

② The soln space of inhomogeneous eqn ⑧

$$A_{(m \times n)} x_{(n \times 1)} = b_{(m \times 1)}$$

Thm ①: To have any soln, b must lie in colm space of A , $b \in C(A)$

Pf.

$$\begin{bmatrix} 1 & & \\ c_1 & \dots & c_n \\ 1 & & \end{bmatrix} \begin{bmatrix} x_1 \\ \vdots \\ x_n \end{bmatrix} = x_1 \begin{bmatrix} 1 \\ c_1 \\ 1 \end{bmatrix} + \dots + x_n \begin{bmatrix} 1 \\ c_n \\ 1 \end{bmatrix} = b$$

\Leftrightarrow " b is a linear comb of colms of A "

$\Leftrightarrow b \in \text{Span} \{c_1, \dots, c_n\} \Leftrightarrow b \in C(A) \checkmark$

Thm 12: If x_p is a particular soln of (2)
 $Ax_p = b$,

then every soln is given by $x = x_n + x_p$

where $x_n \in K(A) \Leftrightarrow Ax_n = 0$

$K(A) \equiv$ kernel of $A \equiv$ nullspace of $A = \{x : Ax = 0\}$

Recall: $\dim K(A) = n - r$ $r = \text{rank}(A)$

P.f. Assume $Ax_p = b$. Let $\bar{X} = \{x : Ax = b\} = \text{Soln Space}$.

(1) If $x_n \in K(A)$, then $A(x_p + x_n) = \underbrace{Ax_p}_b + \underbrace{Ax_n}_0 = b$ ✓

(2) If $\cancel{Ax=b} \ x \in \bar{X}$, $\Rightarrow \cancel{Ax=b} \ x_p + K(A) \in \bar{X}$

then $Ax = b \Rightarrow A(x - x_p) = Ax - Ax_p = b - b = 0$

$\therefore x_n = x - x_p \in K(A)$ and $x = x_n + x_p \Rightarrow \bar{X} \subseteq x_p + K(A)$

$\therefore \bar{X} = x_p + K(A)$ ✓

③ How to find x_p : $A = \begin{bmatrix} \vdots & \vdots & \vdots & \vdots \\ \vdots & \vdots & \vdots & \vdots \end{bmatrix}$

- Construct augmented matrix

$$[A; b] = \begin{bmatrix} \vdots & \vdots & \vdots & \vdots \\ \vdots & \vdots & \vdots & \vdots \end{bmatrix}_{m \times (n+1)}$$

- Let $E_1 \cdots E_N$ be the elementary matrices that take A to $\text{rref}(A) = R$:

$$\underbrace{E_1 \cdots E_N}_E A = R$$

- Then by how cols of A act on matrix to left

$$E_1 \cdots E_N [A; b] = \underbrace{E_1 \cdots E_N}_E \begin{bmatrix} \vdots & \vdots & \vdots & \vdots \\ \vdots & \vdots & \vdots & \vdots \end{bmatrix}$$

$$= \begin{bmatrix} E_1 \vdots & E_1 \vdots & \cdots & E_1 \vdots & E_1 b \\ \vdots & \vdots & \cdots & \vdots & \vdots \end{bmatrix} = [R; Eb]$$

• But $Ax = b \Leftrightarrow EAx = Eb \Leftrightarrow Rx = Eb$

∴ to find x_p we need only solve

$$Rx_p = Eb$$

• To see the simplified soln :

$$\begin{bmatrix} 1 & 0 & * & * & 0 & * & 0 \\ 0 & 1 & * & * & 0 & * & 0 \\ 0 & 0 & 0 & 0 & 1 & * & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \\ x_6 \\ x_7 \end{bmatrix} = \begin{bmatrix} \bar{b}_1 \\ \bar{b}_2 \\ \bar{b}_3 \\ \bar{b}_4 \\ \bar{b}_5 \end{bmatrix} = Eb$$

Set the non-pivot = free variable $= 0 = x_3 = x_4 = x_6$

Set the pivot variable $x_i = \bar{b}_i$

Soln : $x_p = \begin{bmatrix} \bar{b}_1 \\ \bar{b}_2 \\ 0 \\ 0 \\ \bar{b}_3 \\ 0 \\ \bar{b}_7 \end{bmatrix}$

• Q: What is the "solvability condition" for b ? (5)

Ans: Since in the pivot variables R is id , we can find x ~~to~~ s.t. $Rx = b$ in the nonzero rows. However, to get equality in the zero rows, we need

$$(Eb)_i = \bar{b}_i = 0 \quad i = r+1, r+2, \dots, m.$$

In general: if $E = \begin{bmatrix} -\vec{r}_1 & - \\ & \ddots & \\ -\vec{r}_m & - \end{bmatrix}_{m \times m}$ then

$$\bar{b} = E \cdot b = \begin{bmatrix} \vec{r}_1 \cdot b \\ \vdots \\ \vec{r}_m \cdot b \end{bmatrix}$$

So solvability condn is

$$\vec{r}_{r+1} \cdot b = 0, \dots, \vec{r}_m \cdot b = 0$$

(rank of A)

• Note: you can get solvability cond directly from

$$L^{-1}A = U \stackrel{\text{eg}}{=} \begin{bmatrix} -3 & 3 & 1 & -1 \\ 0 & 0 & 2 & 1 \\ 0 & 0 & 0 & 0 \end{bmatrix} = L^{-1}b$$

$$Ax=b \Leftrightarrow Ux = L^{-1}b = c$$

$$\text{solvable iff } (L^{-1}b)_{r+1} = \dots = (L^{-1}b)_m = 0$$

$$c_{r+1} = \dots = c_m = 0 \quad \checkmark$$

Summary: "The zero rows of U or R give the solvability cond on b "

Ex: Find the solvability condn on b st (7)

$$Ax = b$$

has a soln if

$$A = \begin{bmatrix} 1 & 3 & 3 & 2 \\ 2 & 6 & 9 & 7 \\ -1 & -3 & 3 & 4 \end{bmatrix}$$

From before:

$$A = \begin{bmatrix} 1 & 3 & 3 & 2 \\ 2 & 6 & 9 & 7 \\ -1 & -3 & 3 & 4 \end{bmatrix} \xrightarrow{E_{21}(-2)} \begin{bmatrix} 1 & 3 & 3 & 2 \\ 0 & 0 & 3 & 3 \\ -1 & -3 & 3 & 4 \end{bmatrix} \xrightarrow{E_{31}(1)} \begin{bmatrix} 1 & 3 & 3 & 2 \\ 0 & 0 & 3 & 3 \\ 0 & 0 & 6 & 6 \end{bmatrix}$$

$$\xrightarrow{E_{32}(-2)} \begin{bmatrix} 1 & 3 & 3 & 2 \\ 0 & 0 & 3 & 3 \\ 0 & 0 & 0 & 0 \end{bmatrix} = U \quad \text{rank} = 2 = r$$

$$\therefore Ax = b \Leftrightarrow$$

$$E_{32}(-2) E_{31}(1) E_{21}(-2) A x = U x = E_{32}(-2) E_{31}(1) E_{21}(-2) b$$

$$\begin{bmatrix} 1 & 0 & 0 \\ -2 & 1 & 0 \\ 5 & -2 & 1 \end{bmatrix} b = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & -2 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ -2 & 1 & 0 \\ 1 & 0 & 1 \end{bmatrix} b = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & -2 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 1 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ -2 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} b$$

⇒ Solvability condn

$$5b_1 - 2b_2 + b_3 = 0$$

Eg if \exists 3 zero rows \Rightarrow 3 solv condts etc.

Q Matrices of rank-1

Ex

$$\begin{matrix} [1, 2] & \begin{bmatrix} -1 \\ 3 \end{bmatrix} \\ (1 \times 2) & (2 \times 1) \end{matrix} = -1 + 6 = 5 \quad (1 \times 1)$$

$$\begin{matrix} \begin{bmatrix} 1 \\ 2 \end{bmatrix} & [-1, 3] \\ (2 \times 1) & (1 \times 2) \end{matrix} = \begin{bmatrix} -1 & 3 \\ -2 & 6 \end{bmatrix} = \text{"rank-1 matrix"}$$

In general: given $\begin{bmatrix} 1 \\ c \\ 1 \end{bmatrix}$ & $[-\vec{r}-]$

$$\begin{matrix} \begin{bmatrix} 1 \\ c \\ 1 \end{bmatrix} & [-\vec{r}-] \\ (m \times 1) & (1 \times n) \end{matrix} = \begin{matrix} \begin{bmatrix} r_1 & \frac{1}{c} & r_2 & \frac{1}{c} & \dots & r_n & \frac{1}{c} \end{bmatrix} \\ m \times n \end{matrix} = \begin{bmatrix} - & c_1 r_1 & - \\ - & c_1 r_2 & - \\ \vdots & \vdots & \vdots \\ - & c_m r_m & - \end{bmatrix}$$

(9)

Defn: given vector $\vec{c} \in \mathbb{R}^m$ & $\vec{r} \in \mathbb{R}^n$

the $m \times n$ ~~matrix~~ matrix $\vec{c} \cdot \vec{r}^T$

is called a rank-1 matrix

• "coln's are mult's of \vec{c} "

• "rows are mult's of \vec{r} "

Preview: SVD $A = U \Sigma V^T = \sum_{i=1}^n \sigma_i \vec{u}_i \vec{v}_i^T$

↑
as rank-1
matrices

Inverse Matrices

①

Defn: B is a left inverse of A if $BA = I$

B is a right inverse of A if $AB = I$

Defn: we say A has an inverse A^{-1} if

$$A^{-1}A = I = AA^{-1} \quad "A" \text{ is both left/right}$$

Thm: If A has a left & right inverse, then they are equal

Pf. $BA = I$ & $AC = I \Rightarrow B(AC) = B$
 $(BA)C = B \Rightarrow C = B \checkmark$

Thm: If A is $n \times n$, then A^{-1} exists iff

① $|A| \neq 0$

② \exists n nonzero pivots

(2)

• what about $A_{m \times n}$ $m \neq n$

"can only have rt or left not both"

"for rt or left to exist, $\text{rank}(A) = \min(m, n)$ "

$$\underline{\underline{Ex}} \quad \begin{matrix} \begin{bmatrix} 1 & 2 & -1 \\ 2 & 1 & 1 \end{bmatrix} & \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} & = & \begin{bmatrix} b_1 \\ b_2 \end{bmatrix} \\ (2 \times 3) & (3 \times 1) & & (2 \times 1) \end{matrix}$$

Look for B st $B_{3 \times 2} \cdot A_{2 \times 3} = \text{id}_{3 \times 3} \Rightarrow$
can solve $Ax=b$ by ...

$$\begin{matrix} B & A & \underline{x} & = & B & \underline{b} \\ (3 \times 2) & (2 \times 3) & (3 \times 1) & & (3 \times 2) & (2 \times 1) \\ \underbrace{\hspace{2cm}} & & & & & \\ \text{Id}_{3 \times 3} & & & & & \end{matrix}$$

(3)

But B cannot exist:

$$\begin{bmatrix} -b_1 & - \\ -b_2 & - \\ -b_3 & - \end{bmatrix} \begin{bmatrix} 1 & 2 & -1 \\ 2 & 1 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} -e_1 & - \\ -e_2 & - \\ -e_3 & - \end{bmatrix}$$

" $e_1 \in \text{span } (1, 2, -1) \text{ \& } (2, 1, 1)$

$e_2 \in \text{span } \quad \quad \quad "$

$e_3 \in \quad \quad \quad "$

* rows of A only span 2-d

space.

Thm \Rightarrow if $A_{m \times n}$, $m < n \Rightarrow$ no left inv.

if $A_{m \times n}$, $m > n \Rightarrow$ no right inv.

(4)

Thm: If $A_{m \times n}$, $m > n$, then A has a left inverse iff A has max' rank n
 If $A_{m \times n}$, $m < n$ then A has a rt inv iff A has max' rank n

$$\begin{bmatrix} - & r_1 & - \\ - & r_2 & - \end{bmatrix} \begin{bmatrix} 1 & 2 \\ 2 & 1 \\ -1 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} b_1 \\ b_2 \\ b_3 \end{bmatrix}$$

$2 \times 3 \quad (3 \times 2) \quad (2 \times 1)$

Clearly we can solve

$$\begin{bmatrix} - & r_1 & - \\ - & r_2 & - \end{bmatrix} \begin{bmatrix} 1 & 2 \\ 2 & 1 \\ -1 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

if rows of A span a 2-d space $\Rightarrow \text{rank}(A) = n = 2$

" $r_1 = (a_1, b_1, c_1) \Rightarrow \begin{matrix} a_1(1, 2) \\ b_1(2, 1) \\ c_1(-1, 1) \end{matrix} = (1, 0) \parallel \begin{matrix} a_2(1, 2) \\ b_2(2, 1) \\ c_2(-1, 1) \end{matrix} = (0, 1) \checkmark$