

Math 17C

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Establish a Shortcut for Getting Information About Eigenvalues for a 2×2 Matrix

Establish a Shortcut for Establishing the Stability of Equilibrium $(0, 0)$

DEFINITION : Let matrix $A = \begin{pmatrix} a & b \\ c & d \end{pmatrix}$.

- 1.) The determinant of matrix A is $\det(A) = ad - bc$.
- 2.) The trace of matrix A is $\text{tr}(A) = a + d$ (the sum of the main diagonal numbers).

NOTE : Since matrix $A = \begin{pmatrix} a & b \\ c & d \end{pmatrix}$, then

$$\begin{aligned}\det(A - \lambda I) &= \det \begin{pmatrix} a - \lambda & b \\ c & d - \lambda \end{pmatrix} \\ &= (a - \lambda)(d - \lambda) - (b)(c) \\ &= \lambda^2 - a\lambda - d\lambda + ad - bc \\ &= \lambda^2 - (a + d)\lambda + (ad - bc) = 0 \quad (\text{equation } (*))\end{aligned}$$

We also know that if λ_1 and λ_2 are eigenvalues for matrix A , then

$$\begin{aligned}\det(A - \lambda I) &= (\lambda - \lambda_1)(\lambda - \lambda_2) = 0 \\ \longrightarrow \quad \lambda^2 - \lambda_1\lambda - \lambda_2\lambda + \lambda_1\lambda_2 &= 0 \\ \longrightarrow \quad \lambda^2 - (\lambda_1 + \lambda_2)\lambda + \lambda_1\lambda_2 &= 0 \quad (\text{equation } (**))\end{aligned}$$

Combining equations $(*)$ and $(**)$ leads to the following EIGENVALUE SHORTCUTS :

FACT : Consider matrix $A = \begin{pmatrix} a & b \\ c & d \end{pmatrix}$ and its eigenvalues λ_1 and λ_2 .

- 1.) $\text{tr}(A) = a + d = \lambda_1 + \lambda_2$ (SUM of eigenvalues)
- 2.) $\det(A) = ad - bc = \lambda_1\lambda_2$ (PRODUCT of eigenvalues)

Determine the $\text{tr}(A)$ and $\det(A)$ for each of the following cases for λ_1 and λ_2 :

case 1 : If $\lambda_1 > 0$ and $\lambda_2 > 0$, then $\text{tr}(A) = \lambda_1 + \lambda_2 > 0$ and $\det(A) = \lambda_1\lambda_2 > 0$

(and equilibrium $(0, 0)$ is unstable, source)

case 2 : If $\lambda_1 < 0$ and $\lambda_2 < 0$, then $\text{tr}(A) = \lambda_1 + \lambda_2 < 0$ and $\det(A) = \lambda_1\lambda_2 > 0$

(and equilibrium $(0, 0)$ is STABLE, sink)

case 3 : If $\lambda_1 < 0$ and $\lambda_2 > 0$, then $\text{tr}(A) = \lambda_1 + \lambda_2$ is INCONCLUSIVE (why ?) and $\det(A) = \lambda_1 \lambda_2 < 0$

(and equilibrium $(0, 0)$ is unstable, saddle)

case 4 : If $\lambda_1 = a + bi$ and $\lambda_2 = a - bi$ with $a > 0$, then $\text{tr}(A) = \lambda_1 + \lambda_2 = 2a > 0$ and $\det(A) = \lambda_1 \lambda_2 = a^2 + b^2 > 0$

(and equilibrium $(0, 0)$ is unstable, unstable spiral)

case 5 : If $\lambda_1 = a + bi$ and $\lambda_2 = a - bi$ with $a < 0$, then $\text{tr}(A) = \lambda_1 + \lambda_2 = 2a < 0$ and $\det(A) = \lambda_1 \lambda_2 = a^2 + b^2 > 0$

(and equilibrium $(0, 0)$ is STABLE, stable spiral)

case 6 : If $\lambda_1 = a + bi$ and $\lambda_2 = a - bi$ with $a = 0$, then $\text{tr}(A) = \lambda_1 + \lambda_2 = 0$ and $\det(A) = \lambda_1 \lambda_2 = b^2 > 0$

(and equilibrium $(0, 0)$ is unstable, neutral spiral)

These six cases explain the following result :

THEOREM : Let A be a 2×2 matrix with eigenvalues λ_1 and λ_2 . Then the real parts of λ_1 and λ_2 are both negative iff

$$\text{tr}(A) < 0 \quad \text{AND} \quad \det(A) > 0$$

and equilibrium $(0, 0)$ is STABLE. If either condition fails to be true, then equilibrium $(0, 0)$ is UNSTABLE.