

LECTURE 14 PROPERTIES OF THE DETERMINANT

Calculating $\det M$

$$\det M = \sum_{\sigma} \operatorname{sgn}(\sigma) m_{\sigma(1)}^1 m_{\sigma(2)}^2 \dots m_{\sigma(n)}^n$$

$\hat{\sigma}$ are permutations over $n-1$ objects

$$\begin{aligned} &= m_1^1 \sum_{\hat{\sigma}} \operatorname{sgn}(\hat{\sigma}) m_{\hat{\sigma}(2)}^2 \dots m_{\hat{\sigma}(n)}^n \\ &- m_2^1 \sum_{\hat{\sigma}} \operatorname{sgn}(\hat{\sigma}) m_{\hat{\sigma}(1)}^1 \dots m_{\hat{\sigma}(n)}^n \\ &+ m_3^1 \sum_{\hat{\sigma}} \operatorname{sgn}(\hat{\sigma}) m_{\hat{\sigma}(1)}^1 m_{\hat{\sigma}(2)}^2 \dots m_{\hat{\sigma}(n)}^n \\ &\vdots \end{aligned}$$

Expanding
sum in 1st
row.

Notice signs
alternate

Each sum is the
determinant of
the matrix left over
after removing the
1st row and a
column corresponding
to which m_i^1 is
factored out front.

EXAMPLE

$$\det \begin{pmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 7 & 8 & 9 \end{pmatrix}$$

$$= 1 \det \begin{pmatrix} 5 & 6 \\ 8 & 9 \end{pmatrix} - 2 \det \begin{pmatrix} 4 & 6 \\ 7 & 9 \end{pmatrix} + 3 \det \begin{pmatrix} 4 & 5 \\ 7 & 8 \end{pmatrix}$$

↙ expand in 2nd row

$$= (5 \cdot 9 - 6 \cdot 8) - 2(4 \cdot 9 - 6 \cdot 7) + 3(4 \cdot 8 - 5 \cdot 7) = 0$$

so $\begin{pmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 7 & 8 & 9 \end{pmatrix}^{-1}$ does NOT exist.

EXAMPLE

$$\det \begin{pmatrix} 1 & 2 & 3 \\ 4 & 0 & 0 \\ 5 & 6 & 7 \end{pmatrix} \overset{\text{swapped rows}}{=} - \det \begin{pmatrix} 4 & 0 & 0 \\ 1 & 2 & 3 \\ 5 & 6 & 7 \end{pmatrix}$$
$$= 4 \det \begin{pmatrix} 2 & 3 \\ 6 & 7 \end{pmatrix} = -16$$

The same method works expanding in any column because

$$\boxed{\det M^T = \det M}$$

This is true because

$$\sum_{\sigma} \text{sgn}(\sigma) m_{\sigma(1)}^1 \cdots m_{\sigma(n)}^n = \sum_{\sigma} \text{sgn}(\sigma) m_1^{\sigma(1)} \cdots m_n^{\sigma(n)}$$

i.e. commuting row or column entries gives same sum of terms.

DETERMINANT OF THE INVERSE

Let A, B be $n \times n$ matrices

Recall we found

$$\det AB = \det A \det B$$

$$\det I = 1$$

$$\Rightarrow 1 = \det A^{-1}A = \det A^{-1} \det A$$

$$\Rightarrow \boxed{\det A^{-1} = \frac{1}{\det A}}$$

Writing matrices as products of simpler ones is a good trick in computing the determinant.

INVERSES AGAIN

The adjoint of a matrix $M = (m_{j \cdot}^i)$

$$\text{adj } M = (\text{cofactor}(m_{j \cdot}^i))^T$$

where the cofactor $(m_{j \cdot}^i)$ is the determinant of M with row i and column j removed and multiplied by $(-)^{i+j}$

EX $\text{adj} \begin{pmatrix} 3 & -1 & -1 \\ 1 & 2 & 0 \\ 0 & 1 & 1 \end{pmatrix}$

$$= \begin{pmatrix} \det \begin{pmatrix} 2 & 0 \\ 1 & 1 \end{pmatrix} & -\det \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} & \det \begin{pmatrix} 1 & 2 \\ 0 & 1 \end{pmatrix} \\ -\det \begin{pmatrix} -1 & -1 \\ 1 & 1 \end{pmatrix} & \det \begin{pmatrix} 3 & -1 \\ 0 & 1 \end{pmatrix} & -\det \begin{pmatrix} 3 & -1 \\ 0 & 1 \end{pmatrix} \\ \det \begin{pmatrix} -1 & -1 \\ 2 & 0 \end{pmatrix} & -\det \begin{pmatrix} 3 & -1 \\ 1 & 0 \end{pmatrix} & \det \begin{pmatrix} 3 & -1 \\ 1 & 2 \end{pmatrix} \end{pmatrix}^T$$

Notice That the dot product of the i th row of M & the i th row of $(\text{adj } M)^T$ is just the expansion of $\det M$ in the i th row.

For the i^{th} and j^{th} rows ($i \neq j$) the dot product amounts to expanding $\det M$ in the i^{th} row save that the j^{th} row of M is replaced by its i^{th} row. The determinants of a matrix with two equal rows vanish, so these dot products do as well.

Finally note that computing dot products of the rows of M & N^T amounts to computing the elements of MN

Hence

$$M \operatorname{adj}(M) = \det M \begin{pmatrix} 1 & 0 & \cdots & 0 \\ 0 & 1 & & \\ & & \ddots & \\ 0 & \cdots & 0 & 1 \end{pmatrix}$$

Thus computing $\operatorname{adj}(M)$ gives us a formula for M^{-1} when it exists

$$M^{-1} = \frac{1}{\det M} \operatorname{adj}(M)$$

when $\det M \neq 0$.

EX In the above example

$$\operatorname{adj} \begin{pmatrix} 3 & -1 & -1 \\ 1 & 2 & 0 \\ 0 & 1 & 1 \end{pmatrix} = \begin{pmatrix} 2 & 0 & 2 \\ -1 & 3 & -1 \\ 1 & -3 & 7 \end{pmatrix}$$

and

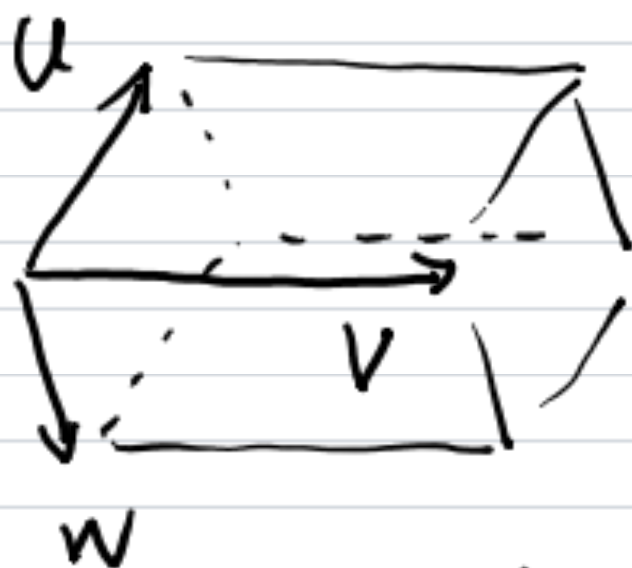
$$\begin{pmatrix} 2 & 0 & 2 \\ -1 & 3 & -1 \\ 1 & -3 & 7 \end{pmatrix} \begin{pmatrix} 3 & -1 & -1 \\ 1 & 2 & 0 \\ 0 & 1 & 1 \end{pmatrix} = \begin{pmatrix} 6 & 0 & 0 \\ 0 & 6 & 0 \\ 0 & 0 & 6 \end{pmatrix}$$

$$\Rightarrow \begin{pmatrix} 3 & -1 & -1 \\ 1 & 2 & 0 \\ 0 & 1 & 1 \end{pmatrix}^{-1} = \frac{1}{6} \begin{pmatrix} 2 & 0 & 2 \\ -1 & 3 & -1 \\ 1 & -3 & 7 \end{pmatrix} //$$

This is sometimes called Cramer's rule.

APPLICATION

Volume of parallelepiped



$$\text{volume} = |\det(u \ v \ w)|$$

This comes from the formula you know which says the volume is $|u \cdot (v \times w)|$ and using the fact that this amounts to computing the determinant by expanding in the first column.

Do you think a similar formula could work for computing higher-dimensional volumes?

Lecture 14 Review Questions:

① Let $M = \begin{pmatrix} a & b \\ c & d \end{pmatrix}$

show

$$\det M = \frac{1}{2} \operatorname{tr} M^2 - \frac{1}{2} (\operatorname{tr} M)^2$$

Suppose M is a 3×3 matrix.

Find and verify a similar formula for $\det M$ in terms of $\operatorname{tr} M^3$, $\operatorname{tr} M$, $\operatorname{tr} M^2$, $(\operatorname{tr} M)^3$.

- ② Suppose $M = LU$ is an LU decomposition. Explain how you would compute $\det M$ efficiently in this case.

