

Lecture 18

Math 22A

Sec. 4.5

HW #18

Dimension of a Vector Space

Theorem: all bases for a finite-dimensional vector space have the same # of vectors.

Proof: (Special case)

Suppose a vector space V has two bases:

$$B_1 = \{\vec{v}_1, \vec{v}_2\}, \quad B_2 = \{\vec{w}_1, \vec{w}_2, \vec{w}_3\},$$

so both sets span V and are linearly independent.

Thus, all vectors in B_2 can be written as linear

combinations of vectors
in B_1 . It follows that

$$\alpha_1 \vec{w}_1 + \alpha_2 \vec{w}_2 + \alpha_3 \vec{w}_3 = \vec{0} \Rightarrow$$

$$\alpha_1 (a\vec{v}_1 + b\vec{v}_2) + \alpha_2 (c\vec{v}_1 + d\vec{v}_2)$$

$$+ \alpha_3 (e\vec{v}_1 + f\vec{v}_2) = \vec{0} \Rightarrow$$

$$(\alpha_1 a + \alpha_2 c + \alpha_3 e) \vec{v}_1$$

$$+ (\alpha_1 b + \alpha_2 d + \alpha_3 f) \vec{v}_2 = \vec{0} \Rightarrow$$

$$\begin{cases} \alpha_1 a + \alpha_2 c + \alpha_3 e = 0 \\ \alpha_1 b + \alpha_2 d + \alpha_3 f = 0 \end{cases} \quad \begin{array}{l} \text{(by} \\ \text{lin.} \\ \text{ind.} \\ \text{of } B_1) \end{array}$$

(Homogeneous System
of 2 equations, 3
unknowns) \Rightarrow
 $\alpha_1, \alpha_2, \alpha_3$

at least $3-2=1$ free variable \Rightarrow NONZERO SOLUTIONS. This contradicts the lin. ind. of set B_2 . Thus, the # of basis elements cannot be different.

Q. E. D.

Theorem: Let V be an n -dimensional vector space, and let $\{\vec{v}_1, \dots, \vec{v}_n\}$ be any basis

a.) If a set S in V has more than n vectors, then S is linearly dependent.

b.) If a set in V has fewer than n vectors, then S does not span V .

Proof: Similar to previous theorem.

Def: The dimension of a vector space V is the # of elements in a basis for V . NOTE: We say the zero vector space has dimension zero.

Ex: 1.) $\dim(\mathbb{R}^n) = n$

2.) $\dim(M_{32}) = 6$

3.) $\dim(P_3) = 4$

Plus/Minus Theorem:

Let S be a nonempty set of vectors in a vector space V .

a.) Let S be linearly independent and consider the subspace $\text{span}(S)$. If $\vec{v} \in V$, but $\vec{v} \notin \text{span}(S)$, then

$S \cup \{\vec{v}\}$ is linearly independent.

b.) Assume $\vec{v} \in S$ can be written as a linear combination of other vectors in S . Then

S and $S - \{v\}$ span the same subspace.

Proof: a.) (Special case)

Let $S = \{\vec{v}_1, \vec{v}_2\}$ ^{be linearly independent.} Let $\vec{v}_3 \in V$, but $\vec{v}_3 \notin \text{span}(S)$. Show $S \cup \{\vec{v}_3\} = \{\vec{v}_1, \vec{v}_2, \vec{v}_3\}$ is linearly independent.

But $\vec{v}_3 \notin \text{span}(S) \Rightarrow$

(#) $\vec{v}_3 \neq k_1 \vec{v}_1 + k_2 \vec{v}_2$ for all constants k_1, k_2 .

Now let

$$k_1 \vec{v}_1 + k_2 \vec{v}_2 + k_3 \vec{v}_3 = \vec{0} \Rightarrow$$

$$(*) \quad k_3 \vec{v}_3 = -k_1 \vec{v}_1 + k_2 \vec{v}_2.$$

case 1: If $k_3 = 0$, then (*) becomes

$$0 \vec{v}_3 = \vec{0} = (-k_1) \vec{v}_1 + (-k_2) \vec{v}_2 \Rightarrow$$

$$-k_1 = 0 \text{ and } -k_2 = 0 \Rightarrow$$

$$k_1 = 0 \text{ and } k_2 \text{ (by lin. ind. of set } S)$$

$\Rightarrow \{ \vec{v}_1, \vec{v}_2, \vec{v}_3 \}$ is lin. ind.

case 2: If $k_3 \neq 0$, then (*) becomes

$$\vec{v}_3 = \left(\frac{-k_1}{k_3} \right) \vec{v}_1 + \left(\frac{-k_2}{k_3} \right) \vec{v}_2$$

a contradiction of (#).

Q.E.D.

b.) (Special case)

assume $S = \{\vec{v}_1, \vec{v}_2, \vec{v}_3\}$

and $\vec{v}_3 = a\vec{v}_1 + b\vec{v}_2$, then

span $\{\vec{v}_1, \vec{v}_2, \vec{v}_3\}$

$$= \{ \alpha_1 \vec{v}_1 + \alpha_2 \vec{v}_2 + \alpha_3 \vec{v}_3 \mid \alpha_1, \alpha_2, \alpha_3 \in \mathbb{R} \}$$

$$= \{ \alpha_1 \vec{v}_1 + \alpha_2 \vec{v}_2 + \alpha_3 (a\vec{v}_1 + b\vec{v}_2) \mid \alpha_1, \alpha_2, \alpha_3 \in \mathbb{R} \}$$

$$= \{ (\alpha_1 + \alpha_3 a) \vec{v}_1 + (\alpha_2 + \alpha_3 b) \vec{v}_2 \mid \alpha_1, \alpha_2, \alpha_3 \in \mathbb{R} \}$$

$$= \{ c\vec{v}_1 + d\vec{v}_2 \mid c, d \in \mathbb{R} \}$$

$$= \text{span} \{ \vec{v}_1, \vec{v}_2 \}.$$

Q.E.D.

Theorem: Let V be an n -dimensional vector space, and let S be a set ~~subset~~ in V with n vectors. Then S is a basis for V iff

S spans V

or S is linearly independent.