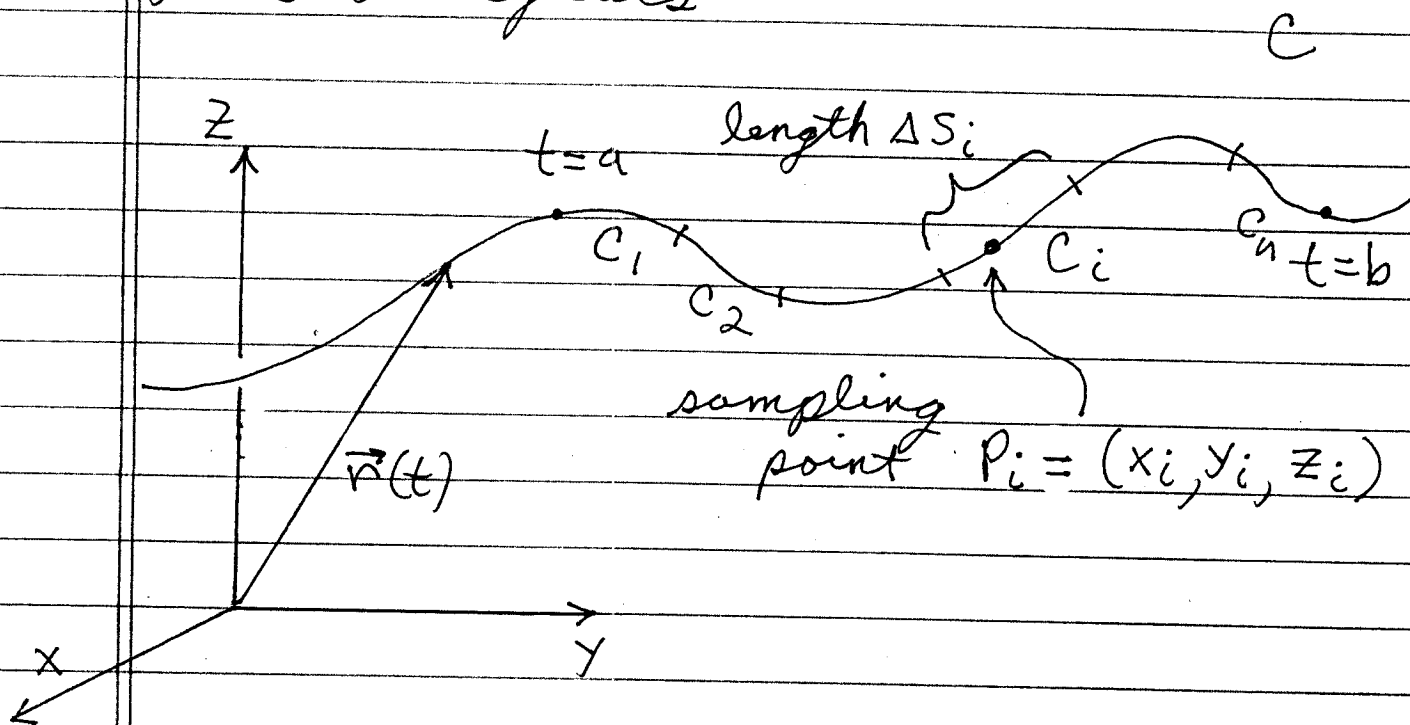


Math 21D

Kouba

Line Integrals



Let C be given by the vector function $\vec{r}(t) = g(t)\vec{i} + h(t)\vec{j} + k(t)\vec{k}$ for $t=a$ to $t=b$. Define function $w = f(x, y, z)$ on curve C by $w = f(g(t), h(t), k(t))$. Divide curve C into n parts $C_1, C_2, C_3, \dots, C_n$ of arc length $\Delta S_1, \Delta S_2, \Delta S_3, \dots, \Delta S_n$. Pick sampling points $P_i = (x_i, y_i, z_i)$ in C_i for $i=1, 2, 3, \dots, n$. We can now define the following new integral.

Def: The line integral of f over curve C from $t=a$ to $t=b$ is

$$\int_C f(x, y, z) dS = \lim_{\text{mesh} \rightarrow 0} \sum_{i=1}^n f(x_i, y_i, z_i) \cdot \Delta s_i$$

Method of Evaluation :

If C is determined by

$$\vec{r}(t) = g(t)\vec{i} + h(t)\vec{j} + k(t)\vec{k} \text{ for}$$

$a \leq t \leq b$, then

$$\int_C f(x, y, z) dS = \int_a^b f(g(t), h(t), k(t)) \cdot \frac{ds}{dt} \cdot dt,$$

where

$$\frac{ds}{dt} = |\vec{v}(t)| = \sqrt{(g'(t))^2 + (h'(t))^2 + (k'(t))^2}.$$

Applications of Line Integrals

Assume that $\delta(x, y, z)$ is the density (mass/length units) at point $P = (x, y, z)$ on curve C determined by $\vec{r}(t) = g(t)\vec{i} + h(t)\vec{j} + k(t)\vec{k}$ for $t = a$ to $t = b$.

$$1.) \text{ Length} = \int_C 1 dS$$

$$2.) \text{ Mass} = \int_C \delta(P) dS$$

3.) Moments about planes :

$$a.) M_{x=a} = \int_C (x-a) \delta(P) ds$$

$$b.) M_{y=a} = \int_C (y-a) \delta(P) ds$$

$$c.) M_{z=a} = \int_C (z-a) \delta(P) ds$$

4.) Center of Mass $(\bar{x}, \bar{y}, \bar{z})$:

$$\bar{x} = \frac{\int_C x \delta(P) ds}{\int_C \delta(P) ds}, \quad \bar{y} = \frac{\int_C y \delta(P) ds}{\int_C \delta(P) ds}, \quad \bar{z} = \frac{\int_C z \delta(P) ds}{\int_C \delta(P) ds}$$

5.) Centroid $(\bar{x}, \bar{y}, \bar{z})$:

$$\bar{x} = \frac{\int_C x ds}{\int_C 1 ds}, \quad \bar{y} = \frac{\int_C y ds}{\int_C 1 ds}, \quad \bar{z} = \frac{\int_C z ds}{\int_C 1 ds}$$

6.) Moment of Inertia :

$$M. of I. = \int_C (\text{distance})^2 \delta(P) ds,$$

where distance refers to the distance from point $P = (x, y, z)$ on curve C to either a point or axis of rotation.