ is meandering-hyperbolic, then the action is structurally stable in the sense of Lipschitz dynamics.*

See Theorem 3.32 for the full statement. This generalization of Sullivan’s theorem is significant enough to encompass actions of certain *non-hyperbolic* groups as we exhibit below. Its proof will take the entire Section 4. We mostly follow Sullivan’s idea of proof, filling in the details he sometimes left out, except in Sections 4.3, 4.8 and 4.9 where the meandering hyperbolicity condition comes in and plays a crucial role.

We investigate various examples of expanding and meandering-hyperbolic actions. Most significantly, in Section 5, we establish the following result regarding *uniform lattices* of semisimple Lie groups:

1.2 Theorem (Theorem 5.1 and Corollary 5.2). *Suppose that G is a semisimple Lie group, $P < G$ is a parabolic subgroup and $\Gamma < G$ is a uniform lattice. Then*

- (1) *the Γ -action on the flag manifold G/P is (uniformly) meandering-hyperbolic;*
- (2) *consequently, the action is structurally stable in the sense of Lipschitz dynamics.*

While stability of the action is consistent with various other rigidity properties of lattices, the hyperbolic nature of the Γ -action is a new phenomenon: higher rank lattices are traditionally regarded as having no hyperbolic features. The main tools in proving Theorem 1.2(1) are

Morse quasigeodesics in higher rank symmetric spaces and asymptotic properties of *regular* sequences in G , established in earlier papers by Kapovich, Leeb and Porti.

We hope that other interesting non-hyperbolic group actions satisfy meandering hyperbolicity as well. For example:

1.3 Conjecture. Let Γ be a group of automorphisms of a CAT(0) cube complex X , acting on X properly discontinuously and cocompactly. Then the action of Γ on the *Roller boundary* $\partial_R X$ of X is meandering-hyperbolic for a suitable metric on $\partial_R X$.

Even for word-hyperbolic groups Γ , meandering-hyperbolic actions $\Gamma \rightarrow \text{Homeo}(M; \Lambda)$ provide interesting results and examples. In such cases, we find a relation between the Γ -invariant set Λ and the Gromov boundary $\partial_\infty \Gamma$ of Γ as follows.

1.4 Theorem (Definition 3.28 and Theorem 6.7). *Let Γ be a non-elementary word-hyperbolic group. If $\Gamma \rightarrow \text{Homeo}(M; \Lambda)$ is a meandering-hyperbolic action, then there exists an equivariant continuous coding map $\pi : \Lambda \rightarrow \partial_\infty \Gamma$ to the Gromov boundary of Γ ; the map π restricts to a quasi-open map on each minimal non-empty closed Γ -invariant subset $\Lambda_\mu \subset \Lambda$.*

By definition, a map between topological spaces is said to be *nowhere constant* (resp. *quasi-open*) if the image of every non-empty open subset is not a singleton (resp. has non-empty interior).

We then explore examples of S-hyperbolic actions of word-hyperbolic groups where the coding maps π above are increasingly more complicated. Simple examples are convex-cocompact Kleinian groups and, more generally, Anosov subgroups, for which the invariant subsets Λ are equivariantly homeomorphic to the Gromov boundary $\partial_\infty \Gamma$ (via the coding map π). In contrast, there are examples where the coding map π can be a covering map (Examples 7.3 and 7.4), can be open but fail to be a local homeomorphism (Example 7.5), and can even fail to be an open map (Example 7.6).

Conversely to Theorem 1.4, we also prove:

1.5 Theorem (Theorem 6.1). *Let Γ be a non-elementary word-hyperbolic group. Suppose that $\Gamma \rightarrow \text{Homeo}(M; \Lambda)$ is an expanding action, for which there exists an equivariant continuous nowhere constant map $f : \Lambda \rightarrow \partial_\infty \Gamma$. Then the action is S-hyperbolic (and thus meandering-hyperbolic) and the map f equals the coding map π (of the previous theorem).*

We note that in the case of real-analytic expanding Γ -actions on the circle, a sharper result is proven by Deroin in [Der20]. Without assuming hyperbolicity of Γ (he only assumes finite generation and *local discreteness* of the action), Deroin proves that the action comes from a lift of a Fuchsian group action under a finite covering map $S^1 \rightarrow S^1$. Compare Example 7.3.

Building upon the work in [KLP17] and Theorem 1.5, we give a (yet another) new characterization of Anosov subgroups in terms of expanding actions. See Theorem 6.13. This characterization shows, among other things, that the action of any Anosov group on its flag limit set in the partial flag manifold is S-hyperbolic. Thus, thanks to Theorem 1.1, we

obtain the stability of Anosov groups in a broader context of group actions on metric spaces than those in [GW12, Theorem 5.13] and [KLP14, Theorems 1.11 and 7.36]. Based on this we also obtain an alternative proof for the openness of Anosov property in the representation variety (Corollary 6.15).

We remark that Bochi, Potrie and Sambarino [BPS19] provided a purely dynamical proof of the structural stability of Anosov representations, which shares many similarities with the concepts in the present paper. For example, one may compare the expansion subsets with the notion of multicones in [BPS19, Section 5]. The existence of codings appears in [BPS19, Lemma 3.20] and the expansion property in [BPS19, Lemma 3.21]. (We thank the referee for pointing out these similarities to us.) On the other hand, in the setting of S-hyperbolic actions, such as Anosov actions, all the ideas in the proof of Theorem 1.1 go back to Sullivan's paper [Sul85].

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2 Notation and preliminaries

The identity element of an abstract group will be denoted by e . We will use the following notation for the sets of non-negative integers and natural numbers:

$$\mathbb{N}_0 = \{0, 1, 2, \dots\} \quad \text{and} \quad \mathbb{N} = \{1, 2, 3, \dots\}.$$

We will follow the Bourbaki convention that neighborhoods of a point a (resp. a subset A) in a topological space X need not be open but are only required to contain an open subset which, in turn, contains a (resp. A). In particular, a topological space X is locally compact if and only if every point in X admits a neighborhood basis consisting of compact subsets of X .

A topological space is called *perfect* if it has no isolated points and has cardinality ≥ 2 .

A map between topological spaces is *nowhere constant* if the image of every open subset is not a singleton. A map is said to be *open* if it sends open sets to open sets. A map $f : X \rightarrow Y$ is *open at a point* $x \in X$ if it sends every neighborhood of x to a neighborhood of $f(x)$. We let O_f denote the subset of X consisting of points where f is open. Thus, a map f is open if and only if $O_f = X$.

A map $f : X \rightarrow Y$ is said to be *quasi-open* (or *quasi-interior*) if for every subset $A \subset X$ with non-empty interior, the image $f(A)$ has non-empty interior in Y . If $f : X \rightarrow Y$ is a

continuous map between locally compact metrizable spaces then it is quasi-open if and only if the subset $O_f \subset X$ is comeagre (that is, its complement is a countable union of nowhere dense subsets). For instance, the map $\mathbb{R} \rightarrow \mathbb{R}, x \mapsto x^2$, is quasi-open but not open. A more interesting example of a (non-open) quasi-open map is a *Cantor function* $f : C \rightarrow [0, 1]$, which is a continuous surjective monotonic function from a Cantor set $C \subset \mathbb{R}$. It has the property that $x_1 < x_2$ implies $f(x_1) < f(x_2)$ unless x_1, x_2 are boundary points of a component of $\mathbb{R} - C$. Thus, $C - O_f$ is the countable subset consisting of boundary points of components of $\mathbb{R} - C$.

Let (X, d) be a metric space. Given $x \in X$ and $r > 0$, the open (resp. closed) r -ball centered at x is denoted by $B_r(x)$ (resp. $\overline{B}_r(x)$). Given a subset $\Lambda \subset X$, its open (resp. closed) r -neighborhood is denoted by $N_r(\Lambda)$ (resp. $\overline{N}_r(\Lambda)$). A *Lebesgue number* of an open cover \mathcal{U} of Λ is defined to be a number $\delta > 0$ such that, for every $x \in \Lambda$, the δ -ball $B_\delta(x)$ is contained in some member of \mathcal{U} ; we denote

$$\delta_{\mathcal{U}} = \sup\{\delta \mid \delta \text{ is a Lebesgue number of } \mathcal{U}\}.$$

For a subset $U \subset X$ and $r > 0$ we define

$$(2.1) \quad U^r = \{x \in U \mid B_r(x) \subset U\} \subset U.$$

A sequence of subsets $W_i \subset X$ is said to be *exponentially shrinking* if the diameters of these subsets converge to zero exponentially fast, that is, there exist constants $A, C > 0$ such that

$$\text{diam}(W_i) \leq A e^{-Ci}$$

for all i .

If X is a Riemannian manifold and Φ is a diffeomorphism of X , the *expansion factor* of Φ at $x \in X$ is defined as

$$(2.2) \quad \epsilon(\Phi, x) = \inf_{0 \neq v \in T_x X} \frac{\|D_x \Phi(v)\|}{\|v\|}.$$

We now present some dynamical and geometric preliminaries to be used later. For more details we refer the readers to [BH99] and [DK18].

2.1 Topological dynamics

A continuous action $\Gamma \times Z \rightarrow Z$ of a topological group on a topological space is *minimal* if Z contains no proper closed Γ -invariant subsets or, equivalently, if every Γ -orbit is dense in Z . A point $z \in Z$ is a *wandering point* for an action $\Gamma \times Z \rightarrow Z$ if there exists a neighborhood U of z such that $gU \cap U = \emptyset$ for all but finitely many $g \in \Gamma$. If the space Z is metrizable, then a point $z \in Z$ is *not* a wandering point if and only if there exist a sequence (g_n) of distinct elements in Γ and a sequence (z_n) in Z converging to z such that $g_n z_n \rightarrow z$. For further discussion of dynamical relations between points under group actions, see [KL18, §4.3].

A continuous action $\Gamma \times Z \rightarrow Z$ of a discrete group Γ on a compact metrizable topological space Z is a *convergence action* if the product action of Γ on Z^3 restricts to a properly discontinuous action on

$$T(Z) = \{(z_1, z_2, z_3) \in Z^3 \mid \text{card}\{z_1, z_2, z_3\} = 3\}.$$

Equivalently, a continuous action of a discrete group is a convergence action if every sequence (g_i) contains a subsequence (g_{i_j}) which is either constant or converges to a point $z_+ \in Z$ uniformly on compacts in $Z - \{z_-\}$ for some $z_- \in Z$; see [Bow98b, Proposition 7.1]. In this situation, the inverse sequence $(g_{i_j}^{-1})$ converges to z_- uniformly on compacts in $Z - \{z_+\}$. The set of such limit points z_+ is the *limit set* Λ of the action of Γ ; this is a closed Γ -invariant subset of Z . Observe that a convergence action need not be faithful but it necessarily has finite kernel, provided that $T(Z) \neq \emptyset$. A convergence action on Z is called *uniform* if it is cocompact on $T(Z)$.

Item (1) of the following theorem can be found in [Tuk94, Theorem 2S]; for item (2) see [Tuk98, Theorem 1A] for instance.

2.3 Theorem. *Suppose $\Gamma \times Z \rightarrow Z$ is a convergence action with limit set Λ such that $\text{card}(\Lambda) \geq 3$. Then*

- (1) Λ is perfect and the action is minimal on Λ .
- (2) If the action is uniform and Z is perfect, then $Z = \Lambda$.

2.2 Coarse geometry

A metric space (X, d) is *proper* if the closed ball $\overline{B}_r(x)$ is compact for every $x \in X$ and every $r > 0$. Note that proper metric spaces are complete. A metric space (X, d) is called a *geodesic space* if every pair of points $x, y \in X$ can be joined by a geodesic segment xy , that is, an isometric embedding of an interval into X joining x to y .

2.4 Definition (Quasi-geodesic). Let I be an interval of \mathbb{R} (or its intersection with \mathbb{Z}) and (X, d) a metric space. A map $c : I \rightarrow X$ is called an (A, C) -*quasigeodesic* with constants $A \geq 1$ and $C \geq 0$ if for all $t, t' \in I$,

$$\frac{1}{A}|t - t'| - C \leq d(c(t), c(t')) \leq A|t - t'| + C.$$

2.5 Definition (Hyperbolic space). Let $\delta \geq 0$. A geodesic space X is said to be δ -*hyperbolic* if for any geodesic triangle in X , each side of the triangle is contained in the closed δ -neighborhood of the union of the other two sides. A geodesic space is said to be *hyperbolic* if it is δ -hyperbolic for some $\delta \geq 0$.

Let X be a proper δ -hyperbolic space. Two geodesic rays $\mathbb{R}_{\geq 0} \rightarrow X$ are said to be *asymptotic* if the Hausdorff distance between their images is finite. Being asymptotic is an equivalence relation on the set of geodesic rays. The set of equivalence classes of geodesic rays in X is called the *visual boundary* of X and denoted by $\partial_\infty X$. In view of the Morse

lemma for hyperbolic spaces (see [BH99, Theorem III.H.1.7] or [DK18, Lemma 11.105] for example), one can also define $\partial_\infty X$ as the set of equivalence classes of quasigeodesic rays $\mathbb{R}_{\geq 0} \rightarrow X$. We will use the notation $x\xi$ for a geodesic ray in X emanating from x and representing the point $\xi \in \partial_\infty X$.

Fix $k > 2\delta$ and let $c_0 : \mathbb{R}_{\geq 0} \rightarrow X$ be a geodesic ray representing $\xi \in \partial_\infty X$ with $c_0(0) = x$. A topology on $\partial_\infty X$ is given by setting the basis of neighborhoods of ξ to be the collection $\{V_n(\xi)\}_{n \in \mathbb{N}}$, where $V_n(\xi)$ is the set of equivalence classes of geodesic rays c such that $c(0) = x$ and $d(c(n), c_0(n)) < k$. This topology extends to the *visual compactification* of X

$$\overline{X} := X \cup \partial_\infty X,$$

which is a compact metrizable space. We refer to [BH99, III.H.3.6] for details.

Let $x, y, z \in X$. The *Gromov product* of y and z with respect to x is defined by

$$(y \cdot z)_x := \frac{1}{2}(d(x, y) + d(x, z) - d(y, z)).$$

The Gromov product is extended to $X \cup \partial_\infty X$ by

$$(y \cdot z)_x := \sup \liminf_{i, j \rightarrow \infty} (y_i \cdot z_j)_x,$$

where the supremum is taken over all sequences (y_i) and (z_j) in X such that $\lim y_i = y$ and $\lim z_j = z$.

2.6 Definition (Visual metric). Let X be a hyperbolic space with base point $x \in X$. A metric d_a on $\partial_\infty X$ is called a *visual metric* with parameter $a > 1$ if there exist constants $k_1, k_2 > 0$ such that

$$k_1 a^{-(\xi \cdot \xi')_x} \leq d_a(\xi, \xi') \leq k_2 a^{-(\xi \cdot \xi')_x}$$

for all $\xi, \xi' \in \partial_\infty X$.

For every $a > 1$ sufficiently close to 1, a proper hyperbolic space admits a visual metric d_a which induces the same topology as the topology on $\partial_\infty X$ described above. We refer to [BH99, Chapter III.H.3] for more details on constructing visual metrics.

In the rest of the section we discuss hyperbolic groups and their relation to convergence actions.

2.7 Definition (Hyperbolic group). A finitely generated group Γ is *word-hyperbolic* (or simply *hyperbolic*) if its Cayley graph with respect to a finite generating set of Γ is a hyperbolic metric space. A hyperbolic group is called *elementary* if it contains a cyclic subgroup of finite index and *non-elementary* otherwise.

The *Gromov boundary* $\partial_\infty \Gamma$ of a hyperbolic group Γ is defined as the visual boundary of a Cayley graph X of Γ . The closure of $\Gamma \subset X$ in the visual compactification \overline{X} equals $\Gamma \cup \partial_\infty \Gamma$ and is denoted $\overline{\Gamma}$; it is the *visual compactification* of Γ .

Every hyperbolic group Γ acts on its visual compactification $\bar{\Gamma}$ by homeomorphisms. This action is a convergence action; see [Tuk94, Theorem 3.A] and [Fre95]. If a sequence (c_i) in Γ represents a quasigeodesic ray within bounded distance from a geodesic ray $g\mu$ ($g \in \Gamma$, $\mu \in \partial_\infty\Gamma$), then this sequence, regarded as a sequence of maps $\bar{\Gamma} \rightarrow \bar{\Gamma}$, converges to μ uniformly on compacts in $\bar{\Gamma} - \{\mu'\}$ for some $\mu' \in \partial_\infty\Gamma$. We will use the following consequence of this property later in the proof of Theorem 6.1:

2.8 Lemma. *Suppose that $c : \mathbb{N}_0 \rightarrow \Gamma$, $i \mapsto c_i$, is an (A, C) -quasigeodesic ray in Γ such that*

- *the word length of c_0 is ≤ 1 , and*
- *there exists a subsequence (c_{i_j}) converging to a point $\xi \in \partial_\infty\Gamma$ pointwise on a subset $S \subset \partial_\infty\Gamma$ with $\text{card}(S) \geq 2$.*

Then the image $c(\mathbb{N}_0)$ is D -Hausdorff close to a geodesic $e\xi$ in the Cayley graph X of Γ , where D depends only on (A, C) and the hyperbolicity constant of X .

Proof. Since the word length of c_0 is ≤ 1 , the Morse lemma for hyperbolic groups implies that there is a geodesic ray $e\mu$ ($\mu \in \partial_\infty\Gamma$) starting at the identity $e \in \Gamma$ such that the Hausdorff distance between the image $c(\mathbb{N}_0)$ and the ray $e\mu$ in X is bounded above by a uniform constant $D > 0$ depending only on (A, C) and X .

By the above property, the sequence (c_i) converges to μ uniformly on compacts in $\bar{\Gamma} - \{\mu'\}$ for some $\mu' \in \partial_\infty\Gamma$. On the other hand, since $\text{card}(S) \geq 2$, there is a point $\nu \in S$ distinct from μ' such that the subsequence (c_{i_j}) converges to ξ on $\{\nu\} \subset \partial_\infty\Gamma$. Therefore, we must have $\mu = \xi$ and $e\mu = e\xi$. \square

Furthermore, the action of Γ on $\partial_\infty\Gamma$ is a uniform convergence action. In particular, if Γ is non-elementary then this action has finite kernel (the unique maximal finite normal subgroup of Γ), is minimal, and $\partial_\infty\Gamma$ is a perfect topological space; compare Theorem 2.3. We refer to [DK18, Lemma 11.130] for more details.

Conversely, Bowditch [Bow98b] gave a topological characterization of hyperbolic groups and their Gromov boundaries as uniform convergence actions $\Gamma \times Z \rightarrow Z$ of discrete groups on perfect metrizable topological spaces:

2.9 Theorem (Bowditch). *Suppose that Z is a compact perfect metrizable space of cardinality ≥ 2 and $\Gamma \times Z \rightarrow Z$ is a continuous action of a discrete group, which is a uniform convergence action. Then Γ is a non-elementary hyperbolic group and Z is equivariantly homeomorphic to the Gromov boundary $\partial_\infty\Gamma$.*

2.3 Geometry of symmetric spaces

We collect several definitions regarding the geometry of symmetric spaces that are necessary for our presentation in Sections 5, 6 and 7. For more details, readers may refer to [BGS85], [Ebe96] or [KLP17, Section 2].

Let X be a symmetric space of non-compact type. Then the identity component, denoted by G , of the group of isometries of X is a connected semisimple Lie group with trivial center and no compact factors. For a point $x \in X$, its stabilizer K in G is a maximal compact subgroup and the quotient space G/K is G -equivariantly diffeomorphic to X .

The visual boundary $\partial_\infty X$ of X has a topological spherical building structure, the Tits building associated to X . Let a_{mod} denote the model apartment of this building and W the Weyl group acting isometrically on a_{mod} . We will fix a chamber $\sigma_{\text{mod}} \subset a_{\text{mod}}$ and call it the *spherical model Weyl chamber*; it is a fundamental domain for the W -action on a_{mod} . Let $w_0 \in W$ denote the unique element sending σ_{mod} to the opposite chamber $-\sigma_{\text{mod}}$. Then the *opposition involution* ι of the model chamber σ_{mod} is defined as $\iota = -w_0$.

We denote by $\Delta := \Delta_{\text{mod}}$ the *model Weyl chamber* corresponding to σ_{mod} , a fundamental domain for the W -action on the model (maximal) flat F_{mod} of X . We will use the notation d_Δ for the G -invariant Δ -valued distance function on X .

Consider the induced action of G on $\partial_\infty X$. Every orbit intersects every chamber exactly once, so there is a natural identification $\partial_\infty X/G \cong \sigma_{\text{mod}}$. The projection $\theta : \partial_\infty X \rightarrow \partial_\infty X/G$ is called the *type map*. Let τ_{mod} be a face of σ_{mod} . We will assume, in what follows, that the simplex τ_{mod} is ι -invariant. The τ_{mod} -*flag manifold* $\text{Flag}(\tau_{\text{mod}})$ is the space of simplices of type τ_{mod} in $\partial_\infty X$. It has a structure of a compact smooth manifold and can be identified with the quotient space G/P_τ , where $P_\tau < G$ is the stabilizer subgroup of a simplex $\tau \subset \partial_\infty X$ of type $\theta(\tau) = \tau_{\text{mod}}$. Two simplices τ_1 and τ_2 in $\partial_\infty X$ are said to be *antipodal* if they are opposite in an apartment containing both of them; their types are related by $\theta(\tau_2) = \iota\theta(\tau_1)$. A subset E of $\text{Flag}(\tau_{\text{mod}})$ is said to be *antipodal* if any two distinct elements of E are antipodal. A map into $\text{Flag}(\tau_{\text{mod}})$ is *antipodal* if it is injective and has antipodal image. We shall always assume that $\text{Flag}(\tau_{\text{mod}})$ is equipped with an auxiliary Riemannian metric.

Let $\tau \subset \partial_\infty X$ be a simplex of type τ_{mod} . The *star* $\text{st}(\tau) \subset \partial_\infty X$ is the union of all chambers containing τ . We denote by $\partial \text{st}(\tau)$ the union of all simplices in $\text{st}(\tau)$ which do not contain τ , and define $\text{ost}(\tau) := \text{st}(\tau) - \partial \text{st}(\tau)$. We denote by $W_{\tau_{\text{mod}}}$ the W -stabilizer of τ_{mod} . A subset $\Theta \subset \sigma_{\text{mod}}$ is $W_{\tau_{\text{mod}}}$ -*convex* if its symmetrization $W_{\tau_{\text{mod}}}\Theta \subset a_{\text{mod}}$ is convex; for such a subset Θ we define $\text{st}_\Theta(\tau) := \text{st}(\tau) \cap \theta^{-1}(\Theta)$.

For $x \in X$ and $S \subset \partial_\infty X$ the *Weyl cone* $V(x, S) \subset X$ is defined to be the union of rays $x\xi$ ($\xi \in S$). For a flat $f \subset X$ the *parallel set* $P(f)$ is the union of all flats f' such that $\partial_\infty f' = \partial_\infty f$. For a pair of antipodal simplices $\tau_1, \tau_2 \subset \partial_\infty X$ we define $P(\tau_1, \tau_2)$ to be the parallel set of the unique minimal flat whose ideal boundary contains $\{\tau_1, \tau_2\}$; equivalently, it is the union of all geodesics in X which are forward/backward asymptotic to points in τ_1 and τ_2 .

2.10 Definition (Finsler geodesic). A τ_{mod} -*Finsler geodesic* is a continuous path $c : I \rightarrow X$ contained in a parallel set $P(\tau_1, \tau_2)$ for $\tau_1, \tau_2 \in \text{Flag}(\tau_{\text{mod}})$ such that $c(t_2) \in V(c(t_1), \text{st}(\tau_2))$ for all subintervals $[t_1, t_2] \subset I$. It is *uniformly τ_{mod} -regular* if $c(t_2) \in V(c(t_1), \text{st}_\Theta(\tau_2))$ for some $W_{\tau_{\text{mod}}}$ -convex compact subset $\Theta \subset \text{int}_{\tau_{\text{mod}}}(\sigma_{\text{mod}})$.

Let xy be a τ_{mod} -*regular* oriented geodesic segment in X and $x\xi$ the geodesic ray extending xy . We denote $\tau(xy)$ the unique simplex $\tau \in \text{Flag}(\tau_{\text{mod}})$ such that $\xi \in \text{ost}(\tau)$. Let $\Theta \subset \text{int}_{\tau_{\text{mod}}}(\sigma_{\text{mod}})$. Then xy is Θ -*regular* if $\theta(\xi) \in \Theta$. If x_1x_2 is Θ -regular, we define its Θ -*diamond* by

$$\diamond_\Theta(x_1, x_2) = V(x_1, \text{st}_\Theta(\tau(x_1x_2))) \cap V(x_2, \text{st}_\Theta(\tau(x_2x_1))).$$

2.11 Definition (Morse quasigeodesic). A (discrete) quasigeodesic $q : I \cap \mathbb{Z} \rightarrow X$ is (Θ, R) -Morse if for every subinterval $[n_1, n_2] \subset I$ the subpath $q|_{[n_1, n_2] \cap \mathbb{Z}}$ is contained in the R -neighborhood of the diamond $\diamond_{\Theta}(x_1, x_2)$ such that $d(x_i, q(n_i)) \leq R$ for $i = 1, 2$.

It is shown in [KLP17, Theorem 5.53] that (Θ, R) -Morse quasigeodesic rays (resp. lines) are uniformly Hausdorff close to a uniformly τ_{mod} -regular Finsler geodesic rays (resp. lines).

3 The structural stability theorem

Throughout Sections 3 and 4, we let (M, d) be a proper metric space and suppose that a discrete group Γ acts continuously on M with a non-empty invariant compact subset $\Lambda \subset M$, no point of which is isolated in M . That is, there is a homomorphism $\rho : \Gamma \rightarrow \text{Homeo}(M)$ such that $\rho(\Gamma)(\Lambda) = \Lambda$. Henceforth, we shall simply write such an action as

$$\rho : \Gamma \rightarrow \text{Homeo}(M; \Lambda)$$

or as $\rho : \Gamma \rightarrow \text{Homeo}(\Lambda)$ when $M = \Lambda$.

3.1 Remark. Note that we do not assume faithfulness of the action of Γ on Λ and even on M .

In this situation, one considers two conditions on ρ called the *expansion* and *meandering hyperbolicity* conditions, respectively. In the present section, we define the expansion condition, and draw the key Lemma 3.18 as well as its various consequences (Sections 3.1-3.2). We then define the meandering hyperbolicity condition (Section 3.3) and formulate the structural stability theorem (Section 3.4).

3.1 The expansion condition

In order to define the expansion condition we need a little preparation.

Let f be a homeomorphism of M . Given $\lambda > 1$ and $U \subset M$, we say f is (λ, U) -*expanding* (or λ -*expanding on* U) if

$$d(f(x), f(y)) \geq \lambda \cdot d(x, y)$$

for all $x, y \in U$. In this case, we also say U is a (λ, f) -*expanding subset*. Note that f is (λ, U) -expanding if and only if f^{-1} is $(\lambda^{-1}, f(U))$ -*contracting*, that is,

$$d(f^{-1}(x), f^{-1}(y)) \leq \frac{1}{\lambda} \cdot d(x, y)$$

for all $x, y \in f(U)$.

Given $\delta > 0$, a (λ, U) -expanding homeomorphism f is said to be $(\lambda, U; \delta)$ -*expanding* if

$$B_{\lambda\eta}(f(x)) \subset f(B_{\eta}(x)) \quad \text{whenever } B_{\eta}(x) \subset U \text{ and } \eta \leq \delta.$$

Clearly, if f is $(\lambda, U; \delta)$ -expanding then it is also $(\lambda, U; \delta')$ -expanding for every $\delta' \leq \delta$.

3.2 Lemma. *If M is a geodesic metric space, then every (λ, U) -expanding homeomorphism is also $(\lambda, U; \delta)$ -expanding for every δ .*

Proof. Suppose to the contrary that there exists a point

$$y \in B_{\lambda\eta}(f(x)) \setminus f(B_\eta(x)).$$

Let c be a geodesic path in M connecting $f(x)$ and y ; the length of this geodesic is less than $\lambda\eta$. Since $f(B_\eta(x))$ is open in M , the path c crosses the boundary of $f(B_\eta(x))$ at a point z . Because f is λ -expanding on the set U containing $B_\eta(x)$ and $f^{-1}(z) \in \partial B_\eta(x)$, we have

$$d(f(x), y) \geq d(f(x), z) \geq \lambda d(x, f^{-1}(z)) = \lambda\eta.$$

This contradicts the assumption that $y \in B_{\lambda\eta}(f(x))$, that is, $d(f(x), y) < \lambda\eta$. \square

The implication in the lemma does not hold for general metric spaces. As a simple example, consider a compact metric space M of diameter D , which is not a singleton, but contains an isolated point x . Consider $f = \text{Id}_M$ and take a neighborhood U of x and $\eta > 0$ such that $\{x\} = B_\eta(x) \subset U = \{x\}$. Then f is (λ, U) -expanding for *any* $\lambda > 1$. Thus, taking λ such that $\lambda\eta \geq D$, we see that

$$M = B_{\lambda\eta}(f(x)) \subsetneq f(B_\eta(x)) = B_\eta(x) = \{x\}.$$

However, we note the following fact:

3.3 Lemma. *Suppose that f is (λ, U) -expanding, where U is a bounded open subset of M . Then for every $\delta > 0$ there exists $\delta' = \delta'_U > 0$ such that f is $(\lambda, U'; \delta')$ -expanding with $U' := \text{int } U^\delta \subset U$.*

Proof. Since $f(U^\delta)$ is compact, we have $\epsilon := d(f(U^\delta), M - f(U)) > 0$. Now we let $\delta' := \lambda^{-1} \cdot \min\{\delta, \epsilon\}$. If $\eta \leq \delta'$ and $B_\eta(x) \subset U'$, in particular, $f(x) \in f(U^\delta)$, then we have $B_{\lambda\eta}(f(x)) \subset B_\epsilon(f(x)) \subset f(U)$ and hence $f^{-1}[B_{\lambda\eta}(f(x))] \subset B_\eta(x)$, since f^{-1} is $(1/\lambda, f(U))$ -contracting. Therefore, we conclude that $B_{\lambda\eta}(f(x)) \subset f(B_\eta(x))$. \square

We are now ready to define the expansion condition.

3.4 Definition (Expansion). An action $\rho : \Gamma \rightarrow \text{Homeo}(M; \Lambda)$ is said to be *expanding* (at Λ) if there exist

- a finite index set \mathcal{I} ,
- a cover $\mathcal{U} = \{U_\alpha \subset M \mid \alpha \in \mathcal{I}\}$ of Λ by open (and possibly empty) subsets U_α ,
- a map $s : \mathcal{I} \rightarrow \Gamma$, $\alpha \mapsto s_\alpha$,
- and positive real numbers $L \geq \lambda > 1$ and $\delta \leq \delta_{\mathcal{U}}$

such that, for every $\alpha \in \mathcal{I}$, the map $\rho(s_\alpha^{-1})$ is

- (i) L -Lipschitz on $N_\delta(\Lambda)$, and
- (ii) $(\lambda, U_\alpha; \delta)$ -expanding,

and that the image $\Sigma := \{s_\alpha \mid \alpha \in \mathcal{I}\} \subset \Gamma$ of the map s is a symmetric generating set of the group Γ .

In this case, the datum $\mathcal{D} := (\mathcal{I}, \mathcal{U}, \Sigma, \delta, L, \lambda)$ (or, occasionally, any subset thereof) will be referred to as an *expansion datum* of ρ .

If $\rho : \Gamma \rightarrow \text{Homeo}(M; \Lambda)$ is an expanding action, let $|\cdot|_\Sigma$ (resp. d_Σ) denote the word length (resp. the word metric) on the group Γ with respect to the generating set Σ from Definition 3.4. Then the L -Lipschitz property (i) implies that

$$(3.5) \quad \text{the map } \rho(g) \text{ is } L^k\text{-Lipschitz on } N_{\delta/L^{k-1}}(\Lambda)$$

for every $g \in \Gamma$ with $|g|_\Sigma = k \in \mathbb{N}$.

3.6 Remark. A few more remarks are in order.

- (a) Expanding actions appear naturally in the context of Anosov actions on flag manifolds [KLP17, Definition 3.1] and hyperbolic group actions on their Gromov boundaries equipped with visual metrics [Coo93]. See Section 6 for further discussion.
- (b) The symmetry of the generating set Σ means that $s \in \Sigma$ if and only if $s^{-1} \in \Sigma$. This implies that $\rho(s_\alpha)$ is L -bi-Lipschitz on $N_{\delta/L}(\Lambda)$ for all $\alpha \in \mathcal{I}$.
- (c) Suppose that M is a Riemannian manifold and the action ρ is by C^1 -diffeomorphisms. Then, ρ is expanding provided that for every $x \in \Lambda$ there exists $g \in \Gamma$ such that $\epsilon(\rho(g), x) > 1$ (see (2.2)). Indeed, by compactness of Λ , there exists a finite cover $\mathcal{U} = \{U_\alpha \mid \alpha \in \mathcal{I}\}$ of Λ and a collection Σ of group elements $s_\alpha \in \Gamma$ such that each $\rho(s_\alpha^{-1})$ is $(\lambda, U_\alpha; \delta_{\mathcal{U}})$ -expanding. By adding, if necessary, extra generators to Σ with empty expanding subsets, we obtain the required symmetric generating set of Γ .
- (d) If $U_\alpha = \emptyset$ for some $\alpha \in \mathcal{I}$ then the condition (ii) is vacuous for this α . Otherwise, it implies that the inverse $\rho(s_\alpha)$ is $(\lambda^{-1}, \rho(s_\alpha^{-1})[U_\alpha])$ -contracting.
- (e) The condition (ii) can be relaxed to the mere (λ, U_α) -expanding condition. Namely, we may first modify the cover $\mathcal{U} = \{U_\alpha \mid \alpha \in \mathcal{I}\}$ so that U_α are all bounded. Then, in view of Lemma 3.3, we can modify it further to $\mathcal{U}' = \{U'_\alpha \mid \alpha \in \mathcal{I}\}$, where $U'_\alpha := \text{int } U_\alpha^\delta$ as in the lemma. For each $\alpha \in \mathcal{I}$ we also let $\delta'_{U'_\alpha}$ denote the number δ'_U given by the lemma, and set

$$\delta' := \min\{\delta_{\mathcal{U}'}, \delta'_{U'_\alpha} \mid \alpha \in \mathcal{I}\}.$$

After such modification \mathcal{U}' is still an open cover of Λ and the maps $\rho(s_\alpha^{-1})$ are $(\lambda, U'_\alpha; \delta')$ -expanding.

- (f) The map $s : \mathcal{I} \rightarrow \Sigma \subset \Gamma$ is not necessarily injective: the ρ -image of an element of Γ can have several expansion subsets. See Examples 3.35, 7.3 and 7.4.
- (g) Clearly, the properties (i) and (ii) also hold on the closures $\overline{N}_\delta(\Lambda)$ and \overline{U}_α , respectively.

It is possible that an action $\rho : \Gamma \rightarrow \text{Homeo}(M; \Lambda)$ is expanding with different expansion data. In such a case we define a relation on the expansion data as follows.

3.7 Definition. Let $\rho : \Gamma \rightarrow \text{Homeo}(M; \Lambda)$ be expanding with expansion data $\mathcal{D}_0 = (\mathcal{I}_0, \mathcal{U}_0, \Sigma_0, \delta_0, L_0, \lambda_0)$ and $\mathcal{D}_1 = (\mathcal{I}_1, \mathcal{U}_1, \Sigma_1, \delta_1, L_1, \lambda_1)$, where $\mathcal{U}_k = \{U_{k,\alpha} \mid \alpha \in \mathcal{I}_k\}$ for $k = 0, 1$. We write $\mathcal{U}_0 \prec \mathcal{U}_1$ if $\mathcal{I}_0 \subset \mathcal{I}_1$ and $U_{0,\alpha} \subset U_{1,\alpha}$ for every $\alpha \in \mathcal{I}_0$. Furthermore, we write $\mathcal{D}_0 \prec \mathcal{D}_1$ and say \mathcal{D}_1 is a *refinement* of \mathcal{D}_0 if

$$\mathcal{I}_0 \subset \mathcal{I}_1, \mathcal{U}_0 \prec \mathcal{U}_1, \Sigma_0 \subset \Sigma_1, \delta_0 > \delta_1, L_0 \leq L_1, \lambda_0 \geq \lambda_1.$$

Note the strict inequality $\delta_0 > \delta_1$, which will be pertinent to Section 4.5.

3.8 Definition. For any expansion datum \mathcal{D} we can define a refinement by replacing δ with a strictly smaller positive number and leaving other objects intact. We say such a refinement is *trivial*.

3.2 Expansion enables encoding

Our goal here is to draw the key Lemma 3.18 for expanding actions and then explore its various implications.

We begin by noting that the expansion condition (Definition 3.4) enables us to encode points of Λ by sequences in the finite index set \mathcal{I} .

To see this, let $\rho : \Gamma \rightarrow \text{Homeo}(M; \Lambda)$ be an expanding action with a datum $\mathcal{D} = (\mathcal{I}, \mathcal{U}, \Sigma, \delta, L, \lambda)$. We first fix a real number η such that

$$0 < \eta \leq \delta.$$

Since $\delta \leq \delta_{\mathcal{U}}$, every η -ball $B_\eta(x)$ centered at $x \in \Lambda$ is contained in some member of \mathcal{U} . Now, to each $x \in \Lambda$ we assign a pair (α, p) of sequences

$$\begin{aligned} \alpha : \mathbb{N}_0 &\rightarrow \mathcal{I}, \quad i \mapsto \alpha(i) \\ p : \mathbb{N}_0 &\rightarrow \Lambda, \quad i \mapsto p_i \end{aligned}$$

as follows. We set

$$p_0 = x.$$

Let $\alpha(0) \in \mathcal{I}$ be an *arbitrary* element and set $p_1 = \rho(s_{\alpha(0)}^{-1})(p_0)$. Now, for $i \in \mathbb{N}$, choose $\alpha(i)$ inductively so that

$$B_\eta(p_i) \subset U_{\alpha(i)}$$

and then set

$$p_{i+1} = \rho(s_{\alpha(i)}^{-1})(p_i).$$

Note that the sequence α , along with the initial point $p_0 = x$, determines the sequence p .

3.9 Definition (Codes). Suppose an action $\rho : \Gamma \rightarrow \text{Homeo}(M; \Lambda)$ is expanding with a datum $\mathcal{D} = (\mathcal{I}, \mathcal{U}, \Sigma, \delta, L, \lambda)$. Let $0 < \eta \leq \delta$ and $x \in \Lambda$. The sequence

$$\alpha : \mathbb{N}_0 \rightarrow \mathcal{I}$$

(or the pair (α, p) of sequences) constructed as above is called a (\mathcal{D}, η) -code for x . (When \mathcal{D} is understood we simply say an η -code in order to emphasize the use of η -balls.) It is said to be *special* if $\alpha(0)$ satisfies $B_\eta(x) \subset U_{\alpha(0)}$. We denote by $\text{Code}_x(\mathcal{D}, \eta)$ the set of all (\mathcal{D}, η) -codes for $x \in \Lambda$.

3.10 Remark. That we do not require $\alpha(0)$ to satisfy $B_\eta(x) \subset U_{\alpha(0)}$ in general is Sullivan's trick, which will be useful in Section 4.4.

- (a) The requirement $B_\eta(p_i) \subset U_{\alpha(i)}$ implies $U_{\alpha(i)} \neq \emptyset$ for $i \in \mathbb{N}$. Thus only for the initial value $\alpha(0)$ of codes α can we possibly have $U_{\alpha(0)} = \emptyset$.
- (b) Since $\delta \leq \delta_{\mathcal{U}}$, we have $\text{Code}_x(\mathcal{D}, \eta) \neq \emptyset$ for all $x \in \Lambda$ and $0 < \eta \leq \delta$. Moreover, if $\eta' \leq \eta \leq \delta$, then $\text{Code}_x(\mathcal{D}, \eta) \subset \text{Code}_x(\mathcal{D}, \eta')$. Indeed, if (α, p) is an η -code for x , then $B_{\eta'}(p_i) \subset B_\eta(p_i) \subset U_{\alpha(i)}$ for all $i \in \mathbb{N}$, which implies that (α, p) is an η' -code for x as well.
- (c) If \mathcal{D}_0 and \mathcal{D}_1 are expansion data of ρ and $\mathcal{D}_0 \prec \mathcal{D}_1$, then for any $\eta \leq \delta_1 \leq \delta_0$, a (\mathcal{D}_0, η) -code $\alpha : \mathbb{N}_0 \rightarrow \mathcal{I}_0 \subset \mathcal{I}_1$ for x may be regarded as a (\mathcal{D}_1, η) -code. Slightly abusing the notation we write this relation as $\text{Code}_x(\mathcal{D}_0, \eta) \subset \text{Code}_x(\mathcal{D}_1, \eta)$.

Now we claim that, for every $x \in \Lambda$, each η -code for x gives rise to a nested sequence of neighborhoods of x whose diameters tend to 0 exponentially fast. See Lemma 3.18 below.

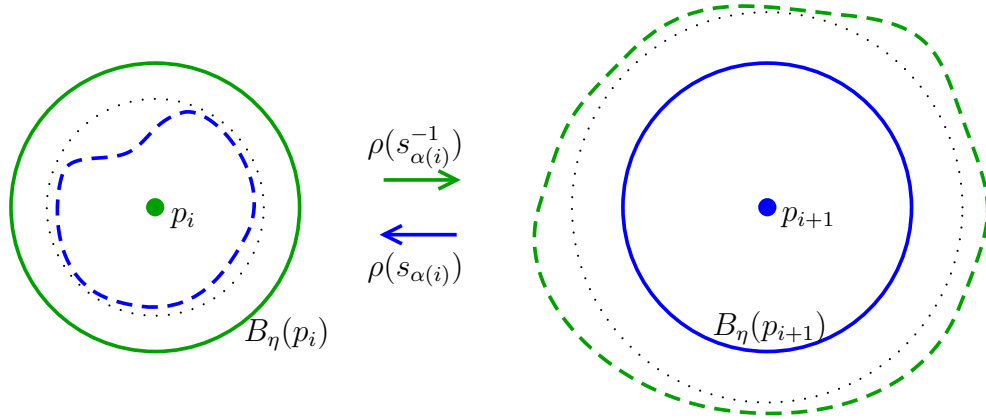


Figure 1: Actions of $\rho(s_{\alpha(i)}^{-1})$ and $\rho(s_{\alpha(i)})$ for $i \in \mathbb{N}$.

In order to prove the claim, suppose (α, p) is an η -code for $x \in \Lambda$ and let $i \in \mathbb{N}$. Since $B_\eta(p_i) \subset U_{\alpha(i)}$ and the homeomorphism $\rho(s_{\alpha(i)}^{-1})$ is $(\lambda, U_{\alpha(i)}; \delta)$ -expanding with $\rho(s_{\alpha(i)}^{-1})(p_i) = p_{i+1}$, we have by definition

$$(3.11) \quad B_{\lambda\eta}(p_{i+1}) \subset \rho(s_{\alpha(i)}^{-1})[B_\eta(p_i)] \subset \rho(s_{\alpha(i)}^{-1})[U_{\alpha(i)}].$$

On the other hand, the inverse map $\rho(s_{\alpha(i)})$ is $(\lambda^{-1}, \rho(s_{\alpha(i)}^{-1})[U_{\alpha(i)}])$ -contracting as we saw in Remark 3.6(d). Since $B_\eta(p_{i+1}) \subset \rho(s_{\alpha(i)}^{-1})[U_{\alpha(i)}]$, we obtain

$$(3.12) \quad \rho(s_{\alpha(i)})[B_\eta(p_{i+1})] \subset B_{\eta/\lambda}(p_i) \subset B_\eta(p_i).$$

See Figure 1. By a similar reasoning, we inductively obtain

$$\begin{aligned} \rho(s_{\alpha(i-1)}s_{\alpha(i)})[B_\eta(p_{i+1})] &\subset B_{\eta/\lambda^2}(p_{i-1}), \\ &\vdots \\ \rho(s_{\alpha(1)} \cdots s_{\alpha(i-1)}s_{\alpha(i)})[B_\eta(p_{i+1})] &\subset B_{\eta/\lambda^i}(p_1). \end{aligned}$$

Lastly, the map $\rho(s_{\alpha(0)})$ is L -Lipschitz on $B_{\eta/\lambda^i}(p_1) \subset N_\delta(\Lambda)$ by Definition 3.4(i). Thus we see that

$$(3.13) \quad \rho(s_{\alpha(0)}s_{\alpha(1)} \cdots s_{\alpha(i-1)}s_{\alpha(i)})[B_\eta(p_{i+1})] \subset B_{L\eta/\lambda^i}(p_0).$$

3.14 Definition (Rays). Let $\rho : \Gamma \rightarrow \text{Homeo}(M; \Lambda)$ be an expanding action with the datum \mathcal{D} . Given a (\mathcal{D}, η) -code α for $x \in \Lambda$, the (\mathcal{D}, η) -ray (or simply η -ray) associated to α is a sequence $c^\alpha : \mathbb{N}_0 \rightarrow \Gamma$ defined by

$$c_i^\alpha = s_{\alpha(0)}s_{\alpha(1)} \cdots s_{\alpha(i)}.$$

We set $\text{Ray}_x(\mathcal{D}, \eta) := \{c^\alpha \mid \alpha \in \text{Code}_x(\mathcal{D}, \eta)\}$ and interpret c as a map

$$c : \text{Code}_x(\mathcal{D}, \eta) \rightarrow \text{Ray}_x(\mathcal{D}, \eta), \quad \alpha \mapsto c^\alpha.$$

3.15 Remark. (a) The initial point $c_0^\alpha = s_{\alpha(0)}$ of c^α is an element of Σ .

(b) Every ray c^α defines an edge-path in the Cayley graph (Γ, d_Σ) of Γ (with respect to the generating set Σ). Note that each word c_i^α is reduced, since an appearance of $s_\alpha^{-1}s_\alpha$ would imply that the composite map $\rho(s_\alpha^{-1})\rho(s_\alpha)$, which is the identity, is λ^2 -expanding on some non-empty open subset of M .

(c) If $(\Sigma_0, \delta_0) = \mathcal{D}_0 \prec \mathcal{D}_1 = (\Sigma_1, \delta_1)$ are expansion data of ρ and $\eta \leq \delta_1 \leq \delta_0$, then we have $\text{Ray}_x(\mathcal{D}_0, \eta) \subset \text{Ray}_x(\mathcal{D}_1, \eta)$ as in Remark 3.10(c).

With this definition of η -rays c^α , we first note that

$$(3.16) \quad \rho(c_i^\alpha)(p_{i+1}) = p_0 = x$$

for all $i \in \mathbb{N}_0$. Then the inclusion (3.13) can be written as

$$x \in \rho(c_i^\alpha)[B_\eta(p_{i+1})] \subset B_{L\eta/\lambda^i}(x)$$

for all $i \in \mathbb{N}_0$. Moreover, from (3.12) we have

$$(3.17) \quad \begin{aligned} \rho(c_i^\alpha)[B_\eta(p_{i+1})] &= \rho(s_{\alpha(0)} \cdots s_{\alpha(i-1)}s_{\alpha(i)})[B_\eta(p_{i+1})] \\ &\subset \rho(s_{\alpha(0)} \cdots s_{\alpha(i-1)})[B_\eta(p_i)] \\ &= \rho(c_{i-1}^\alpha)[B_\eta(p_i)] \end{aligned}$$

for all $i \in \mathbb{N}$.

Let us summarize what we have proved thus far.

3.18 Lemma. *Let $\rho : \Gamma \rightarrow \text{Homeo}(M; \Lambda)$ be an expanding action with a datum $\mathcal{D} = (\mathcal{I}, \mathcal{U}, \Sigma, \delta, L, \lambda)$ and let $0 < \eta \leq \delta$. If (α, p) is a (\mathcal{D}, η) -code for $x \in \Lambda$, then the sequence of neighborhoods of x*

$$x \in \rho(c_i^\alpha)[B_\eta(p_{i+1})] \quad (i \in \mathbb{N}_0)$$

is nested and exponentially shrinking. More precisely, we have

- (i) $\rho(c_i^\alpha)[B_\eta(p_{i+1})] \subset \rho(c_{i-1}^\alpha)[B_\eta(p_i)]$ for $i \in \mathbb{N}$, and
- (ii) $\rho(c_i^\alpha)[B_\eta(p_{i+1})] \subset B_{L\eta/\lambda^i}(x)$ for all $i \in \mathbb{N}_0$.

Consequently, we have the equality

$$\{x\} = \bigcap_{i=0}^{\infty} \rho(c_i^\alpha)[B_\eta(p_{i+1})].$$

The map $\rho(c_i^\alpha)^{-1}$ is λ^i/L -expanding on the neighborhood $\rho(c_i^\alpha)[B_\eta(p_{i+1})]$ of x for all $i \in \mathbb{N}_0$, and the map

$$\rho(c_i^\alpha)^{-1} \rho(c_j^\alpha) = \rho(s_{\alpha(i)}^{-1} s_{\alpha(i-1)}^{-1} \cdots s_{\alpha(j+1)}^{-1})$$

is λ^{i-j} -expanding on $\rho(c_j^\alpha)^{-1}[\rho(c_i^\alpha)[B_\eta(p_{i+1})]]$ for all $0 \leq j < i$.

A number of corollaries will follow.

We say an action $\rho : \Gamma \rightarrow \text{Homeo}(M; \Lambda)$ has an *expansivity constant* $\epsilon > 0$ if for every distinct pair of points $x, y \in \Lambda$ there exists an element $g \in \Gamma$ such that $d(\rho(g)(x), \rho(g)(y)) \geq \epsilon$. Compare [CP93, Proposition 2.2.4].

3.19 Corollary. *If an action $\rho : \Gamma \rightarrow \text{Homeo}(M; \Lambda)$ is expanding with a datum $\mathcal{D} = (\delta)$, then δ is an expansivity constant of this action.*

Proof. Let $x, y \in \Lambda$ be distinct and consider a δ -code (α, p) for x . By Lemma 3.18, the sequence of neighborhoods of x

$$\rho(c_i^\alpha)[B_\delta(p_{i+1})] \quad (i \in \mathbb{N}_0)$$

is nested and exponentially shrinking. Thus there exists an $n \in \mathbb{N}_0$ such that

$$y \notin \rho(c_n^\alpha)[B_\delta(p_{n+1})],$$

that is, $\rho(c_n^\alpha)^{-1}(y) \notin B_\delta(p_{n+1}) = B_\delta(\rho(c_n^\alpha)^{-1}(x))$.

Therefore, $d(\rho(c_n^\alpha)^{-1}(x), \rho(c_n^\alpha)^{-1}(y)) \geq \delta$ as desired. □

The following corollary will be crucial for Definition 3.28 below, which in turn plays an essential role when we discuss actions of hyperbolic groups in Section 6. The corollary is also the reason why we need the assumption that no point of Λ is isolated in M .

3.20 Corollary. *Let $\rho : \Gamma \rightarrow \text{Homeo}(M; \Lambda)$ be an expanding action with a datum $\mathcal{D} = (\Sigma, \delta, L, \lambda)$ and let $\eta \in (0, \delta]$. Then the rays $c^\alpha \in \text{Ray}_x(\mathcal{D}, \eta)$ are (A, C) -quasigeodesic rays in (Γ, d_Σ) with A and C depending only on L and λ .*

Proof. Let (α, p) be an η -code for $x \in \Lambda$. Since no point of Λ is isolated in M , for each $i \in \mathbb{N}_0$ we can choose a point y_i such that

$$x \neq y_i \in \rho(c_i^\alpha)[B_\eta(p_{i+1})] \cap N_{\delta/L^i}(\Lambda).$$

Let $i, j \in \mathbb{N}_0$ be such that $0 \leq j < i$ and set $r_{ij} := (c_i^\alpha)^{-1}c_j^\alpha$. By (the last statement of) Lemma 3.18, the map $\rho(r_{ij})$ is λ^{i-j} -expanding on $\rho(c_j^\alpha)^{-1}[\rho(c_i^\alpha)[B_\eta(p_{i+1})]] \supset \{\rho(c_j^\alpha)^{-1}(y_i), \rho(c_j^\alpha)^{-1}(x)\}$, hence

$$d(\rho(r_{ij})(y_{ij}), \rho(r_{ij})(x_j)) \geq \lambda^{i-j}d(y_{ij}, x_j),$$

where we set $y_{ij} := \rho(c_j^\alpha)^{-1}(y_i)$ and $x_j := \rho(c_j^\alpha)^{-1}(x)$. On the other hand, we have

$$L^{|r_{ij}|_\Sigma}d(y_{ij}, x_j) \geq d(\rho(r_{ij})(y_{ij}), \rho(r_{ij})(x_j))$$

from (3.5), since $x_j \in \Lambda$ while $y_{ij} \in N_{\delta/L^{i-j-1}}(\Lambda)$ and $|r_{ij}|_\Sigma \leq i - j$. From these two inequalities we obtain

$$d_\Sigma(c_i^\alpha, c_j^\alpha) = |r_{ij}|_\Sigma \geq \frac{\log \lambda}{\log L} \cdot (i - j).$$

Therefore, the η -ray c^α is a uniform quasigeodesic ray. \square

Another consequence of the encoding concerns the dynamics of the action of Γ on Λ . The action of Γ on Λ need not be minimal in general even if Γ is a non-elementary hyperbolic group (see Example 7.4). Nevertheless, the action of Γ on Λ has no *wandering points*:

3.21 Theorem. *Let $\rho : \Gamma \rightarrow \text{Homeo}(M; \Lambda)$ be an expanding action with a datum $\mathcal{D} = (\delta)$. For $x \in \Lambda$ and $\eta \in (0, \delta]$, consider a ray $c^\alpha \in \text{Ray}_x(\mathcal{D}, \eta)$ associated to an η -code (α, p) for x . Then*

- (1) *there exist a subsequence (g_j) of (c_i^α) and a point $q \in \Lambda$ such that $(\rho(g_j))$ converges to x uniformly on $B_{\eta/2}(q)$;*
- (2) *there exists an infinite sequence (h_j) in Γ such that*

$$\lim_{j \rightarrow \infty} \rho(h_j)(x) = x.$$

Proof. (1) By the compactness of Λ , the sequence $p = (p_i)$ contains a subsequence (p_{i_j+1}) converging to some point $q \in \Lambda$. The point q is then covered by infinitely many balls $B_{\eta/2}(p_{i_j+1})$, $j \in \mathbb{N}$. By Lemma 3.18 the corresponding elements $g_j := c_{i_j}^\alpha \in \Gamma$ will send $B_{\eta/2}(q) \subset B_\eta(p_{i_j+1})$ to a subset $\rho(g_j)[B_{\eta/2}(q)]$ of diameter at most $L\eta/\lambda^{i_j}$ containing x . From this we conclude that the sequence $(\rho(g_j))$ converges to x uniformly on $B_{\eta/2}(q)$.

(2) On the other hand, since, in particular, $p_{i_1+1} \in B_{\eta/2}(q)$, we obtain

$$\lim_{j \rightarrow \infty} \rho(c_{i_j}^\alpha)(p_{i_1+1}) = x.$$

Since $\rho(c_{i_1}^\alpha)^{-1}(x) = p_{i_1+1}$, it follows that for $h_j := c_{i_j}^\alpha (c_{i_1}^\alpha)^{-1}$ we have

$$\lim_{j \rightarrow \infty} \rho(h_j)(x) = x. \quad \square$$

3.22 Remark. The idea of *Markov coding* of limit points of actions of finitely generated groups Γ by sequences in Γ is rather standard in *symbolic dynamics* and goes back to Nielsen, Hedlund and Morse; we refer the reader to the paper by Series [Ser81] for references and historical discussion. In the setting of hyperbolic groups this was introduced in Gromov’s paper [Gro87, §.8] and discussed in more detail in the book by Coornaert and Papadopoulos [CP93]. Section 8.5.Y of Gromov’s paper discusses a relation to Sullivan’s stability theorem.

3.3 The meandering hyperbolicity condition

We continue the discussion from the previous section. In order to define the meandering hyperbolicity condition we need to introduce an equivalence relation $\sim_{(\mathcal{D}, \eta)}^N$ on the set $\text{Ray}_x(\mathcal{D}, \eta)$ of rays in Γ associated to (\mathcal{D}, η) -codes for $x \in \Lambda$; recall Definitions 3.9 and 3.14.

3.23 Definition ($(\mathcal{D}, \eta; N)$ -equivalence). Suppose $\rho : \Gamma \rightarrow \text{Homeo}(M; \Lambda)$ is an expanding action with a datum $\mathcal{D} = (\Sigma, \delta)$ and let $0 < \eta \leq \delta$.

- (a) For each integer $N \geq 0$ we define the relation $\approx_{(\mathcal{D}, \eta)}^N$ on $\text{Ray}_x(\mathcal{D}, \eta)$ by declaring that $c^\alpha \approx_{(\mathcal{D}, \eta)}^N c^\beta$ if there exist infinite subsets $P, Q \subset \mathbb{N}_0$ such that the subsets

$$c^\alpha(P) = \{c_i^\alpha \mid i \in P\}, \quad c^\beta(Q) = \{c_i^\beta \mid i \in Q\}$$

of (Γ, d_Σ) are within Hausdorff distance N from each other. The $(\mathcal{D}, \eta; N)$ -*equivalence*, denoted $\sim_{(\mathcal{D}, \eta)}^N$, is the equivalence relation on the set $\text{Ray}_x(\mathcal{D}, \eta)$ generated by the relation $\approx_{(\mathcal{D}, \eta)}^N$. In other words, we write $c^\alpha \sim_{(\mathcal{D}, \eta)}^N c^\beta$ and say c^α and c^β are $(\mathcal{D}, \eta; N)$ -equivalent if there is a finite chain of “interpolating” rays $c^\alpha = c^{\gamma_1}, c^{\gamma_2}, \dots, c^{\gamma_n} = c^\beta$ in $\text{Ray}_x(\mathcal{D}, \eta)$ such that

$$c^{\gamma_1} \approx_{(\mathcal{D}, \eta)}^N c^{\gamma_2} \approx_{(\mathcal{D}, \eta)}^N \dots \approx_{(\mathcal{D}, \eta)}^N c^{\gamma_n}.$$

- (b) The (\mathcal{D}, η) -rays c^α and c^β are said to $(\mathcal{D}, \eta; N)$ -*fellow-travel* if their images $c^\alpha(\mathbb{N}_0)$ and $c^\beta(\mathbb{N}_0)$ are within Hausdorff distance N from each other.

3.24 Remark. (a) Observe that $(\mathcal{D}, \eta; N)$ -fellow-traveling rays are $(\mathcal{D}, \eta; N)$ -equivalent.

- (b) The notion of $(\mathcal{D}, \eta; N)$ -equivalence is much more complex than that of $(\mathcal{D}, \eta; N)$ -fellow-traveling for a reason: while fellow-traveling is a natural condition in the context of hyperbolic groups where quasigeodesics with common end-points uniformly fellow-travel, our notion of equivalence is defined this way in order to incorporate non-hyperbolic groups, such as higher rank uniform lattices, into the theory of hyperbolic group actions. In all examples that we have, two rays are $(\mathcal{D}, \eta; N)$ -equivalent if and only if they admit an interpolation by at most one extra ray. However, in general, we see no reason for interpolation via one ray to define an equivalence relation on coding rays. A picture describing the behavior of an interpolating ray can be found in Figure 4 in Section 5.3: the red interpolating ray “meanders” between the two black rays. This explains the terminology *meandering hyperbolicity*.

- (c) If $(\Sigma_0, \delta_0) = \mathcal{D}_0 \prec \mathcal{D} = (\Sigma, \delta)$ and $\eta \leq \delta < \delta_0$, then we have the inclusion $\text{Ray}_x(\mathcal{D}_0, \eta) \subset \text{Ray}_x(\mathcal{D}, \eta)$ as in Remark 3.15(c) and can talk about the $(\mathcal{D}, \eta; N)$ -equivalence of (\mathcal{D}_0, η) -rays.

We are now ready to define the meandering hyperbolicity condition. First, we recall the notion of S-hyperbolicity which Sullivan defined in [Sul85].

3.25 Definition (S-hyperbolicity). Let $\rho : \Gamma \rightarrow \text{Homeo}(M; \Lambda)$ be an expanding action with a datum $\mathcal{D} = (\mathcal{I}, \mathcal{U}, \Sigma, \delta, L, \lambda)$.

- (a) The action ρ is said to be *S-hyperbolic* if there exists an integer $N \geq 1$ such that, for every $x \in \Lambda$, all rays in $\text{Ray}_x(\mathcal{D}, \delta)$ are $(\mathcal{D}, \delta; N)$ -fellow-traveling.
- (b) The action ρ is said to be *uniformly S-hyperbolic* if there is an integer $N \geq 1$ such that, for every $\eta \in (0, \delta]$ and every $x \in \Lambda$, all rays in $\text{Ray}_x(\mathcal{D}, \eta)$ are $(\mathcal{D}, \eta; N)$ -fellow-traveling. We shall refer to the pair $(\mathcal{D}; N)$ as a *(uniform) S-hyperbolicity datum* of ρ .

By weakening the $(\mathcal{D}, \eta; N)$ -fellow-traveling condition in the definition of S-hyperbolicity to the $(\mathcal{D}, \eta; N)$ -equivalence, as well as considering a refined expansion datum (Definition 3.7), we define the notion of *meandering hyperbolicity* as follows.

3.26 Definition (Meandering hyperbolicity). Let $\rho : \Gamma \rightarrow \text{Homeo}(M; \Lambda)$ be an expanding action with the expansion datum $\mathcal{D}_0 = (\mathcal{I}_0, \mathcal{U}_0, \Sigma_0, \delta_0, L_0, \lambda_0)$.

- (a) The action ρ is said to be *meandering-hyperbolic* if there exist a refinement $\mathcal{D} = (\mathcal{I}, \mathcal{U}, \Sigma, \delta, L, \lambda) \succ \mathcal{D}_0$ and an integer $N \geq 1$ such that, for every $x \in \Lambda$, all rays in $\text{Ray}_x(\mathcal{D}_0, \delta_0)$ are $(\mathcal{D}, \delta; N)$ -equivalent (as rays in $\text{Ray}_x(\mathcal{D}, \delta)$).
- (b) The action ρ is said to be *uniformly meandering-hyperbolic* if there are a refinement $\mathcal{D} = (\mathcal{I}, \mathcal{U}, \Sigma, \delta, L, \lambda) \succ \mathcal{D}_0$ and an integer $N \geq 1$ such that for every $\eta \in (0, \delta]$ and every $x \in \Lambda$, all rays in $\text{Ray}_x(\mathcal{D}_0, \eta)$ are $(\mathcal{D}, \eta; N)$ -equivalent (as rays in $\text{Ray}_x(\mathcal{D}, \eta)$).

We shall refer to the triple $(\mathcal{D}_0 \prec \mathcal{D}; N)$ as a *(uniform) meandering hyperbolicity datum* of ρ .

- 3.27 Remark.* (a) Obviously, uniform meandering hyperbolicity implies meandering hyperbolicity.
- (b) If an action is S-hyperbolic with a datum $(\mathcal{D}_0; N)$ then, for any trivial refinement \mathcal{D} of \mathcal{D}_0 (see Definition 3.8), it is meandering-hyperbolic with the datum $(\mathcal{D}_0 \prec \mathcal{D}; N)$, since $(\mathcal{D}_0, \eta; N)$ -fellow-traveling rays are $(\mathcal{D}, \eta; N)$ -equivalent.
- (c) A prime example of a meandering-hyperbolic action which is not S-hyperbolic is given by uniform lattices in higher rank semisimple Lie groups (see Section 5). Every other examples of meandering-hyperbolic actions we present in this paper are actually S-hyperbolic (see Sections 3.5, 6 and 7).
- (d) We exhibit expanding actions which fail to be meandering-hyperbolic in Section 7.1.

In view of Corollary 3.20, any two $(\mathcal{D}, \delta; N)$ -equivalent rays in a *hyperbolic group* are $(\mathcal{D}, \delta; N')$ -fellow-traveling for some $N' \geq 1$, since two quasigeodesics in a hyperbolic space X which are Hausdorff-close on unbounded subsets define the same point in $\partial_\infty X$. Thus, the meandering hyperbolicity condition enables us to define the following map when Γ is a hyperbolic group:

3.28 Definition (Coding map). Let Γ be a hyperbolic group and $\rho : \Gamma \rightarrow \text{Homeo}(M; \Lambda)$ a meandering-hyperbolic action with a datum $(\mathcal{D}_0 \prec \mathcal{D}; N)$. Then we define the *coding map*

$$\pi : \Lambda \rightarrow \partial_\infty \Gamma, \quad x \mapsto \pi(x)$$

of ρ as follows: the value $\pi(x)$ of $x \in \Lambda$ is the equivalence class in $\partial_\infty \Gamma$ (in the sense of Section 2.2) of a ray $c^\alpha \in \text{Ray}_x(\mathcal{D}_0, \delta_0)$. The equivalence class is well-defined since any two $(\mathcal{D}_0, \delta_0)$ -rays for $x \in \Lambda$ are $(\mathcal{D}, \delta; N')$ -fellow-traveling as mentioned above.

The map π is clearly equivariant. In Theorem 6.7 we will prove that π is a continuous surjective map.

We note that, as we show later in Corollary 6.10, meandering-hyperbolic actions of a *non-elementary* hyperbolic group are in fact (uniformly) S-hyperbolic.

3.4 Statement of the theorem: meandering hyperbolicity implies stability

Suppose $\rho : \Gamma \rightarrow \text{Homeo}(M; \Lambda)$ is an expanding action. Following Sullivan’s remark (at the very end of his paper [Sul85]) we would like to talk about small perturbations of ρ which are still expanding.

For this purpose, we equip $\text{Homeo}(M)$ with what we call the *compact-open Lipschitz topology*. A neighborhood basis of $f \in \text{Homeo}(M)$ in this topology is of the form $U(f; K, \epsilon)$ for compacts $K \subset M$ and $\epsilon > 0$; it consists of all $g \in \text{Homeo}(M)$ that are ϵ -close to f on K :

$$(3.29) \quad d_{\text{Lip}, K}(f, g) := \sup_{x \in K} d(f(x), g(x)) + \sup_{\substack{x, y \in K \\ x \neq y}} \left| \frac{d(f(x), f(y))}{d(x, y)} - \frac{d(g(x), g(y))}{d(x, y)} \right| < \epsilon.$$

3.30 Remark. As we mentioned in the introduction, Sullivan [Sul85, §9] actually considers the case when M is a Riemannian manifold with the Riemannian distance function d and the actions are by C^1 -diffeomorphisms. In this case $\rho(s) \in \text{Diff}^1(M)$ is said to be λ -expanding on U if $\|D_x \rho(s)(v)\| \geq \lambda \|v\|$ for all $x \in U$ and $v \in T_x M$, and the compact-open Lipschitz topology on $\text{Diff}^1(M)$ is nothing but the compact-open C^1 -topology.

Suppose $\rho : \Gamma \rightarrow \text{Homeo}(M; \Lambda)$ is an expanding action with a datum $\mathcal{D} = (\mathcal{I}, \Sigma)$ (Definition 3.4). Given a compact K and $\epsilon > 0$, we say a homomorphism $\rho' : \Gamma \rightarrow \text{Homeo}(M)$ is a (K, ϵ) -perturbation of ρ if $\rho'(s_\alpha)$ is ϵ -close to $\rho(s_\alpha)$ on K for all $\alpha \in \mathcal{I}$. The set of all (K, ϵ) -perturbations of ρ will be denoted by

$$(3.31) \quad U(\rho; K, \epsilon).$$

Accordingly, we topologize $\text{Hom}(\Gamma, \text{Homeo}(M))$ via the topology of “algebraic convergence” by identifying it, via the map $\rho \mapsto (\rho(s_\alpha))_{\alpha \in \mathcal{I}}$, with a subset of $[\text{Homeo}(M)]^{\mathcal{I}}$ equipped with the subspace topology. Then the subset $U(\rho; K, \epsilon)$ of $\text{Hom}(\Gamma, \text{Homeo}(M))$ is an open neighborhood of ρ . Note that, when the ambient space M itself is compact, we can set $K = M$ and simply talk about ϵ -perturbations.

Now we are able to state our structural stability theorem for meandering-hyperbolic actions.

3.32 Theorem. *If an action $\rho : \Gamma \rightarrow \text{Homeo}(M; \Lambda)$ is meandering-hyperbolic with a datum $(\mathcal{D}_0 \prec \mathcal{D}; N)$, then the following hold.*

- (1) *The action ρ is structurally stable in the sense of Lipschitz dynamics. In other words, there exist a compact set $K \supset \Lambda$ and a constant $\epsilon = \epsilon(\mathcal{D}, N) > 0$ such that for every*

$$\rho' \in U(\rho; K, \epsilon)$$

there exist a ρ' -invariant compact subset $\Lambda' \subset M$ and an equivariant homeomorphism

$$\phi : \Lambda \rightarrow \Lambda',$$

that is, $\rho'(g) \circ \phi = \phi \circ \rho(g)$ on Λ for all $g \in \Gamma$.

- (2) *The map $U(\rho; K, \epsilon) \rightarrow C^0(\Lambda, M)$, $\rho' \mapsto \phi$ is continuous at ρ .*
(3) *Every action $\rho' \in U(\rho; K, \epsilon)$ is expanding.*

If an action $\rho : \Gamma \rightarrow \text{Homeo}(M; \Lambda)$ is uniformly meandering-hyperbolic then, in addition to the preceding statements, the following is true as well.

- (4) *Every action $\rho' \in U(\rho; K, \epsilon)$ is again uniformly meandering-hyperbolic.*

A proof will be given in the next section. As an immediate consequence of Theorem 3.32(1), we have:

3.33 Corollary. *A meandering-hyperbolic action $\rho : \Gamma \rightarrow \text{Homeo}(M; \Lambda)$ is algebraically stable in the following sense: for every $\rho' \in U(\rho; K, \epsilon)$, the kernel of the ρ' -action on Λ' equals the kernel of the ρ -action on Λ .*

We note, however, that faithfulness of the ρ -action on M does not imply faithfulness of nearby actions: see Example 7.7.

In view of Remark 3.27(b), we obtain Sullivan's structural stability theorem [Sul85, Theorem II] in the C^1 -setting as a corollary of Theorem 3.32(1):

3.34 Corollary. *Consider a group action $\Gamma \rightarrow \text{Diff}^1(M)$ on a Riemannian manifold M with a compact invariant subset $\Lambda \subset M$. If the action is S-hyperbolic, then it is structurally stable in the sense of C^1 -dynamics.*

3.5 Toy examples

The most basic example of an S-hyperbolic action is a cyclic hyperbolic group of Möbius transformations acting on the unit circle S^1 . Namely, we consider the Poincaré (conformal) disk model of \mathbb{H}^2 in $\mathbb{C} = \mathbb{R}^2$ and endow $M = S^1 = \partial_\infty \mathbb{H}^2$ with the induced Euclidean metric. Let $\gamma \in \text{Isom}(\mathbb{H}^2)$ be a hyperbolic element and $\Gamma = \langle \gamma \rangle \cong \mathbb{Z}$. The *limit set* of the group Γ is $\Lambda = \{\lambda_-, \lambda_+\}$, with λ_+ the attracting and λ_- the repelling fixed points of γ in M . Expanding subsets U_α, U_β for γ, γ^{-1} are sufficiently small arcs containing λ_-, λ_+ , respectively.

Explicit expanding subsets can be found by considering the isometric circles I_γ and $I_{\gamma^{-1}}$ of γ and γ^{-1} , respectively. See Figure 2(Left). The arc of I_γ in \mathbb{H}^2 is a complete geodesic which is the perpendicular bisector of the points o and $\gamma^{-1}(o)$, where o denotes the Euclidean

center of the Poincaré disk. Then we obtain a (λ, γ) -expanding subset U_α (with $\lambda > 1$) by cutting down slightly the open arc of $S^1 = \partial_\infty \mathbb{H}^2$ inside I_γ . For more details on isometric circles (or spheres) and their relation to Ford and Dirichlet fundamental domains, we refer to [Mas88, IV.G], for example. See also the discussion in the beginning of Section 7.2.

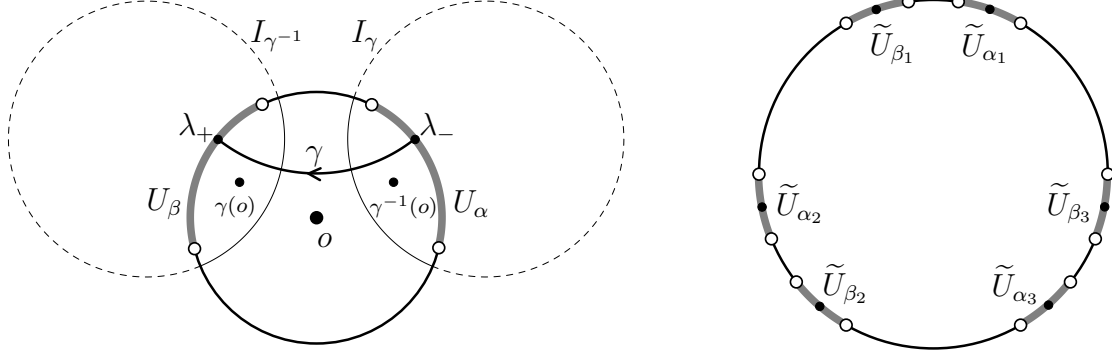


Figure 2: Expanding arcs for γ and γ^{-1} are colored gray in both examples. (Left) A hyperbolic transformation γ of \mathbb{H}^2 . (Right) A covering of degree 3.

3.35 Example (k -fold non-trivial covering). A more interesting example is obtained by taking a degree $k > 1$ covering $p : S^1 \rightarrow S^1$ of the preceding example. See Figure 2(Right) for the case of $k = 3$. The preimage of $\Lambda = \{\lambda_-, \lambda_+\}$ consists of $2k$ points and we can lift γ to a diffeomorphism $\tilde{\gamma} : S^1 \rightarrow S^1$ fixing all these points. Let $\tilde{\rho} : \Gamma = \langle \gamma \rangle \cong \mathbb{Z} \rightarrow \text{Diff}(S^1)$ be the homomorphism sending the generator γ of Γ to $\tilde{\gamma}$. The preimages $p^{-1}(U_\alpha), p^{-1}(U_\beta)$ break into connected components

$$\tilde{U}_{\alpha_i}, \tilde{U}_{\beta_i} \quad (i = 1, \dots, k)$$

and the mappings $\tilde{\gamma}$ and $\tilde{\gamma}^{-1}$ act as expanding maps on each of these components. Therefore, we set

$$\mathcal{I} = \{\alpha_1, \dots, \alpha_k, \beta_1, \dots, \beta_k\}$$

and define the map $s : \mathcal{I} \rightarrow \Sigma$,

$$\alpha_i \mapsto s_{\alpha_i} = \gamma, \quad \beta_i \mapsto s_{\beta_i} = \gamma^{-1}$$

from this index set to the generating set $\Sigma = \{\gamma, \gamma^{-1}\}$ of Γ . Then $\tilde{U}_{\alpha_i}, \tilde{U}_{\beta_i}$ will be expanding subsets for the actions $\tilde{\rho}(s_{\alpha_i}), \tilde{\rho}(s_{\beta_i})$ on S^1 . (Note that the entire preimage $p^{-1}(U_\alpha)$ (resp. $p^{-1}(U_\beta)$) is *not* an expanding subset for the action $\tilde{\rho}(s_{\alpha_i})$ (resp. $\tilde{\rho}(s_{\beta_i})$.) The reader will verify that this action is S-hyperbolic.

The same construction works for surface group actions; see Example 7.3.

A trivial example where $U_\alpha = \emptyset$ for an index $\alpha \in \mathcal{I}$ is the action of a cyclic group $\Gamma = \langle \gamma \rangle \cong \mathbb{Z}$ generated by a loxodromic transformation $\gamma(z) = mz$, $|m| > 1$, on $M = \mathbb{C}$ (with the standard Euclidean metric) and $\Lambda = \{0\}$. Any open subset of M containing 0 is an expanding subset for γ , while the expanding subset for γ^{-1} is empty.

In Sections 6.3, 7.2 and 7.3, we give more complicated examples of S-hyperbolic actions.

4 Proof of the structural stability theorem

In this section we prove Theorem 3.32. The assertion (1) will be proved in Sections 4.1-4.6, and the assertions (2)-(4) in Sections 4.7-4.9, respectively.

Let $\rho : \Gamma \rightarrow \text{Homeo}(M; \Lambda)$ be a meandering-hyperbolic action (Definition 3.26) with a datum $(\mathcal{D}_0 \prec \mathcal{D}; N)$, where

$$\begin{aligned} (\mathcal{I}_0, \mathcal{U}_0, \Sigma_0, \delta_0, L_0, \lambda_0) &= \mathcal{D}_0 \prec \mathcal{D} = (\mathcal{I}, \mathcal{U}, \Sigma, \delta, L, \lambda), \\ \text{that is, } \mathcal{I}_0 &\subset \mathcal{I}, \mathcal{U}_0 \prec \mathcal{U}, \Sigma_0 \subset \Sigma, \delta_0 > \delta, L_0 \leq L, \lambda_0 \geq \lambda. \end{aligned}$$

Recall, in particular, that ρ is expanding with the refined datum \mathcal{D} .

4.1 Specifying small perturbations ρ'

We first need to determine a compact $K \supset \Lambda$ and a constant $\epsilon = \epsilon(\mathcal{D}, N) > 0$ in order to specify the open set $U(\rho; K, \epsilon)$ of all (K, ϵ) -perturbations ρ' of ρ . We set them as follows:

$$\begin{aligned} K &:= \overline{N}_\delta(\Lambda), \\ \epsilon &:= \frac{\lambda - 1}{2} \cdot \min \left\{ \frac{\delta}{(N + 1)L^N}, 1 \right\}. \end{aligned}$$

Note that K is compact since (M, d) is assumed to be proper. Since $\delta \leq \delta_{\mathcal{U}}$ is a Lebesgue number of \mathcal{U} , it follows that \mathcal{U} is a cover of $N_\delta(\Lambda)$.

Now, we suppose

$$\rho' \in U(\rho; K, \epsilon).$$

Then, by the definitions (3.29) and (3.31), we have

$$(4.1) \quad d_{\text{Lip}, K}(\rho(s_\alpha), \rho'(s_\alpha)) < \epsilon$$

for all $s_\alpha \in \Sigma$.

We first observe that

$$(4.2) \quad \rho'(s_\alpha^{-1}) \text{ is } \lambda' \text{-expanding on } U_\alpha \cap K$$

for each $\alpha \in \mathcal{I}$, where

$$\lambda' := \lambda - \epsilon \geq \lambda - \frac{\lambda - 1}{2} = \frac{\lambda + 1}{2} > 1.$$

Indeed, since $\rho(s_\alpha^{-1})$ is λ -expanding on U_α , we see from (4.1) that

$$\frac{d(\rho'(s_\alpha^{-1})(x), \rho'(s_\alpha^{-1})(y))}{d(x, y)} > \frac{d(\rho(s_\alpha^{-1})(x), \rho(s_\alpha^{-1})(y))}{d(x, y)} - \epsilon \geq \lambda - \epsilon = \lambda'$$

for all distinct $x, y \in U_\alpha \cap K$.

Moreover, we also note that

$$(4.3) \quad \rho'(s_\alpha) \text{ is } (L + \epsilon)\text{-Lipschitz on } N_\delta(\Lambda)$$

for every $\alpha \in \mathcal{I}$. To see this recall that the maps $\rho(s_\alpha)$ are L -Lipschitz on $N_\delta(\Lambda)$ by Definition 3.4(i), thus by (4.1) again

$$\frac{d(\rho'(s_\alpha)(x), \rho'(s_\alpha)(y))}{d(x, y)} < \frac{d(\rho(s_\alpha)(x), \rho(s_\alpha)(y))}{d(x, y)} + \epsilon \leq L + \epsilon$$

for all distinct $x, y \in N_\delta(\Lambda) \subset K$. Note that $L + \epsilon \geq \lambda + \epsilon > \lambda - \epsilon = \lambda'$.

4.2 Definition of ϕ

We first construct a map $\phi : \Lambda \rightarrow M$.

Let $x \in \Lambda$. In order to define $\phi(x)$, choose a $(\mathcal{D}_0, \delta_0)$ -code (α, p) for x as in Section 3.2. Since $\delta < \delta_0$, we may regard α as a (\mathcal{D}, δ) -code as in Remark 3.24(b). Then, as we know from Lemma 3.18, the point x has an exponentially shrinking nested sequence of neighborhoods $\rho(c_i^\alpha)[B_\delta(p_{i+1})]$ ($i \in \mathbb{N}_0$) such that

$$\{x\} = \bigcap_{i=0}^{\infty} \rho(c_i^\alpha)[B_\delta(p_{i+1})].$$

Now, consider a perturbation $\rho' \in U(\rho; K, \epsilon)$ of ρ as specified in Section 4.1. Then, under ρ' , the sequence $\rho(c_i^\alpha)[B_\delta(p_{i+1})]$ ($i \in \mathbb{N}_0$) of neighborhoods of x will be perturbed slightly to a sequence of subsets

$$\rho'(c_i^\alpha)[B_\delta(p_{i+1})] \quad (i \in \mathbb{N}_0).$$

Nonetheless, we claim that this new sequence of subsets is still nested and exponentially shrinking. Since M is complete, the intersection of this collection of subsets is a singleton in M and we can define $\phi_\alpha(x)$ by the formula

$$\{\phi_\alpha(x)\} = \bigcap_{i=0}^{\infty} \rho'(c_i^\alpha)[B_\delta(p_{i+1})].$$

It remains to prove the above claim. In fact, we shall prove a bit more general statement, which will later be used often, for example, when we show that ϕ is well-defined (Section 4.3) and is continuous (Section 4.5).

4.4 Lemma. *Let $\rho : \Gamma \rightarrow \text{Homeo}(M; \Lambda)$ be a meandering-hyperbolic action with the datum $(\mathcal{D}_0 \prec \mathcal{D}; N)$. Consider a number $0 < \epsilon \leq \min\{\frac{\delta}{(N+1)L^N}, 1\}$ (so that $\frac{\lambda-1}{2}\epsilon \leq \epsilon$) and let*

$$\rho' \in U(\rho; K, \frac{\lambda-1}{2}\epsilon) \subset U(\rho; K, \epsilon).$$

If (α, p) is a (\mathcal{D}, δ) -code for $x \in \Lambda$, then for every $\eta \in [\epsilon, \delta]$ the sequence of subsets

$$\rho'(c_i^\alpha)[B_\eta(p_{i+1})] \quad (i \in \mathbb{N}_0)$$

is nested and exponentially shrinking. Consequently, we have

$$\{\phi_\alpha(x)\} = \bigcap_{i=0}^{\infty} \rho'(c_i^\alpha)[B_\eta(p_{i+1})] = \bigcap_{i=0}^{\infty} \rho'(c_i^\alpha)[B_\delta(p_{i+1})]$$

and thus, for every $i \in \mathbb{N}_0$,

$$\rho'(c_i^\alpha)^{-1}(\phi_\alpha(x)) \in B_\eta(p_{i+1}).$$

If the δ -code (α, p) is special, then

$$d(x, \phi_\alpha(x)) < \varepsilon.$$

4.5 Remark. Throughout Section 4, except in Section 4.7, we have to set

$$\varepsilon = \min \left\{ \frac{\delta}{(N+1)L^N}, 1 \right\}$$

(so that $\frac{\lambda-1}{2}\varepsilon = \epsilon$) in this lemma, because we are considering (K, ϵ) -perturbations ρ' of ρ .

Proof. Since $\varepsilon \leq \eta$, we see from the assumption $\rho' \in U(\rho; K, \frac{\lambda-1}{2}\varepsilon)$ that

$$(4.6) \quad \sup_{x \in K} d(\rho(s_\alpha^{-1})(x), \rho'(s_\alpha^{-1})(x)) \leq d_{\text{Lip}, K}(\rho(s_\alpha^{-1}), \rho'(s_\alpha^{-1})) < \frac{\lambda-1}{2}\varepsilon \leq \frac{1}{2}(\lambda\eta - \eta)$$

for all $\alpha \in \mathcal{I}$. Since $\eta \leq \delta$, we have by Definition 3.4(ii) the inclusion (3.11) for ρ

$$(4.7) \quad B_\eta(p_{i+1}) \subset B_{\lambda\eta}(p_{i+1}) \subset \rho(s_{\alpha(i)}^{-1})[B_\eta(p_i)] \subset \rho(s_{\alpha(i)}^{-1})[U_{\alpha(i)}]$$

for all $i \in \mathbb{N}$, while $B_\eta(p_i) \subset B_\delta(p_i) \subset U_{\alpha(i)} \cap K$ as α is a δ -code. Therefore, as for ρ' , we conclude from (4.6) and (4.7) that

$$(4.8) \quad B_\eta(p_{i+1}) \subset \rho'(s_{\alpha(i)}^{-1})[B_\eta(p_i)] \subset \rho'(s_{\alpha(i)}^{-1})[U_{\alpha(i)} \cap K].$$

Thus

$$(4.9) \quad \rho'(s_{\alpha(i)})[B_\eta(p_{i+1})] \subset B_\eta(p_i)$$

for all $i \in \mathbb{N}$, and we check as in (3.17) the nesting property

$$\rho'(c_i^\alpha)[B_\eta(p_{i+1})] \subset \rho'(c_{i-1}^\alpha)[B_\eta(p_i)]$$

for all $i \in \mathbb{N}$.

Furthermore, the diameter of

$$\rho'(c_i^\alpha)[B_\eta(p_{i+1})] = \rho'(s_{\alpha(0)}s_{\alpha(1)} \cdots s_{\alpha(i)})[B_\eta(p_{i+1})]$$

is at most $2\eta(L + \epsilon)/(\lambda')^i$, because we have (4.8) and each $\rho'(s_{\alpha(j)})$ ($1 \leq j \leq i$) is $(1/\lambda')$ -contracting on $\rho'(s_{\alpha(j)}^{-1})[U_{\alpha(j)} \cap K]$ by (4.2), and the last map $\rho'(s_{\alpha(0)})$ is $(L + \epsilon)$ -Lipschitz on $B_\eta(p_1) \subset N_\delta(\Lambda)$ by (4.3). Hence the exponentially shrinking property also holds.

If the δ -code (α, p) is special, then the inclusion (4.8) as well as (4.9) hold for $i = 0$. Thus

$$\phi_\alpha(x) \in \rho'(c_0^\alpha)[B_\eta(p_1)] = \rho'(s_{\alpha(0)})[B_\eta(p_1)] \subset B_\eta(x)$$

for all $\eta \in [\varepsilon, \delta]$. It follows that $d(x, \phi_\alpha(x)) < \varepsilon$. \square

4.3 ϕ is well-defined

We would like to show that $\phi_\alpha(x) = \phi_\beta(x)$ for two $(\mathcal{D}_0, \delta_0)$ -codes (α, p) and (β, q) . Since ρ is meandering-hyperbolic with the datum $(\mathcal{D}_0 \prec \mathcal{D}; N)$, the corresponding $(\mathcal{D}_0, \delta_0)$ -rays c^α and c^β are $(\mathcal{D}, \delta; N)$ -equivalent, that is, $c^\alpha \sim_{(\mathcal{D}, \delta)}^N c^\beta$ in $\text{Ray}_x(\mathcal{D}, \delta)$. By definition, the equivalence relation $\sim_{(\mathcal{D}, \delta)}^N$ is generated by the relation $\approx_{(\mathcal{D}, \delta)}^N$ (see Definition 3.23(a)). Thus, it suffices to show the equality $\phi_\alpha(x) = \phi_\beta(x)$ when c^α and c^β are (\mathcal{D}, δ) -rays and satisfy $c^\alpha \approx_{(\mathcal{D}, \delta)}^N c^\beta$, that is, there exist infinite subsets $P, Q \subset \mathbb{N}_0$ such that the subsets $c^\alpha(P), c^\beta(Q)$ are within Hausdorff distance N from each other in (Γ, d_Σ) .

Suppose to the contrary that

$$\bigcap_{i \in P} \rho'(c_i^\alpha)[B_\delta(p_{i+1})] = \{\phi_\alpha(x)\} \neq \{\phi_\beta(x)\} = \bigcap_{i \in Q} \rho'(c_i^\beta)[B_\delta(q_{i+1})].$$

Since the open sets $\rho'(c_i^\beta)[B_\delta(q_{i+1})]$ shrink to $\phi_\beta(x)$, there exists an integer $n \in Q$ such that $\phi_\alpha(x) \notin \rho'(c_n^\beta)[B_\delta(q_{n+1})]$, that is,

$$(4.10) \quad \rho'(c_n^\beta)^{-1}(\phi_\alpha(x)) \notin B_\delta(q_{n+1}).$$

Since the Hausdorff distance between $\{c_i^\alpha\}_{i \in P}$ and $\{c_i^\beta\}_{i \in Q}$ is at most N , there is an integer $m \in P$ such that $d_\Sigma(c_n^\beta, c_m^\alpha) \leq N$. Set

$$r = (c_n^\beta)^{-1}c_m^\alpha,$$

so that $|r|_\Sigma \leq N$. Note from (3.16) that $\rho(r)$ maps p_{m+1} to q_{n+1} :

$$\rho(r)(p_{m+1}) = \rho(r)[\rho(c_m^\alpha)^{-1}(x)] = \rho(c_n^\beta)^{-1}(x) = q_{n+1}.$$

See Figure 3.

In view of Lemma 4.4 (with $\varepsilon = \eta = \min\{\frac{\delta}{(N+1)L^N}, 1\}$), we may assume that we used η -balls in the definition of $\phi_\alpha(x)$, so that

$$\rho'(c_m^\alpha)^{-1}(\phi_\alpha(x)) \in B_\eta(p_{m+1}).$$

Now, if we show that $\rho'(r)$ maps $B_\eta(p_{m+1})$ into $B_\delta(q_{n+1})$ and hence

$$\begin{aligned} \rho'(c_n^\beta)^{-1}(\phi_\alpha(x)) &= \rho'(r)[\rho'(c_m^\alpha)^{-1}(\phi_\alpha(x))] \\ &\in \rho'(r)[B_\eta(p_{m+1})] \subset B_\delta(q_{n+1}), \end{aligned}$$

then we are done, since we are in contradiction with (4.10).

To show that $\rho'(r)[B_\eta(p_{m+1})] \subset B_\delta(q_{n+1})$, we first need the following:

Claim. For every $w \in \Gamma$ such that $|w|_\Sigma = k \leq N$, we have

$$d(\rho(w)(y), \rho'(w)(y)) < kL^{k-1}\epsilon$$

for all $y \in B_\eta(p_{m+1})$.

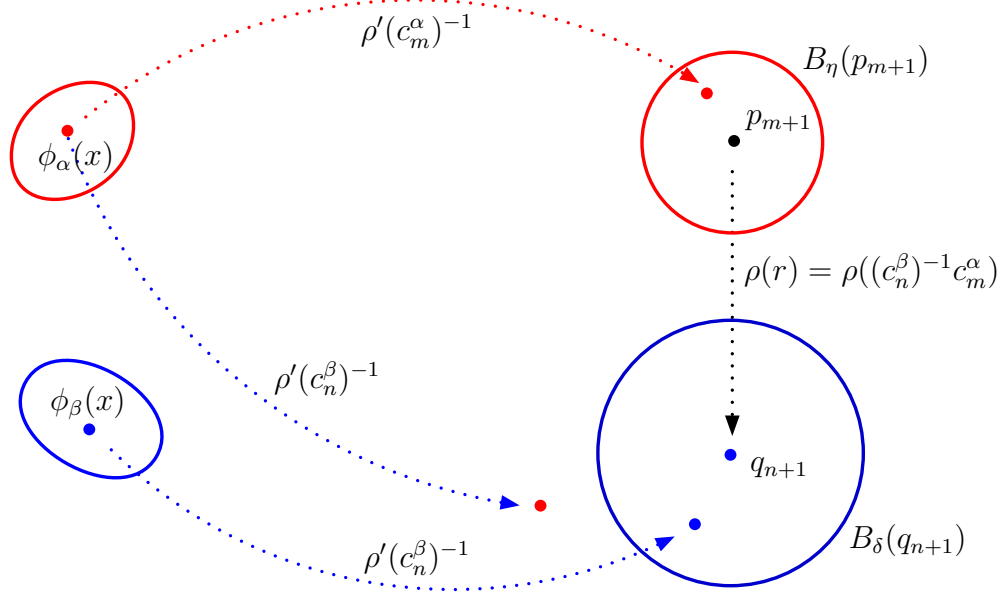


Figure 3: The points $\phi_\alpha(x)$ and $\phi_\beta(x)$.

Proof. We prove this by induction on k . If $|w|_\Sigma = 1$, the claim is true by (4.1) since $B_\eta(p_{m+1}) \subset N_\delta(\Lambda)$. Suppose $w = st$ with $s \in \Sigma$, $|t|_\Sigma = k - 1$ and $|w|_\Sigma = k$. Since $\rho(t)$ is L^{k-1} -Lipschitz on $N_{\delta/L^{k-2}}(\Lambda) \supset B_\eta(p_{m+1})$ by (3.5), we have $\rho(t)(y) \in N_{L^{k-1}\eta}(\Lambda) \subset N_\delta(\Lambda)$. By the induction hypothesis $d(\rho(t)(y), \rho'(t)(y)) < (k-1)L^{k-2}\epsilon$, we then have $\rho'(t)(y) \in N_\delta(\Lambda)$ as well, since $\epsilon = \frac{\lambda-1}{2}\eta < L\eta$ and thus

$$L^{k-1}\eta + (k-1)L^{k-2}\epsilon < L^{k-1}\eta + (k-1)L^{k-2}L\eta = kL^{k-1}\eta < \delta.$$

As $\rho(s)$ is L -Lipschitz on $N_\delta(\Lambda)$, we obtain

$$d(\rho(s)[\rho(t)(y)], \rho(s)[\rho'(t)(y)]) < L \cdot (k-1)L^{k-2}\epsilon.$$

Furthermore, we have from (4.1)

$$d(\rho(s)[\rho'(t)(y)], \rho'(s)[\rho'(t)(y)]) < \epsilon$$

since $\rho'(t)(y) \in N_\delta(\Lambda)$. Thus

$$\begin{aligned} d(\rho(w)(y), \rho'(w)(y)) &\leq d(\rho(s)[\rho(t)(y)], \rho(s)[\rho'(t)(y)]) + d(\rho(s)[\rho'(t)(y)], \rho'(s)[\rho'(t)(y)]) \\ &< (k-1)L^{k-1}\epsilon + \epsilon \\ &< (k-1)L^{k-1}\epsilon + L^{k-1}\epsilon = kL^{k-1}\epsilon \end{aligned}$$

and the claim is proved. \square

Now, we let $k = |r|_\Sigma \leq N$ and verify that $\rho'(r)$ maps $B_\eta(p_{m+1})$ into $B_\delta(q_{n+1})$. If $y \in B_\eta(p_{m+1})$ then

$$\begin{aligned} d(\rho'(r)(y), q_{n+1}) &= d(\rho'(r)(y), \rho(r)(p_{m+1})) \\ &\leq d(\rho'(r)(y), \rho(r)(y)) + d(\rho(r)(y), \rho(r)(p_{m+1})) \\ &< kL^{k-1}\epsilon + L^k\eta \\ &< NL^{N-1}L\eta + L^N\eta \leq \delta, \end{aligned}$$

where the second inequality holds by the above claim and since $\rho(r)$ is L^k -Lipschitz on $N_{\delta/L^{k-1}}(\Lambda) \supset B_\eta(p_{m+1})$ by (3.5), and the third inequality holds since $\epsilon = \frac{\lambda-1}{2}\eta < L\eta$.

This completes the proof of the equality $\phi_\alpha(x) = \phi_\beta(x)$.

From now on we may write $\phi(x)$ for $x \in \Lambda$ without ambiguity. An immediate consequence of this is that we are henceforth free to choose a *special* δ -code for x . Without loss of generality, we may assume that $N \geq 4$. Then from Lemma 4.4 (with $\varepsilon = \min\{\frac{\delta}{(N+1)L^N}, 1\}$) we conclude that

$$(4.11) \quad d(x, \phi(x)) < \varepsilon \leq \frac{\delta}{(N+1)L^N} < \frac{\delta}{5}$$

for all $x \in \Lambda$.

4.4 ϕ is equivariant

To show the equivariance of ϕ , it suffices to check it on the generating set Σ of Γ .

Given $x \in \Lambda$ and $s \in \Sigma$, set $y = \rho(s^{-1})(x)$. Let (β, q) be a *special* δ -code for y , so that $B_\delta(y) \subset U_{\beta(0)}$ (see Definition 3.9). Then we consider a δ -code (α, p) for x defined by $s_{\alpha(0)} = s$ and

$$\begin{aligned} \alpha(i) &= \beta(i-1), \\ p_i &= q_{i-1} \end{aligned}$$

for $i \in \mathbb{N}$: indeed, we verify the requirement that

$$B_\delta(p_i) = B_\delta(q_{i-1}) \subset U_{\beta(i-1)} = U_{\alpha(i)}$$

for $i \in \mathbb{N}$. The associated rays $\{c_i^\alpha\}_{i \in \mathbb{N}_0}$ and $\{c_i^\beta\}_{i \in \mathbb{N}_0}$ (see Definition 3.14) are related by

$$c_i^\alpha = s_{\alpha(0)}(s_{\alpha(1)} \cdots s_{\alpha(i)}) = s(s_{\beta(0)} \cdots s_{\beta(i-1)}) = s c_{i-1}^\beta$$

for $i \in \mathbb{N}$. Therefore, we have

$$\begin{aligned}
\{\phi[\rho(s)(y)]\} &= \{\phi(x)\} = \bigcap_{i=0}^{\infty} \rho'(c_i^\alpha)[B_\delta(p_{i+1})] \\
&= \bigcap_{i=1}^{\infty} \rho'(c_i^\alpha)[B_\delta(p_{i+1})] \\
&= \bigcap_{i=1}^{\infty} \rho'(s)\rho'(c_{i-1}^\beta)[B_\delta(q_i)] \\
&= \rho'(s) \left[\bigcap_{i=0}^{\infty} \rho'(c_i^\beta)[B_\delta(q_{i+1})] \right] = \rho'(s)\{\phi(y)\},
\end{aligned}$$

which implies the equivariance of ϕ .

4.5 ϕ is continuous

Let $\varepsilon' > 0$ be given. In order to show that ϕ is continuous at $x \in \Lambda$, assign a (\mathcal{D}, δ) -code (α, p) for x which comes from a (\mathcal{D}, δ_0) -code for x . (Recall $\delta_0 > \delta$ and Remark 3.10(b). Also note that Lemma 4.4 applies to the (\mathcal{D}, δ) -code (α, p) with $\eta = \delta$). Choose an integer $k \in \mathbb{N}_0$ such that $2\delta_1(L + \epsilon)/(\lambda')^k < \varepsilon'$. Since $\rho(c_k^\alpha)^{-1}$ maps x to p_{k+1} and is continuous, there exists $\delta' > 0$ such that $\rho(c_k^\alpha)^{-1}[B_{\delta'}(x)] \subset B_{\delta_0 - \delta}(p_{k+1})$. Below we will show that if $y \in \Lambda$ satisfies $d(x, y) < \delta'$ then $d(\phi(x), \phi(y)) < \varepsilon'$ thereby proving that ϕ is continuous at x .

Let $y \in \Lambda$ be such that $d(x, y) < \delta'$. Then $\rho(c_k^\alpha)^{-1}(y) \in B_{\delta_0 - \delta}(p_{k+1})$, hence

$$y \in \rho(c_k^\alpha)[B_{\delta_0 - \delta}(p_{k+1})] \subset \rho(c_{k-1}^\alpha)[B_{\delta_1 - \delta}(p_k)] \subset \cdots \subset \rho(c_0^\alpha)[B_{\delta_0 - \delta}(p_1)]$$

by Lemma 3.18(i). In other words, for $0 \leq i \leq k$, we have

$$\begin{aligned}
\rho(c_i^\alpha)^{-1}(y) &\in B_{\delta_0 - \delta}(p_{i+1}), \\
\text{hence } B_\delta(\rho(c_i^\alpha)^{-1}(y)) &\subset B_{\delta_0}(p_{i+1}) \subset U_{\alpha(i+1)}.
\end{aligned}$$

This means that there is a δ -code (β, q) for $y \in \Lambda$ with a property that

$$\beta(i) = \alpha(i) \quad \text{for } 0 \leq i \leq k.$$

In particular, $c_k^\beta = c_k^\alpha$ and hence $q_{k+1} = \rho(c_k^\beta)^{-1}(y) = \rho(c_k^\alpha)^{-1}(y) \in B_{\delta_0 - \delta}(p_{k+1})$. Consequently, we have $B_\delta(q_{k+1}) \subset B_{\delta_0}(p_{k+1})$ and

$$\begin{aligned}
\{\phi(y)\} &= \bigcap_{i=0}^{\infty} \rho'(c_i^\beta)[B_\delta(q_{i+1})] \\
&\subset \rho'(c_k^\beta)[B_\delta(q_{k+1})] \\
&= \rho'(c_k^\alpha)[B_\delta(q_{k+1})] \\
&\subset \rho'(c_k^\alpha)[B_{\delta_0}(p_{k+1})],
\end{aligned}$$

By (the proof of) Lemma 4.4, the diameter of the last set $\rho'(c_k^\alpha)[B_{\delta_0}(p_{k+1})]$ is at most $2\delta_0(L + \epsilon)/(\lambda')^k < \epsilon'$. Since $\phi(x) \in \rho'(c_k^\alpha)[B_{\delta_0}(p_{k+1})]$ as well, we showed

$$d(\phi(x), \phi(y)) \leq 2\delta_0(L + \epsilon)/(\lambda')^k < \epsilon'$$

as desired.

4.6 ϕ is injective

Suppose, to the contrary, that $\phi(x) = \phi(y)$ but $x \neq y$. Since ϕ is equivariant, we then have $\phi[\rho(g)(x)] = \phi[\rho(g)(y)]$ for any $g \in \Gamma$, hence, by (4.11),

$$d(\rho(g)(x), \rho(g)(y)) < d(\rho(g)(x), \phi[\rho(g)(x)]) + d(\phi[\rho(g)(y)], \rho(g)(y)) < \delta/2 + \delta/2 = \delta$$

for all $g \in \Gamma$. But this contradicts Corollary 3.19, since ρ has an expansivity constant δ . Therefore, ϕ is injective.

So far, we have proved the claim that ϕ is an equivariant homeomorphism. This completes the proof of Theorem 3.32(1).

4.7 ϕ depends continuously on ρ'

We will show that if ρ' is close to ρ then ϕ is close to the identity map, and hence $\phi(\Lambda) = \Lambda'$ is close to Λ . More precisely, we claim that the map

$$\begin{aligned} \text{Hom}(\Gamma, \text{Homeo}(M)) \supset U(\rho; K, \epsilon) &\rightarrow C^0(\Lambda, (M, d)) \\ \rho' &\mapsto \phi \end{aligned}$$

is continuous at ρ , where we equip $\text{Hom}(\Gamma, \text{Homeo}(M))$ with the topology of “algebraic convergence” as in Section 3.4 and $C^0(\Lambda, (M, d))$ with the uniform topology. As for Λ and Λ' , this will imply that the map $\rho' \mapsto d_{\text{Haus}}(\Lambda, \Lambda')$ is continuous at ρ , where d_{Haus} stands for the Hausdorff distance.

To prove the claim, suppose a sufficiently small constant $\epsilon > 0$ is given. Of course, we may assume $\epsilon \leq \min\{\frac{\delta}{(N+1)L^N}, 1\}$. Then we have to find a neighborhood $U(\rho; K', \epsilon')$ of ρ such that $\sup\{d(x, \phi(x)) \mid x \in \Lambda\} < \epsilon$ for every $\rho' \in U(\rho; K', \epsilon')$. So, we let

$$K' = K \quad \text{and} \quad \epsilon' = \frac{\lambda - 1}{2}\epsilon.$$

Suppose $\rho' \in U(\rho; K', \epsilon')$. Let $x \in \Lambda$ and choose a *special* δ -code (α, p) for x . Then by Lemma 4.4 we have $d(x, \phi(x)) = d(x, \phi_\alpha(x)) < \epsilon$. Since $x \in \Lambda$ is arbitrary, the proof is complete.

4.8 ρ' is expanding

We now show how, given an expansion datum \mathcal{D} of the action ρ , to get a new expansion datum $\mathcal{D}' = (\mathcal{I}', \mathcal{U}', \Sigma', \delta', L', \lambda')$ of the action ρ' .

First take the same data \mathcal{I} and Σ of \mathcal{D} i.e., set $\mathcal{I}' = \mathcal{I}$ and $\Sigma' = \Sigma$, and set $L' = L + \epsilon$ and $\lambda' = \lambda - \epsilon$ from (4.3) and (4.2). Then every $\rho'(s_\alpha^{-1})$ is λ' -expanding on $U_\alpha \cap N_\delta(\Lambda)$ and L' -Lipschitz on $N_\delta(\Lambda)$. For a positive number $r < 4\delta/5$, if we set

$$\mathcal{U}' = \{U'_\alpha := \text{int}(U_\alpha \cap N_\delta(\Lambda))^r = \text{int} U_\alpha^r \cap N_{\delta-r}(\Lambda) \mid \alpha \in \mathcal{I}\}$$

(recall (2.1) for the definition of U^r), then by Remark 3.6(e) there is a constant $\delta' = \delta'(r) > 0$ such that every $\rho'(s_\alpha^{-1})$ is $(\lambda', U'_\alpha; \delta')$ -expanding. Note that δ' can be chosen as small as we want and thus we may assume that $\delta' < 4\delta/5$. Let $x \in \Lambda$. Then, since $d(x, \phi(x)) < \delta/5$ by (4.11) and $0 < r < 4\delta/5$, it follows that

$$\overline{B}_r(\phi(x)) \subset B_{r+\delta/5}(x) \subset B_\delta(x) \subset U_\alpha \cap N_\delta(\Lambda)$$

for some $\alpha \in \mathcal{I}$, and hence $\phi(x) \in U'_\alpha$. This implies that \mathcal{U}' covers Λ' and $N_{\delta'}(\Lambda') \subset N_\delta(\Lambda)$. Thus every $\rho'(s_\alpha^{-1})$ is L' -Lipschitz on $N_{\delta'}(\Lambda')$. If we choose δ' so that δ' is smaller than a Lebesgue number of the open covering \mathcal{U}' of Λ' , the properties (i) and (ii) of Definition 3.4 are verified for ρ' with the datum $\mathcal{D}' = (\mathcal{I}', \mathcal{U}', \Sigma', \delta', L', \lambda')$. Therefore, ρ' is expanding.

4.9 ρ' is again uniformly meandering-hyperbolic

Assume that the action $\rho : \Gamma \rightarrow \text{Homeo}(M; \Lambda)$ is uniformly meandering-hyperbolic with a datum $(\mathcal{D}_0 \prec \mathcal{D}; N)$ (Definition 3.26). Then, for every $\eta \in (0, \delta]$ and every $x \in \Lambda$, all rays in $\text{Ray}_x(\mathcal{D}_0, \eta)$ are $(\mathcal{D}, \eta; N)$ -equivalent. In order to show that every $\rho' \in U(\rho; K, \epsilon)$ is uniformly meandering-hyperbolic, we first let \mathcal{D}' be the expansion data of ρ' obtained from \mathcal{D} via the way described in Section 4.8 by taking $r = \delta/5$, so that, in particular,

$$\mathcal{U}' = \{U'_\alpha := \text{int}(U_\alpha \cap N_\delta(\Lambda))^{\delta/5} = \text{int} U_\alpha^{\delta/5} \cap N_{4\delta/5}(\Lambda) \mid \alpha \in \mathcal{I}\}.$$

Then, we will define an expansion data $\mathcal{D}'_0 \prec \mathcal{D}'$ of ρ' and show that $(\mathcal{D}'_0 \prec \mathcal{D}'; N)$ is a uniform meandering hyperbolicity datum of ρ' .

Since $\mathcal{D}_0 \prec \mathcal{D}$, one can easily derive an expansion datum $\mathcal{D}'_0 = (\mathcal{I}'_0, \mathcal{U}'_0, \Sigma'_0, \delta'_0, L'_0, \lambda'_0)$ of ρ' from \mathcal{D}_0 as follows. Set $\mathcal{I}'_0 = \mathcal{I}_0$, $\Sigma'_0 = \Sigma_0$, $L'_0 = L'$ and $\lambda'_0 = \lambda'$. Let $\mathcal{U}_0 = \{U_{0,\alpha} \mid \alpha \in \mathcal{I}_0\}$. From $\mathcal{U}_0 \prec \mathcal{U}$, it immediately follows that $\rho'(s_\alpha^{-1})$ is λ' -expanding on $U_{0,\alpha} \cap N_\delta(\Lambda)$ and L' -Lipschitz on $N_\delta(\Lambda)$ for all $\alpha \in \mathcal{I}_0$. If we set

$$\mathcal{U}'_0 = \{U'_{0,\alpha} := \text{int}(U_{0,\alpha} \cap N_\delta(\Lambda))^{3\delta/5} = \text{int} U_{0,\alpha}^{3\delta/5} \cap N_{2\delta/5}(\Lambda) \mid \alpha \in \mathcal{I}_0\},$$

then Remark 3.6(e) implies that there is $\delta'_0 > 0$ such that $\rho'(s_\alpha^{-1})$ is $(\lambda', U'_{0,\alpha}; \delta'_0)$ -expanding for all $\alpha \in \mathcal{I}_0$. For any $x \in \Lambda$, since $d(x, \phi(x)) < \delta/5$, we have

$$\overline{B}_{3\delta/5}(\phi(x)) \subset B_{4\delta/5}(x) \subset B_\delta(x) \subset U_{0,\alpha} \cap N_\delta(\Lambda)$$

for some $\alpha \in \mathcal{I}_0$. We may choose δ'_0 and δ' so that $\delta' < \delta'_0 < 2\delta/5$. Then \mathcal{D}'_0 is another expansion datum of ρ' such that $\mathcal{D}'_0 \prec \mathcal{D}'$.

In order to check that $(\mathcal{D}'_0 \prec \mathcal{D}'; N)$ is a uniform meandering hyperbolicity datum of ρ' , let $0 < \eta \leq \delta' < 2\delta/5$ and $x \in \Lambda$. We need to show that all rays in $\text{Ray}_x(\mathcal{D}'_0, \eta)$ are $(\mathcal{D}', \eta; N)$ -equivalent.

Let $x \in \Lambda$ and (α, p') be a (\mathcal{D}'_0, η) -code for $\phi(x)$. Recall Definition 3.9. Since (α, p') is an (\mathcal{D}'_0, η) -code for $\phi(x) \in \Lambda'$, we have

$$\begin{aligned} p'_0 &= \phi(x), \\ p'_{i+1} &= \rho'(s_{\alpha(i)}^{-1})(p'_i), \\ B_\eta(p'_i) &\subset U'_{0, \alpha(i)} \end{aligned}$$

for all $i \in \mathbb{N}_0$. By the definition of $U'_{0, \alpha} := \text{int } U_{0, \alpha}^{3\delta/5} \cap N_{2\delta/5}(\Lambda)$, it follows that $B_{\eta+3\delta/5}(p'_i) \subset U_{0, \alpha(i)}$ for all $i \in \mathbb{N}_0$. Let $p_i = \phi^{-1}(p'_i)$ for $i \in \mathbb{N}_0$ and $p : \mathbb{N}_0 \rightarrow \Lambda$ be the sequence corresponding to $\{p_i\}_{i \in \mathbb{N}_0}$. We first check

$$(\phi^{-1} \circ p')(0) = \phi^{-1}(\phi(x)) = x$$

and then, for $i \in \mathbb{N}$, check

$$p_{i+1} = (\phi^{-1} \circ p')(i+1) = \phi^{-1}[\rho'(s_{\alpha(i)}^{-1})(p'_i)] = \rho(s_{\alpha(i)}^{-1})[(\phi^{-1} \circ p')(i)] = \rho(s_{\alpha(i)}^{-1})(p_i),$$

where the second equality is due to the equivariance of ϕ . Since $d(p_i, p'_i) < \delta/5$, we have that for all $i \in \mathbb{N}_0$,

$$B_{\eta+2\delta/5}(p_i) \subset B_{\eta+3\delta/5}(p'_i) \subset U_{0, \alpha(i)},$$

which implies that (α, p) is a $(\mathcal{D}_0, \eta + 2\delta/5)$ -code for $x \in \Lambda$.

By the uniform meandering hyperbolicity of ρ , there is a finite chain of interpolating rays $c^\alpha = c^{\gamma_1}, c^{\gamma_2}, \dots, c^{\gamma_n} = c^\beta$ in $\text{Ray}_x(\mathcal{D}, \eta + 2\delta/5)$ such that

$$c^{\gamma_1} \approx_{(\mathcal{D}, \eta + 2\delta/5)}^N c^{\gamma_2} \approx_{(\mathcal{D}, \eta + 2\delta/5)}^N \dots \approx_{(\mathcal{D}, \eta + 2\delta/5)}^N c^{\gamma_n}.$$

We claim that $\text{Ray}_x(\mathcal{D}, \eta + 2\delta/5) \subset \text{Ray}_{\phi(x)}(\mathcal{D}', \eta)$ holds. Then we have

$$c^{\gamma_1} \approx_{(\mathcal{D}', \eta)}^N c^{\gamma_2} \approx_{(\mathcal{D}', \eta)}^N \dots \approx_{(\mathcal{D}', \eta)}^N c^{\gamma_n}$$

and, therefore, we conclude that ρ' is uniformly meandering-hyperbolic with a datum $(\mathcal{D}'_0 \prec \mathcal{D}'; N)$.

Now it only remains to prove the claim. Let (γ, q) be a $(\mathcal{D}, \eta + 2\delta/5)$ -code for $x \in \Lambda$. Then for all $i \in \mathbb{N}_0$,

$$B_{\eta+\delta/5}(\phi(q_i)) \subset B_{\eta+2\delta/5}(q_i) \subset U_{\gamma(i)} \cap N_{4\delta/5}(\Lambda),$$

which implies that $B_\eta(\phi(q_i)) \subset U'_{\gamma(i)}$ and thus (γ, q') is a (\mathcal{D}', η) -code for $\phi(x)$ as desired. The claim is proved.

5 Uniform lattices in semisimple Lie groups are structurally stable

In this section we shall prove the following theorem that, for every uniform lattice Γ in a semisimple Lie group G , the Γ -action on each flag manifold G/P is meandering-hyperbolic.

5.1 Theorem. *Let $\Gamma < G$ be a uniform lattice in a semisimple Lie group G (with finitely many connected components and finite center). Then, for each face $\tau_{\text{mod}} \subset \sigma_{\text{mod}}$, the Γ -action on the flag manifold $\text{Flag}(\tau_{\text{mod}})$ is uniformly meandering-hyperbolic.*

From the structural stability theorem (Theorem 3.32) we then conclude:

5.2 Corollary. *The actions on flag manifolds of uniform lattices in semisimple Lie groups are structurally stable in the sense of Lipschitz dynamics.*

Let $X = G/K$ be the symmetric space associated with the semisimple Lie group G . Our proof will use definitions and results regarding asymptotic geometry of X established in a series of papers of Kapovich, Leeb and Porti [KL18b, KLP17, KLP18], to which we refer the reader for details; surveys of these notions and results can be found in [KLP16, KL18].

The key notion used in the proof is the one of *Morse quasigeodesics* in X , which was first introduced in [KLP14] in order to give one of many alternative interpretations of Anosov subgroups. While uniform lattices in higher rank Lie groups are clearly non-Anosov, some key geometric results developed for the purpose of analyzing Anosov subgroups are still very useful when dealing with higher rank lattices, as we will see below.

In the remainder of the section we prove Theorem 5.1 in the following steps:

- (§5.1) we find an expansion datum \mathcal{D} for the action;
- (§5.2) we show that coding rays are Morse quasigeodesics, and
- (§5.3) that asymptotic Morse quasigeodesics can be interpolated;
- (§5.4) for each $\eta \in (0, \delta]$, we find a refinement \mathcal{D}_η of the expansion datum \mathcal{D} using steps (2) and (3);
- (§5.5) we verify the uniform meandering hyperbolicity using Proposition 5.3 below.

5.3 Proposition. *Let $\rho : \Gamma \rightarrow \text{Homeo}(M)$ be an expanding action with a datum $\mathcal{D} = (\mathcal{I}, \mathcal{U}, \Sigma, \delta, L, \lambda)$. Suppose that, for each $\eta \in (0, \delta]$, there exist a positive constant $r_\eta < \eta$, an integer $N_\eta > 0$ and an expansion datum $\mathcal{D}_\eta = (\mathcal{I}_\eta, \mathcal{U}_\eta, \Sigma_\eta, r_\eta, L_\eta, \lambda_\eta) \succ \mathcal{D}$ such that for every $x \in \Lambda$, all rays in $\text{Ray}_x(\mathcal{D}, \eta)$ are $(\mathcal{D}_\eta, r_\eta; N_\eta)$ -equivalent as rays in $\text{Ray}_x(\mathcal{D}_\eta, r_\eta)$. Then ρ is uniformly meandering-hyperbolic.*

Proof. To define a uniform meandering hyperbolicity datum of ρ , we set $\delta_0 = r_{\delta/2} + \delta/2$, $\mathcal{U}_0 = \{\text{int } U_\alpha^{\delta/2} \mid \alpha \in \mathcal{I}\}$ (recall (2.1)) and $\mathcal{D}_0 = (\mathcal{I}, \mathcal{U}_0, \Sigma, \delta_0, L, \lambda)$. Note that $\mathcal{D}_{\delta/2}, r_{\delta/2}$ and $N_{\delta/2}$ are the data determined by $\delta/2 \in (0, \delta]$ from the hypothesis. It is obvious that \mathcal{D}_0 is an expansion datum of ρ since $\mathcal{U}^{\delta/2} \prec \mathcal{U}$ and $\delta_0 = r_{\delta/2} + \delta/2 < \delta/2 + \delta/2 = \delta$. We take \mathcal{D}_0 as the initial expansion datum of ρ and claim that $(\mathcal{D}_0 \prec \mathcal{D}_{\delta/2}; N_{\delta/2})$ is a uniform meandering hyperbolicity datum of ρ .

For $\eta \in (0, r_{\delta/2})$, let α and β be (\mathcal{D}_0, η) -codes for $x \in \Lambda$. Then, from the definition of \mathcal{U}_0 , it follows that α and β are $(\mathcal{D}, \eta + \delta/2)$ -codes and hence $(\mathcal{D}, \delta/2)$ -codes for $x \in \Lambda$. In other words, all (\mathcal{D}_0, η) -codes are $(\mathcal{D}, \delta/2)$ -codes for any $\eta \in (0, r_{\delta/2})$. By the hypothesis, there is a finite chain of interpolating rays $c^\alpha = c^{\gamma_1}, c^{\gamma_2}, \dots, c^{\gamma_n} = c^\beta$ in $\text{Ray}_x(\mathcal{D}_{\delta/2}, r_{\delta/2})$ such that

$$c^{\gamma_1} \underset{(\mathcal{D}_{\delta/2}, r_{\delta/2})}{\approx}^{N_{\delta/2}} c^{\gamma_2} \underset{(\mathcal{D}_{\delta/2}, r_{\delta/2})}{\approx}^{N_{\delta/2}} \cdots \underset{(\mathcal{D}_{\delta/2}, r_{\delta/2})}{\approx}^{N_{\delta/2}} c^{\gamma_n}.$$

Since $\eta < r_{\delta/2}$, it is possible to regard all the $(\mathcal{D}_{\delta/2}, r_{\delta/2})$ -codes γ_i above as $(\mathcal{D}_{\delta/2}, \eta)$ -codes. Hence all rays in $\text{Ray}_x(\mathcal{D}_0, \eta)$ are $(\mathcal{D}_{\delta/2}, \eta; N_{\delta/2})$ -equivalent. Furthermore, one can easily check that $\mathcal{D}_0 \prec \mathcal{D}_{\delta/2}$. Therefore, we conclude that $(\mathcal{D}_0 \prec \mathcal{D}_{\delta/2}; N_{\delta/2})$ is a uniform meandering hyperbolicity datum of ρ . \square

5.1 Expansion

In order to obtain an expansion data for the Γ -action on the flag manifold $G/P = \text{Flag}(\tau_{\text{mod}})$, we proceed as in Remark 3.6(c).

First fix a number $\lambda > 1$ and a base point $x \in X$.

Let $D > 0$ be the diameter of a compact fundamental domain for the Γ -action on X . Then the orbit $\Gamma x \subset X$ is D -dense in X , that is, $B_D(y) \cap \Gamma x \neq \emptyset$ for any $y \in X$. In view of [KLP17, Theorem 2.41], the D -density of Γx implies that for each $\tau \in \text{Flag}(\tau_{\text{mod}})$, there is an element $g_\tau \in \Gamma$ such that $\epsilon(g_\tau^{-1}, \tau) > \lambda$. Define an open subset $U_\tau \subset \text{Flag}(\tau_{\text{mod}})$ by

$$U_\tau = \{\tau' \in \text{Flag}(\tau_{\text{mod}}) \mid \epsilon(g_\tau^{-1}, \tau') > \lambda\},$$

so that $\tau \in U_\tau$ and g_τ^{-1} is (λ, U_τ) -expanding. Then we have an open cover $\{U_\tau\}_{\tau \in \text{Flag}(\tau_{\text{mod}})}$ of $\text{Flag}(\tau_{\text{mod}})$. Since $\text{Flag}(\tau_{\text{mod}})$ is compact, there is a finite subcover $\{U_{\tau_1}, \dots, U_{\tau_k}\}$. Let us abbreviate U_{τ_i} and g_{τ_i} to U_i and g_i , respectively, for $i = 1, \dots, k$. Let $\Sigma' = \{g_1, \dots, g_k\}$.

By adding extra generators to Σ' with empty expanding subsets, we obtain a symmetric generating set Σ of Γ . Let \mathcal{I} be the index set for Σ and \mathcal{U} the collection of all (λ, g_i^{-1}) -expanding subsets U_i where $g_i \in \Sigma$. Since $\text{Flag}(\tau_{\text{mod}})$ is compact, Σ is finite and the Γ -action is by C^1 -diffeomorphisms, there exist a constant $L > 1$ such that every $g_i \in \Sigma$ is L -Lipschitz on $\text{Flag}(\tau_{\text{mod}})$. Let $\delta < \delta_{\mathcal{U}}$ be a Lebesgue number of \mathcal{U} . Then we conclude that $\mathcal{D} = (\mathcal{I}, \mathcal{U}, \Sigma, \delta, L, \lambda)$ is an expansion datum of the Γ -action.

5.2 Coding rays are uniform Morse quasigeodesics

In the proof of the next lemma we will be using the notions of τ_{mod} -regular (and uniformly regular) sequences and τ_{mod} -convergence property for such sequences; the reader will find a detailed treatment of these notions in [KLP17, Section 4].

5.4 Lemma. *Let $\eta \in (0, \delta]$ and α be a (\mathcal{D}, η) -code for $\tau \in \text{Flag}(\tau_{\text{mod}})$ and $c^\alpha : \mathbb{N}_0 \rightarrow \Gamma < G$ be the ray associated to α . Then the sequence $c^\alpha x$ in X is a (Θ, R) -Morse quasigeodesic with endpoint τ for some data (Θ, R) depending only on the pair (\mathcal{D}, η) .*

Proof. Recall from Corollary 3.20 that the ray c^α is a uniform quasigeodesic in Γ which is quasi-isometric to X . Thus, in order to prove the Morse property, it suffices to establish the uniform τ_{mod} -regularity of the sequence c^α ; see [KLP18, Theorem 1.3].

First of all, there exists a closed ball $B \subset \text{Flag}(\tau_{\text{mod}})$ such that c^α restricted to B subconverges uniformly to τ . Moreover, the limit set of the sequence $(c^\alpha)^{-1}(\tau)$ lies in B by Theorem 3.21. Since B is Zariski dense in $\text{Flag}(\tau_{\text{mod}})$, the sequence c^α is τ_{mod} -regular; see the proof of [KL18b, Theorem 9.6].

Now we show that the sequence c^α is uniformly τ_{mod} -regular. We first verify that the sequence c^α conically converges to τ . Since it suffices to prove this for all subsequences in c^α , we will freely pass to such subsequences. Note that the inverse sequence $(c^\alpha)^{-1}$ is also $\iota\tau_{\text{mod}}$ -regular and, hence, flag-subconverges to a simplex $\tau_- \in \text{Flag}(\iota\tau_{\text{mod}})$. Furthermore, the sequence c^α subconverges to τ uniformly on compacts in the open Schubert cell $C(\tau_-) \subset \text{Flag}(\tau_{\text{mod}})$ of τ_- and, whenever B' is a closed ball in $\text{Flag}(\tau_{\text{mod}})$ which is *not* contained in $C(\tau_-)$, the sequence c^α cannot subconverge to τ uniformly on B' . Thus the ball B , and hence its center ν (which is the limit of a subsequence in $(c^\alpha)^{-1}(\tau)$), is contained in $C(\tau_-)$. Since $\nu \in C(\tau_-)$, according to [KLP17, Proposition 5.31], the convergence $c^\alpha \rightarrow \tau$ is conical.

Lastly, by [KLP17, Theorem 2.41], the uniform exponential expansion of the sequence $(c^\alpha)^{-1}$ at τ (guaranteed by Lemma 3.18) implies (uniform) Θ -regularity of the sequence c^α , where Θ is a certain fixed $W_{\tau_{\text{mod}}}$ -convex compact subset of the open star $\text{ost}(\tau_{\text{mod}})$ of τ_{mod} in σ_{mod} . \square

5.3 Morse interpolation

As in Definition 3.23, given two maps $p, q : \mathbb{R}_+ \rightarrow X$ and an integer $N \geq 0$, we define the relation $p \approx^N q$ by the condition that there exist unbounded monotonic sequences (P_i) and (Q_i) in \mathbb{R}_+ such that the subsets $\{p(P_i) \mid i \in \mathbb{N}_0\}$ and $\{q(Q_i) \mid i \in \mathbb{N}_0\}$ in X are within Hausdorff distance N from each other.

5.5 Lemma. *Let p and q be (Θ, R) -Morse quasigeodesic rays in X with $p(\infty) = q(\infty) = \tau$. Let $\Theta' \subset \text{ost}(\tau_{\text{mod}})$ be a $W_{\tau_{\text{mod}}}$ -convex compact subset such that $\Theta \subset \text{int}(\Theta')$. Then there is a (Θ', R) -Morse quasigeodesic ray r in X such that $r(\infty) = \tau$ and*

$$p \approx^0 r \approx^0 q.$$

Moreover, if $p(0) = q(0) = x \in X$, then r can be chosen such that $r(0) = x$.

Proof. Since τ_{mod} -Morse quasigeodesics are uniformly close to τ_{mod} -Finsler geodesics by [KLP17, Theorem 5.53], without loss of generality, we may assume p and q are Θ -Finsler geodesic rays in the Weyl cone $V = V(x, \text{st}(\tau))$, where Θ is a compact $W_{\tau_{\text{mod}}}$ -convex subset in the open star $\text{ost}(\tau_{\text{mod}})$ of τ_{mod} in σ_{mod} , see Definition 2.10.

Let Θ' be a $W_{\tau_{\text{mod}}}$ -convex compact subset in $\text{ost}(\tau_{\text{mod}})$ such that Θ is contained in the interior of Θ' . We will define a Θ' -Finsler geodesic ray r in the Weyl cone V such that for

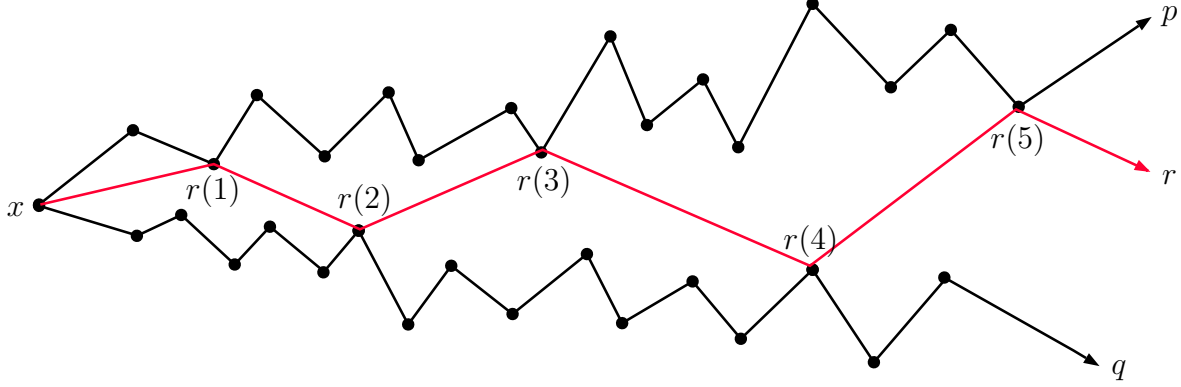


Figure 4: Interpolating ray.

an unbounded monotonic sequence $t_n \in \mathbb{R}_+$, we have

$$\begin{aligned} r(t_n) &\in p(\mathbb{R}_+) && \text{if } n \text{ is odd, and} \\ r(t_n) &\in q(\mathbb{R}_+) && \text{if } n \text{ is even.} \end{aligned}$$

On each interval $[t_n, t_{n+1}]$ the ray r will be a *longitudinal* Θ' -regular Riemannian geodesic $r(t_n)r(t_{n+1})$ in the symmetric space X , that is, a Θ' -regular Riemannian geodesic contained in a Riemannian geodesic ray emanating from $r(t_n)$ which is in V .

We define the points $r(t_n)$ inductively as follows. Set $r(t_0) = q(0)$. Suppose that n is odd and $r(t_n) \in p(\mathbb{R}_+)$ is defined. (The case when n is even and $r(t_n) \in q(\mathbb{R}_+)$ is similar.) Since the Finsler geodesic ray q is Θ -regular, the limit (as $t \rightarrow \infty$) of directions of oriented segments

$$p(t_n)q(t)$$

belongs to $\text{st}_\Theta(\tau)$. Therefore, for a sufficiently large t (which we denote t_{n+1}), the direction of the geodesic segment $p(t_n)q(t_{n+1})$ is in the interior of $\text{st}_{\Theta'}(\tau)$.

Since the cone V is convex in X , the infinite concatenation of the above segments $p(t_n)q(t_{n+1})$ is a piecewise geodesic ray r in V whose restriction to each interval $[t_n, t_{n+1}]$ is Θ' -regular and longitudinal (see Figure 4). Therefore, by the nestedness property of Θ' -cones (see [KLP17, Section 2.12]), the entire ray r is a Θ' -Finsler geodesic ray in V . Since r is contained in V , it also follows that $r(\infty) = \tau$.

From the above construction, the ray r clearly satisfies $r \approx^0 p$ and $r \approx^0 q$. \square

5.4 Refined expansion data

Now we find a refinement \mathcal{D}_η of the expansion datum \mathcal{D} for each $\eta \in (0, \delta]$.

Let α and β be (\mathcal{D}, η) -codes for $\tau \in \text{Flag}(\tau_{\text{mod}})$. By Lemma 5.4, the associated rays c^α and c^β project in X to (Θ, R) -Morse quasigeodesic rays with endpoint τ , where the datum (Θ, R) depends only on \mathcal{D} and η . Hence $c^\alpha(n)x$ and $c^\beta(n)x$ are contained in the R -neighborhood of $V(x, \text{st}_\Theta(\tau))$ for any integer $n \geq 0$. We fix compact $W_{\tau_{\text{mod}}}$ -convex subsets $\Theta', \Theta'' \subset \text{ost}(\tau_{\text{mod}})$ in σ_{mod} such that

$$\Theta \subset \text{int}(\Theta') \subset \Theta' \subset \text{int}(\Theta'') \subset \Theta''.$$

Then by Lemma 5.5 we can construct a (Θ', R) -Morse quasigeodesic ray r in X with $r(0) = x$ and $r(\infty) = \tau$ such that $r(t_n) \in c^\alpha(\mathbb{N}_0)x$ if n is odd and $r(t_n) \in c^\beta(\mathbb{N}_0)x$ if n is even for an unbounded increasing sequence $t_n \in \mathbb{R}_+$, and such that the restriction of r to each interval $[t_n, t_{n+1}]$ is Θ' -regular and longitudinal. In addition, the construction in the proof of Lemma 5.5 also shows that, for a given constant $l > 0$, the ray r can be assumed to satisfy $d_X(r(t_n), r(t_{n+1})) > l$ for all integers $n \geq 0$.

We will choose a suitable constant l by

$$(5.6) \quad l := \max\{l_1, l_2, l_3\} + 4(D + R),$$

where the constants l_1, l_2 and l_3 are defined as follows. First, choose a constant $l_1 = l_1(\Theta', \Theta'', D, R) > 0$ so that if $d_\Delta(x, y) \in V(0, W_{\tau_{\text{mod}}}\Theta') \cap \Delta$ and $d_X(x, y) > l_1$, then

$$d_\Delta(x', y') \in V(0, W_{\tau_{\text{mod}}}\Theta'') \cap \Delta$$

for any $x' \in B_{D+R}(x)$ and any $y' \in B_{D+R}(y)$. This is possible due to the following inequality

$$\|d_\Delta(x, y) - d_\Delta(x', y')\| \leq d_X(x, x') + d_X(y, y') \leq 2(D + R).$$

Let x_n denote the nearest point projection of $r(t_n)$ to $V(x, \text{st}(\tau))$. If $d_X(r(t_n), r(t_{n+1})) > l_1$ for all integers $n \geq 0$, it can be easily seen that the piecewise geodesic with vertices x_n is a Θ'' -regular τ_{mod} -Finsler geodesic ray.

For the second constant $l_2 > 0$, we recall [KLP17, Theorem 2.41] again that there are constants $C, A > 0$ depending only on x, R, D and the chosen Riemannian metric on $\text{Flag}(\tau_{\text{mod}})$ such that if $d_X(gx, V(x, \text{st}(\tau))) \leq 2(D + R)$, then

$$(5.7) \quad C^{-1} \cdot d_X(gx, \partial V(x, \text{st}(\tau))) - A \leq \log \epsilon(g^{-1}, \tau) \leq C \cdot d_X(gx, \partial V(x, \text{st}(\tau))) + A.$$

(Recall from (2.2) that $\epsilon(g^{-1}, \tau)$ is the expansion factor of g^{-1} at $\tau \in \text{Flag}(\tau_{\text{mod}})$.) Given $\lambda > 1$, the inequality (5.7) makes it possible to choose a constant $l_2 = l_2(x, R, D, \lambda) > 0$ such that if $d_X(gx, \partial V(x, \text{st}(\tau))) \geq l_2$ and $d_X(gx, V(x, \text{st}(\tau))) \leq 2(D + R)$, then $\epsilon(g^{-1}, \tau) \geq 2\lambda$. Finally, we choose a constant $l_3 > 0$ as follows. If $y \in V(x, \text{st}_{\Theta''}(\tau))$, the distance of y from $\partial V(x, \text{st}(\tau))$ grows linearly with the distance of x and y . Its linear growth rate only depends on Θ'' and hence there is a constant $l_3 = l_3(\Theta'', l_2) > 0$ such that if $y \in V(x, \text{st}_{\Theta''}(\tau))$ and $d_X(x, y) \geq l_3$, then $d_X(y, \partial V(x, \text{st}(\tau))) \geq l_2 + 2(D + R)$ for any $x, y \in X$ and any $\tau \in \text{Flag}(\tau_{\text{mod}})$.

Now we are ready to add new generators to Σ . Let Σ_0 be the set of all elements $g \in \Gamma$ such that

$$d_\Delta(x, gx) \in V(0, W_{\tau_{\text{mod}}}\Theta'') \cap \Delta \quad \text{and} \quad l - 2D < d_X(x, gx) < 2l + 2D.$$

Since Γ acts properly discontinuously on X , Σ_0 is finite. To each $g \in \Sigma_0$, we associate its expansion domain

$$U_g^\lambda = \{\tau \in \text{Flag}(\tau_{\text{mod}}) \mid \epsilon(g^{-1}, \tau) > \lambda\}.$$

Add all elements $g \in \Sigma_0$ together with λ -expanding domains U_g^λ to Σ and \mathcal{U} , respectively. Furthermore, when necessary, add the inverses of Σ_0 together with their (possibly empty) λ -expanding domains. Then we obtain a symmetric generating finite set Σ_η and the collection \mathcal{U}_η of all (λ, g) -expanding subsets for $g \in \Sigma_\eta$. The index set \mathcal{I}_η for Σ_η , and the Lipschitz constant $L_\eta \geq L$ are determined in the obvious way. Lastly, by setting

$$\delta_\eta := \min \left\{ \frac{99}{100}\eta, \min_{g \in \Sigma_0} d_X(U_g^{2\lambda}, \partial U_g^\lambda) \right\} < \eta \leq \delta,$$

we obtain a refined expansion datum

$$\mathcal{D}_\eta = (\mathcal{I}_\eta, \mathcal{U}_\eta, \Sigma_\eta, \delta_\eta, L_\eta, \lambda) \succ (\mathcal{I}, \mathcal{U}, \Sigma, \delta, L, \lambda) = \mathcal{D}$$

for the Γ -action on $\text{Flag}(\tau_{\text{mod}})$. Note that by the definition of δ_η above, if $\epsilon(g^{-1}, \tau) > 2\lambda$, that is, $\tau \in U_g^{2\lambda}$ for some $g \in \Sigma_0$, then $B_{\delta_\eta}(\tau) \subset U_g^\lambda$.

5.5 Uniform meandering hyperbolicity

Lastly, we are left with checking the uniform meandering hyperbolicity condition.

Fix $\tau \in \text{Flag}(\tau_{\text{mod}})$. Let α and β be (\mathcal{D}, η) -codes for τ . In view of Proposition 5.3, it suffices to show that the associated rays c^α and c^β are $(\mathcal{D}_\eta, \delta_\eta; N)$ -equivalent for some integer $N \geq 1$. But we claim, as a matter of fact, that there exists a $(\mathcal{D}_\eta, \delta_\eta)$ -code γ for τ such that

$$c^\alpha \approx_{(\mathcal{D}_\eta, \delta_\eta)}^0 c^\gamma \approx_{(\mathcal{D}_\eta, \delta_\eta)}^0 c^\beta.$$

That is to say, only one interpolation step is needed and we may take $N = 1 > 0$.

Let us prove the claim. According to Lemma 5.4, the sequences $c^\alpha x$ and $c^\beta x$ are (Θ, R) -Morse quasigeodesic rays in Γx with endpoint τ for a uniform datum (Θ, R) depending only on (\mathcal{D}, η) . We fix compact $W_{\tau_{\text{mod}}}$ -convex subsets $\Theta', \Theta'' \subset \text{ost}(\tau_{\text{mod}}) \subset \sigma_{\text{mod}}$ such that $\Theta \subset \text{int}(\Theta') \subset \Theta' \subset \text{int}(\Theta'')$. Then, by (the proof of) Lemma 5.5 and by the choice of the constant $l > 0$ in (5.6), there is a (Θ', R) -Morse quasigeodesic r in Γx with $r(0) = x$ and $r(\infty) = \tau$ and an unbounded increasing sequence $t_n \in \mathbb{R}_+$ with $t_0 = 0$ such that

- (i) $r(t_n) \in c^\alpha(\mathbb{N}_0)x$ if n is odd and $r(t_n) \in c^\beta(\mathbb{N}_0)x$ if n is even,
- (ii) the restriction of r to each interval $[t_n, t_{n+1}]$ is Θ' -regular and longitudinal,
- (iii) the piecewise geodesic with vertices x_n is a τ_{mod} -Finsler geodesic ray,
- (iv) $d_X(r(t_n), r(t_{n+1})) \geq l = \max\{l_1, l_2, l_3\} + 4(D + R)$ for all integers $n \geq 0$.

Recall that x_n is the projection of $r(t_n)$ onto $V(x, \text{st}(\tau))$ and $d(r(t_n), x_n) < R$ for all $n \in \mathbb{N}_0$, and that $D > 0$ is defined in Section 5.1 as the diameter of a compact fundamental domain for the Γ -action on X .

Due to the condition (iv), and since r is piecewise-geodesic, we can form an unbounded increasing sequence $s_k \in \mathbb{R}_+$ with $s_0 = 0$ such that $\{t_n \mid n \in \mathbb{N}_0\} \subset \{s_i \mid i \in \mathbb{N}_0\}$ and $l \leq d_X(r(s_i), r(s_{i+1})) < 2l$ for any integer $i \geq 0$. By the D -density of Γx in X , for each $r(s_i)$ there exists an element $g_i \in \Gamma$ such that $g_i x \in B_D(r(s_i))$. Here we require that if

$r(s_i) \in c^\alpha(\mathbb{N}_0)x$ (resp. $r(s_i) \in c^\beta(\mathbb{N}_0)x$), then $g_i \in c^\alpha(\mathbb{N}_0)$ (resp. $g_i \in c^\beta(\mathbb{N}_0)x$) and $g_0 = e$. Then $\{g_i \mid i \in \mathbb{N}_0\}$ has infinitely many elements of both $c^\alpha(\mathbb{N}_0)$ and $c^\beta(\mathbb{N}_0)$. From the inequalities $l \leq d_X(r(s_i), r(s_{i+1})) < 2l$ and $g_i x \in B_D(r(s_i))$,

$$(5.8) \quad l - 2D \leq d_X(g_i x, g_{i+1} x) < 2l + 2D.$$

Since r is a (Θ', R) -Morse quasigeodesic ray, we have

$$d_\Delta(r(s_i), r(s_{i+1})) \in V(0, W_{\tau_{\text{mod}}} \Theta') \cap \Delta.$$

By the condition (iv), $d_X(r(s_i), r(s_{i+1})) \geq l > l_1$ for any integer $i \geq 0$, and hence

$$(5.9) \quad d_\Delta(g_i x, g_{i+1} x), d_\Delta(x_i, x_{i+1}) \in V(0, W_{\tau_{\text{mod}}} \Theta'') \cap \Delta.$$

By the triangle inequality $d_X(g_i x, x_i) \leq d_X(g_i x, r(s_i)) + d_X(r(s_i), x_i) \leq D + R$,

$$\begin{aligned} & d_X(g_{i+1} x, V(g_i x, \text{st}(\tau))) \\ & \leq d_X(g_{i+1} x, x_{i+1}) + d_X(x_{i+1}, V(x_i, \text{st}(\tau))) + d_X(V(x_i, \text{st}(\tau)), V(g_i x, \text{st}(\tau))) \\ & \leq d_X(g_{i+1} x, x_{i+1}) + 0 + d_X(g_i x, x_i) \leq 2(D + R). \end{aligned}$$

Since the piecewise geodesic ray with vertices x_i is a Θ'' -Finsler geodesic, the condition $d_\Delta(x_i, x_{i+1}) \in V(0, W_{\tau_{\text{mod}}} \Theta'') \cap \Delta$ implies $x_{i+1} \in V(x_i, \text{st}_{\Theta''}(\tau))$. Applying the triangle inequality, we get

$$d_X(x_i, x_{i+1}) \geq d_X(g_i x, g_{i+1} x) - 2(D + R) \geq l - 2(2D + R) > l_3$$

and hence

$$d_X(x_{i+1}, \partial V(x_i, \text{st}(\tau))) \geq l_2 + 2(D + R).$$

This inequality, together with the following inequality

$$\begin{aligned} & d_X(x_{i+1}, \partial V(x_i, \text{st}(\tau))) \\ & \leq d_X(x_{i+1}, g_{i+1} x) + d_X(g_{i+1} x, \partial V(g_i x, \text{st}(\tau))) + d_X(\partial V(g_i x, \text{st}(\tau)), \partial V(x_i, \text{st}(\tau))) \\ & \leq 2(D + R) + d_X(g_{i+1} x, \partial V(g_i x, \text{st}(\tau))), \end{aligned}$$

yields $d_X(g_{i+1} x, \partial V(g_i x, \text{st}(\tau))) > l_2$ and thus $\epsilon(g_{i+1}^{-1} g_i, g_i^{-1} \tau) > 2\lambda$ for all integers $i \geq 0$.

Let $h_i = g_i^{-1} g_{i+1}$. Summarizing so far, by (5.8) and (5.9), every h_i is an element of Σ_0 and moreover $g_i^{-1} \tau \in U_{h_i}^{2\lambda}$. Thus $B_{\delta_\eta}(g_i^{-1}(\tau)) \subset U_{h_i}^\lambda$. Observing that $h_{i-1}^{-1} \cdots h_0^{-1} = g_i^{-1}$, we have

$$B_{\delta_\eta}(h_{i-1}^{-1} \cdots h_0^{-1}(\tau)) \subset U_{h_i}^\lambda$$

for all integers $i \geq 0$. This implies that there is a $(\mathcal{D}_\eta, \delta_\eta)$ -code γ such that $s_{\gamma(i)} = h_i \in \Sigma_0$ and hence

$$c^\gamma(i) = s_{\gamma(0)} s_{\gamma(1)} \cdots s_{\gamma(i)} = h_0 h_1 \cdots h_i = g_{i+1}$$

for any integer $i \geq 0$. By the construction of g_i , $\{c^\gamma(i) = g_{i+1} \mid i \in \mathbb{N}_0\}$ has infinitely many elements of both $c^\alpha(\mathbb{N}_0)$ and $c^\beta(\mathbb{N}_0)$. Therefore, we conclude that $c^\alpha \approx_{(\mathcal{D}_\eta, \delta_\eta)}^0 c^\gamma \approx_{(\mathcal{D}_\eta, \delta_\eta)}^0 c^\beta$.

This completes the proof of the claim as well as the proof of Theorem 5.1. \square

6 Actions of word-hyperbolic groups

In this section we first prove that expansion implies uniform S-hyperbolicity for certain nice actions of hyperbolic groups, and then explore to which extent S-hyperbolic actions of hyperbolic groups arise from their actions on Gromov boundaries.

6.1 Expansion implies S-hyperbolicity

6.1 Theorem. *Let Γ be a non-elementary hyperbolic group. Suppose that an action $\rho : \Gamma \rightarrow \text{Homeo}(M; \Lambda)$ is expanding and there exists an equivariant continuous nowhere constant map $f : \Lambda \rightarrow \partial_\infty \Gamma$. Then ρ is uniformly S-hyperbolic (and thus meandering-hyperbolic) and f is the coding map of ρ .*

Proof. Let $\mathcal{D} = (\Sigma, \delta)$ be the expansion datum of ρ (see Definition 3.4). Recall that d_Σ denotes the word metric on Γ with respect to Σ .

We claim that if $x \in \Lambda$ and $\eta \in (0, \delta]$ then, for every η -code α for x , the η -ray $c^\alpha \in \text{Ray}_{\mathcal{D}}^\eta(x)$ is a uniform quasigeodesic ray in (Γ, d_Σ) asymptotic to $f(x)$. To see this, we first note that by Corollary 3.20 the ray c^α is indeed an (A, C) -quasigeodesic ray with A and C independent of x and η .

By Theorem 3.21(1), there is a subsequence (g_j) of (c_i^α) such that $(\rho(g_j))$ converges to x on some ball $B_{\eta/2}(q) \subset \Lambda$. Since f is nowhere constant, the image $S := f(B_{\eta/2}(q)) \subset \partial_\infty \Gamma$ is not a singleton. By the equivariance of f , the subsequence (g_j) converges to $\xi := f(x)$ pointwise on S . Moreover, the initial point $c_0^\alpha = s_{\alpha(0)} \in \Sigma$ is a generator of Γ . Therefore, Lemma 2.8 applies to the ray c^α and we conclude that the image $c^\alpha(\mathbb{N}_0)$ is D -Hausdorff close to a geodesic ray $e\xi$ in (Γ, d_Σ) , where the constant D depends only on the hyperbolicity constant of (Γ, d_Σ) and the quasi-isometry constants (A, C) .

Now, suppose that $c^\alpha, c^\beta \in \text{Ray}_{\mathcal{D}}^\eta(x)$ are rays associated to η -codes α, β for $x \in \Lambda$, respectively. Then the images of c^α, c^β are within Hausdorff distance D from a geodesic ray $e\xi$, hence, these images are $2D$ -Hausdorff close. Therefore, the rays $2D$ -follow-travel each other. Since $x \in \Lambda$ is arbitrary, we conclude that the action is uniformly S-hyperbolic with data $(\mathcal{D}; N_\eta) = (\delta; 2D)$; recall Definitions 3.23 and 3.26. \square

6.2 Corollary. *Let Γ be a non-elementary hyperbolic group. Suppose that the action of Γ on its Gromov boundary $\partial_\infty \Gamma$ is expanding with respect to a metric d_∞ compatible with the topology. Then this action is uniformly S-hyperbolic.*

Proof. We set $M = \Lambda = \partial_\infty \Gamma$ and $f = \text{id} : \partial_\infty \Gamma \rightarrow \partial_\infty \Gamma$ in the preceding theorem. \square

Let Γ be a non-elementary hyperbolic group and d_a a visual metric on $\partial_\infty \Gamma$. Coornaert [Coo93, Proposition 3.1, Lemma 6.2] showed that the Γ -action on $(\partial_\infty \Gamma, d_a)$ is expanding. Thus, we have:

6.3 Corollary. *Let Γ be a non-elementary hyperbolic group with the Gromov boundary $\partial_\infty \Gamma$ equipped with a visual metric d_a . Then the action of Γ on $(\partial_\infty \Gamma, d_a)$ is uniformly S-hyperbolic.*

6.2 Meandering-hyperbolic actions of word-hyperbolic groups

It is natural to ask to what extent the converse of Corollary 6.3 is true:

6.4 Question. Does every meandering-hyperbolic action $\Gamma \rightarrow \text{Homeo}(M; \Lambda)$ come from the action of a hyperbolic group on its Gromov boundary?

Assume first that $\text{card}(\Lambda) \geq 3$ and the action of Γ on Λ in Question 6.4 is a convergence action (see Section 2.1 for definition). Then, in view of the expansion condition, it is also a uniform convergence action; see [KLP17, Lemma 3.13] or [KL18, Theorem 8.8] for a different argument. If we assume, in addition, that Λ is perfect (or that Λ is the limit set of the action of Γ on Λ , see Theorem 2.3), then Γ is hyperbolic and Λ is equivariantly homeomorphic to the Gromov boundary $\partial_\infty \Gamma$ (Theorem 2.9). To summarize:

6.5 Proposition. *Suppose an expanding action $\Gamma \rightarrow \text{Homeo}(M; \Lambda)$ is a convergence action with limit set Λ satisfying $\text{card}(\Lambda) \geq 3$. Then Γ is hyperbolic and Λ is equivariantly homeomorphic to $\partial_\infty \Gamma$.*

Note that we do not even need to assume faithfulness of the action of Γ on Λ since, by the convergence action assumption, such an action necessarily has finite kernel.

As another application of the formalism of convergence group actions we obtain:

6.6 Proposition. *Suppose that Γ is hyperbolic, d_∞ is a compatible metric on the Gromov boundary $\partial_\infty \Gamma$, and the Γ -action on $(\partial_\infty \Gamma, d_\infty)$ is expanding. Define the subset $\Sigma_0 \subset \Sigma$ of the finite generating set Σ , consisting of elements s_α with non-empty expansion subsets $U_\alpha \subset \Lambda$. Then Σ_0 generates a finite index subgroup $\Gamma_0 < \Gamma$.*

Proof. The action of Γ_0 on $\partial_\infty \Gamma$ is still expanding and convergence. Therefore, as noted above, the action of Γ_0 on $T(\partial_\infty \Gamma)$ is also cocompact. Since the action of Γ on $T(\partial_\infty \Gamma)$ is properly discontinuous, it follows that Γ_0 has finite index in Γ . \square

Next, assuming hyperbolicity of Γ in Question 6.4, we can relate Λ and $\partial_\infty \Gamma$. Recall the coding map $\pi : \Lambda \rightarrow \partial_\infty \Gamma$ in Definition 3.28.

6.7 Theorem. *Let Γ be a non-elementary hyperbolic group. If $\Gamma \rightarrow \text{Homeo}(M; \Lambda)$ is a meandering-hyperbolic action, then the following hold.*

- (1) *The coding map $\pi : \Lambda \rightarrow \partial_\infty \Gamma$ is an equivariant continuous surjective map.*
- (2) *For each minimal non-empty closed Γ -invariant subset $\Lambda_\mu \subset \Lambda$, the restriction $\pi_\mu : \Lambda_\mu \rightarrow \partial_\infty \Gamma$ of π to Λ_μ is a surjective quasi-open map.*
- (3) *Every Λ_μ as above is perfect.*

Proof. (1) Continuity of $\pi : \Lambda \rightarrow \partial_\infty \Gamma$ can be seen as in Section 4.5, where we showed that if $x, y \in \Lambda$ are close then there exist δ -codes α and β for x and y , respectively, such that $\alpha(i) = \beta(i)$ for all $0 \leq i \leq n$, where $n \in \mathbb{N}$ is sufficiently large. Then

$$c_i^\alpha = s_{\alpha(0)} s_{\alpha(1)} \cdots s_{\alpha(i)} = s_{\beta(0)} s_{\beta(1)} \cdots s_{\beta(i)} = c_i^\beta$$

for all $0 \leq i \leq n$. This means $\pi(y) \in V_n(\pi(x))$ for a sufficiently large n , hence $\pi(x)$ and $\pi(y)$ are close.

Since Λ is compact, the image $\pi(\Lambda)$ is closed and Γ -invariant. By the minimality of the action of Γ on $\partial_\infty\Gamma$, we have $\pi(\Lambda) = \partial_\infty\Gamma$.

(2) Surjectivity of π_μ follows from the minimality of the action of Γ on $\partial_\infty\Gamma$ as in part (1). We now prove that each π_μ is quasi-open. Since Λ_μ is compact, it is locally compact, hence it suffices to prove that for every compact subset $K \subset \Lambda_\mu$ with non-empty interior, the image $\pi(K) \subset \partial_\infty\Gamma$ also has non-empty interior.

In view of the minimality of the Γ -action on Λ_μ and compactness of Λ_μ , there exists a finite subset $\{g_1, \dots, g_n\} \subset \Gamma$ such that

$$\rho(g_1)(\text{int } K) \cup \dots \cup \rho(g_n)(\text{int } K) = \Lambda_\mu.$$

By the equivariance of π and surjectivity of $\pi_\mu : \Lambda_\mu \rightarrow \partial_\infty\Gamma$, we also have

$$g_1(\pi(K)) \cup \dots \cup g_n(\pi(K)) = \partial_\infty\Gamma.$$

Since a finite collection (even a countable collection) of nowhere dense subsets cannot cover $\partial_\infty\Gamma$, it follows that $\pi(K)$ has non-empty interior.

(3) Suppose that Λ_μ has an isolated point z . Since the action of Γ on Λ_μ is minimal, the compact subset $\Lambda_\mu \subset \Lambda$ consists entirely of isolated points, i.e. is finite. Therefore, $\pi(\Lambda_\mu) \subset \partial_\infty\Gamma$ is a finite non-empty Γ -invariant subset. This contradicts the minimality of the action of Γ on $\partial_\infty\Gamma$. \square

6.8 Remark. For some minimal S-hyperbolic actions of hyperbolic groups $\Gamma \rightarrow \text{Homeo}(\Lambda)$, the map π is not open; see Example 7.6.

6.9 Corollary. *Let Γ be a non-elementary hyperbolic group. If $\Gamma \rightarrow \text{Homeo}(M; \Lambda)$ is a meandering-hyperbolic action, then:*

- (1) Γ acts on Λ with finite kernel K .
- (2) If (g_i) is a sequence in Γ converging to the identity on Λ then the projection of this sequence to Γ/K is eventually equal to $e \in \Gamma/K$.

Proof. Both statements are immediate consequences of Theorem 6.7(1) and the convergence property for the action of a Γ on $\partial_\infty\Gamma$; see Section 2.2. \square

As another immediate corollary of the theorem and Theorem 6.1 we obtain:

6.10 Corollary. *Let Γ be a non-elementary hyperbolic group. Then every meandering-hyperbolic action of Γ is in fact uniformly S-hyperbolic.*

These are positive results regarding Question 6.4. In Sections 5 and 7, however, we present several examples which show that in general the question has negative answer.

6.3 Anosov subgroups

We recall the definition of Anosov subgroups of a semisimple Lie group G . The following definition of *Anosov* and *non-uniformly Anosov* subgroups is given by Kapovich, Leeb and Porti in [KLP17, Definitions 5.43 and 5.62]. Many other equivalent characterizations of the Anosov subgroups are established in [KLP17, Theorem 5.47] and their equivalence with the original definitions given by Labourie [Lab06] and Guichard and Wienhard [GW12] is proven in [KLP17, Section 5.11].

Let G be a semisimple Lie group and $X = G/K$ the associated symmetric space. We refer to Section 2.3 for notations used below.

6.11 Definition. Let $\tau_{\text{mod}} \subset \sigma_{\text{mod}}$ be an ι -invariant face. A subgroup $\Gamma < G$ is τ_{mod} -*boundary embedded* if

- (a) it is a hyperbolic group;
- (b) there is an antipodal Γ -equivariant continuous map (called a *boundary embedding*)

$$\beta : \partial_{\infty}\Gamma \rightarrow \text{Flag}(\tau_{\text{mod}}).$$

A τ_{mod} -boundary embedded subgroup $\Gamma < G$ with a boundary embedding α is τ_{mod} -*Anosov* if

- (c) for every $\xi \in \partial_{\infty}\Gamma$ and for every geodesic ray $r : \mathbb{N}_0 \rightarrow \Gamma$ starting at $e \in \Gamma$ and asymptotic to ξ , the expansion factor (see (2.2)) satisfies

$$\epsilon(r(n)^{-1}, \alpha(\xi)) \geq A e^{Cn}$$

for $n \in \mathbb{N}_0$ with constants $A, C > 0$ independent of the point ξ and the ray r .

A τ_{mod} -boundary embedded subgroup $\Gamma < G$ with a boundary embedding α is *non-uniformly τ_{mod} -Anosov* if

- (d) for every $\xi \in \partial_{\infty}\Gamma$ and for every geodesic ray $r : \mathbb{N}_0 \rightarrow \Gamma$ starting at $e \in \Gamma$ and asymptotic to ξ , the expansion factor satisfies

$$\sup_{n \in \mathbb{N}_0} \epsilon(r(n)^{-1}, \alpha(\xi)) = +\infty.$$

A τ_{mod} -boundary embedded subgroup $\Gamma < G$ is said to be *non-elementary* if it is a non-elementary hyperbolic group.

6.12 Remark. (a) In fact, for τ_{mod} -boundary embedded subgroups, the conditions (c) and (d) are equivalent; see [KLP17, Theorem 5.47]. For the purpose of this paper, the definition of non-uniformly τ_{mod} -Anosov subgroups will suffice.

- (b) A τ_{mod} -Anosov subgroup $\Gamma < G$ may have other boundary embeddings $\beta : \partial_{\infty}\Gamma \rightarrow \text{Flag}(\tau_{\text{mod}})$ besides the map α which appears in the definition; see [KLP14, Example 6.20]. However, the boundary embedding α as in the conditions (c) and (d) is unique; its image is the τ_{mod} -*limit set* of Γ in $\text{Flag}(\tau_{\text{mod}})$,

$$\alpha(\partial_{\infty}\Gamma) = \Lambda_{\Gamma}(\tau_{\text{mod}}) \subset \text{Flag}(\tau_{\text{mod}}).$$

We thus will refer to the map α as the *asymptotic embedding* for $\Gamma < G$.

6.4 S-hyperbolicity and stability for Anosov subgroups

Our goal in this section is to characterize Anosov subgroups in terms of the expansion condition on suitable subsets of partial flag manifolds (Theorem 6.13) and show that the corresponding actions are S-hyperbolic. As an application, we give an alternative proof of the stability of Anosov subgroups (Corollary 6.15).

For the sake of simplicity, we shall restrict our attention to the case of non-elementary hyperbolic groups and make use of Corollary 3.20 and Theorems 6.1 and 6.7. Then Lemma 6.14 below says that the condition (d) in Definition 6.11 is also equivalent to the expansion condition (Definition 3.4) at the image of the boundary embedding. Consequently, we obtain the following characterization of Anosov subgroups:

6.13 Theorem. *For a non-elementary hyperbolic subgroup $\Gamma < G$ the following are equivalent.*

- (1) Γ is non-uniformly τ_{mod} -Anosov with asymptotic embedding $\alpha : \partial_\infty \Gamma \rightarrow \Lambda_\Gamma(\tau_{\text{mod}})$.
- (2) Γ is τ_{mod} -boundary embedded with a boundary embedding $\beta : \partial_\infty \Gamma \rightarrow \text{Flag}(\tau_{\text{mod}})$ and the Γ -action on $\text{Flag}(\tau_{\text{mod}})$ is expanding at $\beta(\partial_\infty \Gamma)$; in this case, β equals the asymptotic embedding α .
- (3) There exists a closed Γ -invariant antipodal subset $\Lambda \subset \text{Flag}(\tau_{\text{mod}})$ such that the action $\Gamma \rightarrow \text{Homeo}(\text{Flag}(\tau_{\text{mod}}); \Lambda)$ is S-hyperbolic with injective coding map $\pi : \Lambda \rightarrow \partial_\infty \Gamma$; in this case, π equals the inverse of the asymptotic embedding α .

Proof. (2 \Rightarrow 3) Let $\Lambda = \beta(\partial_\infty \Gamma) \subset \text{Flag}(\tau_{\text{mod}})$. It is a closed Γ -invariant antipodal subset such that the action $\Gamma \rightarrow \text{Homeo}(\text{Flag}(\tau_{\text{mod}}); \Lambda)$ is expanding and the equivariant homeomorphism $\beta^{-1} : \Lambda \rightarrow \partial_\infty \Gamma$ is nowhere constant. By Theorem 6.1, this action is S-hyperbolic with coding map β^{-1} .

(3 \Rightarrow 2) By Theorem 6.7(1) the coding map π is equivariant, continuous and surjective. Since π is assumed to be injective and Λ is compact, π is in fact a homeomorphism. Since Λ is antipodal, the inverse $\pi^{-1} : \partial_\infty \Gamma \rightarrow \Lambda \subset \text{Flag}(\tau_{\text{mod}})$ is a boundary embedding. The Γ -action on Λ is S-hyperbolic, in particular, expanding.

(1 \Leftrightarrow 2) This equivalence reduces to the lemma below. □

6.14 Lemma. *Suppose $\Gamma < G$ is τ_{mod} -boundary embedded with a boundary embedding $\beta : \partial_\infty \Gamma \rightarrow \text{Flag}(\tau_{\text{mod}})$.*

- (1) *If Γ is non-uniformly τ_{mod} -Anosov with the asymptotic embedding β , then the Γ -action on $\text{Flag}(\tau_{\text{mod}})$ is expanding at $\beta(\partial_\infty \Gamma)$.*
- (2) *If Γ is non-elementary and the Γ -action on $\text{Flag}(\tau_{\text{mod}})$ is expanding at $\beta(\partial_\infty \Gamma)$, then it is non-uniformly τ_{mod} -Anosov and β is the asymptotic embedding for Γ .*

Proof. (1) This is a special case of [KLP17, Equivalence Theorem 1.1]: every τ_{mod} -Anosov subgroup $\Gamma < G$ is expanding at $\beta(\partial_\infty \Gamma)$. It is also an immediate consequence of the condition (d) in Definition 6.11 combined with Remark 3.6(c).

(2) Suppose the Γ -action on $\text{Flag}(\tau_{\text{mod}})$ is expanding at $\beta(\partial_\infty \Gamma)$ with data $\mathcal{D} = (\delta)$. Since $\partial_\infty \Gamma$ is perfect, Corollary 3.20 applies. Thus, for any $\eta \in (0, \delta]$, the rays c^α associated to η -codes α for $f(\xi) \in f(\partial_\infty \Gamma)$ are uniform quasigeodesic rays in Γ .

Let $\xi \in \partial_\infty \Gamma$ and let $r : \mathbb{N}_0 \rightarrow \Gamma$ be a geodesic ray starting at $e \in \Gamma$ and asymptotic to ξ . If α is an η -code for $\beta(\xi)$ then, as in the proof of Lemma 2.8, the Hausdorff distance between $\{r(i)\}_{i \in \mathbb{N}_0}$ and $\{c_j^\alpha\}_{j \in \mathbb{N}_0}$ is bounded above by a uniform constant $C > 0$. This means that for each $i \in \mathbb{N}_0$, there exist $n_i \in \mathbb{N}_0$ and an element $g_i \in \Gamma$ with $|g_i|_\Sigma \leq C$ such that $r(i) = c_{n_i}^\alpha g_i$. Then we have

$$\epsilon(r(i)^{-1}, f(\xi)) = \epsilon(g_i^{-1}(c_{n_i}^\alpha)^{-1}, \beta(\xi)) \geq A \cdot \epsilon((c_{n_i}^\alpha)^{-1}, \beta(\xi)),$$

where $A = \inf\{\epsilon(g, \beta(\zeta)) \mid \zeta \in \partial_\infty \Gamma, g \in \Gamma \text{ and } |g|_\Sigma \leq C\}$. Since $\epsilon((c_j^\alpha)^{-1}, \beta(\xi))$ tends to infinity as j tends to infinity (by the last statement of Lemma 3.18), it follows that

$$\sup_{i \in \mathbb{N}} \epsilon(r(i)^{-1}, \beta(\xi)) = +\infty.$$

Therefore, the Γ -action satisfies the condition (d) of Definition 6.11. \square

A corollary of this theorem is the stability of Anosov subgroups; see, for example, [GW12, Theorem 1.2] and [KLP14, Theorem 1.10]. Let us denote by

$$\text{Hom}^\tau(\Gamma, G)$$

the space of faithful representations $\Gamma \rightarrow G$ with (non-uniformly) τ_{mod} -Anosov images.

6.15 Corollary. *Suppose that Γ is a non-elementary hyperbolic group. Then*

- (1) $\text{Hom}^\tau(\Gamma, G)$ is open in $\text{Hom}(\Gamma, G)$.
- (2) For any sequence of representations $\rho_i \in \text{Hom}^\tau(\Gamma, G)$ converging to $\rho \in \text{Hom}^\tau(\Gamma, G)$, the asymptotic embeddings $\alpha_i : \partial_\infty \Gamma \rightarrow \Lambda_{\rho_i(\Gamma)}(\tau_{\text{mod}})$ converge uniformly to the asymptotic embedding $\alpha : \partial_\infty \Gamma \rightarrow \Lambda_\rho(\Gamma)(\tau_{\text{mod}})$.

Proof. We start with an embedding $\rho \in \text{Hom}^\tau(\Gamma, G)$; let $\Lambda := \Lambda_\rho(\Gamma)(\tau_{\text{mod}})$ and

$$\alpha : \partial_\infty \Gamma \rightarrow \Lambda \subset \text{Flag}(\tau_{\text{mod}})$$

denote the asymptotic embedding of ρ . By Theorem 6.13, the Γ -action on Λ is S-hyperbolic. By Theorem 3.32 there exists a small neighborhood U' of ρ in $\text{Hom}(\Gamma, G)$ such that, for each $\rho' \in U'$, there exists a ρ' -invariant compact $\Lambda' \subset \text{Flag}(\tau_{\text{mod}})$ at which the ρ' -action is expanding and there is an equivariant homeomorphism $\phi : \Lambda \rightarrow \Lambda'$.

By Corollary 3.33, for every $\rho' \in U'$, the kernel of the action of $\Gamma' = \rho'(\Gamma)$ on Λ' equals the kernel of the action of Γ on Λ . Since Γ is assumed to be non-elementary, it acts on Λ with finite kernel Φ (Corollary 6.9). Therefore, the kernel of ρ' is contained in the finite subgroup $\Phi < \Gamma$. As explained in [KLP14, proof of Corollary 7.34], rigidity of finite subgroups of Lie groups implies that U' contains a smaller neighborhood U of ρ such that every $\rho' \in U$ is injective on Φ . Therefore, every $\rho' \in U$ is faithful.

Since Λ' depends continuously on ρ' (see Section 4.7), the antipodality of Λ leads to the antipodality of Λ' . (In order to guarantee this, one may further reduce the size of U if necessary.) Thus $\phi \circ \alpha : \partial_\infty \Gamma \rightarrow \Lambda'$ is a boundary embedding of Γ' . From Lemma 6.14(2) we conclude that $\Gamma' < G$ is again (non-uniformly) τ_{mod} -Anosov and the boundary embedding $\phi \circ \alpha$ of Γ' is uniformly close to α . \square

7 Other examples

We present a number of examples and non-examples of S-hyperbolic actions.

7.1 Expanding but not S-hyperbolic actions

In general, even for hyperbolic groups, the expansion condition alone does not imply the S-hyperbolicity condition.

7.1 Example (Action with infinite kernel). Suppose that Γ' and Γ are non-elementary hyperbolic groups and $\phi : \Gamma' \rightarrow \Gamma$ is an epimorphism with infinite kernel. We equip the Gromov boundary $\Lambda = \partial_\infty \Gamma$ with a visual metric. Then the action $\rho : \Gamma \rightarrow \text{Homeo}(\Lambda)$ is expanding (compare Corollary 6.3). Thus, the associated Γ' -action $\rho \circ \phi : \Gamma' \rightarrow \text{Homeo}(\Lambda)$ is expanding as well. But this action cannot be S-hyperbolic: see Corollary 6.9.

7.2 Example (Non-discrete action). Suppose that Γ is a non-elementary hyperbolic group and $\rho : \Gamma \rightarrow G = \text{Isom}(\mathbb{H}^n)$ is a representation with dense image. Then the associated action $\rho : \Gamma \rightarrow \text{Homeo}(\Lambda)$ on the visual boundary $\Lambda = \partial_\infty \mathbb{H}^n$ is expanding due to the density of $\rho(\Gamma)$ in G . But the action $\rho : \Gamma \rightarrow \text{Homeo}(\Lambda)$ cannot be S-hyperbolic. Indeed, by the density of $\rho(\Gamma)$ in G , there is a sequence of distinct elements $g_i \in \Gamma$ such that $\rho(g_i)$ converges to the identity element of G . If ρ were S-hyperbolic, then Corollary 6.9 would give a contradiction that the set $\{g_i\}$ is finite.

More generally, the same argument works for representations $\rho : \Gamma \rightarrow G$ of non-elementary hyperbolic groups to a semisimple Lie group G with dense images $\rho(\Gamma)$. The associated actions ρ of Γ on the partial flag manifolds G/P are expanding but not S-hyperbolic.

7.2 S-hyperbolic actions of hyperbolic groups

In addition to the toy examples in Section 3.5 we now give more interesting examples of S-hyperbolic actions of hyperbolic groups. As we proceed, the associated coding maps $\pi : \Lambda \rightarrow \partial_\infty \Gamma$ will be increasingly more complicated.

Recall that a discrete subgroup $\Gamma < \text{Isom}(\mathbb{H}^n)$ is *convex-cocompact* if its limit set $\Lambda = \Lambda_\Gamma \subset S^{n-1} = \partial_\infty \mathbb{H}^n$ is not a singleton and Γ acts cocompactly on the closed convex hull of Λ in \mathbb{H}^n . We refer to [Bow93] for details on convex-cocompact and, more generally, geometrically finite isometry groups of hyperbolic spaces.

Every convex-cocompact (discrete) subgroup Γ of isometries of \mathbb{H}^n (and, more generally, a rank one symmetric space) is S-hyperbolic. More precisely, for $\Lambda = \Lambda_\Gamma$, the action $\Gamma \rightarrow \text{Homeo}(S^{n-1}; \Lambda)$ is S-hyperbolic. This can be either proven directly using a *Ford fundamental domain* (as in [Sul85, Theorem I]) by considering the conformal ball model of \mathbb{H}^n inside \mathbb{R}^n) or regarded as a special case of S-hyperbolicity of Anosov subgroups (Theorem 6.13).

Unlike the convex-cocompact or Anosov examples, the invariant compact set Λ is not equivariantly homeomorphic to the Gromov boundary in the examples below.

7.3 Example (k -fold non-trivial covering). Let S_g be a closed oriented hyperbolic surface of genus $g \geq 2$; it is isometric to the quotient \mathbb{H}^2/Γ , where $\Gamma \cong \pi_1(S_g)$ is a discrete subgroup of $\mathrm{PSL}(2, \mathbb{R})$. Take any $k \geq 2$ dividing $2g - 2$. Since the Euler number of the unit circle bundle of S_g is $2 - 2g$, same as the Euler number of the action of Γ on $S^1 = \partial_\infty \mathbb{H}^2$, it follows that the action of Γ lifts to a smooth action

$$\tilde{\rho} : \Gamma \rightarrow \mathrm{Homeo}(S^1)$$

with respect to the degree k covering $p : \Lambda = S^1 \rightarrow S^1$. We pull-back the Riemannian metric from the range to the domain Λ via the map p . Since $\Gamma < \mathrm{PSL}(2, \mathbb{R})$ is convex-cocompact, its action on $\partial_\infty \mathbb{H}^2$ is S-hyperbolic. Let $\{U_\alpha \mid \alpha \in \mathcal{I}\}$ be a collection of expanding subsets (arcs) in $S^1 = \partial_\infty \mathbb{H}^2$ corresponding to a generating set $\Sigma = \{s_\alpha \mid \alpha \in \mathcal{I}\}$ of Γ . As in Example 3.35, we lift these arcs to connected components

$$\{\tilde{U}_{\alpha_i} \subset p^{-1}(U_\alpha) \mid \alpha \in \mathcal{I}, i = 1, \dots, k\}.$$

These will be expanding subsets for the generators $s_{\alpha_i} = s_\alpha$ ($\alpha \in \mathcal{I}, i = 1, \dots, k$) of Γ . The action $\tilde{\rho}$ will be minimal and S-hyperbolic (because the original action of Γ is).

Thus, we obtain an example of a minimal S-hyperbolic action of a hyperbolic group on a set Λ which is not equivariantly homeomorphic to $\partial_\infty \Gamma$.

Similar examples of S-hyperbolic actions on S^1 can be obtained by starting with a general convex-cocompact Fuchsian subgroup $\Gamma_0 < \mathrm{PSL}(2, \mathbb{R})$ and lifting it to an action of a finite central extension Γ of Γ_0 on S^1 via a finite covering $S^1 \rightarrow S^1$. We refer to the paper [Der20] of Deroin for details as well as the related classification of expanding real-analytic group actions on the circle.

Below is a variation of the above construction.

7.4 Example (Trivial covering). Let Γ_0 be a non-elementary hyperbolic group with the Gromov boundary $\Lambda_0 = \partial_\infty \Gamma_0$ equipped with a visual metric. Let $\Lambda = \Lambda_0 \times \{0, 1\}$ and $\Gamma_0 \rightarrow \mathrm{Homeo}(\Lambda)$ be the product action where Γ_0 acts trivially on $\{0, 1\}$. This action is S-hyperbolic but, obviously, non-minimal.

We extend this action of Γ_0 to an action of $\Gamma = \Gamma_0 \times \mathbb{Z}_2$, where the generator of \mathbb{Z}_2 acts by the map

$$(\xi, i) \mapsto (\xi, 1 - i) \quad (\text{for } \xi \in \Lambda_0 \text{ and } i = 0, 1)$$

with an empty expansion subset. The action $\Gamma \rightarrow \mathrm{Homeo}(\Lambda)$ is easily seen to be faithful, S-hyperbolic and minimal. It is clear, however, that Λ is not equivariantly homeomorphic to $\partial_\infty \Gamma \cong \partial_\infty \Gamma_0$.

In the preceding examples we had an equivariant finite covering map $\pi : \Lambda \rightarrow \partial_\infty \Gamma$. In the next example the coding map $\pi : \Lambda \rightarrow \partial_\infty \Gamma$ is a finite-to-one open map but not a local homeomorphism; one can regard the map π as a *generalized branched covering* (in the sense that it is an open finite-to-one map which is a covering map away from a codimension 2 subset).

7.5 Example (Generalized branched covering). Let $\Gamma < \mathrm{PSL}(2, \mathbb{R})$ be a *Schottky subgroup*, that is, a convex-cocompact non-elementary free subgroup. Its limit set $\Lambda_\Gamma \subset S^1$ is homeomorphic to the Cantor set; it is also equivariantly homeomorphic to the Gromov boundary $\partial_\infty \Gamma$.

We regard Γ as a subgroup of $\mathrm{PSL}(2, \mathbb{C})$ via the standard embedding $\mathrm{PSL}(2, \mathbb{R}) \rightarrow \mathrm{PSL}(2, \mathbb{C})$. The domain of discontinuity of the action of Γ on S^2 is $\Omega_\Gamma = S^2 - \Lambda_\Gamma$; the quotient surface $S = \Omega_\Gamma / \Gamma$ is compact and its genus equals to the rank r of Γ . We let $\chi : \pi_1(S) \rightarrow F$ be a homomorphism to a finite group F which is non-trivial on the image of $\pi_1(\Omega_\Gamma)$ in $\pi_1(S)$. For concreteness, we take the following homomorphism $\chi : \pi_1(S) \rightarrow F = \mathbb{Z}_2$. We let $\{a_1, b_1, \dots, a_r, b_r\}$ denote a generating set of $\pi_1(S)$ such that a_1, \dots, a_r lie in the kernel of the natural homomorphism $\phi : \pi_1(S) \rightarrow \Gamma$, while ϕ sends b_1, \dots, b_r to (free) generators of Γ . Then take χ such that $\chi(a_1) = 1 \in \mathbb{Z}_2$, while χ sends the rest of the generators to $0 \in \mathbb{Z}_2$. This homomorphism to F , therefore, lifts to an epimorphism $\tilde{\chi} : \pi_1(\Omega_\Gamma) \rightarrow F$ with Γ -invariant kernel $K < \pi_1(\Omega_\Gamma)$. Hence, there exists a non-trivial 2-fold covering

$$p : \tilde{\Omega} \rightarrow \Omega_\Gamma$$

associated to K and the action of the group Γ on Ω_Γ lifts to an action of Γ on $\tilde{\Omega}$. One verifies that p is a proper map which induces a surjective but not injective map $p_\infty : \mathrm{End}(\tilde{\Omega}) \rightarrow \mathrm{End}(\Omega_\Gamma)$ between the spaces of ends of the surfaces $\tilde{\Omega}$ and Ω_Γ . Since p is a 2-fold covering map, the induced map p_∞ is at most 2-to-1 (that is, the fibers of p_∞ have cardinality ≤ 2).

We let ds^2 denote the restriction of the standard Riemannian metric on S^2 to the domain Ω_Γ and let \tilde{ds}^2 denote the pull-back of ds^2 to $\tilde{\Omega}$. The Riemannian metric ds^2 is, of course, incomplete; the Cauchy completion of the associated Riemannian distance function d_{Ω_Γ} on Ω_Γ is naturally homeomorphic to S^2 (which is also the end-compactification of Ω_Γ), as a sequence in Ω_Γ is Cauchy with respect to the metric d_{Ω_Γ} if and only if it converges in S^2 . (Here we are using the assumption that Λ_Γ is contained in the circle S^1 .)

We therefore let (M, d) denote the Cauchy completion of the Riemannian distance function of $(\tilde{\Omega}, \tilde{ds}^2)$. One verifies that M is compact and is naturally homeomorphic to the end-compactification of $\tilde{\Omega}$. In particular, the covering map $p : \tilde{\Omega} \rightarrow \Omega_\Gamma$ extends to a continuous open finite-to-one map

$$p : M \rightarrow S^2$$

sending $\Lambda := M - \tilde{\Omega}$ to Λ_Γ . The map $p : M \rightarrow S^2$ is locally one-to-one on $\tilde{\Omega}$ but fails to be a local homeomorphism at Λ . Since every element of Γ acts as a Lipschitz map to $(\tilde{\Omega}, \tilde{ds}^2)$, the action of Γ on $(\tilde{\Omega}, \tilde{ds}^2)$ extends to an action of Γ on M so that every element of Γ is a Lipschitz map and Λ is a Γ -invariant compact subset of M . The map $p : M \rightarrow S^2$ is equivariant with respect to the actions of Γ on M and on S^2 . Similarly to our covering maps examples, the action $\Gamma \rightarrow \mathrm{Homeo}(M; \Lambda)$ is S-hyperbolic at Λ . The coding map $\pi : \Lambda \rightarrow \Lambda_\Gamma = \partial_\infty \Gamma$ equals the restriction of p to Λ and, hence, is not a local homeomorphism.

In the next example the coding map $\pi : \Lambda \rightarrow \partial_\infty \Gamma$ is not even an open map.

7.6 Example (Denjoy blow-up). We let Γ be the fundamental group of a closed hyperbolic surface M^2 . Let $c \subset M^2$ be a simple closed geodesic representing the conjugacy class $[\gamma]$ in Γ . The Gromov boundary of Γ is the circle S^1 . We perform a *blow-up* of S^1 at the set $\Phi \subset S^1$ of fixed points of the elements in the conjugacy class $[\gamma]$, replacing every fixed point by a pair of points. See Figure 5. The resulting topological space Λ is homeomorphic to the Cantor set; the quotient map

$$q : \Lambda \rightarrow S^1$$

is 1-to-1 over $S^1 - \Phi$ and is 2-to-1 over Φ . The map q is quasi-open (with $O_q = \Lambda - q^{-1}(\Phi)$) but not open. (This map is an analogue of the Cantor function $f : C \rightarrow [0, 1]$ mentioned in the beginning of Section 2.) The action of Γ on S^1 lifts to a continuous action of Γ on Λ with every $g \in [\gamma]$ fixing all the points of the preimage of the fixed-point set of g in S^1 . In particular, the action of Γ on Λ is minimal. One can metrize Λ so that the action $\Gamma \rightarrow \text{Homeo}(\Lambda)$ is S-hyperbolic with the coding map $\pi : \Lambda \rightarrow \partial_\infty \Gamma$ being equal to the quotient map $q : \Lambda \rightarrow S^1$.

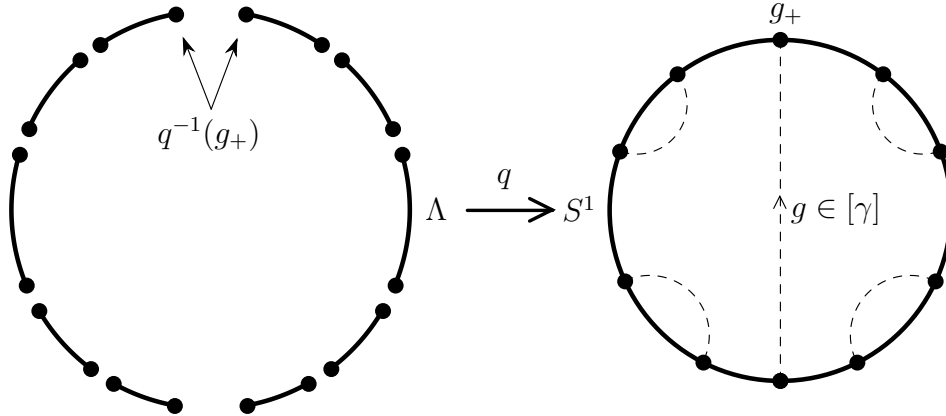


Figure 5: Denjoy blow-up.

More generally, one can define a Denjoy blow-up for actions of fundamental groups of higher-dimensional compact hyperbolic manifolds. Let $M^n = \mathbb{H}^n / \Gamma$ be a compact hyperbolic n -manifold containing a compact totally geodesic hypersurface C . Let $A \subset \mathbb{H}^n$ denote the preimage of C in \mathbb{H}^n . The visual boundary of each component A_i of A is an $(n - 2)$ -dimensional sphere $S_i \subset S^{n-1} = \partial_\infty \mathbb{H}^n$. The blow-up Λ of S^{n-1} is then performed by replacing each sphere S_i with two copies of this sphere. The result is a compact topological space Λ equipped with a quotient map $q : \Lambda \rightarrow S^{n-1}$ such that q is 1-to-1 over every point not in $S = \cup_i S_i$ and is 2-to-1 over every point in S . Each connected component of Λ is either a singleton or is homeomorphic to the $(n - 2)$ -dimensional Sierpinski carpet. The action of Γ on S^{n-1} lifts to a continuous action of Γ on Λ which is S-hyperbolic for a suitable choice of a metric on Λ .

7.3 S-hyperbolic actions of non-hyperbolic groups

Here we consider non-hyperbolic groups and examples of their S-hyperbolic actions.

The following example shows that faithfulness of an S-hyperbolic action on M does not imply faithfulness of perturbed actions.

7.7 Example (Non-discrete representation). Suppose that M is the standard compactification of the hyperbolic space \mathbb{H}^4 , $P = \mathbb{H}^2 \subset \mathbb{H}^4$ is a hyperbolic plane, and $\Lambda = S^1 \subset S^3 = \partial_\infty \mathbb{H}^4$ is the ideal boundary of P . We let

$$\Gamma = \Gamma_1 \times \Gamma_2,$$

where Γ_1 is a hyperbolic surface group and $\Gamma_2 \cong \mathbb{Z}$. We consider a faithful isometric action ρ of Γ on \mathbb{H}^4 where Γ_1 preserves P and acts on it properly discontinuously and cocompactly, while Γ_2 acts as a group of elliptic isometries fixing P pointwise. This action admits a conformal extension to M . Since the subgroup $\Gamma_1 < \text{Isom}(\mathbb{H}^4)$ is convex-cocompact, it is expanding at its limit set, which is equal to Λ . We take $\Sigma = \Sigma_1 \times \{e\} \cup \{e\} \times \{r, r^{-1}\}$ as a symmetric generating set of Γ , where Σ_1 is a finite generating set of Γ_1 (given by its expanding action) and r is a single generator of Γ_2 . The expansion subsets $U_r, U_{r^{-1}}$ of r, r^{-1} (as in the definition of an expanding action) are defined to be the empty set. The action ρ on M is uniformly S-hyperbolic: the expansion property is clear; for uniform S-hyperbolicity, we observe that all the rays in $\text{Ray}_x(\mathcal{D}, \delta)$ for the action of Γ have the form

$$(s c_i^\alpha)_{i \in \mathbb{N}}$$

where $s \in \Sigma$ and c^α is a δ -ray in $\Gamma_1 \times \{e\}$ associated to a special code α for $x \in \Lambda$.

The image $\rho(r)$ is an infinite order elliptic rotation. Therefore, we can approximate ρ by isometric actions ρ_i of Γ on \mathbb{H}^4 such that $\rho_i|_{\Gamma_1} = \rho|_{\Gamma_1}$, while $\rho_i(r)$ is an elliptic transformation of order i fixing P pointwise. In particular, the representations ρ_i are not faithful.

In the next two examples, a non-hyperbolic Γ acts faithfully and S-hyperbolically on Λ .

7.8 Example (Actions of product groups). For $i = 1, 2$, we consider S-hyperbolic actions $\rho_i : \Gamma_i \rightarrow \text{Homeo}(\Lambda_i)$. Let $(\mathcal{I}_i, \mathcal{U}_i, \Sigma_i)$ be the respective expansion datum. Since Λ_i 's are non-empty, the groups Γ_i are infinite. Consider the group

$$\Gamma = \Gamma_1 \times \Gamma_2.$$

This group is non-hyperbolic since its Cayley graph contains a quasi-flat (the product of complete geodesics in the Cayley graphs of Γ_1 and Γ_2). Let $\mathcal{I} = \mathcal{I}_1 \cup \mathcal{I}_2$ and we equip Γ with a symmetric generating set

$$\Sigma = \Sigma_1 \times \{e\} \sqcup \{e\} \times \Sigma_2.$$

Define the space $\Lambda = \Lambda_1 \sqcup \Lambda_2$. The group Γ acts on Λ as follows:

$$(\gamma_1, \gamma_2)(x) = \gamma_i(x) \text{ if } x \in \Lambda_i,$$

where $(\gamma_1, \gamma_2) \in \Gamma_1 \times \Gamma_2$. If the actions of Γ_i on Λ_i are both faithful, so is the action of Γ on Λ . As a cover \mathcal{U} of Λ we take the union $\mathcal{U}_1 \cup \mathcal{U}_2$ of respective covers. We leave it to the reader to verify that the action of Γ on Λ is S-hyperbolic.

This example can be modified to a minimal action. Namely, take identical actions $\rho_1 = \rho_2$ of the same group $\Gamma_1 = \Gamma_2$ and then extend the action of $\Gamma = \Gamma_1 \times \Gamma_1$ on Λ to a minimal action of $\Gamma \times \mathbb{Z}_2$ as in Example 7.4. Here the generator of \mathbb{Z}_2 swaps the direct factors of Γ .

7.9 Example (\mathbb{Z}^n acting on $P^n(\mathbb{R})$). There is an S-hyperbolic action of \mathbb{Z}^n on $M = P^n(\mathbb{R})$ by projective transformations.

Let $\{E_i \mid i = 0, 1, \dots, n\}$ be the standard basis of \mathbb{R}^{n+1} . Let $\mathbb{Z}^n < \text{GL}(n+1, \mathbb{R})$ be the free abelian group of rank n generated by *bi-proximal* diagonal matrices G_j ($1 \leq j \leq n$) for which E_0 (resp. E_j) is the eigenvector of the biggest (resp. smallest) modulus eigenvalue. Denote by $e_i \in P^n(\mathbb{R})$ and $g_j \in \text{PGL}(n+1, \mathbb{R})$ the projectivizations of E_i and G_j , respectively. Let $\Lambda = \{e_i \mid i = 0, 1, \dots, n\} \subset P^n(\mathbb{R}) = M$ and $\Sigma = \{g_j, g_j^{-1} \mid 1 \leq j \leq n\}$. We claim that the action $\mathbb{Z}^n \rightarrow \text{Homeo}(M; \Lambda)$ is S-hyperbolic.

Let $U_{g_j} \subset M$ denote an expanding subset of g_j and similarly $U_{g_j^{-1}}$ for g_j^{-1} . We assume that $U_{g_j^{-1}} = \emptyset$ for $j = 2, 3, \dots, n$ but that $U_{g_1^{-1}}$ as well as U_{g_j} ($1 \leq j \leq n$) are non-empty. Then $\mathcal{U} = \{U_{g_j}, U_{g_j^{-1}} \mid 1 \leq j \leq n\}$ covers Λ , since $e_0 \in U_{g_1^{-1}}$ and $e_j \in U_{g_j}$ for $1 \leq j \leq n$. Thus the action is expanding.

A ray associated to $e_j \in \Lambda$ is of the form $(g(g_j^{-1})^k)_{k \in \mathbb{N}_0}$ with $g \in \Sigma$ and a ray associated to $e_0 \in \Lambda$ is of the form $(g(g_1)^k)_{k \in \mathbb{N}_0}$ with $g \in \Sigma$. In any case, each point in Λ has only a finite number of rays associated to it. Hence the S-hyperbolicity follows.

7.4 Embedding into Lie group actions on homogeneous manifolds

Examples 7.3, 7.4 and 7.8 can be embedded in smooth Lie group actions on homogeneous manifolds.

For instance, consider the action of $\text{GL}(3, \mathbb{R})$ on the space of oriented lines in \mathbb{R}^3 , which we identify with the 2-sphere S^2 equipped with its standard metric. We have the equivariant 2-fold covering $p : S^2 \rightarrow P^2(\mathbb{R})$ with the covering group generated by the antipodal map $-I \in \text{GL}(3, \mathbb{R})$. Let $\mathbb{H}^2 \subset P^2(\mathbb{R})$ be the Klein model of the hyperbolic plane invariant under a subgroup $\text{PSO}(2, 1) < \text{PSL}(3, \mathbb{R})$. Then $p^{-1}(\mathbb{H}^2)$ consists of two disjoint copies of the hyperbolic plane bounded by two circles Λ_1 and Λ_2 . Taking a discrete convex-cocompact subgroup $\Gamma_1 < \text{SO}(2, 1) < \text{SL}(3, \mathbb{R})$, $\Gamma = \Gamma_1 \times \langle -I \rangle \cong \Gamma_1 \times \mathbb{Z}_2$ and $\Lambda = \Lambda_1 \cup \Lambda_2$, we obtain an S-hyperbolic action

$$\Gamma \rightarrow \text{Homeo}(S^2; \Lambda),$$

which restricts on Λ to Example 7.4. (When the group Γ_1 is free, such an action is studied in detail by Choi and Goldman [CG17]; see also [ST18] for a greater generalization of the Choi-Goldman construction.)

Below is a more general version of the preceding construction. Recall that the set $\text{Hom}^\tau(\Gamma, G)$ of τ_{mod} -Anosov representations $\Gamma \rightarrow G$ forms an open subset of the representa-

tion variety $\text{Hom}(\Gamma, G)$ (see Corollary 6.15). Let $\Gamma = \pi_1(S_g)$ ($g \geq 2$) and $G = \text{PSL}(n, \mathbb{R})$ ($n \geq 3$). We will consider two types of simplices τ_{mod} for the Lie group G :

- σ_{mod} ; the corresponding flag manifold $\text{Flag}(\sigma_{\text{mod}})$ consists of full flags in \mathbb{R}^n .
- τ_{mod} of the type “pointed hyperplanes”; the corresponding flag manifold $\text{Flag}(\tau_{\text{mod}})$ consists of pairs $V_1 \subset V_{n-1} \subset \mathbb{R}^n$ of lines contained in hyperplanes in \mathbb{R}^n .

In both cases we have a natural fibration $q : \text{Flag}(\tau_{\text{mod}}) \rightarrow P(\mathbb{R}^n)$ sending each flag to the line in the flag.

7.10 Example (Hitchin and Barbot representations). The Hitchin representations are σ_{mod} -Anosov representations belonging to a connected component $\text{Hom}^{\text{Hit}}(\Gamma, G)$ of $\text{Hom}^\sigma(\Gamma, G)$ containing a representation

$$\Gamma \hookrightarrow \text{PSL}(2, \mathbb{R}) \hookrightarrow \text{PSL}(n, \mathbb{R}),$$

where the first map is a Fuchsian representation of Γ and the second an irreducible embedding of $\text{PSL}(2, \mathbb{R})$.

We may also consider the standard reducible embedding $\iota : \text{SL}(2, \mathbb{R}) \hookrightarrow \text{SL}(n, \mathbb{R})$ given by $A \mapsto \begin{pmatrix} A & 0 \\ 0 & I \end{pmatrix}$. Let $\varphi : \Gamma \hookrightarrow \text{PSL}(2, \mathbb{R})$ be a Fuchsian representation and $\tilde{\varphi} : \Gamma \hookrightarrow \text{SL}(2, \mathbb{R})$ one of the $2g$ lifts of φ . Let $p : \text{SL}(n, \mathbb{R}) \rightarrow \text{PSL}(n, \mathbb{R})$ denote the covering map, which is of degree 2 if and only if n is even. Representations of the form

$$p \circ \iota \circ \tilde{\varphi} : \Gamma \hookrightarrow \text{SL}(2, \mathbb{R}) \hookrightarrow \text{SL}(n, \mathbb{R}) \rightarrow \text{PSL}(n, \mathbb{R})$$

are τ_{mod} -Anosov, where τ_{mod} has the type of pointed hyperplanes. Let $\text{Hom}^{\text{Bar}}(\Gamma, G)$ be the union of connected components of $\text{Hom}^\tau(\Gamma, G)$ containing such representations. We say representations in $\text{Hom}^{\text{Bar}}(\Gamma, G)$ are of *Barbot type*; see [Bar10] for the case $n = 3$.

Let $\rho : \Gamma \rightarrow \text{PSL}(n, \mathbb{R})$ be a Hitchin representation. It is known [Lab06] that the projection $q \circ \alpha : \partial_\infty \Gamma \rightarrow \text{Flag}(\sigma_{\text{mod}}) \rightarrow P^{n-1}(\mathbb{R})$ of the asymptotic embedding α is a hyper-convex curve. This curve is homotopically trivial if and only if n is odd. On the other hand, if ρ is of Barbot type, the curve $q \circ \alpha : \partial_\infty \Gamma \rightarrow \text{Flag}(\tau_{\text{mod}}) \rightarrow P^{n-1}(\mathbb{R})$ is always homotopically non-trivial.

We now lift to the space of oriented full flags (resp. oriented line-hyperplane flags). Accordingly, we lift the action of Γ on the sphere S^{n-1} . The preimage Λ of $(q \circ \alpha)(\partial_\infty \Gamma)$ in S^{n-1} is either a Jordan curve or a disjoint union of two Jordan curves, with the 2-fold equivariant covering map

$$\Lambda \rightarrow (q \circ \alpha)(\partial_\infty \Gamma) \cong P^1(\mathbb{R}) \cong S^1.$$

The result is an S-hyperbolic action $\tilde{\rho} : \Gamma \rightarrow \text{Diff}(S^n; \Lambda)$ where $\tilde{\rho}(\Gamma)$ is contained in the image of the group $\text{SL}(n, \mathbb{R})$ in $\text{Diff}(S^n)$. The restrictions of the Γ -actions to Λ are as in Example 7.3 (with $k = 2$) and Example 7.4.

7.11 Example (Embedded product examples). We embed Example 7.8 in the action of $\text{SL}(4, \mathbb{R})$ on $P^3(\mathbb{R})$. Consider $G_1 \times G_2 = \text{SL}(2, \mathbb{R}) \times \text{SL}(2, \mathbb{R}) < G = \text{SL}(4, \mathbb{R})$. The action of $G_1 \times G_2$ on \mathbb{R}^4 is reducible, preserving a direct sum decomposition

$$\mathbb{R}^4 = V_1 \oplus V_2,$$

where V_1 and V_2 are 2-dimensional subspaces and G_i acts trivially on V_{3-i} for $i = 1, 2$. Let τ be an involution of \mathbb{R}^4 swapping V_1 and V_2 . For $i = 1, 2$, take $\Gamma_i < G_i$ to be an infinite (possibly elementary) convex-cocompact subgroup with the limit set $\Lambda_i \subset P(V_i)$. Then the subgroup $\Gamma = \Gamma_1 \times \Gamma_2 < G$ acts on $P^3(\mathbb{R})$ preserving the union $\Lambda = \Lambda_1 \sqcup \Lambda_2 \subset P(V_1) \sqcup P(V_2)$. We equip $P^3(\mathbb{R})$ with its standard Riemannian metric. The action

$$\Gamma \rightarrow \text{Homeo}(P^3(\mathbb{R}); \Lambda)$$

is S-hyperbolic and restricts on Λ to Example 7.8. As in Example 7.8, taking $\Gamma_1 = \Gamma_2$ and an index two extension Γ of $\Gamma_1 \times \Gamma_2$ we can extend this action to an S-hyperbolic action minimal on Λ using the involution τ .

7.5 Algebraically stable but not convex-cocompact

We provide an example to the claim made in the introduction that for groups with torsion the implication (4 \Rightarrow 1) in Sullivan's paper [Sul85] is false. See the introduction of the present paper for the precise formulation of the statements (1) and (4).

7.12 Example (Quasiconformally stable non-convex-cocompact subgroups of $\text{PSL}(2, \mathbb{C})$). We recall also that a *von Dyck group* $D(p, q, r)$ is given by the presentation

$$\langle a, b, c \mid a^p = b^q = c^r = 1, abc = 1 \rangle.$$

Such groups are called *hyperbolic* (resp. *parabolic*, *elliptic*) if the number

$$\chi = \chi(p, q, r) = \frac{1}{p} + \frac{1}{q} + \frac{1}{r}$$

is < 1 (resp. $= 1$, > 1). Depending on the type $D(p, q, r)$ can be embedded (uniquely up to conjugation) as a discrete cocompact subgroup of isometries of hyperbolic plane (if $\chi < 1$), a discrete cocompact subgroup of the group $\text{Aff}(\mathbb{C})$ of complex affine transformations of \mathbb{C} (if $\chi = 1$), or is finite and embeds in the group of isometries of the 2-sphere (if $\chi > 1$).

Let Γ_i ($i = 1, 2$) be two discrete elementary subgroups of $\text{Aff}(\mathbb{C}) < \text{PSL}(2, \mathbb{C})$ isomorphic to parabolic von Dyck groups

$$D(p_i, q_i, r_i) \quad (i = 1, 2).$$

These groups consist of elliptic and parabolic elements and are virtually free abelian of rank 2; hence they cannot be contained in a convex-cocompact group. Subgroups of $\text{PSL}(2, \mathbb{C})$ isomorphic to von Dyck groups are (locally) rigid. One can choose embeddings of the groups Γ_1 and Γ_2 into $\text{PSL}(2, \mathbb{C})$ such that they generate a free product

$$\Gamma = \Gamma_1 \star \Gamma_2 < \text{PSL}(2, \mathbb{C}),$$

which is geometrically finite and every parabolic element of Γ is conjugate into one of the free factors. (The group Γ is obtained via the Klein combination of Γ_1 and Γ_2 , see [Kap01, §4.18])

for example). The discontinuity domain Ω of Γ in $P^1(\mathbb{C})$ is connected and the quotient orbifold $\mathcal{O} = \Omega/\Gamma$ is a sphere with six cone points of the orders p_i , q_i and r_i ($i = 1, 2$).

Being geometrically finite, the group Γ is relatively stable (relative its parabolic elements): let

$$\mathrm{Hom}_{\mathrm{par}}(\Gamma, \mathrm{PSL}(2, \mathbb{C}))$$

denote the *relative representation variety*, which is the subvariety in the representation variety defined by the condition that images of parabolic elements of Γ are again parabolic. Let $\iota_\Gamma : \Gamma \rightarrow \mathrm{PSL}(2, \mathbb{C})$ denote the identity embedding. Then there is a small neighborhood U of ι_Γ in $\mathrm{Hom}_{\mathrm{par}}(\Gamma, \mathrm{PSL}(2, \mathbb{C}))$ which consists entirely of faithful geometrically finite representations which are, moreover, given by quasiconformal conjugations of Γ . Since the subgroups Γ_1 and Γ_2 are rigid, there is a neighborhood V of ι_Γ such that

$$V \cap \mathrm{Hom}_{\mathrm{par}}(\Gamma, \mathrm{PSL}(2, \mathbb{C})) = V \cap \mathrm{Hom}(\Gamma, \mathrm{PSL}(2, \mathbb{C})).$$

It follows that the action of Γ on its limit set is structurally stable in $\mathrm{PSL}(2, \mathbb{C})$, in particular, algebraically stable. However, Γ is not convex-cocompact. Lastly, the group Γ is not rigid, the (complex) dimension of the character variety

$$X(\Gamma, \mathrm{PSL}(2, \mathbb{C})) // \mathrm{PSL}(2, \mathbb{C})$$

near $[\iota_\Gamma]$ equals the (complex) dimension of the Teichmüller space of \mathcal{O} , which is 3.

On the other hand, one can show that if $\Gamma < \mathrm{PSL}(2, \mathbb{C})$ is a finitely generated discrete subgroup which is not a lattice and contains no parabolic von Dyck subgroups, then algebraic stability of Γ implies quasiconvexity of Γ .

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