Math 22A Kouba Solving the Linear Systems  $A\vec{x} = \vec{b}$  Using an LU-Decomposition

<u>PROBLEM 1:</u> Solve the following system using an *LU*-Decomposition:

$$\begin{cases} 2x_1 + 6x_2 = -2 \\ 3x_1 - x_2 = 7 \end{cases} \implies \begin{pmatrix} 2 & 6 \\ 3 & -1 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} -2 \\ 7 \end{pmatrix} \implies A\vec{x} = \vec{b}$$

$$FIRST FIND the LU-DECOMPOSITION for MATRIX A$$

$$A = \begin{pmatrix} 2 & 6 \\ 3 & -1 \end{pmatrix}$$

$$E_1 = \begin{pmatrix} 1/2 & 0 \\ 0 & 1 \end{pmatrix}$$

$$\sim \begin{pmatrix} 1 & 3 \\ 3 & -1 \end{pmatrix}$$

$$E_2 = \begin{pmatrix} 1 & 0 \\ -3 & 1 \end{pmatrix}$$

$$E_3 = \begin{pmatrix} 1 & 0 \\ 0 & -1/10 \end{pmatrix}$$

$$\sim \begin{pmatrix} 1 & 3 \\ 0 & 1 \end{pmatrix}$$
,
$$E_3 = \begin{pmatrix} 1 & 0 \\ 0 & -1/10 \end{pmatrix}$$

so  $U = \begin{pmatrix} 1 & 3 \\ 0 & 1 \end{pmatrix}$  is Upper Triangular. Then  $L = E_1^{-1} E_2^{-1} E_3^{-1} = \begin{pmatrix} 2 & 0 \\ 3 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 3 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 0 & -10 \end{pmatrix}$   $= \begin{pmatrix} 2 & 0 \\ 3 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 0 & -10 \end{pmatrix}$   $= \begin{pmatrix} 2 & 0 \\ 3 & -10 \end{pmatrix},$ 

so  $L = \begin{pmatrix} 2 & 0 \\ 3 & -10 \end{pmatrix}$  is Lower Triangular, and A = LU.

## NOW SOLVE the SYSTEM $A\vec{x} = LU\vec{x} = L(U\vec{x}) = \vec{b}$ for $\vec{x}$

STEP I.) First Let  $U\vec{x} = \vec{y}$  and Solve  $L\vec{y} = \vec{b}$  for  $\vec{y} \implies$   $\begin{pmatrix} 2 & 0 \\ 3 & -10 \end{pmatrix} \begin{pmatrix} y_1 \\ y_2 \end{pmatrix} = \begin{pmatrix} -2 \\ 7 \end{pmatrix} \implies$   $\begin{cases} 2y_1 = -2 \\ 3y_1 - 10y_2 = 7 \end{cases}$  (Forward Substitution)  $\implies$  $y_1 = -1 \implies 3(-1) - 10y_2 = 7 \implies 10y_2 = -10 \implies y_2 = -1 \implies$ 

$$\vec{y} = \begin{pmatrix} -1 \\ -1 \end{pmatrix}$$

STEP II.) Now Solve  $U\vec{x} = \vec{y}$  for  $\vec{x} \implies$   $\begin{pmatrix} 1 & 3 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} -1 \\ -1 \end{pmatrix} \implies$   $\begin{cases} x_1 + 3x_2 = -1 \\ x_2 = -1 \end{cases}$  (Back Substitution)  $\implies$   $x_1 + 3(-1) = -1 \implies x_1 = 2 \implies$  $\vec{x} = \begin{pmatrix} 2 \\ -1 \end{pmatrix}$ 

<u>PROBLEM 2:</u> Solve the following system using an LU-Decomposition:

$$\begin{cases} x_1 - x_2 + x_3 = 1\\ 2x_1 + x_2 + 8x_3 = -1\\ -x_1 + 3x_2 + 2x_3 = -2 \end{cases} \implies \begin{pmatrix} 1 & -1 & 1\\ 2 & 1 & 8\\ -1 & 3 & 2 \end{pmatrix} \begin{pmatrix} x_1\\ x_2\\ x_3 \end{pmatrix} = \begin{pmatrix} 1\\ -1\\ -2 \end{pmatrix} \implies A\vec{x} = \vec{b}$$

## FIRST FIND the LU-DECOMPOSITION for MATRIX A

$$A = \begin{pmatrix} 1 & -1 & 1 \\ 2 & 1 & 8 \\ -1 & 3 & 2 \end{pmatrix}$$

so

$$L = E_1^{-1} E_2^{-1} E_3^{-1} E_4^{-1} E_5^{-1}$$

$$= \begin{pmatrix} 1 & 0 & 0 \\ 2 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ -1 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 \\ 0 & 3 & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 \\ 0 & 2 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 \\ 0 & 2 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 \\ 0 & 3 & 0 \\ 0 & 2 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & -1 \end{pmatrix}$$
$$= \begin{pmatrix} 1 & 0 & 0 \\ 2 & 3 & 0 \\ -1 & 2 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & -1 \end{pmatrix}$$
$$= \begin{pmatrix} 1 & 0 & 0 \\ 2 & 3 & 0 \\ -1 & 2 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & -1 \end{pmatrix}$$

so  $L = \begin{pmatrix} 1 & 0 & 0 \\ 2 & 3 & 0 \\ -1 & 2 & -1 \end{pmatrix}$  is Lower Triangular, and A = LU.

NOW SOLVE the SYSTEM 
$$A\vec{x} = LU\vec{x} = L(U\vec{x}) = \vec{b}$$
 for  $\vec{x}$ 

STEP I.) First Let  $U\vec{x} = \vec{y}$  and Solve  $L\vec{y} = \vec{b}$  for  $\vec{y} \implies$  $\begin{pmatrix} 1 & 0 & 0 \\ 2 & 3 & 0 \\ -1 & 2 & -1 \end{pmatrix} \begin{pmatrix} y_1 \\ y_2 \\ y_3 \end{pmatrix} = \begin{pmatrix} 1 \\ -1 \\ -2 \end{pmatrix} \implies$   $\begin{cases} y_1 = 1 \\ 2y_1 + 3y_2 = -1 \\ -y_1 + 2y_2 - y_3 = -2 \end{cases}$ (Forward Substitution)  $\implies$   $y_1 = 1 \implies 2(1) + 3y_2 = -1 \implies 3y_2 = -3 \implies y_2 = -1$ and  $-(1) + 2(-1) - y_3 = -2 \implies y_3 = -1 \implies$   $\vec{y} = \begin{pmatrix} 1 \\ -1 \\ -1 \end{pmatrix}$ 

STEP II.) Now Solve  $U\vec{x} = \vec{y}$  for  $\vec{x} \implies$ 

$$\begin{pmatrix} 1 & -1 & 1 \\ 0 & 1 & 2 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} 1 \\ -1 \\ -1 \end{pmatrix} \implies$$
$$\begin{cases} x_1 - x_2 + x_3 = 1 \\ x_2 + 2x_3 = -1 \end{cases} (Back \ Substitution) \implies$$
$$x_3 = -1 \implies x_2 + 2(-1) = -1 \implies x_2 = 1 \implies$$
$$x_1 - (1) + (-1) = 1 \implies x_1 = 3 \implies$$
$$\vec{x} = \begin{pmatrix} 3 \\ 1 \\ -1 \end{pmatrix}$$

## NOTES on LU-DECOMPOSITION :

I.) Alan Turing (1912-1954), a British Mathematician and the "Father of Computer Science", is credited with inventing LU-Decomposition.

II.) Assume that A is a "large"  $n \times n$  matrix and A = LU is its *LU*-Decomposition. It is estimated that the number of "floating point operations" to solve  $A\vec{x} = \vec{b}$  using Gauss Elimination (Row Echelon Form) is approximately  $(2/3)n^3$ , and the the number of "floating point operations" to solve  $LU\vec{x} = \vec{b}$  is approximately  $n^2$ . This means that it takes approximately

$$\frac{(2/3)n^3}{n^2} = (2/3)n$$

times more operations to solve  $A\vec{x} = \vec{b}$  than it does to solve  $LU\vec{x} = \vec{b}$ .

III.) To save storage space on the computer, the  $n \times n$  matrices L and U can be stored as a single matrix B. For example,

$$L = \begin{pmatrix} 2 & 0 & 0 \\ 3 & -1 & 0 \\ -2 & 1 & 4 \end{pmatrix} \quad and \quad U = \begin{pmatrix} 1 & -1 & 7 \\ 0 & 1 & 2 \\ 0 & 0 & 1 \end{pmatrix}$$

can be stored as

$$B = \begin{pmatrix} 2 & -1 & 7 \\ 3 & -1 & 2 \\ -2 & 1 & 4 \end{pmatrix}$$

Conversely, if

$$B = \begin{pmatrix} 3 & 4 & -5\\ 2 & -1 & -2\\ 1 & 3 & 2 \end{pmatrix}$$

then it follows that

$$L = \begin{pmatrix} 3 & 0 & 0 \\ 2 & -1 & 0 \\ 1 & 3 & 2 \end{pmatrix} \quad and \quad U = \begin{pmatrix} 1 & 4 & -5 \\ 0 & 1 & -2 \\ 0 & 0 & 1 \end{pmatrix}$$

IV.) Later we will learn about the Determinant of a matrix. If an  $n \times n$  matrix A can be written as A = LU, then computing it's Determinant is extremely easy.