

§2.6 Linear Transformations:

Defn: $T: V \rightarrow W$ between vector spaces is linear trans if

$$T(cu + dv) = cTu + dTv$$

"Can pass T thru add/scal mult" (Always assume V, W are finite-dim)

• Ex: an $m \times n$ matrix defines a lin trans from $\mathbb{R}^n \rightarrow \mathbb{R}^m$:

$$\begin{array}{ccc} Tx & = & Ax \\ \begin{array}{c} (m \times 1) \\ \uparrow \\ \text{in } \mathbb{R}^m \end{array} & & \begin{array}{c} (m \times n)(n \times 1) \\ \uparrow \\ \text{in } \mathbb{R}^n \end{array} \end{array}$$

check: $A(cx + dy) = cAx + dAy$ ✓

□ Thm: Every linear trans. can be represented by a matrix, but the matrix depends on the choice of basis (2)

Ex: $T: V \rightarrow W$. Let $\{v_1, \dots, v_n\}$ basis for

V $\{w_1, \dots, w_m\}$ basis for W . Then

$$Tv_1 = \sum_{i=1}^m w_i a_{i1} \quad (Tv_1 \in W!)$$

(*)

$$Tv_n = \sum_{i=1}^m w_i a_{in} \quad (Tv_n \in W!)$$

Thus for any $v \in V$, $v = x_1 v_1 + \dots + x_n v_n$ $\underline{x} \in \mathbb{R}^n$

$$\left. \begin{array}{l} x_1 Tv_1 \\ + \\ \vdots \\ + \\ x_n Tv_n \end{array} \right\} = \left. \begin{array}{l} \sum_{i=1}^m w_i a_{i1} x_1 \\ + \\ \vdots \\ + \\ \sum_{i=1}^m w_i a_{in} x_n \end{array} \right\} \begin{array}{l} (w_1, \dots, w_m) A \\ \uparrow \\ A = (a_{ij}) \end{array} \begin{bmatrix} x_1 \\ \vdots \\ x_n \end{bmatrix}$$

Notation: Bases $\{v_1, \dots, v_n\}$, $\{w_1, \dots, w_m\}$

$$\underline{v} = (v_1, \dots, v_n) \in V^n$$

$$\underline{w} = (w_1, \dots, w_m) \in W^n$$

Components $\underline{x} = (x_1, \dots, x_n) \in \mathbb{R}^n$

$$\underline{y} = (y_1, \dots, y_m) \in \mathbb{R}^m$$

Conclude: if $V = \sum_{i=1}^n x_i v_i = \underline{v}^T \cdot \underline{x}$ (3)

$(v_1, \dots, v_n) \begin{pmatrix} x_1 \\ \vdots \\ x_n \end{pmatrix}$

Then

$$T(\underline{v}^T \cdot \underline{x}) = \underline{w}^T \cdot A \underline{x} \quad A = (a_{ij})$$

"T sends the $\underline{x}$ -linear comb of $\underline{v}$ " TO "The $A\underline{x}$ -linear comb of $\underline{w}$ "

" $A = (a_{ij})$ is the matrix representation of T in terms of bases $\underline{v}, \underline{w}$ "

$$\underline{y} = A \underline{x}$$

$(m \times 1) \quad (m \times n) \quad (n \times 1)$

↑
comp's of Tv
rel to $\underline{w}$

↑
comp's of v rel to $\underline{v}$

Corollary: A linear transformation is determined by where it sends a basis

Important: The matrix ~~A~~ $A = (a_{ij})_{n \times n}$ depends on choice of bases!

⊗ Linear Transformations $\mathbb{R}^n \rightarrow \mathbb{R}^m$

• Matrix $A_{(m \times n)}$ determines a linear Transp.

$$y = Ax$$

$$(y_1, \dots, y_m) = A \begin{bmatrix} x_1 \\ \vdots \\ x_n \end{bmatrix}$$

• Actually: This is the matrix associated with the standard bases $(e_1, \dots, e_n)$ on $\mathbb{R}^n$

$$\& (e_1, \dots, e_m) \in \mathbb{R}^m$$

Eg: $T(\underline{e} \cdot \underline{x}) = \underline{e} \cdot A \cdot \underline{x}$

$$\Leftrightarrow T\left(\sum_{i=1}^n x_i e_i\right) = (e_1, \dots, e_n) A \underbrace{\begin{bmatrix} x_1 \\ \vdots \\ x_n \end{bmatrix}}_{\substack{\uparrow \\ Ax \text{ gives} \\ \text{comp of } Tv \text{ in} \\ \text{terms of standard} \\ \text{basis } \{e_1, \dots, e_n\}}}$$

$\underline{x} \in \mathbb{R}^n$ gives comps
of v wrt standard
basis $\{e_1, \dots, e_n\}$

Ax gives
comp of Tv in
terms of standard
basis $\{e_1, \dots, e_n\}$

$$\Leftrightarrow \begin{array}{ccc} Ax & = & y \\ \uparrow & & \nwarrow \\ \text{comps} & & \text{comps} \\ \text{of } v & & T v \end{array}$$

Ex ① : $T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$

$$T \begin{pmatrix} 1 \\ 0 \end{pmatrix} = \begin{pmatrix} 2 \\ -1 \end{pmatrix}$$

Find A .

$$T \begin{pmatrix} 0 \\ 1 \end{pmatrix} = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

Soln : $A = \begin{bmatrix} c_1 & c_2 \\ c_1 & c_2 \end{bmatrix}$

$$\begin{array}{ccc} \mathbb{R}^2 \times & = & \mathbb{R}^2 \\ \uparrow & & \uparrow \\ \text{comps} & & \text{comps} \\ \text{of } v & & T v \end{array}$$

$$A \begin{pmatrix} 1 \\ 0 \end{pmatrix} = \begin{pmatrix} 2 \\ -1 \end{pmatrix} \Leftrightarrow \begin{bmatrix} c_1 & c_2 \\ c_1 & c_2 \end{bmatrix} \begin{bmatrix} 1 \\ 0 \end{bmatrix} = \begin{bmatrix} 2 \\ -1 \end{bmatrix}$$

$$\Leftrightarrow \begin{bmatrix} c_1 \\ c_1 \end{bmatrix} = \begin{bmatrix} 2 \\ -1 \end{bmatrix}$$

$$A \begin{pmatrix} 0 \\ 1 \end{pmatrix} = \begin{pmatrix} 1 \\ 1 \end{pmatrix} \Leftrightarrow \begin{bmatrix} c_1 & c_2 \\ c_1 & c_2 \end{bmatrix} \begin{bmatrix} 0 \\ 1 \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

$$\Leftrightarrow \begin{bmatrix} c_2 \\ c_2 \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

$$\Rightarrow A = \begin{bmatrix} 2 & 1 \\ -1 & 1 \end{bmatrix}$$

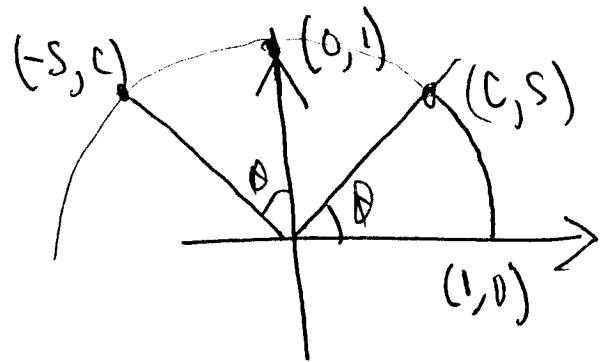
⑥

Ex(2): Find the matrix that represent rotation by angle θ in xy -plane. ⑦

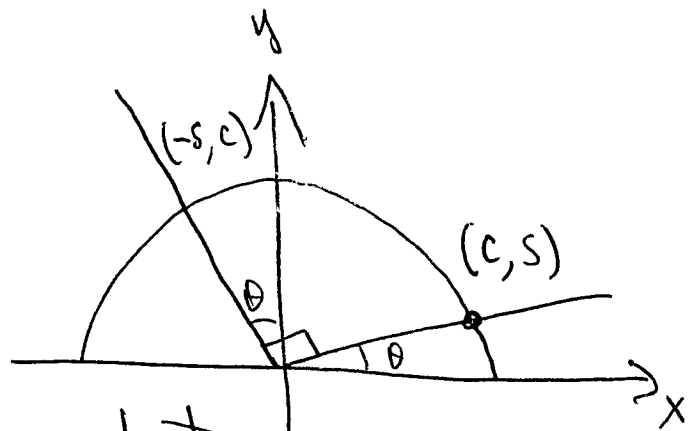
Soln: Look for 2×2 matrix $A(\theta)$ st

$$A(\theta) \begin{pmatrix} 1 \\ 0 \end{pmatrix} = \begin{pmatrix} c \\ s \end{pmatrix}$$

$$A(\theta) \begin{pmatrix} 0 \\ 1 \end{pmatrix} = \begin{pmatrix} -s \\ c \end{pmatrix}$$



$$A(\theta) = \begin{bmatrix} c & -s \\ s & c \end{bmatrix} \checkmark$$



Ex(3): Find the matrix that rotates $\theta + \phi$

$$\text{Ans: } \underbrace{\begin{bmatrix} c(\phi) & -s(\phi) \\ s(\phi) & c(\phi) \end{bmatrix}}_{\text{rotation } \phi} \underbrace{\begin{bmatrix} c(\theta) & -s(\theta) \\ s(\theta) & c(\theta) \end{bmatrix}}_{\text{rotation } \theta} \begin{bmatrix} x \\ y \end{bmatrix}$$

Check

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$$\begin{bmatrix} c(\varphi) & -s(\varphi) \\ s(\varphi) & c(\varphi) \end{bmatrix} \begin{bmatrix} c(\theta) & -s(\theta) \\ s(\theta) & c(\theta) \end{bmatrix} = \begin{bmatrix} c(\varphi)c(\theta) - s(\varphi)s(\theta) & -c(\varphi)s(\theta) - s(\varphi)c(\theta) \\ s(\varphi)c(\theta) + c(\varphi)s(\theta) & -s(\varphi)s(\theta) + c(\varphi)c(\theta) \end{bmatrix}$$

$$= \begin{bmatrix} c(\varphi+\theta) & -s(\varphi+\theta) \\ s(\varphi+\theta) & c(\varphi+\theta) \end{bmatrix} \quad \checkmark$$

~~In general: If A represents T and B represents S, then T o S is represented by B o A.~~

• In general: $S \circ T = S(Tv)$ is represented by $B \circ A$ if A rep's T & B rep's S. ✓

Ex ③: Find matrix A that projects onto line L_θ in $\mathbb{R}^2$ (9)

Soln: Find image of basis $\begin{pmatrix} 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \end{pmatrix}$

$$A \begin{pmatrix} 1 \\ 0 \end{pmatrix} = c \begin{pmatrix} c \\ s \end{pmatrix} \quad A \begin{pmatrix} 0 \\ 1 \end{pmatrix} = s \begin{pmatrix} c \\ s \end{pmatrix}$$

$$A = \begin{pmatrix} cc & sc \\ cs & ss \end{pmatrix} \equiv P(\theta)$$

check: $|A| = ccss - sclcs = 0 \quad \checkmark$

check: $P^2 = P$

$$= \begin{bmatrix} c^2c^2 + c^2s^2, & cc^2s + s^2sc \\ c^2cs + s^2cs, & c^2s^2 + s^2s^2 \end{bmatrix}$$

$$\begin{bmatrix} c^2 & cs \\ cs & s^2 \end{bmatrix} \quad \checkmark$$

$$c^2 + s^2 = 1$$

