Add −3 times the first equation to the third to obtain

$$\begin{aligned} x + y + 2z &= 9 \\ 2y - 7z &= -17 \\ 3y - 11z &= -27 \end{aligned}$$

Add −3 times the first row to the third to obtain

$$\begin{bmatrix} 1 & 1 & 2 & 9 \\ 0 & 2 & -7 & -17 \\ 0 & 3 & -11 & -27 \end{bmatrix}$$

Multiply the second equation by $\frac{1}{2}$ to obtain

$$\begin{aligned} x + y + 2z &= 9 \\ y - \tfrac{7}{2}z &= -\tfrac{17}{2} \\ 3y - 11z &= -27 \end{aligned}$$

Multiply the second row by $\frac{1}{2}$ to obtain

$$\begin{bmatrix} 1 & 1 & 2 & 9 \\ 0 & 1 & -\frac{7}{2} & -\frac{17}{2} \\ 0 & 3 & -11 & -27 \end{bmatrix}$$

Add −3 times the second equation to the third to obtain

$$\begin{aligned} x + y + 2z &= 9 \\ y - \tfrac{7}{2}z &= -\tfrac{17}{2} \\ -\tfrac{1}{2}z &= -\tfrac{3}{2} \end{aligned}$$

Add −3 times the second row to the third to obtain

$$\begin{bmatrix} 1 & 1 & 2 & 9 \\ 0 & 1 & -\frac{7}{2} & -\frac{17}{2} \\ 0 & 0 & -\frac{1}{2} & -\frac{3}{2} \end{bmatrix}$$

Multiply the third equation by −2 to obtain

$$\begin{aligned} x + y + 2z &= 9 \\ y - \tfrac{7}{2}z &= -\tfrac{17}{2} \\ z &= 3 \end{aligned}$$

Multiply the third row by −2 to obtain

$$\begin{bmatrix} 1 & 1 & 2 & 9 \\ 0 & 1 & -\frac{7}{2} & -\frac{17}{2} \\ 0 & 0 & 1 & 3 \end{bmatrix}$$

Add −1 times the second equation to the first to obtain

$$\begin{aligned} x \qquad + \tfrac{11}{2}z &= \tfrac{35}{2} \\ y - \tfrac{7}{2}z &= -\tfrac{17}{2} \\ z &= 3 \end{aligned}$$

Add −1 times the second row to the first to obtain

$$\begin{bmatrix} 1 & 0 & \frac{11}{2} & \frac{35}{2} \\ 0 & 1 & -\frac{7}{2} & -\frac{17}{2} \\ 0 & 0 & 1 & 3 \end{bmatrix}$$

Add $-\frac{11}{2}$ times the third equation to the first and $\frac{7}{2}$ times the third equation to the second to obtain

$$\begin{aligned} x \qquad &= 1 \\ y \quad &= 2 \\ z &= 3 \end{aligned}$$

Add $-\frac{11}{2}$ times the third row to the first and $\frac{7}{2}$ times the third row to the second to obtain

$$\begin{bmatrix} 1 & 0 & 0 & 1 \\ 0 & 1 & 0 & 2 \\ 0 & 0 & 1 & 3 \end{bmatrix}$$

The solution $x = 1$, $y = 2$, $z = 3$ is now evident. ◀

The solution in this example can also be expressed as the ordered triple $(1, 2, 3)$ with the understanding that the numbers in the triple are in the same order as the variables in the system, namely, x, y, z.

Exercise Set 1.1

1. In each part, determine whether the equation is linear in x_1, x_2, and x_3.

(a) $x_1 + 5x_2 - \sqrt{2}x_3 = 1$
(b) $x_1 + 3x_2 + x_1x_3 = 2$
(c) $x_1 = -7x_2 + 3x_3$
(d) $x_1^{-2} + x_2 + 8x_3 = 5$
(e) $x_1^{3/5} - 2x_2 + x_3 = 4$
(f) $\pi x_1 - \sqrt{2}x_2 = 7^{1/3}$

2. In each part, determine whether the equation is linear in x and y.

(a) $2^{1/3}x + \sqrt{3}y = 1$
(b) $2x^{1/3} + 3\sqrt{y} = 1$
(c) $\cos\left(\frac{\pi}{7}\right)x - 4y = \log 3$
(d) $\frac{\pi}{7}\cos x - 4y = 0$
(e) $xy = 1$
(f) $y + 7 = x$

3. Using the notation of Formula (7), write down a general linear system of
   (a) two equations in two unknowns.
   (b) three equations in three unknowns.
   (c) two equations in four unknowns.

4. Write down the augmented matrix for each of the linear systems in Exercise 3.

In each part of Exercises 5–6, find a linear system in the unknowns $x_1, x_2, x_3, \ldots$, that corresponds to the given augmented matrix.

5. (a) $\begin{bmatrix} 2 & 0 & 0 \\ 3 & -4 & 0 \\ 0 & 1 & 1 \end{bmatrix}$ (b) $\begin{bmatrix} 3 & 0 & -2 & 5 \\ 7 & 1 & 4 & -3 \\ 0 & -2 & 1 & 7 \end{bmatrix}$

6. (a) $\begin{bmatrix} 0 & 3 & -1 & -1 & -1 \\ 5 & 2 & 0 & -3 & -6 \end{bmatrix}$

   (b) $\begin{bmatrix} 3 & 0 & 1 & -4 & 3 \\ -4 & 0 & 4 & 1 & -3 \\ -1 & 3 & 0 & -2 & -9 \\ 0 & 0 & 0 & -1 & -2 \end{bmatrix}$

In each part of Exercises 7–8, find the augmented matrix for the linear system.

7. (a) $\begin{aligned} -2x_1 &= 6 \\ 3x_1 &= 8 \\ 9x_1 &= -3 \end{aligned}$ (b) $\begin{aligned} 6x_1 - x_2 + 3x_3 &= 4 \\ 5x_2 - x_3 &= 1 \end{aligned}$

   (c) $\begin{aligned} 2x_2 \quad - 3x_4 + x_5 &= 0 \\ -3x_1 - x_2 + x_3 \quad &= -1 \\ 6x_1 + 2x_2 - x_3 + 2x_4 - 3x_5 &= 6 \end{aligned}$

8. (a) $\begin{aligned} 3x_1 - 2x_2 &= -1 \\ 4x_1 + 5x_2 &= 3 \\ 7x_1 + 3x_2 &= 2 \end{aligned}$ (b) $\begin{aligned} 2x_1 \quad + 2x_3 &= 1 \\ 3x_1 - x_2 + 4x_3 &= 7 \\ 6x_1 + x_2 - x_3 &= 0 \end{aligned}$

   (c) $\begin{aligned} x_1 \quad &= 1 \\ x_2 \quad &= 2 \\ x_3 &= 3 \end{aligned}$

9. In each part, determine whether the given 3-tuple is a solution of the linear system

$$\begin{aligned} 2x_1 - 4x_2 - x_3 &= 1 \\ x_1 - 3x_2 + x_3 &= 1 \\ 3x_1 - 5x_2 - 3x_3 &= 1 \end{aligned}$$

   (a) $(3, 1, 1)$ (b) $(3, -1, 1)$ (c) $(13, 5, 2)$
   (d) $(\frac{13}{2}, \frac{5}{2}, 2)$ (e) $(17, 7, 5)$

10. In each part, determine whether the given 3-tuple is a solution of the linear system

$$\begin{aligned} x + 2y - 2z &= 3 \\ 3x - y + z &= 1 \\ -x + 5y - 5z &= 5 \end{aligned}$$

   (a) $(\frac{5}{7}, \frac{8}{7}, 1)$ (b) $(\frac{5}{7}, \frac{8}{7}, 0)$ (c) $(5, 8, 1)$
   (d) $(\frac{5}{7}, \frac{10}{7}, \frac{2}{7})$ (e) $(\frac{5}{7}, \frac{22}{7}, 2)$

11. In each part, solve the linear system, if possible, and use the result to determine whether the lines represented by the equations in the system have zero, one, or infinitely many points of intersection. If there is a single point of intersection, give its coordinates, and if there are infinitely many, find parametric equations for them.

   (a) $\begin{aligned} 3x - 2y &= 4 \\ 6x - 4y &= 9 \end{aligned}$ (b) $\begin{aligned} 2x - 4y &= 1 \\ 4x - 8y &= 2 \end{aligned}$ (c) $\begin{aligned} x - 2y &= 0 \\ x - 4y &= 8 \end{aligned}$

12. Under what conditions on a and b will the following linear system have no solutions, one solution, infinitely many solutions?

$$\begin{aligned} 2x - 3y &= a \\ 4x - 6y &= b \end{aligned}$$

In each part of Exercises 13–14, use parametric equations to describe the solution set of the linear equation.

13. (a) $7x - 5y = 3$
   (b) $3x_1 - 5x_2 + 4x_3 = 7$
   (c) $-8x_1 + 2x_2 - 5x_3 + 6x_4 = 1$
   (d) $3v - 8w + 2x - y + 4z = 0$

14. (a) $x + 10y = 2$
   (b) $x_1 + 3x_2 - 12x_3 = 3$
   (c) $4x_1 + 2x_2 + 3x_3 + x_4 = 20$
   (d) $v + w + x - 5y + 7z = 0$

In Exercises 15–16, each linear system has infinitely many solutions. Use parametric equations to describe its solution set.

15. (a) $\begin{aligned} 2x - 3y &= 1 \\ 6x - 9y &= 3 \end{aligned}$

   (b) $\begin{aligned} x_1 + 3x_2 - x_3 &= -4 \\ 3x_1 + 9x_2 - 3x_3 &= -12 \\ -x_1 - 3x_2 + x_3 &= 4 \end{aligned}$

16. (a) $\begin{aligned} 6x_1 + 2x_2 &= -8 \\ 3x_1 + x_2 &= -4 \end{aligned}$ (b) $\begin{aligned} 2x - y + 2z &= -4 \\ 6x - 3y + 6z &= -12 \\ -4x + 2y - 4z &= 8 \end{aligned}$

In Exercises 17–18, find a single elementary row operation that will create a 1 in the upper left corner of the given augmented matrix and will not create any fractions in its first row.

17. (a) $\begin{bmatrix} -3 & -1 & 2 & 4 \\ 2 & -3 & 3 & 2 \\ 0 & 2 & -3 & 1 \end{bmatrix}$ (b) $\begin{bmatrix} 0 & -1 & -5 & 0 \\ 2 & -9 & 3 & 2 \\ 1 & 4 & -3 & 3 \end{bmatrix}$

18. (a) $\begin{bmatrix} 2 & 4 & -6 & 8 \\ 7 & 1 & 4 & 3 \\ -5 & 4 & 2 & 7 \end{bmatrix}$ (b) $\begin{bmatrix} 7 & -4 & -2 & 2 \\ 3 & -1 & 8 & 1 \\ -6 & 3 & -1 & 4 \end{bmatrix}$

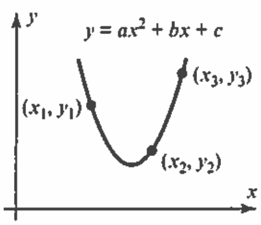
In Exercises 19–20, find all values of k for which the given augmented matrix corresponds to a consistent linear system.

19. (a) $\begin{bmatrix} 1 & k & -4 \\ 4 & 8 & 2 \end{bmatrix}$ (b) $\begin{bmatrix} 1 & k & -1 \\ 4 & 8 & -4 \end{bmatrix}$

20. (a) $\begin{bmatrix} 3 & -4 & k \\ -6 & 8 & 5 \end{bmatrix}$ (b) $\begin{bmatrix} k & 1 & -2 \\ 4 & -1 & 2 \end{bmatrix}$

21. The curve $y = ax^2 + bx + c$ shown in the accompanying figure passes through the points (x_1, y_1), (x_2, y_2), and (x_3, y_3). Show that the coefficients a, b, and c form a solution of the system of linear equations whose augmented matrix is

$$\begin{bmatrix} x_1^2 & x_1 & 1 & y_1 \\ x_2^2 & x_2 & 1 & y_2 \\ x_3^2 & x_3 & 1 & y_3 \end{bmatrix}$$



◀ Figure Ex-21

22. Explain why each of the three elementary row operations does not affect the solution set of a linear system.

23. Show that if the linear equations

$$x_1 + kx_2 = c \quad \text{and} \quad x_1 + lx_2 = d$$

have the same solution set, then the two equations are identical (i.e., $k = l$ and $c = d$).

24. Consider the system of equations

$$\begin{aligned} ax + by &= k \\ cx + dy &= l \\ ex + fy &= m \end{aligned}$$

Discuss the relative positions of the lines $ax + by = k$, $cx + dy = l$, and $ex + fy = m$ when

(a) the system has no solutions.

(b) the system has exactly one solution.

(c) the system has infinitely many solutions.

25. Suppose that a certain diet calls for 7 units of fat, 9 units of protein, and 16 units of carbohydrates for the main meal, and suppose that an individual has three possible foods to choose from to meet these requirements:

Food 1: Each ounce contains 2 units of fat, 2 units of protein, and 4 units of carbohydrates.

Food 2: Each ounce contains 3 units of fat, 1 unit of protein, and 2 units of carbohydrates.

Food 3: Each ounce contains 1 unit of fat, 3 units of protein, and 5 units of carbohydrates.

Let x, y, and z denote the number of ounces of the first, second, and third foods that the dieter will consume at the main meal. Find (but do not solve) a linear system in x, y, and z whose solution tells how many ounces of each food must be consumed to meet the diet requirements.

26. Suppose that you want to find values for a, b, and c such that the parabola $y = ax^2 + bx + c$ passes through the points $(1, 1)$, $(2, 4)$, and $(-1, 1)$. Find (but do not solve) a system of linear equations whose solutions provide values for a, b, and c. How many solutions would you expect this system of equations to have, and why?

27. Suppose you are asked to find three real numbers such that the sum of the numbers is 12, the sum of two times the first plus the second plus two times the third is 5, and the third number is one more than the first. Find (but do not solve) a linear system whose equations describe the three conditions.

True-False Exercises

TF. In parts (a)–(h) determine whether the statement is true or false, and justify your answer.

(a) A linear system whose equations are all homogeneous must be consistent.

(b) Multiplying a row of an augmented matrix through by zero is an acceptable elementary row operation.

(c) The linear system

$$\begin{aligned} x - y &= 3 \\ 2x - 2y &= k \end{aligned}$$

cannot have a unique solution, regardless of the value of k.

(d) A single linear equation with two or more unknowns must have infinitely many solutions.

(e) If the number of equations in a linear system exceeds the number of unknowns, then the system must be inconsistent.

(f) If each equation in a consistent linear system is multiplied through by a constant c, then all solutions to the new system can be obtained by multiplying solutions from the original system by c.

(g) Elementary row operations permit one row of an augmented matrix to be subtracted from another.

(h) The linear system with corresponding augmented matrix

$$\begin{bmatrix} 2 & -1 & 4 \\ 0 & 0 & -1 \end{bmatrix}$$

is consistent.

Working with Technology

T1. Solve the linear systems in Examples 2, 3, and 4 to see how your technology utility handles the three types of systems.

T2. Use the result in Exercise 21 to find values of a, b, and c for which the curve $y = ax^2 + bx + c$ passes through the points $(-1, 1, 4)$, $(0, 0, 8)$, and $(1, 1, 7)$.

▶ EXAMPLE 9 Pivot Positions and Columns

Earlier in this section (immediately after Definition 1) we found a row echelon form of

$$A = \begin{bmatrix} 0 & 0 & -2 & 0 & 7 & 12 \\ 2 & 4 & -10 & 6 & 12 & 28 \\ 2 & 4 & -5 & 6 & -5 & -1 \end{bmatrix}$$

to be

$$\begin{bmatrix} 1 & 2 & -5 & 3 & 6 & 14 \\ 0 & 0 & 1 & 0 & -\frac{7}{2} & -6 \\ 0 & 0 & 0 & 0 & 1 & 2 \end{bmatrix}$$

The leading 1's occur in positions (row 1, column 1), (row 2, column 3), and (row 3, column 5). These are the pivot positions. The pivot columns are columns 1, 3, and 5. ◀

If A is the augmented matrix for a linear system, then the pivot columns identify the leading variables. As an illustration, in Example 5 the pivot columns are 1, 3, and 6, and the leading variables are x_1, x_3, and x_6.

Roundoff Error and Instability

There is often a gap between mathematical theory and its practical implementation—Gauss–Jordan elimination and Gaussian elimination being good examples. The problem is that computers generally approximate numbers, thereby introducing ***roundoff*** errors, so unless precautions are taken, successive calculations may degrade an answer to a degree that makes it useless. Algorithms (procedures) in which this happens are called ***unstable***. There are various techniques for minimizing roundoff error and instability. For example, it can be shown that for large linear systems Gauss–Jordan elimination involves roughly 50% more operations than Gaussian elimination, so most computer algorithms are based on the latter method. Some of these matters will be considered in Chapter 9.

Exercise Set 1.2

In Exercises 1–2, determine whether the matrix is in row echelon form, reduced row echelon form, both, or neither.

1. (a) $\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$ (b) $\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix}$ (c) $\begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix}$

(d) $\begin{bmatrix} 1 & 0 & 3 & 1 \\ 0 & 1 & 2 & 4 \end{bmatrix}$ (e) $\begin{bmatrix} 1 & 2 & 0 & 3 & 0 \\ 0 & 0 & 1 & 1 & 0 \\ 0 & 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$

(f) $\begin{bmatrix} 0 & 0 \\ 0 & 0 \\ 0 & 0 \end{bmatrix}$ (g) $\begin{bmatrix} 1 & -7 & 5 & 5 \\ 0 & 1 & 3 & 2 \end{bmatrix}$

2. (a) $\begin{bmatrix} 1 & 2 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix}$ (b) $\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 2 & 0 \end{bmatrix}$ (c) $\begin{bmatrix} 1 & 3 & 4 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix}$

(d) $\begin{bmatrix} 1 & 5 & -3 \\ 0 & 1 & 1 \\ 0 & 0 & 0 \end{bmatrix}$ (e) $\begin{bmatrix} 1 & 2 & 3 \\ 0 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix}$

(f) $\begin{bmatrix} 1 & 2 & 3 & 4 & 5 \\ 1 & 0 & 7 & 1 & 3 \\ 0 & 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$ (g) $\begin{bmatrix} 1 & -2 & 0 & 1 \\ 0 & 0 & 1 & -2 \end{bmatrix}$

In Exercises 3–4, suppose that the augmented matrix for a linear system has been reduced by row operations to the given row echelon form. Solve the system.

3. (a) $\begin{bmatrix} 1 & -3 & 4 & 7 \\ 0 & 1 & 2 & 2 \\ 0 & 0 & 1 & 5 \end{bmatrix}$

(b) $\begin{bmatrix} 1 & 0 & 8 & -5 & 6 \\ 0 & 1 & 4 & -9 & 3 \\ 0 & 0 & 1 & 1 & 2 \end{bmatrix}$

(c) $\begin{bmatrix} 1 & 7 & -2 & 0 & -8 & -3 \\ 0 & 0 & 1 & 1 & 6 & 5 \\ 0 & 0 & 0 & 1 & 3 & 9 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix}$

(d) $\begin{bmatrix} 1 & -3 & 7 & 1 \\ 0 & 1 & 4 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$

4. (a) $\begin{bmatrix} 1 & 0 & 0 & -3 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 7 \end{bmatrix}$

(b) $\begin{bmatrix} 1 & 0 & 0 & -7 & 8 \\ 0 & 1 & 0 & 3 & 2 \\ 0 & 0 & 1 & 1 & -5 \end{bmatrix}$

(c) $\begin{bmatrix} 1 & -6 & 0 & 0 & 3 & -2 \\ 0 & 0 & 1 & 0 & 4 & 7 \\ 0 & 0 & 0 & 1 & 5 & 8 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix}$

(d) $\begin{bmatrix} 1 & -3 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$

In Exercises 5–8, solve the linear system by Gaussian elimination.

5. $\begin{aligned} x_1 + x_2 + 2x_3 &= 8 \\ -x_1 - 2x_2 + 3x_3 &= 1 \\ 3x_1 - 7x_2 + 4x_3 &= 10 \end{aligned}$

6. $\begin{aligned} 2x_1 + 2x_2 + 2x_3 &= 0 \\ -2x_1 + 5x_2 + 2x_3 &= 1 \\ 8x_1 + x_2 + 4x_3 &= -1 \end{aligned}$

7. $\begin{aligned} x - y + 2z - w &= -1 \\ 2x + y - 2z - 2w &= -2 \\ -x + 2y - 4z + w &= 1 \\ 3x \qquad\qquad - 3w &= -3 \end{aligned}$

8. $\begin{aligned} -2b + 3c &= 1 \\ 3a + 6b - 3c &= -2 \\ 6a + 6b + 3c &= 5 \end{aligned}$

In Exercises 9–12, solve the linear system by Gauss–Jordan elimination.

9. Exercise 5

10. Exercise 6

11. Exercise 7

12. Exercise 8

In Exercises 13–14, determine whether the homogeneous system has nontrivial solutions by inspection (without pencil and paper).

13. $\begin{aligned} 2x_1 - 3x_2 + 4x_3 - x_4 &= 0 \\ 7x_1 + x_2 - 8x_3 + 9x_4 &= 0 \\ 2x_1 + 8x_2 + x_3 - x_4 &= 0 \end{aligned}$

14. $\begin{aligned} x_1 + 3x_2 - x_3 &= 0 \\ x_2 - 8x_3 &= 0 \\ 4x_3 &= 0 \end{aligned}$

In Exercises 15–22, solve the given linear system by any method.

15. $\begin{aligned} 2x_1 + x_2 + 3x_3 &= 0 \\ x_1 + 2x_2 \qquad &= 0 \\ x_2 + x_3 &= 0 \end{aligned}$

16. $\begin{aligned} 2x - y - 3z &= 0 \\ -x + 2y - 3z &= 0 \\ x + y + 4z &= 0 \end{aligned}$

17. $\begin{aligned} 3x_1 + x_2 + x_3 + x_4 &= 0 \\ 5x_1 - x_2 + x_3 - x_4 &= 0 \end{aligned}$

18. $\begin{aligned} v + 3w - 2x &= 0 \\ 2u + v - 4w + 3x &= 0 \\ 2u + 3v + 2w - x &= 0 \\ -4u - 3v + 5w - 4x &= 0 \end{aligned}$

19. $\begin{aligned} 2x + 2y + 4z &= 0 \\ w \qquad - y - 3z &= 0 \\ 2w + 3x + y + z &= 0 \\ -2w + x + 3y - 2z &= 0 \end{aligned}$

20. $\begin{aligned} x_1 + 3x_2 \qquad + x_4 &= 0 \\ x_1 + 4x_2 + 2x_3 \qquad &= 0 \\ -2x_2 - 2x_3 - x_4 &= 0 \\ 2x_1 - 4x_2 + x_3 + x_4 &= 0 \\ x_1 - 2x_2 - x_3 + x_4 &= 0 \end{aligned}$

21. $\begin{aligned} 2I_1 - I_2 + 3I_3 + 4I_4 &= 9 \\ I_1 \qquad - 2I_3 + 7I_4 &= 11 \\ 3I_1 - 3I_2 + I_3 + 5I_4 &= 8 \\ 2I_1 + I_2 + 4I_3 + 4I_4 &= 10 \end{aligned}$

22. $\begin{aligned} Z_3 + Z_4 + Z_5 &= 0 \\ -Z_1 - Z_2 + 2Z_3 - 3Z_4 + Z_5 &= 0 \\ Z_1 + Z_2 - 2Z_3 \qquad - Z_5 &= 0 \\ 2Z_1 + 2Z_2 - Z_3 \qquad + Z_5 &= 0 \end{aligned}$

In each part of Exercises 23–24, the augmented matrix for a linear system is given in which the asterisk represents an unspecified real number. Determine whether the system is consistent, and if so whether the solution is unique. Answer "inconclusive" if there is not enough information to make a decision.

23. (a) $\begin{bmatrix} 1 & * & * & * \\ 0 & 1 & * & * \\ 0 & 0 & 1 & * \end{bmatrix}$ (b) $\begin{bmatrix} 1 & * & * & * \\ 0 & 1 & * & * \\ 0 & 0 & 0 & 0 \end{bmatrix}$

(c) $\begin{bmatrix} 1 & * & * & * \\ 0 & 1 & * & * \\ 0 & 0 & 0 & 1 \end{bmatrix}$ (d) $\begin{bmatrix} 1 & * & * & * \\ 0 & 0 & * & 0 \\ 0 & 0 & 1 & * \end{bmatrix}$

24. (a) $\begin{bmatrix} 1 & * & * & * \\ 0 & 1 & * & * \\ 0 & 0 & 1 & 1 \end{bmatrix}$ (b) $\begin{bmatrix} 1 & 0 & 0 & * \\ * & 1 & 0 & * \\ * & * & 1 & * \end{bmatrix}$

(c) $\begin{bmatrix} 1 & 0 & 0 & 0 \\ 1 & 0 & 0 & 1 \\ 1 & * & * & * \end{bmatrix}$ (d) $\begin{bmatrix} 1 & * & * & * \\ 1 & 0 & 0 & 1 \\ 1 & 0 & 0 & 1 \end{bmatrix}$

In Exercises 25–26, determine the values of a for which the system has no solutions, exactly one solution, or infinitely many solutions.

25. $\begin{aligned} x + 2y - \qquad 3z &= 4 \\ 3x - y + \qquad 5z &= 2 \\ 4x + y + (a^2 - 14)z &= a + 2 \end{aligned}$

26. $$\begin{aligned} x + 2y + \quad\quad z &= 2 \\ 2x - 2y + \quad\quad 3z &= 1 \\ x + 2y - (a^2 - 3)z &= a \end{aligned}$$

In Exercises 27–28, what condition, if any, must a, b, and c satisfy for the linear system to be consistent?

27. $$\begin{aligned} x + 3y - z &= a \\ x + y + 2z &= b \\ 2y - 3z &= c \end{aligned}$$

28. $$\begin{aligned} x + 3y + z &= a \\ -x - 2y + z &= b \\ 3x + 7y - z &= c \end{aligned}$$

In Exercises 29–30, solve the following systems, where a, b, and c are constants.

29. $$\begin{aligned} 2x + y &= a \\ 3x + 6y &= b \end{aligned}$$

30. $$\begin{aligned} x_1 + x_2 + x_3 &= a \\ 2x_1 \quad\quad + 2x_3 &= b \\ 3x_2 + 3x_3 &= c \end{aligned}$$

31. Find two different row echelon forms of

$$\begin{bmatrix} 1 & 3 \\ 2 & 7 \end{bmatrix}$$

This exercise shows that a matrix can have multiple row echelon forms.

32. Reduce

$$\begin{bmatrix} 2 & 1 & 3 \\ 0 & -2 & -29 \\ 3 & 4 & 5 \end{bmatrix}$$

to reduced row echelon form without introducing fractions at any intermediate stage.

33. Show that the following nonlinear system has 18 solutions if $0 \le \alpha \le 2\pi$, $0 \le \beta \le 2\pi$, and $0 \le \gamma \le 2\pi$.

$$\begin{aligned} \sin\alpha + 2\cos\beta + 3\tan\gamma &= 0 \\ 2\sin\alpha + 5\cos\beta + 3\tan\gamma &= 0 \\ -\sin\alpha - 5\cos\beta + 5\tan\gamma &= 0 \end{aligned}$$

[*Hint:* Begin by making the substitutions $x = \sin\alpha$, $y = \cos\beta$, and $z = \tan\gamma$.]

34. Solve the following system of nonlinear equations for the unknown angles α, β, and γ, where $0 \le \alpha \le 2\pi$, $0 \le \beta \le 2\pi$, and $0 \le \gamma < \pi$.

$$\begin{aligned} 2\sin\alpha - \cos\beta + 3\tan\gamma &= 3 \\ 4\sin\alpha + 2\cos\beta - 2\tan\gamma &= 2 \\ 6\sin\alpha - 3\cos\beta + \tan\gamma &= 9 \end{aligned}$$

35. Solve the following system of nonlinear equations for x, y, and z.

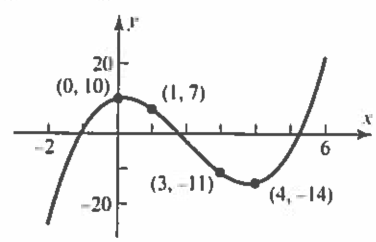
$$\begin{aligned} x^2 + y^2 + z^2 &= 6 \\ x^2 - y^2 + 2z^2 &= 2 \\ 2x^2 + y^2 - z^2 &= 3 \end{aligned}$$

[*Hint:* Begin by making the substitutions $X = x^2$, $Y = y^2$, $Z = z^2$.]

36. Solve the following system for x, y, and z.

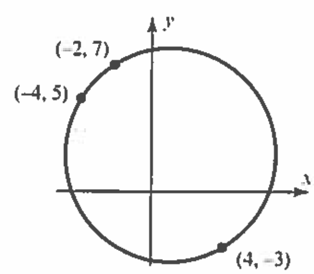
$$\begin{aligned} \frac{1}{x} + \frac{2}{y} - \frac{4}{z} &= 1 \\ \frac{2}{x} + \frac{3}{y} + \frac{8}{z} &= 0 \\ -\frac{1}{x} + \frac{9}{y} + \frac{10}{z} &= 5 \end{aligned}$$

37. Find the coefficients a, b, c, and d so that the curve shown in the accompanying figure is the graph of the equation $y = ax^3 + bx^2 + cx + d$.



◀ Figure Ex-37

38. Find the coefficients a, b, c, and d so that the circle shown in the accompanying figure is given by the equation $ax^2 + ay^2 + bx + cy + d = 0$.



◀ Figure Ex-38

39. If the linear system

$$\begin{aligned} a_1x + b_1y + c_1z &= 0 \\ a_2x - b_2y + c_2z &= 0 \\ a_3x + b_3y - c_3z &= 0 \end{aligned}$$

has only the trivial solution, what can be said about the solutions of the following system?

$$\begin{aligned} a_1x + b_1y + c_1z &= 3 \\ a_2x - b_2y + c_2z &= 7 \\ a_3x + b_3y - c_3z &= 11 \end{aligned}$$

40. (a) If A is a matrix with three rows and five columns, then what is the maximum possible number of leading 1's in its reduced row echelon form?

(b) If B is a matrix with three rows and six columns, then what is the maximum possible number of parameters in the general solution of the linear system with augmented matrix B?

(c) If C is a matrix with five rows and three columns, then what is the minimum possible number of rows of zeros in any row echelon form of C?

41. Describe all possible reduced row echelon forms of

(a) $\begin{bmatrix} a & b & c \\ d & e & f \\ g & h & i \end{bmatrix}$ (b) $\begin{bmatrix} a & b & c & d \\ e & f & g & h \\ i & j & k & l \\ m & n & p & q \end{bmatrix}$

42. Consider the system of equations

$$\begin{aligned} ax + by &= 0 \\ cx + dy &= 0 \\ ex + fy &= 0 \end{aligned}$$

Discuss the relative positions of the lines $ax + by = 0$, $cx + dy = 0$, and $ex + fy = 0$ when the system has only the trivial solution and when it has nontrivial solutions.

Working with Proofs

43. (a) Prove that if $ad - bc \neq 0$, then the reduced row echelon form of

$$\begin{bmatrix} a & b \\ c & d \end{bmatrix} \text{ is } \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

(b) Use the result in part (a) to prove that if $ad - bc \neq 0$, then the linear system

$$\begin{aligned} ax + by &= k \\ cx + dy &= l \end{aligned}$$

has exactly one solution.

True-False Exercises

TF. In parts (a)–(i) determine whether the statement is true or false, and justify your answer.

(a) If a matrix is in reduced row echelon form, then it is also in row echelon form.

(b) If an elementary row operation is applied to a matrix that is in row echelon form, the resulting matrix will still be in row echelon form.

(c) Every matrix has a unique row echelon form.

(d) A homogeneous linear system in n unknowns whose corresponding augmented matrix has a reduced row echelon form with r leading 1's has $n - r$ free variables.

(e) All leading 1's in a matrix in row echelon form must occur in different columns.

(f) If every column of a matrix in row echelon form has a leading 1, then all entries that are not leading 1's are zero.

(g) If a homogeneous linear system of n equations in n unknowns has a corresponding augmented matrix with a reduced row echelon form containing n leading 1's, then the linear system has only the trivial solution.

(h) If the reduced row echelon form of the augmented matrix for a linear system has a row of zeros, then the system must have infinitely many solutions.

(i) If a linear system has more unknowns than equations, then it must have infinitely many solutions.

Working with Technology

T1. Find the reduced row echelon form of the augmented matrix for the linear system:

$$\begin{aligned} 6x_1 + x_2 \qquad\quad + 4x_4 &= -3 \\ -9x_1 + 2x_2 + 3x_3 - 8x_4 &= 1 \\ 7x_1 \qquad - 4x_3 + 5x_4 &= 2 \end{aligned}$$

Use your result to determine whether the system is consistent and, if so, find its solution.

T2. Find values of the constants A, B, C, and D that make the following equation an identity (i.e., true for all values of x).

$$\frac{3x^3 + 4x^2 - 6x}{(x^2 + 2x + 2)(x^2 - 1)} = \frac{Ax + B}{x^2 + 2x + 2} + \frac{C}{x - 1} + \frac{D}{x + 1}$$

[*Hint:* Obtain a common denominator on the right, and then equate corresponding coefficients of the various powers of x in the two numerators. Students of calculus will recognize this as a problem in partial fractions.]

1.3 Matrices and Matrix Operations

Rectangular arrays of real numbers arise in contexts other than as augmented matrices for linear systems. In this section we will begin to study matrices as objects in their own right by defining operations of addition, subtraction, and multiplication on them.

Matrix Notation and Terminology

In Section 1.2 we used rectangular arrays of numbers, called *augmented matrices*, to abbreviate systems of linear equations. However, rectangular arrays of numbers occur in other contexts as well. For example, the following rectangular array with three rows and seven columns might describe the number of hours that a student spent studying three subjects during a certain week:

Trace of a Matrix

DEFINITION 8 If A is a square matrix, then the ***trace of*** A, denoted by $\operatorname{tr}(A)$, is defined to be the sum of the entries on the main diagonal of A. The trace of A is undefined if A is not a square matrix.

EXAMPLE 12 Trace

The following are examples of matrices and their traces.

$$A = \begin{bmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{bmatrix}, \quad B = \begin{bmatrix} -1 & 2 & 7 & 0 \\ 3 & 5 & -8 & 4 \\ 1 & 2 & 7 & -3 \\ 4 & -2 & 1 & 0 \end{bmatrix}$$

$$\operatorname{tr}(A) = a_{11} + a_{22} + a_{33} \qquad \operatorname{tr}(B) = -1 + 5 + 7 + 0 = 11 \blacktriangleleft$$

In the exercises you will have some practice working with the transpose and trace operations.

Exercise Set 1.3

In Exercises 1–2, suppose that A, B, C, D, and E are matrices with the following sizes:

A	B	C	D	E
(4×5)	(4×5)	(5×2)	(4×2)	(5×4)

In each part, determine whether the given matrix expression is defined. For those that are defined, give the size of the resulting matrix.

1. (a) BA (b) AB^T (c) $AC + D$
(d) $E(AC)$ (e) $A - 3E^T$ (f) $E(5B + A)$

2. (a) CD^T (b) DC (c) $BC - 3D$
(d) $D^T(BE)$ (e) $B^TD + ED$ (f) $BA^T + D$

In Exercises 3–6, use the following matrices to compute the indicated expression if it is defined.

$$A = \begin{bmatrix} 3 & 0 \\ -1 & 2 \\ 1 & 1 \end{bmatrix}, \quad B = \begin{bmatrix} 4 & -1 \\ 0 & 2 \end{bmatrix}, \quad C = \begin{bmatrix} 1 & 4 & 2 \\ 3 & 1 & 5 \end{bmatrix},$$

$$D = \begin{bmatrix} 1 & 5 & 2 \\ -1 & 0 & 1 \\ 3 & 2 & 4 \end{bmatrix}, \quad E = \begin{bmatrix} 6 & 1 & 3 \\ -1 & 1 & 2 \\ 4 & 1 & 3 \end{bmatrix}$$

3. (a) $D + E$ (b) $D - E$ (c) $5A$
(d) $-7C$ (e) $2B - C$ (f) $4E - 2D$
(g) $-3(D + 2E)$ (h) $A - A$ (i) $\operatorname{tr}(D)$
(j) $\operatorname{tr}(D - 3E)$ (k) $4\operatorname{tr}(7B)$ (l) $\operatorname{tr}(A)$

4. (a) $2A^T + C$ (b) $D^T - E^T$ (c) $(D - E)^T$
(d) $B^T + 5C^T$ (e) $\frac{1}{2}C^T - \frac{1}{4}A$ (f) $B - B^T$
(g) $2E^T - 3D^T$ (h) $(2E^T - 3D^T)^T$ (i) $(CD)E$
(j) $C(BA)$ (k) $\operatorname{tr}(DE^T)$ (l) $\operatorname{tr}(BC)$

5. (a) AB (b) BA (c) $(3E)D$
(d) $(AB)C$ (e) $A(BC)$ (f) CC^T
(g) $(DA)^T$ (h) $(C^TB)A^T$ (i) $\operatorname{tr}(DD^T)$
(j) $\operatorname{tr}(4E^T - D)$ (k) $\operatorname{tr}(C^TA^T + 2E^T)$ (l) $\operatorname{tr}((EC^T)^TA)$

6. (a) $(2D^T - E)A$ (b) $(4B)C + 2B$
(c) $(-AC)^T + 5D^T$ (d) $(BA^T - 2C)^T$
(e) $B^T(CC^T - A^TA)$ (f) $D^TE^T - (ED)^T$

In Exercises 7–8, use the following matrices and either the row method or the column method, as appropriate, to find the indicated row or column.

$$A = \begin{bmatrix} 3 & -2 & 7 \\ 6 & 5 & 4 \\ 0 & 4 & 9 \end{bmatrix} \quad \text{and} \quad B = \begin{bmatrix} 6 & -2 & 4 \\ 0 & 1 & 3 \\ 7 & 7 & 5 \end{bmatrix}$$

7. (a) the first row of AB (b) the third row of AB
(c) the second column of AB (d) the first column of BA
(e) the third row of AA (f) the third column of AA

8. (a) the first column of AB (b) the third column of BB
(c) the second row of BB (d) the first column of AA
(e) the third column of AB (f) the first row of BA

▶ In Exercises 9–10, use matrices A and B from Exercises 7–8. ◀

9. (a) Express each column vector of AA as a linear combination of the column vectors of A.
(b) Express each column vector of BB as a linear combination of the column vectors of B.

10. (a) Express each column vector of AB as a linear combination of the column vectors of A.
(b) Express each column vector of BA as a linear combination of the column vectors of B.

▶ In each part of Exercises 11–12, find matrices A, $\mathbf{x}$, and $\mathbf{b}$ that express the given linear system as a single matrix equation $A\mathbf{x} = \mathbf{b}$, and write out this matrix equation. ◀

11. (a)
$$\begin{aligned} 2x_1 - 3x_2 + 5x_3 &= 7 \\ 9x_1 - x_2 + x_3 &= -1 \\ x_1 + 5x_2 + 4x_3 &= 0 \end{aligned}$$

(b)
$$\begin{aligned} 4x_1 \qquad - 3x_3 + x_4 &= 1 \\ 5x_1 + x_2 \qquad - 8x_4 &= 3 \\ 2x_1 - 5x_2 + 9x_3 - x_4 &= 0 \\ 3x_2 - x_3 + 7x_4 &= 2 \end{aligned}$$

12. (a)
$$\begin{aligned} x_1 - 2x_2 + 3x_3 &= -3 \\ 2x_1 + x_2 \qquad &= 0 \\ - 3x_2 + 4x_3 &= 1 \\ x_1 \qquad + x_3 &= 5 \end{aligned}$$

(b)
$$\begin{aligned} 3x_1 + 3x_2 + 3x_3 &= -3 \\ -x_1 - 5x_2 - 2x_3 &= 3 \\ - 4x_2 + x_3 &= 0 \end{aligned}$$

▶ In each part of Exercises 13–14, express the matrix equation as a system of linear equations. ◀

13. (a)
$$\begin{bmatrix} 5 & 6 & -7 \\ -1 & -2 & 3 \\ 0 & 4 & -1 \end{bmatrix}\begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 2 \\ 0 \\ 3 \end{bmatrix}$$

(b)
$$\begin{bmatrix} 1 & 1 & 1 \\ 2 & 3 & 0 \\ 5 & -3 & -6 \end{bmatrix}\begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 2 \\ 2 \\ -9 \end{bmatrix}$$

14. (a)
$$\begin{bmatrix} 3 & -1 & 2 \\ 4 & 3 & 7 \\ -2 & 1 & 5 \end{bmatrix}\begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 2 \\ -1 \\ 4 \end{bmatrix}$$

(b)
$$\begin{bmatrix} 3 & -2 & 0 & 1 \\ 5 & 0 & 2 & -2 \\ 3 & 1 & 4 & 7 \\ -2 & 5 & 1 & 6 \end{bmatrix}\begin{bmatrix} w \\ x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}$$

▶ In Exercises 15–16, find all values of k, if any, that satisfy the equation. ◀

15. $$\begin{bmatrix} k & 1 & 1 \end{bmatrix}\begin{bmatrix} 1 & 1 & 0 \\ 1 & 0 & 2 \\ 0 & 2 & -3 \end{bmatrix}\begin{bmatrix} k \\ 1 \\ 1 \end{bmatrix} = 0$$

16. $$\begin{bmatrix} 2 & 2 & k \end{bmatrix}\begin{bmatrix} 1 & 2 & 0 \\ 2 & 0 & 3 \\ 0 & 3 & 1 \end{bmatrix}\begin{bmatrix} 2 \\ 2 \\ k \end{bmatrix} = 0$$

▶ In Exercises 17–20, use the column-row expansion of AB to express this product as a sum of matrices. ◀

17. $A = \begin{bmatrix} 4 & -3 \\ 2 & -1 \end{bmatrix}, \quad B = \begin{bmatrix} 0 & 1 & 2 \\ -2 & 3 & 1 \end{bmatrix}$

18. $A = \begin{bmatrix} 0 & -2 \\ 4 & -3 \end{bmatrix}, \quad B = \begin{bmatrix} 1 & 4 & 1 \\ -3 & 0 & 2 \end{bmatrix}$

19. $A = \begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \end{bmatrix}, \quad B = \begin{bmatrix} 1 & 2 \\ 3 & 4 \\ 5 & 6 \end{bmatrix}$

20. $A = \begin{bmatrix} 0 & 4 & 2 \\ 1 & -2 & 5 \end{bmatrix}, \quad B = \begin{bmatrix} 2 & -1 \\ 4 & 0 \\ 1 & -1 \end{bmatrix}$

21. For the linear system in Example 5 of Section 1.2, express the general solution that we obtained in that example as a linear combination of column vectors that contain only numerical entries. [*Suggestion:* Rewrite the general solution as a single column vector, then write that column vector as a sum of column vectors each of which contains at most one parameter, and then factor out the parameters.]

22. Follow the directions of Exercise 21 for the linear system in Example 6 of Section 1.2.

▶ In Exercises 23–24, solve the matrix equation for a, b, c, and d. ◀

23. $$\begin{bmatrix} a & 3 \\ -1 & a+b \end{bmatrix} = \begin{bmatrix} 4 & d-2c \\ d+2c & -2 \end{bmatrix}$$

24. $$\begin{bmatrix} a-b & b+a \\ 3d+c & 2d-c \end{bmatrix} = \begin{bmatrix} 8 & 1 \\ 7 & 6 \end{bmatrix}$$

25. (a) Show that if A has a row of zeros and B is any matrix for which AB is defined, then AB also has a row of zeros.
(b) Find a similar result involving a column of zeros.

26. In each part, find a 6×6 matrix $[a_{ij}]$ that satisfies the stated condition. Make your answers as general as possible by using letters rather than specific numbers for the nonzero entries.
(a) $a_{ij} = 0$ if $i \neq j$ (b) $a_{ij} = 0$ if $i > j$
(c) $a_{ij} = 0$ if $i < j$ (d) $a_{ij} = 0$ if $|i - j| > 1$

In Exercises 27–28, how many 3×3 matrices A can you find for which the equation is satisfied for all choices of x, y, and z?

27. $A\begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} x+y \\ x-y \\ 0 \end{bmatrix}$

28. $A\begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} xy \\ 0 \\ 0 \end{bmatrix}$

29. A matrix B is said to be a ***square root*** of a matrix A if $BB = A$.

(a) Find two square roots of $A = \begin{bmatrix} 2 & 2 \\ 2 & 2 \end{bmatrix}$.

(b) How many different square roots can you find of $A = \begin{bmatrix} 5 & 0 \\ 0 & 9 \end{bmatrix}$?

(c) Do you think that every 2×2 matrix has at least one square root? Explain your reasoning.

30. Let 0 denote a 2×2 matrix, each of whose entries is zero.

(a) Is there a 2×2 matrix A such that $A \neq 0$ and $AA = 0$? Justify your answer.

(b) Is there a 2×2 matrix A such that $A \neq 0$ and $AA = A$? Justify your answer.

31. Establish Formula (11) by using Formula (5) to show that

$$(AB)_{ij} = (\mathbf{c}_1\mathbf{r}_1 + \mathbf{c}_2\mathbf{r}_2 + \cdots + \mathbf{c}_r\mathbf{r}_r)_{ij}$$

32. Find a 4×4 matrix $A = [a_{ij}]$ whose entries satisfy the stated condition.

(a) $a_{ij} = i + j$

(b) $a_{ij} = i^{j-1}$

(c) $a_{ij} = \begin{cases} 1 & \text{if } |i-j| > 1 \\ -1 & \text{if } |i-j| \le 1 \end{cases}$

33. Suppose that type I items cost $1 each, type II items cost $2 each, and type III items cost $3 each. Also, suppose that the accompanying table describes the number of items of each type purchased during the first four months of the year.

Table Ex-33

	Type I	Type II	Type III
Jan.	3	4	3
Feb.	5	6	0
Mar.	2	9	4
Apr.	1	1	7

What information is represented by the following product?

$$\begin{bmatrix} 3 & 4 & 3 \\ 5 & 6 & 0 \\ 2 & 9 & 4 \\ 1 & 1 & 7 \end{bmatrix}\begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}$$

34. The accompanying table shows a record of May and June unit sales for a clothing store. Let M denote the 4×3 matrix of May sales and J the 4×3 matrix of June sales.

(a) What does the matrix $M + J$ represent?

(b) What does the matrix $M - J$ represent?

(c) Find a column vector $\mathbf{x}$ for which $M\mathbf{x}$ provides a list of the number of shirts, jeans, suits, and raincoats sold in May.

(d) Find a row vector $\mathbf{y}$ for which $\mathbf{y}M$ provides a list of the number of small, medium, and large items sold in May.

(e) Using the matrices $\mathbf{x}$ and $\mathbf{y}$ that you found in parts (c) and (d), what does $\mathbf{y}M\mathbf{x}$ represent?

Table Ex-34

May Sales

	Small	Medium	Large
Shirts	45	60	75
Jeans	30	30	40
Suits	12	65	45
Raincoats	15	40	35

June Sales

	Small	Medium	Large
Shirts	30	33	40
Jeans	21	23	25
Suits	9	12	11
Raincoats	8	10	9

Working with Proofs

35. Prove: If A and B are $n \times n$ matrices, then

$$\text{tr}(A + B) = \text{tr}(A) + \text{tr}(B)$$

36. (a) Prove: If AB and BA are both defined, then AB and BA are square matrices.

(b) Prove: If A is an $m \times n$ matrix and $A(BA)$ is defined, then B is an $n \times m$ matrix.

True-False Exercises

TF. In parts (a)–(o) determine whether the statement is true or false, and justify your answer.

(a) The matrix $\begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \end{bmatrix}$ has no main diagonal.

(b) An $m \times n$ matrix has m column vectors and n row vectors.

(c) If A and B are 2×2 matrices, then $AB = BA$.

(d) The ith row vector of a matrix product AB can be computed by multiplying A by the ith row vector of B.

(e) For every matrix A, it is true that $(A^T)^T = A$.

(f) If A and B are square matrices of the same order, then
$$\text{tr}(AB) = \text{tr}(A)\text{tr}(B)$$

(g) If A and B are square matrices of the same order, then
$$(AB)^T = A^T B^T$$

(h) For every square matrix A, it is true that $\text{tr}(A^T) = \text{tr}(A)$.

(i) If A is a 6×4 matrix and B is an $m \times n$ matrix such that $B^T A^T$ is a 2×6 matrix, then $m = 4$ and $n = 2$.

(j) If A is an $n \times n$ matrix and c is a scalar, then $\text{tr}(cA) = c\,\text{tr}(A)$.

(k) If A, B, and C are matrices of the same size such that $A - C = B - C$, then $A = B$.

(l) If A, B, and C are square matrices of the same order such that $AC = BC$, then $A = B$.

(m) If $AB + BA$ is defined, then A and B are square matrices of the same size.

(n) If B has a column of zeros, then so does AB if this product is defined.

(o) If B has a column of zeros, then so does BA if this product is defined.

Working with Technology

T1. (a) Compute the product AB of the matrices in Example 5, and compare your answer to that in the text.

(b) Use your technology utility to extract the columns of A and the rows of B, and then calculate the product AB by a column-row expansion.

T2. Suppose that a manufacturer uses Type I items at \$1.35 each, Type II items at \$2.15 each, and Type III items at \$3.95 each. Suppose also that the accompanying table describes the purchases of those items (in thousands of units) for the first quarter of the year. Write down a matrix product, the computation of which produces a matrix that lists the manufacturer's expenditure in each month of the first quarter. Compute that product.

	Type I	Type II	Type III
Jan.	3.1	4.2	3.5
Feb.	5.1	6.8	0
Mar.	2.2	9.5	4.0
Apr.	1.0	1.0	7.4

1.4 Inverses; Algebraic Properties of Matrices

In this section we will discuss some of the algebraic properties of matrix operations. We will see that many of the basic rules of arithmetic for real numbers hold for matrices, but we will also see that some do not.

Properties of Matrix Addition and Scalar Multiplication

The following theorem lists the basic algebraic properties of the matrix operations.

THEOREM 1.4.1 Properties of Matrix Arithmetic

Assuming that the sizes of the matrices are such that the indicated operations can be performed, the following rules of matrix arithmetic are valid.

(a) $A + B = B + A$ **[Commutative law for matrix addition]**

(b) $A + (B + C) = (A + B) + C$ **[Associative law for matrix addition]**

(c) $A(BC) = (AB)C$ **[Associative law for matrix multiplication]**

(d) $A(B + C) = AB + AC$ **[Left distributive law]**

(e) $(B + C)A = BA + CA$ **[Right distributive law]**

(f) $A(B - C) = AB - AC$

(g) $(B - C)A = BA - CA$

(h) $a(B + C) = aB + aC$

(i) $a(B - C) = aB - aC$

(j) $(a + b)C = aC + bC$

(k) $(a - b)C = aC - bC$

(l) $a(bC) = (ab)C$

(m) $a(BC) = (aB)C = B(aC)$

The following theorem establishes a relationship between the inverse of a matrix and the inverse of its transpose.

THEOREM 1.4.9 *If A is an invertible matrix, then A^T is also invertible and*

$$(A^T)^{-1} = (A^{-1})^T$$

Proof We can establish the invertibility and obtain the formula at the same time by showing that

$$A^T(A^{-1})^T = (A^{-1})^T A^T = I$$

But from part (*e*) of Theorem 1.4.8 and the fact that $I^T = I$, we have

$$A^T(A^{-1})^T = (A^{-1}A)^T = I^T = I$$
$$(A^{-1})^T A^T = (AA^{-1})^T = I^T = I$$

which completes the proof. ◀

▶ **EXAMPLE 13 Inverse of a Transpose**

Consider a general 2 × 2 invertible matrix and its transpose:

$$A = \begin{bmatrix} a & b \\ c & d \end{bmatrix} \quad \text{and} \quad A^T = \begin{bmatrix} a & c \\ b & d \end{bmatrix}$$

Since A is invertible, its determinant $ad - bc$ is nonzero. But the determinant of A^T is also $ad - bc$ (verify), so A^T is also invertible. It follows from Theorem 1.4.5 that

$$(A^T)^{-1} = \begin{bmatrix} \dfrac{d}{ad - bc} & -\dfrac{c}{ad - bc} \\ -\dfrac{b}{ad - bc} & \dfrac{a}{ad - bc} \end{bmatrix}$$

which is the same matrix that results if A^{-1} is transposed (verify). Thus,

$$(A^T)^{-1} = (A^{-1})^T$$

as guaranteed by Theorem 1.4.9. ◀

Exercise Set 1.4

▶ In Exercises 1–2, verify that the following matrices and scalars satisfy the stated properties of Theorem 1.4.1.

$$A = \begin{bmatrix} 3 & -1 \\ 2 & 4 \end{bmatrix}, \quad B = \begin{bmatrix} 0 & 2 \\ 1 & -4 \end{bmatrix},$$

$$C = \begin{bmatrix} 4 & 1 \\ -3 & -2 \end{bmatrix}, \quad a = 4, \quad b = -7 \text{ ◀}$$

1. (a) The associative law for matrix addition.
   (b) The associative law for matrix multiplication.
   (c) The left distributive law.
   (d) $(a + b)C = aC + bC$

2. (a) $a(BC) = (aB)C = B(aC)$
   (b) $A(B - C) = AB - AC$ (c) $(B + C)A = BA + CA$
   (d) $a(bC) = (ab)C$

▶ In Exercises 3–4, verify that the matrices and scalars in Exercise 1 satisfy the stated properties. ◀

3. (a) $(A^T)^T = A$ (b) $(AB)^T = B^TA^T$

4. (a) $(A + B)^T = A^T + B^T$ (b) $(aC)^T = aC^T$

▶ In Exercises 5–8, use Theorem 1.4.5 to compute the inverse of the matrix. ◀

5. $A = \begin{bmatrix} 2 & -3 \\ 4 & 4 \end{bmatrix}$

6. $B = \begin{bmatrix} 3 & 1 \\ 5 & 2 \end{bmatrix}$

7. $C = \begin{bmatrix} 2 & 0 \\ 0 & 3 \end{bmatrix}$

8. $D = \begin{bmatrix} 6 & 4 \\ -2 & -1 \end{bmatrix}$

9. Find the inverse of

$$\begin{bmatrix} \frac{1}{2}(e^x + e^{-x}) & \frac{1}{2}(e^x - e^{-x}) \\ \frac{1}{2}(e^x - e^{-x}) & \frac{1}{2}(e^x + e^{-x}) \end{bmatrix}$$

10. Find the inverse of

$$\begin{bmatrix} \cos\theta & \sin\theta \\ -\sin\theta & \cos\theta \end{bmatrix}$$

In Exercises 11–14, verify that the equations are valid for the matrices in Exercises 5–8.

11. $(A^T)^{-1} = (A^{-1})^T$

12. $(A^{-1})^{-1} = A$

13. $(ABC)^{-1} = C^{-1}B^{-1}A^{-1}$

14. $(ABC)^T = C^TB^TA^T$

In Exercises 15–18, use the given information to find A.

15. $(7A)^{-1} = \begin{bmatrix} -3 & 7 \\ 1 & -2 \end{bmatrix}$

16. $(5A^T)^{-1} = \begin{bmatrix} -3 & -1 \\ 5 & 2 \end{bmatrix}$

17. $(I + 2A)^{-1} = \begin{bmatrix} -1 & 2 \\ 4 & 5 \end{bmatrix}$

18. $A^{-1} = \begin{bmatrix} 2 & -1 \\ 3 & 5 \end{bmatrix}$

In Exercises 19–20, compute the following using the given matrix A.

(a) A^3 (b) A^{-3} (c) $A^2 - 2A + I$

19. $A = \begin{bmatrix} 3 & 1 \\ 2 & 1 \end{bmatrix}$

20. $A = \begin{bmatrix} 2 & 0 \\ 4 & 1 \end{bmatrix}$

In Exercises 21–22, compute $p(A)$ for the given matrix A and the following polynomials.

(a) $p(x) = x - 2$

(b) $p(x) = 2x^2 - x + 1$

(c) $p(x) = x^3 - 2x + 1$

21. $A = \begin{bmatrix} 3 & 1 \\ 2 & 1 \end{bmatrix}$

22. $A = \begin{bmatrix} 2 & 0 \\ 4 & 1 \end{bmatrix}$

In Exercises 23–24, let

$$A = \begin{bmatrix} a & b \\ c & d \end{bmatrix}, \quad B = \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}, \quad C = \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix}$$

23. Find all values of a, b, c, and d (if any) for which the matrices A and B commute.

24. Find all values of a, b, c, and d (if any) for which the matrices A and C commute.

In Exercises 25–28, use the method of Example 8 to find the unique solution of the given linear system.

25. $3x_1 - 2x_2 = -1$
$4x_1 + 5x_2 = 3$

26. $-x_1 + 5x_2 = 4$
$-x_1 - 3x_2 = 1$

27. $6x_1 + x_2 = 0$
$4x_1 - 3x_2 = -2$

28. $2x_1 - 2x_2 = 4$
$x_1 + 4x_2 = 4$

If a polynomial $p(x)$ can be factored as a product of lower degree polynomials, say

$$p(x) = p_1(x)p_2(x)$$

and if A is a square matrix, then it can be proved that

$$p(A) = p_1(A)p_2(A)$$

In Exercises 29–30, verify this statement for the stated matrix A and polynomials

$$p(x) = x^2 - 9, \quad p_1(x) = x + 3, \quad p_2(x) = x - 3$$

29. The matrix A in Exercise 21.

30. An arbitrary square matrix A.

31. (a) Give an example of two 2×2 matrices such that

$$(A + B)(A - B) \neq A^2 - B^2$$

(b) State a valid formula for multiplying out

$$(A + B)(A - B)$$

(c) What condition can you impose on A and B that will allow you to write $(A + B)(A - B) = A^2 - B^2$?

32. The numerical equation $a^2 = 1$ has exactly two solutions. Find at least eight solutions of the matrix equation $A^2 = I_3$. [*Hint:* Look for solutions in which all entries off the main diagonal are zero.]

33. (a) Show that if a square matrix A satisfies the equation $A^2 + 2A + I = 0$, then A must be invertible. What is the inverse?

(b) Show that if $p(x)$ is a polynomial with a nonzero constant term, and if A is a square matrix for which $p(A) = 0$, then A is invertible.

34. Is it possible for A^3 to be an identity matrix without A being invertible? Explain.

35. Can a matrix with a row of zeros or a column of zeros have an inverse? Explain.

36. Can a matrix with two identical rows or two identical columns have an inverse? Explain.

► In Exercises 37–38, determine whether A is invertible, and if so, find the inverse. [*Hint:* Solve $AX = I$ for X by equating corresponding entries on the two sides.] ◄

37. $A = \begin{bmatrix} 1 & 0 & 1 \\ 1 & 1 & 0 \\ 0 & 1 & 1 \end{bmatrix}$ 38. $A = \begin{bmatrix} 1 & 1 & 1 \\ 1 & 0 & 0 \\ 0 & 1 & 1 \end{bmatrix}$

► In Exercises 39–40, simplify the expression assuming that A, B, C, and D are invertible. ◄

39. $(AB)^{-1}(AC^{-1})(D^{-1}C^{-1})^{-1}D^{-1}$

40. $(AC^{-1})^{-1}(AC^{-1})(AC^{-1})^{-1}AD^{-1}$

41. Show that if R is a $1 \times n$ matrix and C is an $n \times 1$ matrix, then $RC = \text{tr}(CR)$.

42. If A is a square matrix and n is a positive integer, is it true that $(A^n)^T = (A^T)^n$? Justify your answer.

43. (a) Show that if A is invertible and $AB = AC$, then $B = C$.
 (b) Explain why part (a) and Example 3 do not contradict one another.

44. Show that if A is invertible and k is any nonzero scalar, then $(kA)^n = k^nA^n$ for all integer values of n.

45. (a) Show that if A, B, and $A + B$ are invertible matrices with the same size, then

$$A(A^{-1} + B^{-1})B(A + B)^{-1} = I$$

 (b) What does the result in part (a) tell you about the matrix $A^{-1} + B^{-1}$?

46. A square matrix A is said to be ***idempotent*** if $A^2 = A$.
 (a) Show that if A is idempotent, then so is $I - A$.
 (b) Show that if A is idempotent, then $2A - I$ is invertible and is its own inverse.

47. Show that if A is a square matrix such that $A^k = 0$ for some positive integer k, then the matrix $I - A$ is invertible and

$$(I - A)^{-1} = I + A + A^2 + \cdots + A^{k-1}$$

48. Show that the matrix

$$A = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$$

satisfies the equation

$$A^2 - (a + d)A + (ad - bc)I = 0$$

49. Assuming that all matrices are $n \times n$ and invertible, solve for D.

$$C^TB^{-1}A^2BAC^{-1}DA^{-2}B^TC^{-2} = C^T$$

50. Assuming that all matrices are $n \times n$ and invertible, solve for D.

$$ABC^TDBA^TC = AB^T$$

Working with Proofs

► In Exercises 51–58, prove the stated result. ◄

51. Theorem 1.4.1(*a*)

52. Theorem 1.4.1(*b*)

53. Theorem 1.4.1(*f*)

54. Theorem 1.4.1(*c*)

55. Theorem 1.4.2(*c*)

56. Theorem 1.4.2(*b*)

57. Theorem 1.4.8(*d*)

58. Theorem 1.4.8(*e*)

True-False Exercises

TF. In parts (a)–(k) determine whether the statement is true or false, and justify your answer.

(a) Two $n \times n$ matrices, A and B, are inverses of one another if and only if $AB = BA = 0$.

(b) For all square matrices A and B of the same size, it is true that $(A + B)^2 = A^2 + 2AB + B^2$.

(c) For all square matrices A and B of the same size, it is true that $A^2 - B^2 = (A - B)(A + B)$.

(d) If A and B are invertible matrices of the same size, then AB is invertible and $(AB)^{-1} = A^{-1}B^{-1}$.

(e) If A and B are matrices such that AB is defined, then it is true that $(AB)^T = A^TB^T$.

(f) The matrix

$$A = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$$

is invertible if and only if $ad - bc \neq 0$.

(g) If A and B are matrices of the same size and k is a constant, then $(kA + B)^T = kA^T + B^T$.

(h) If A is an invertible matrix, then so is A^T.

(i) If $p(x) = a_0 + a_1x + a_2x^2 + \cdots + a_mx^m$ and I is an identity matrix, then $p(I) = a_0 + a_1 + a_2 + \cdots + a_m$.

(j) A square matrix containing a row or column of zeros cannot be invertible.

(k) The sum of two invertible matrices of the same size must be invertible.

Working with Technology

T1. Let A be the matrix

$$A = \begin{bmatrix} 0 & \frac{1}{2} & \frac{1}{3} \\ \frac{1}{4} & 0 & \frac{1}{5} \\ \frac{1}{6} & \frac{1}{7} & 0 \end{bmatrix}$$

Discuss the behavior of A^k as k increases indefinitely, that is, as $k \to \infty$.

T2. In each part use your technology utility to make a conjecture about the form of A^n for positive integer powers of n.

(a) $A = \begin{bmatrix} a & 1 \\ 0 & a \end{bmatrix}$ (b) $A = \begin{bmatrix} \cos\theta & \sin\theta \\ -\sin\theta & \cos\theta \end{bmatrix}$

T3. The ***Fibonacci sequence*** (named for the Italian mathematician Leonardo Fibonacci 1170–1250) is

$$0, 1, 1, 2, 3, 5, 8, 13, 21, 34, 55, 89, 144, \ldots$$

the terms of which are commonly denoted as

$$F_0, F_1, F_2, F_3, \ldots, F_n, \ldots$$

After the initial terms $F_0 = 0$ and $F_1 = 1$, each term is the sum of the previous two; that is,

$$F_n = F_{n-1} + F_{n-2}$$

Confirm that if

$$Q = \begin{bmatrix} F_2 & F_1 \\ F_1 & F_0 \end{bmatrix} = \begin{bmatrix} 1 & 1 \\ 1 & 0 \end{bmatrix}$$

then

$$Q^n = \begin{bmatrix} F_{n+1} & F_n \\ F_n & F_0 \end{bmatrix}$$

1.5 Elementary Matrices and a Method for Finding A^{-1}

In this section we will develop an algorithm for finding the inverse of a matrix, and we will discuss some of the basic properties of invertible matrices.

In Section 1.1 we defined three elementary row operations on a matrix A:

1. Multiply a row by a nonzero constant c.
2. Interchange two rows.
3. Add a constant c times one row to another.

It should be evident that if we let B be the matrix that results from A by performing one of the operations in this list, then the matrix A can be recovered from B by performing the corresponding operation in the following list:

1. Multiply the same row by $1/c$.
2. Interchange the same two rows.
3. If B resulted by adding c times row r_i of A to row r_j, then add $-c$ times r_j to r_i.

It follows that if B is obtained from A by performing a sequence of elementary row operations, then there is a second sequence of elementary row operations, which when applied to B recovers A (Exercise 33). Accordingly, we make the following definition.

DEFINITION 1 Matrices A and B are said to be ***row equivalent*** if either (hence each) can be obtained from the other by a sequence of elementary row operations.

Our next goal is to show how matrix multiplication can be used to carry out an elementary row operation.

DEFINITION 2 A matrix E is called an ***elementary matrix*** if it can be obtained from an identity matrix by performing a *single* elementary row operation.

Applying the procedure of Example 4 yields

$$\left[\begin{array}{rrr|rrr} 1 & 6 & 4 & 1 & 0 & 0 \\ 2 & 4 & -1 & 0 & 1 & 0 \\ -1 & 2 & 5 & 0 & 0 & 1 \end{array}\right]$$

$$\left[\begin{array}{rrr|rrr} 1 & 6 & 4 & 1 & 0 & 0 \\ 0 & -8 & -9 & -2 & 1 & 0 \\ 0 & 8 & 9 & 1 & 0 & 1 \end{array}\right]$$ ← We added −2 times the first row to the second and added the first row to the third.

$$\left[\begin{array}{rrr|rrr} 1 & 6 & 4 & 1 & 0 & 0 \\ 0 & -8 & -9 & -2 & 1 & 0 \\ 0 & 0 & 0 & -1 & 1 & 1 \end{array}\right]$$ ← We added the second row to the third.

Since we have obtained a row of zeros on the left side, A is not invertible.

▶ EXAMPLE 6 Analyzing Homogeneous Systems

Use Theorem 1.5.3 to determine whether the given homogeneous system has nontrivial solutions.

(a)
$$\begin{aligned} x_1 + 2x_2 + 3x_3 &= 0 \\ 2x_1 + 5x_2 + 3x_3 &= 0 \\ x_1 + 8x_3 &= 0 \end{aligned}$$

(b)
$$\begin{aligned} x_1 + 6x_2 + 4x_3 &= 0 \\ 2x_1 + 4x_2 - x_3 &= 0 \\ -x_1 + 2x_2 + 5x_3 &= 0 \end{aligned}$$

Solution From parts (*a*) and (*b*) of Theorem 1.5.3 a homogeneous linear system has only the trivial solution if and only if its coefficient matrix is invertible. From Examples 4 and 5 the coefficient matrix of system (a) is invertible and that of system (b) is not. Thus, system (a) has only the trivial solution while system (b) has nontrivial solutions. ◀

Exercise Set 1.5

▶ In Exercises 1–2, determine whether the given matrix is elementary. ◀

1. (a) $\begin{bmatrix} 1 & 0 \\ -5 & 1 \end{bmatrix}$ (b) $\begin{bmatrix} -5 & 1 \\ 1 & 0 \end{bmatrix}$

(c) $\begin{bmatrix} 1 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix}$ (d) $\begin{bmatrix} 2 & 0 & 0 & 2 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$

2. (a) $\begin{bmatrix} 1 & 0 \\ 0 & \sqrt{3} \end{bmatrix}$ (b) $\begin{bmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ 1 & 0 & 0 \end{bmatrix}$

(c) $\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 9 \\ 0 & 0 & 1 \end{bmatrix}$ (d) $\begin{bmatrix} -1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{bmatrix}$

▶ In Exercises 3–4, find a row operation and the corresponding elementary matrix that will restore the given elementary matrix to the identity matrix. ◀

3. (a) $\begin{bmatrix} 1 & -3 \\ 0 & 1 \end{bmatrix}$ (b) $\begin{bmatrix} -7 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$

(c) $\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ -5 & 0 & 1 \end{bmatrix}$ (d) $\begin{bmatrix} 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 \\ 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$

4. (a) $\begin{bmatrix} 1 & 0 \\ -3 & 1 \end{bmatrix}$ (b) $\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 3 \end{bmatrix}$

(c) $\begin{bmatrix} 0 & 0 & 0 & 1 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 1 & 0 & 0 & 0 \end{bmatrix}$ (d) $\begin{bmatrix} 1 & 0 & -\frac{1}{7} & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$

In Exercises 5–6 an elementary matrix E and a matrix A are given. Identify the row operation corresponding to E and verify that the product EA results from applying the row operation to A.

5. (a) $E = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}, \quad A = \begin{bmatrix} -1 & -2 & 5 & -1 \\ 3 & -6 & -6 & -6 \end{bmatrix}$

(b) $E = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & -3 & 1 \end{bmatrix}, \quad A = \begin{bmatrix} 2 & -1 & 0 & -4 & -4 \\ 1 & -3 & -1 & 5 & 3 \\ 2 & 0 & 1 & 3 & -1 \end{bmatrix}$

(c) $E = \begin{bmatrix} 1 & 0 & 4 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}, \quad A = \begin{bmatrix} 1 & 4 \\ 2 & 5 \\ 3 & 6 \end{bmatrix}$

6. (a) $E = \begin{bmatrix} -6 & 0 \\ 0 & 1 \end{bmatrix}, \quad A = \begin{bmatrix} -1 & -2 & 5 & -1 \\ 3 & -6 & -6 & -6 \end{bmatrix}$

(b) $E = \begin{bmatrix} 1 & 0 & 0 \\ -4 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}, \quad A = \begin{bmatrix} 2 & -1 & 0 & -4 & -4 \\ 1 & -3 & -1 & 5 & 3 \\ 2 & 0 & 1 & 3 & -1 \end{bmatrix}$

(c) $E = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 5 & 0 \\ 0 & 0 & 1 \end{bmatrix}, \quad A = \begin{bmatrix} 1 & 4 \\ 2 & 5 \\ 3 & 6 \end{bmatrix}$

In Exercises 7–8, use the following matrices and find an elementary matrix E that satisfies the stated equation.

$$A = \begin{bmatrix} 3 & 4 & 1 \\ 2 & -7 & -1 \\ 8 & 1 & 5 \end{bmatrix}, \quad B = \begin{bmatrix} 8 & 1 & 5 \\ 2 & -7 & -1 \\ 3 & 4 & 1 \end{bmatrix}$$

$$C = \begin{bmatrix} 3 & 4 & 1 \\ 2 & -7 & -1 \\ 2 & -7 & 3 \end{bmatrix}, \quad D = \begin{bmatrix} 8 & 1 & 5 \\ -6 & 21 & 3 \\ 3 & 4 & 1 \end{bmatrix}$$

$$F = \begin{bmatrix} 8 & 1 & 5 \\ 8 & 1 & 1 \\ 3 & 4 & 1 \end{bmatrix}$$

7. (a) $EA = B$ (b) $EB = A$

(c) $EA = C$ (d) $EC = A$

8. (a) $EB = D$ (b) $ED = B$

(c) $EB = F$ (d) $EF = B$

In Exercises 9–10, first use Theorem 1.4.5 and then use the inversion algorithm to find A^{-1}, if it exists.

9. (a) $A = \begin{bmatrix} 1 & 4 \\ 2 & 7 \end{bmatrix}$ (b) $A = \begin{bmatrix} 2 & -4 \\ -4 & 8 \end{bmatrix}$

10. (a) $A = \begin{bmatrix} 1 & -5 \\ 3 & -16 \end{bmatrix}$ (b) $A = \begin{bmatrix} 6 & 4 \\ -3 & -2 \end{bmatrix}$

In Exercises 11–12, use the inversion algorithm to find the inverse of the matrix (if the inverse exists).

11. (a) $\begin{bmatrix} 1 & 2 & 3 \\ 2 & 5 & 3 \\ 1 & 0 & 8 \end{bmatrix}$ (b) $\begin{bmatrix} -1 & 3 & -4 \\ 2 & 4 & 1 \\ -4 & 2 & -9 \end{bmatrix}$

12. (a) $\begin{bmatrix} \frac{1}{5} & \frac{1}{5} & -\frac{2}{5} \\ \frac{1}{5} & \frac{1}{5} & \frac{1}{10} \\ \frac{1}{5} & -\frac{4}{5} & \frac{1}{10} \end{bmatrix}$ (b) $\begin{bmatrix} \frac{1}{5} & \frac{1}{5} & -\frac{2}{5} \\ \frac{2}{5} & -\frac{3}{5} & -\frac{3}{10} \\ \frac{1}{5} & -\frac{4}{5} & \frac{1}{10} \end{bmatrix}$

In Exercises 13–18, use the inversion algorithm to find the inverse of the matrix (if the inverse exists).

13. $\begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & 1 \\ 1 & 1 & 0 \end{bmatrix}$

14. $\begin{bmatrix} \sqrt{2} & 3\sqrt{2} & 0 \\ -4\sqrt{2} & \sqrt{2} & 0 \\ 0 & 0 & 1 \end{bmatrix}$

15. $\begin{bmatrix} 2 & 6 & 6 \\ 2 & 7 & 6 \\ 2 & 7 & 7 \end{bmatrix}$

16. $\begin{bmatrix} 1 & 0 & 0 & 0 \\ 1 & 3 & 0 & 0 \\ 1 & 3 & 5 & 0 \\ 1 & 3 & 5 & 7 \end{bmatrix}$

17. $\begin{bmatrix} 2 & -4 & 0 & 0 \\ 1 & 2 & 12 & 0 \\ 0 & 0 & 2 & 0 \\ 0 & -1 & -4 & -5 \end{bmatrix}$

18. $\begin{bmatrix} 0 & 0 & 2 & 0 \\ 1 & 0 & 0 & 1 \\ 0 & -1 & 3 & 0 \\ 2 & 1 & 5 & -3 \end{bmatrix}$

In Exercises 19–20, find the inverse of each of the following 4×4 matrices, where k_1, k_2, k_3, k_4, and k are all nonzero.

19. (a) $\begin{bmatrix} k_1 & 0 & 0 & 0 \\ 0 & k_2 & 0 & 0 \\ 0 & 0 & k_3 & 0 \\ 0 & 0 & 0 & k_4 \end{bmatrix}$ (b) $\begin{bmatrix} k & 1 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & k & 1 \\ 0 & 0 & 0 & 1 \end{bmatrix}$

20. (a) $\begin{bmatrix} 0 & 0 & 0 & k_1 \\ 0 & 0 & k_2 & 0 \\ 0 & k_3 & 0 & 0 \\ k_4 & 0 & 0 & 0 \end{bmatrix}$ (b) $\begin{bmatrix} k & 0 & 0 & 0 \\ 1 & k & 0 & 0 \\ 0 & 1 & k & 0 \\ 0 & 0 & 1 & k \end{bmatrix}$

In Exercises 21–22, find all values of c, if any, for which the given matrix is invertible.

21. $\begin{bmatrix} c & c & c \\ 1 & c & c \\ 1 & 1 & c \end{bmatrix}$

22. $\begin{bmatrix} c & 1 & 0 \\ 1 & c & 1 \\ 0 & 1 & c \end{bmatrix}$

▶ In Exercises 23–26, express the matrix and its inverse as products of elementary matrices. ◀

23. $\begin{bmatrix} -3 & 1 \\ 2 & 2 \end{bmatrix}$

24. $\begin{bmatrix} 1 & 0 \\ -5 & 2 \end{bmatrix}$

25. $\begin{bmatrix} 1 & 0 & -2 \\ 0 & 4 & 3 \\ 0 & 0 & 1 \end{bmatrix}$

26. $\begin{bmatrix} 1 & 1 & 0 \\ 1 & 1 & 1 \\ 0 & 1 & 1 \end{bmatrix}$

▶ In Exercises 27–28, show that the matrices A and B are row equivalent by finding a sequence of elementary row operations that produces B from A, and then use that result to find a matrix C such that $CA = B$. ◀

27. $A = \begin{bmatrix} 1 & 2 & 3 \\ 1 & 4 & 1 \\ 2 & 1 & 9 \end{bmatrix}, \quad B = \begin{bmatrix} 1 & 0 & 5 \\ 0 & 2 & -2 \\ 1 & 1 & 4 \end{bmatrix}$

28. $A = \begin{bmatrix} 2 & 1 & 0 \\ -1 & 1 & 0 \\ 3 & 0 & -1 \end{bmatrix}, \quad B = \begin{bmatrix} 6 & 9 & 4 \\ -5 & -1 & 0 \\ -1 & -2 & -1 \end{bmatrix}$

29. Show that if

$$A = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ a & b & c \end{bmatrix}$$

is an elementary matrix, then at least one entry in the third row must be zero.

30. Show that

$$A = \begin{bmatrix} 0 & a & 0 & 0 & 0 \\ b & 0 & c & 0 & 0 \\ 0 & d & 0 & e & 0 \\ 0 & 0 & f & 0 & g \\ 0 & 0 & 0 & h & 0 \end{bmatrix}$$

is not invertible for any values of the entries.

Working with Proofs

31. Prove that if A and B are $m \times n$ matrices, then A and B are row equivalent if and only if A and B have the same reduced row echelon form.

32. Prove that if A is an invertible matrix and B is row equivalent to A, then B is also invertible.

33. Prove that if B is obtained from A by performing a sequence of elementary row operations, then there is a second sequence of elementary row operations, which when applied to B recovers A.

True-False Exercises

TF. In parts (a)–(g) determine whether the statement is true or false, and justify your answer.

(a) The product of two elementary matrices of the same size must be an elementary matrix.

(b) Every elementary matrix is invertible.

(c) If A and B are row equivalent, and if B and C are row equivalent, then A and C are row equivalent.

(d) If A is an $n \times n$ matrix that is not invertible, then the linear system $A\mathbf{x} = \mathbf{0}$ has infinitely many solutions.

(e) If A is an $n \times n$ matrix that is not invertible, then the matrix obtained by interchanging two rows of A cannot be invertible.

(f) If A is invertible and a multiple of the first row of A is added to the second row, then the resulting matrix is invertible.

(g) An expression of an invertible matrix A as a product of elementary matrices is unique.

Working with Technology

T1. It can be proved that if the partitioned matrix

$$\begin{bmatrix} A & B \\ C & D \end{bmatrix}$$

is invertible, then its inverse is

$$\begin{bmatrix} A^{-1} + A^{-1}B(D - CA^{-1}B)^{-1}CA^{-1} & -A^{-1}B(D - CA^{-1}B)^{-1} \\ -(D - CA^{-1}B)^{-1}CA^{-1} & (D - CA^{-1}B)^{-1} \end{bmatrix}$$

provided that all of the inverses on the right side exist. Use this result to find the inverse of the matrix

$$\begin{bmatrix} 1 & 2 & 1 & 0 \\ 0 & -1 & 0 & 1 \\ 0 & 0 & 2 & 0 \\ 0 & 0 & 3 & 3 \end{bmatrix}$$

Solution The augmented matrix is

$$\begin{bmatrix} 1 & 2 & 3 & b_1 \\ 2 & 5 & 3 & b_2 \\ 1 & 0 & 8 & b_3 \end{bmatrix}$$

Reducing this to reduced row echelon form yields (verify)

$$\begin{bmatrix} 1 & 0 & 0 & -40b_1 + 16b_2 + 9b_3 \\ 0 & 1 & 0 & 13b_1 - 5b_2 - 3b_3 \\ 0 & 0 & 1 & 5b_1 - 2b_2 - b_3 \end{bmatrix} \tag{2}$$

What does the result in Example 4 tell you about the coefficient matrix of the system?

In this case there are no restrictions on b_1, b_2, and b_3, so the system has the unique solution

$$x_1 = -40b_1 + 16b_2 + 9b_3, \quad x_2 = 13b_1 - 5b_2 - 3b_3, \quad x_3 = 5b_1 - 2b_2 - b_3 \tag{3}$$

for all values of b_1, b_2, and b_3. ◀

Exercise Set 1.6

▶ In Exercises 1–8, solve the system by inverting the coefficient matrix and using Theorem 1.6.2. ◀

1. $\begin{aligned} x_1 + x_2 &= 2 \\ 5x_1 + 6x_2 &= 9 \end{aligned}$

2. $\begin{aligned} 4x_1 - 3x_2 &= -3 \\ 2x_1 - 5x_2 &= 9 \end{aligned}$

3. $\begin{aligned} x_1 + 3x_2 + x_3 &= 4 \\ 2x_1 + 2x_2 + x_3 &= -1 \\ 2x_1 + 3x_2 + x_3 &= 3 \end{aligned}$

4. $\begin{aligned} 5x_1 + 3x_2 + 2x_3 &= 4 \\ 3x_1 + 3x_2 + 2x_3 &= 2 \\ x_2 + x_3 &= 5 \end{aligned}$

5. $\begin{aligned} x + y + z &= 5 \\ x + y - 4z &= 10 \\ -4x + y + z &= 0 \end{aligned}$

6. $\begin{aligned} -x - 2y - 3z &= 0 \\ w + x + 4y + 4z &= 7 \\ w + 3x + 7y + 9z &= 4 \\ -w - 2x - 4y - 6z &= 6 \end{aligned}$

7. $\begin{aligned} 3x_1 + 5x_2 &= b_1 \\ x_1 + 2x_2 &= b_2 \end{aligned}$

8. $\begin{aligned} x_1 + 2x_2 + 3x_3 &= b_1 \\ 2x_1 + 5x_2 + 5x_3 &= b_2 \\ 3x_1 + 5x_2 + 8x_3 &= b_3 \end{aligned}$

▶ In Exercises 9–12, solve the linear systems together by reducing the appropriate augmented matrix. ◀

9. $\begin{aligned} x_1 - 5x_2 &= b_1 \\ 3x_1 + 2x_2 &= b_2 \end{aligned}$
   (i) $b_1 = 1,\ b_2 = 4$ (ii) $b_1 = -2,\ b_2 = 5$

10. $\begin{aligned} -x_1 + 4x_2 + x_3 &= b_1 \\ x_1 + 9x_2 - 2x_3 &= b_2 \\ 6x_1 + 4x_2 - 8x_3 &= b_3 \end{aligned}$
    (i) $b_1 = 0,\ b_2 = 1,\ b_3 = 0$
    (ii) $b_1 = -3,\ b_2 = 4,\ b_3 = -5$

11. $\begin{aligned} 4x_1 - 7x_2 &= b_1 \\ x_1 + 2x_2 &= b_2 \end{aligned}$
    (i) $b_1 = 0,\ b_2 = 1$ (ii) $b_1 = -4,\ b_2 = 6$
    (iii) $b_1 = -1,\ b_2 = 3$ (iv) $b_1 = -5,\ b_2 = 1$

12. $\begin{aligned} x_1 + 3x_2 + 5x_3 &= b_1 \\ -x_1 - 2x_2 &= b_2 \\ 2x_1 + 5x_2 + 4x_3 &= b_3 \end{aligned}$
    (i) $b_1 = 1,\ b_2 = 0,\ b_3 = -1$
    (ii) $b_1 = 0,\ b_2 = 1,\ b_3 = 1$
    (iii) $b_1 = -1,\ b_2 = -1,\ b_3 = 0$

▶ In Exercises 13–17, determine conditions on the b_i's, if any, in order to guarantee that the linear system is consistent. ◀

13. $\begin{aligned} x_1 + 3x_2 &= b_1 \\ -2x_1 + x_2 &= b_2 \end{aligned}$

14. $\begin{aligned} 6x_1 - 4x_2 &= b_1 \\ 3x_1 - 2x_2 &= b_2 \end{aligned}$

15. $\begin{aligned} x_1 - 2x_2 + 5x_3 &= b_1 \\ 4x_1 - 5x_2 + 8x_3 &= b_2 \\ -3x_1 + 3x_2 - 3x_3 &= b_3 \end{aligned}$

16. $\begin{aligned} x_1 - 2x_2 - x_3 &= b_1 \\ -4x_1 + 5x_2 + 2x_3 &= b_2 \\ -4x_1 + 7x_2 + 4x_3 &= b_3 \end{aligned}$

17. $\begin{aligned} x_1 - x_2 + 3x_3 + 2x_4 &= b_1 \\ -2x_1 + x_2 + 5x_3 + x_4 &= b_2 \\ -3x_1 + 2x_2 + 2x_3 - x_4 &= b_3 \\ 4x_1 - 3x_2 + x_3 + 3x_4 &= b_4 \end{aligned}$

18. Consider the matrices

$$A = \begin{bmatrix} 2 & 1 & 2 \\ 2 & 2 & -2 \\ 3 & 1 & 1 \end{bmatrix} \quad \text{and} \quad \mathbf{x} = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}$$

   (a) Show that the equation $A\mathbf{x} = \mathbf{x}$ can be rewritten as $(A - I)\mathbf{x} = \mathbf{0}$ and use this result to solve $A\mathbf{x} = \mathbf{x}$ for $\mathbf{x}$.
   (b) Solve $A\mathbf{x} = 4\mathbf{x}$.

▶ In Exercises 19–20, solve the matrix equation for X. ◀

19. $\begin{bmatrix} 1 & -1 & 1 \\ 2 & 3 & 0 \\ 0 & 2 & -1 \end{bmatrix} X = \begin{bmatrix} 2 & -1 & 5 & 7 & 8 \\ 4 & 0 & -3 & 0 & 1 \\ 3 & 5 & -7 & 2 & 1 \end{bmatrix}$

20. $\begin{bmatrix} -2 & 0 & 1 \\ 0 & -1 & -1 \\ 1 & 1 & -4 \end{bmatrix} X = \begin{bmatrix} 4 & 3 & 2 & 1 \\ 6 & 7 & 8 & 9 \\ 1 & 3 & 7 & 9 \end{bmatrix}$

Working with Proofs

21. Let $A\mathbf{x} = \mathbf{0}$ be a homogeneous system of n linear equations in n unknowns that has only the trivial solution. Prove that if k is any positive integer, then the system $A^k\mathbf{x} = \mathbf{0}$ also has only the trivial solution.

22. Let $A\mathbf{x} = \mathbf{0}$ be a homogeneous system of n linear equations in n unknowns, and let Q be an invertible $n \times n$ matrix. Prove that $A\mathbf{x} = \mathbf{0}$ has only the trivial solution if and only if $(QA)\mathbf{x} = \mathbf{0}$ has only the trivial solution.

23. Let $A\mathbf{x} = \mathbf{b}$ be any consistent system of linear equations, and let $\mathbf{x}_1$ be a fixed solution. Prove that every solution to the system can be written in the form $\mathbf{x} = \mathbf{x}_1 + \mathbf{x}_0$, where $\mathbf{x}_0$ is a solution to $A\mathbf{x} = \mathbf{0}$. Prove also that every matrix of this form is a solution.

24. Use part (*a*) of Theorem 1.6.3 to prove part (*b*).

True-False Exercises

TF. In parts (a)–(g) determine whether the statement is true or false, and justify your answer.

(a) It is impossible for a system of linear equations to have exactly two solutions.

(b) If A is a square matrix, and if the linear system $A\mathbf{x} = \mathbf{b}$ has a unique solution, then the linear system $A\mathbf{x} = \mathbf{c}$ also must have a unique solution.

(c) If A and B are $n \times n$ matrices such that $AB = I_n$, then $BA = I_n$.

(d) If A and B are row equivalent matrices, then the linear systems $A\mathbf{x} = \mathbf{0}$ and $B\mathbf{x} = \mathbf{0}$ have the same solution set.

(e) Let A be an $n \times n$ matrix and S is an $n \times n$ invertible matrix. If $\mathbf{x}$ is a solution to the linear system $(S^{-1}AS)\mathbf{x} = \mathbf{b}$, then $S\mathbf{x}$ is a solution to the linear system $A\mathbf{y} = S\mathbf{b}$.

(f) Let A be an $n \times n$ matrix. The linear system $A\mathbf{x} = 4\mathbf{x}$ has a unique solution if and only if $A - 4I$ is an invertible matrix.

(g) Let A and B be $n \times n$ matrices. If A or B (or both) are not invertible, then neither is AB.

Working with Technology

T1. Colors in print media, on computer monitors, and on television screens are implemented using what are called "color models". For example, in the RGB model, colors are created by mixing percentages of red (R), green (G), and blue (B), and in the YIQ model (used in TV broadcasting), colors are created by mixing percentages of luminescence (Y) with percentages of a chrominance factor (I) and a chrominance factor (Q). The conversion from the RGB model to the YIQ model is accomplished by the matrix equation

$$\begin{bmatrix} \text{Y} \\ \text{I} \\ \text{Q} \end{bmatrix} = \begin{bmatrix} .299 & .587 & .114 \\ .596 & -.275 & -.321 \\ .212 & -.523 & .311 \end{bmatrix} \begin{bmatrix} \text{R} \\ \text{G} \\ \text{B} \end{bmatrix}$$

What matrix would you use to convert the YIQ model to the RGB model?

T2. Let

$$A = \begin{bmatrix} 1 & -2 & 2 \\ 4 & 5 & 1 \\ 0 & 3 & -1 \end{bmatrix}, \quad B_1 = \begin{bmatrix} 0 \\ 1 \\ 7 \end{bmatrix}, \quad B_2 = \begin{bmatrix} 11 \\ 5 \\ 3 \end{bmatrix}, \quad B_3 = \begin{bmatrix} 1 \\ -4 \\ 2 \end{bmatrix}$$

Solve the linear systems $A\mathbf{x} = B_1$, $A\mathbf{x} = B_2$, $A\mathbf{x} = B_3$ using the method of Example 2.

1.7 Diagonal, Triangular, and Symmetric Matrices

In this section we will discuss matrices that have various special forms. These matrices arise in a wide variety of applications and will play an important role in our subsequent work.

Diagonal Matrices

A square matrix in which all the entries off the main diagonal are zero is called a ***diagonal matrix***. Here are some examples:

$$\begin{bmatrix} 2 & 0 \\ 0 & -5 \end{bmatrix}, \quad \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}, \quad \begin{bmatrix} 6 & 0 & 0 & 0 \\ 0 & -4 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 8 \end{bmatrix}, \quad \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}$$

▶ EXAMPLE 6 The Product of a Matrix and Its Transpose Is Symmetric

Let A be the 2×3 matrix

$$A = \begin{bmatrix} 1 & -2 & 4 \\ 3 & 0 & -5 \end{bmatrix}$$

Then

$$A^TA = \begin{bmatrix} 1 & 3 \\ -2 & 0 \\ 4 & -5 \end{bmatrix} \begin{bmatrix} 1 & -2 & 4 \\ 3 & 0 & -5 \end{bmatrix} = \begin{bmatrix} 10 & -2 & -11 \\ -2 & 4 & -8 \\ -11 & -8 & 41 \end{bmatrix}$$

$$AA^T = \begin{bmatrix} 1 & -2 & 4 \\ 3 & 0 & -5 \end{bmatrix} \begin{bmatrix} 1 & 3 \\ -2 & 0 \\ 4 & -5 \end{bmatrix} = \begin{bmatrix} 21 & -17 \\ -17 & 34 \end{bmatrix}$$

Observe that A^TA and AA^T are symmetric as expected. ◀

Later in this text, we will obtain general conditions on A under which AA^T and A^TA are invertible. However, in the special case where A is *square*, we have the following result.

THEOREM 1.7.5 *If A is an invertible matrix, then AA^T and A^TA are also invertible.*

Proof Since A is invertible, so is A^T by Theorem 1.4.9. Thus AA^T and A^TA are invertible, since they are the products of invertible matrices. ◀

Exercise Set 1.7

▶ In Exercises 1–2, classify the matrix as upper triangular, lower triangular, or diagonal, and decide by inspection whether the matrix is invertible. [*Note:* Recall that a diagonal matrix is both upper and lower triangular, so there may be more than one answer in some parts.] ◀

1. (a) $\begin{bmatrix} 2 & 1 \\ 0 & 3 \end{bmatrix}$ (b) $\begin{bmatrix} 0 & 0 \\ 4 & 0 \end{bmatrix}$

(c) $\begin{bmatrix} -1 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & \frac{1}{5} \end{bmatrix}$ (d) $\begin{bmatrix} 3 & -2 & 7 \\ 0 & 0 & 3 \\ 0 & 0 & 8 \end{bmatrix}$

2. (a) $\begin{bmatrix} 4 & 0 \\ 1 & 7 \end{bmatrix}$ (b) $\begin{bmatrix} 0 & -3 \\ 0 & 0 \end{bmatrix}$

(c) $\begin{bmatrix} 4 & 0 & 0 \\ 0 & \frac{3}{5} & 0 \\ 0 & 0 & -2 \end{bmatrix}$ (d) $\begin{bmatrix} 3 & 0 & 0 \\ 3 & 1 & 0 \\ 7 & 0 & 0 \end{bmatrix}$

▶ In Exercises 3–6, find the product by inspection. ◀

3. $\begin{bmatrix} 3 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 2 \end{bmatrix} \begin{bmatrix} 2 & 1 \\ -4 & 1 \\ 2 & 5 \end{bmatrix}$

4. $\begin{bmatrix} 1 & 2 & -5 \\ -3 & -1 & 0 \end{bmatrix} \begin{bmatrix} -4 & 0 & 0 \\ 0 & 3 & 0 \\ 0 & 0 & 2 \end{bmatrix}$

5. $\begin{bmatrix} 5 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & -3 \end{bmatrix} \begin{bmatrix} -3 & 2 & 0 & 4 & -4 \\ 1 & -5 & 3 & 0 & 3 \\ -6 & 2 & 2 & 2 & 2 \end{bmatrix}$

6. $\begin{bmatrix} 2 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 4 \end{bmatrix} \begin{bmatrix} 4 & -1 & 3 \\ 1 & 2 & 0 \\ -5 & 1 & -2 \end{bmatrix} \begin{bmatrix} -3 & 0 & 0 \\ 0 & 5 & 0 \\ 0 & 0 & 2 \end{bmatrix}$

▶ In Exercises 7–10, find A^2, A^{-2}, and A^{-k} (where k is any integer) by inspection. ◀

7. $A = \begin{bmatrix} 1 & 0 \\ 0 & -2 \end{bmatrix}$

8. $A = \begin{bmatrix} -6 & 0 & 0 \\ 0 & 3 & 0 \\ 0 & 0 & 5 \end{bmatrix}$

9. $A = \begin{bmatrix} \frac{1}{2} & 0 & 0 \\ 0 & \frac{1}{3} & 0 \\ 0 & 0 & \frac{1}{4} \end{bmatrix}$

10. $A = \begin{bmatrix} -2 & 0 & 0 & 0 \\ 0 & -4 & 0 & 0 \\ 0 & 0 & -3 & 0 \\ 0 & 0 & 0 & 2 \end{bmatrix}$

In Exercises 11–12, compute the product by inspection.

11. $\begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 3 \end{bmatrix}\begin{bmatrix} 2 & 0 & 0 \\ 0 & 5 & 0 \\ 0 & 0 & 0 \end{bmatrix}\begin{bmatrix} 0 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 1 \end{bmatrix}$

12. $\begin{bmatrix} -1 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 4 \end{bmatrix}\begin{bmatrix} 3 & 0 & 0 \\ 0 & 5 & 0 \\ 0 & 0 & 7 \end{bmatrix}\begin{bmatrix} 5 & 0 & 0 \\ 0 & -2 & 0 \\ 0 & 0 & 3 \end{bmatrix}$

In Exercises 13–14, compute the indicated quantity.

13. $\begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix}^{39}$ 14. $\begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix}^{1000}$

In Exercises 15–16, use what you have learned in this section about multiplying by diagonal matrices to compute the product by inspection.

15. (a) $\begin{bmatrix} a & 0 & 0 \\ 0 & b & 0 \\ 0 & 0 & c \end{bmatrix}\begin{bmatrix} u & v \\ w & x \\ y & z \end{bmatrix}$ (b) $\begin{bmatrix} r & s & t \\ u & v & w \\ x & y & z \end{bmatrix}\begin{bmatrix} a & 0 & 0 \\ 0 & b & 0 \\ 0 & 0 & c \end{bmatrix}$

16. (a) $\begin{bmatrix} u & v \\ w & x \\ y & z \end{bmatrix}\begin{bmatrix} a & 0 \\ 0 & b \end{bmatrix}$ (b) $\begin{bmatrix} a & 0 & 0 \\ 0 & b & 0 \\ 0 & 0 & c \end{bmatrix}\begin{bmatrix} r & s & t \\ u & v & w \\ x & y & z \end{bmatrix}$

In Exercises 17–18, create a symmetric matrix by substituting appropriate numbers for the ×'s.

17. (a) $\begin{bmatrix} 2 & -1 \\ \times & 3 \end{bmatrix}$ (b) $\begin{bmatrix} 1 & \times & \times & \times \\ 3 & 1 & \times & \times \\ 7 & -8 & 0 & \times \\ 2 & -3 & 9 & 0 \end{bmatrix}$

18. (a) $\begin{bmatrix} 0 & \times \\ 3 & 0 \end{bmatrix}$ (b) $\begin{bmatrix} 1 & 7 & -3 & 2 \\ \times & 4 & 5 & -7 \\ \times & \times & 1 & -6 \\ \times & \times & \times & 3 \end{bmatrix}$

In Exercises 19–22, determine by inspection whether the matrix is invertible.

19. $\begin{bmatrix} 0 & 6 & -1 \\ 0 & 7 & -4 \\ 0 & 0 & -2 \end{bmatrix}$ 20. $\begin{bmatrix} -1 & 2 & 4 \\ 0 & 3 & 0 \\ 0 & 0 & 5 \end{bmatrix}$

21. $\begin{bmatrix} 1 & 0 & 0 & 0 \\ 2 & -5 & 0 & 0 \\ 4 & -3 & 4 & 0 \\ 1 & -2 & 1 & 3 \end{bmatrix}$ 22. $\begin{bmatrix} 2 & 0 & 0 & 0 \\ -3 & -1 & 0 & 0 \\ -4 & -6 & 0 & 0 \\ 0 & 3 & 8 & -5 \end{bmatrix}$

In Exercises 23–24, find the diagonal entries of AB by inspection.

23. $A = \begin{bmatrix} 3 & 2 & 6 \\ 0 & 1 & -2 \\ 0 & 0 & -1 \end{bmatrix}, \quad B = \begin{bmatrix} -1 & 2 & 7 \\ 0 & 5 & 3 \\ 0 & 0 & 6 \end{bmatrix}$

24. $A = \begin{bmatrix} 4 & 0 & 0 \\ -2 & 0 & 0 \\ -3 & 0 & 7 \end{bmatrix}, \quad B = \begin{bmatrix} 6 & 0 & 0 \\ 1 & 5 & 0 \\ 3 & 2 & 6 \end{bmatrix}$

In Exercises 25–26, find all values of the unknown constant(s) for which A is symmetric.

25. $A = \begin{bmatrix} 4 & -3 \\ a+5 & -1 \end{bmatrix}$

26. $A = \begin{bmatrix} 2 & a-2b+2c & 2a+b+c \\ 3 & 5 & a+c \\ 0 & -2 & 7 \end{bmatrix}$

In Exercises 27–28, find all values of x for which A is invertible.

27. $A = \begin{bmatrix} x-1 & x^2 & x^4 \\ 0 & x+2 & x^3 \\ 0 & 0 & x-4 \end{bmatrix}$

28. $A = \begin{bmatrix} x-\frac{1}{2} & 0 & 0 \\ x & x-\frac{1}{3} & 0 \\ x^2 & x^3 & x+\frac{1}{4} \end{bmatrix}$

29. If A is an invertible upper triangular or lower triangular matrix, what can you say about the diagonal entries of A^{-1}?

30. Show that if A is a symmetric $n \times n$ matrix and B is any $n \times m$ matrix, then the following products are symmetric:

$$B^TB, \quad BB^T, \quad B^TAB$$

In Exercises 31–32, find a diagonal matrix A that satisfies the given condition.

31. $A^5 = \begin{bmatrix} 1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & -1 \end{bmatrix}$ 32. $A^{-2} = \begin{bmatrix} 9 & 0 & 0 \\ 0 & 4 & 0 \\ 0 & 0 & 1 \end{bmatrix}$

33. Verify Theorem 1.7.1(*b*) for the matrix product AB and Theorem 1.7.1(*d*) for the matrix A, where

$$A = \begin{bmatrix} -1 & 2 & 5 \\ 0 & 1 & 3 \\ 0 & 0 & -4 \end{bmatrix}, \quad B = \begin{bmatrix} 2 & -8 & 0 \\ 0 & 2 & 1 \\ 0 & 0 & 3 \end{bmatrix}$$

34. Let A be an $n \times n$ symmetric matrix.

(a) Show that A^2 is symmetric.

(b) Show that $2A^2 - 3A + I$ is symmetric.

35. Verify Theorem 1.7.4 for the given matrix A.

(a) $A = \begin{bmatrix} 2 & -1 \\ -1 & 3 \end{bmatrix}$ (b) $A = \begin{bmatrix} 1 & -2 & 3 \\ -2 & 1 & -7 \\ 3 & -7 & 4 \end{bmatrix}$

36. Find all 3×3 diagonal matrices A that satisfy $A^2 - 3A - 4I = 0$.

37. Let $A = [a_{ij}]$ be an $n \times n$ matrix. Determine whether A is symmetric.

(a) $a_{ij} = i^2 + j^2$ (b) $a_{ij} = i^2 - j^2$

(c) $a_{ij} = 2i + 2j$ (d) $a_{ij} = 2i^2 + 2j^3$

38. On the basis of your experience with Exercise 37, devise a general test that can be applied to a formula for a_{ij} to determine whether $A = [a_{ij}]$ is symmetric.

39. Find an upper triangular matrix that satisfies

$$A^3 = \begin{bmatrix} 1 & 30 \\ 0 & -8 \end{bmatrix}$$

40. If the $n \times n$ matrix A can be expressed as $A = LU$, where L is a lower triangular matrix and U is an upper triangular matrix, then the linear system $A\mathbf{x} = \mathbf{b}$ can be expressed as $LU\mathbf{x} = \mathbf{b}$ and can be solved in two steps:

Step 1. Let $U\mathbf{x} = \mathbf{y}$, so that $LU\mathbf{x} = \mathbf{b}$ can be expressed as $L\mathbf{y} = \mathbf{b}$. Solve this system.

Step 2. Solve the system $U\mathbf{x} = \mathbf{y}$ for $\mathbf{x}$.

In each part, use this two-step method to solve the given system.

(a) $\begin{bmatrix} 1 & 0 & 0 \\ -2 & 3 & 0 \\ 2 & 4 & 1 \end{bmatrix} \begin{bmatrix} 2 & -1 & 3 \\ 0 & 1 & 2 \\ 0 & 0 & 4 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 1 \\ -2 \\ 0 \end{bmatrix}$

(b) $\begin{bmatrix} 2 & 0 & 0 \\ 4 & 1 & 0 \\ -3 & -2 & 3 \end{bmatrix} \begin{bmatrix} 3 & -5 & 2 \\ 0 & 4 & 1 \\ 0 & 0 & 2 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 4 \\ -5 \\ 2 \end{bmatrix}$

► In the text we defined a matrix A to be symmetric if $A^T = A$. Analogously, a matrix A is said to be ***skew-symmetric*** if $A^T = -A$. Exercises 41–45 are concerned with matrices of this type. ◄

41. Fill in the missing entries (marked with $\times$) so the matrix A is skew-symmetric.

(a) $A = \begin{bmatrix} \times & \times & 4 \\ 0 & \times & \times \\ \times & -1 & \times \end{bmatrix}$ (b) $A = \begin{bmatrix} \times & 0 & \times \\ \times & \times & -4 \\ 8 & \times & \times \end{bmatrix}$

42. Find all values of $a, b, c,$ and d for which A is skew-symmetric.

$$A = \begin{bmatrix} 0 & 2a - 3b + c & 3a - 5b + 5c \\ -2 & 0 & 5a - 8b + 6c \\ -3 & -5 & d \end{bmatrix}$$

43. We showed in the text that the product of symmetric matrices is symmetric if and only if the matrices commute. Is the product of commuting skew-symmetric matrices skew-symmetric? Explain.

Working with Proofs

44. Prove that every square matrix A can be expressed as the sum of a symmetric matrix and a skew-symmetric matrix. [*Hint:* Note the identity $A = \frac{1}{2}(A + A^T) + \frac{1}{2}(A - A^T)$.]

45. Prove the following facts about skew-symmetric matrices.

(a) If A is an invertible skew-symmetric matrix, then A^{-1} is skew-symmetric.

(b) If A and B are skew-symmetric matrices, then so are A^T, $A + B$, $A - B$, and kA for any scalar k.

46. Prove: If the matrices A and B are both upper triangular or both lower triangular, then the diagonal entries of both AB and BA are the products of the diagonal entries of A and B.

47. Prove: If $A^TA = A$, then A is symmetric and $A = A^2$.

True-False Exercises

TF. In parts (a)–(m) determine whether the statement is true or false, and justify your answer.

(a) The transpose of a diagonal matrix is a diagonal matrix.

(b) The transpose of an upper triangular matrix is an upper triangular matrix.

(c) The sum of an upper triangular matrix and a lower triangular matrix is a diagonal matrix.

(d) All entries of a symmetric matrix are determined by the entries occurring on and above the main diagonal.

(e) All entries of an upper triangular matrix are determined by the entries occurring on and above the main diagonal.

(f) The inverse of an invertible lower triangular matrix is an upper triangular matrix.

(g) A diagonal matrix is invertible if and only if all of its diagonal entries are positive.

(h) The sum of a diagonal matrix and a lower triangular matrix is a lower triangular matrix.

(i) A matrix that is both symmetric and upper triangular must be a diagonal matrix.

(j) If A and B are $n \times n$ matrices such that $A + B$ is symmetric, then A and B are symmetric.

(k) If A and B are $n \times n$ matrices such that $A + B$ is upper triangular, then A and B are upper triangular.

(l) If A^2 is a symmetric matrix, then A is a symmetric matrix.

(m) If kA is a symmetric matrix for some $k \neq 0$, then A is a symmetric matrix.