

Lecture #25 LEAST SQUARES

Consider the linear system

$$L(u) = v$$

where $L : U \xrightarrow{\text{linear}} W$

and $v \in W$ is given.

So u are the unknowns.

Sometimes such a system has a unique solution, sometimes there are many solutions (a solution space). But if v is not in the range of L

$$v \notin L(W)$$

we will never solve $L(u) = v$ for u . i.e. this system is consistent if and only if $v \in L(W)$.

But for many problems, we do not need an exact solution and nor do we care if an exact solution even exists. Instead we simply want to find the best approximation possible, i.e. find u such that

$$L(u) - v$$

is as "small as possible".

"My work always tried to unite the Truth with the Beautiful, but when I had to choose one or the other, I usually chose the Beautiful"

Hermann Weyl

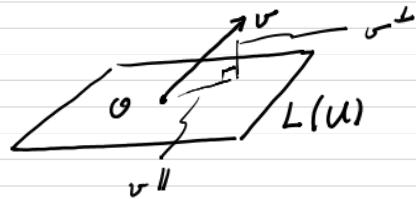
Suppose M is the matrix of L in bases for U & W while v and u are given by column vectors V and X in those bases.

Therefore we need to approximate

$$MX - V \approx 0 \quad (4)$$

Note, if $\dim U = n$, $\dim W = m$
then M is an $m \times n$ matrix.

Idea



$$\text{Write } W = L(U) \oplus L(U)^\perp$$

$$\Rightarrow v = v^// + v^\perp \text{ uniquely.}$$

$$\text{Solve } L(u) = v^//$$

In components, v^\perp is just $V - MX$

In terms of M notice that $L(V)$ is spanned by the rows of M (choose the natural basis e_1, \dots, e_n for V , then $\{Me_1, \dots, Me_n\}$ are the rows of M). So v^\perp must be perpendicular to the rows of M . i.e., $M^T(V - MX) = 0$ or

$$M^T M X = M^T V$$

Solutions X to $M^T M X = M^T V$ are called least squares solutions to $MX = V$.

Note any solution to $MX = V$ is a least squares solution but the converse is often false.

(In fact $MX = V$ may have no solutions at all but still have least squares solutions to $M^T M X = M^T V$)

Suppose $\ker L = \{0\}$

i.e. the only solution to

$Mx = 0$
is the zero vector.

Then if $x \neq 0$, $Mx \neq 0$.

But $M^T Mx \neq 0$ also because
if it were then

$$0 = x^T M^T Mx = \|Mx\|^2$$

or equivalently $Mx = 0$, a
contradiction. Thus if $\ker L = \{0\}$,
the matrix

$$M^T M$$

is invertible (because 0 is the
only solution to $Mx = 0$). Therefore
the least squares solution is
unique and equals

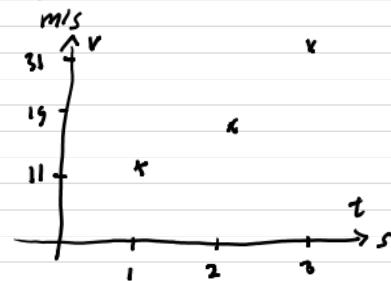
$$\boxed{X = (M^T M)^{-1} M^T V}$$

This is the least squares
method.

- ① Compute $M^T M$ and $M^T V$
- ② Solve $(M^T M)X = (M^T V)$
by Gaussian elimination.

Example Captain Conundrum

falls off the leaning tower
of Pisa and makes 3
(rather shaky) measurements
of his velocity at 3 different
times



He believes that his data are best approximated by a straight line

$$v = at + b$$

which a and b best fit his data:

$$\begin{aligned} 11 &= a \cdot 1 + b \\ 19 &= a \cdot 2 + b \\ 31 &= a \cdot 3 + b \end{aligned} \Leftrightarrow \begin{pmatrix} 1 & 1 \\ 2 & 1 \\ 3 & 1 \end{pmatrix} \begin{pmatrix} a \\ b \end{pmatrix} \stackrel{?}{=} \begin{pmatrix} 11 \\ 19 \\ 31 \end{pmatrix}$$

$n \quad X \quad v$

There is likely NO straight line solution so instead solve $M^T M X = M V$

$$\begin{pmatrix} 1 & 2 & 3 \\ 1 & 1 & 1 \\ 1 & 1 & 1 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 2 & 1 \\ 3 & 1 \end{pmatrix} \begin{pmatrix} a \\ b \end{pmatrix} = \begin{pmatrix} 1 & 2 & 3 \\ 1 & 1 & 1 \\ 1 & 1 & 1 \end{pmatrix} \begin{pmatrix} 11 \\ 19 \\ 31 \end{pmatrix}$$

$$\Rightarrow \left(\begin{array}{cc|c} 14 & 6 & 142 \\ 6 & 3 & 61 \end{array} \right) \sim \left(\begin{array}{cc|c} 1 & 0 & 10 \\ 0 & 1 & 13 \end{array} \right)$$

The least squares fit is

$$v = 10t + \frac{1}{3}$$

Review Exercises

① Let $L: U \rightarrow V$ be a linear transformation.

Suppose $v \in L(U)$ and you have found a vector u_{ps} that obeys $L(u_{ps}) = v$

Explain why you need to compute

$$\ker L$$

to find the solution space of the linear system

$$L(u) = v.$$

- (4) Explain why elements of $\text{span}(U \cup V)$ all have the form $u + v$ with $u \in U, v \in V$.
- (5) Show that elements of $U \oplus V$ can be expressed uniquely as $u + v$ with $u \in U, v \in V$.
[Hint: suppose the opposite were true and derive a contradiction.]
- (6) Use the subspace theorem to show that U^\perp is a subspace.

(vii') Explain why $\lambda = \bar{\lambda}$. What does this mean?