

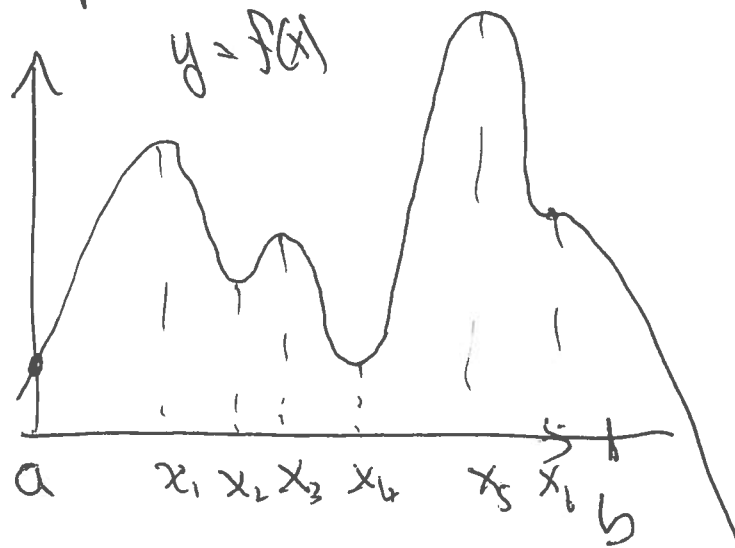
Math 21C Temple

(1)

Max/Min Pts

1-D Theory

Problem: Find max/min of f on $[a, b]$, f' has two derivatives.



Thm: The max/min occurs at a critical pt where $f'(x) = 0$ or at end pt $x = a, x = b$.

Defn: x_0 is a crit pt of f if $f'(x_0) = 0$

x_0 is a rel max if $f''(x_0) < 0$

x_0 is a rel min if $f''(x_0) > 0$

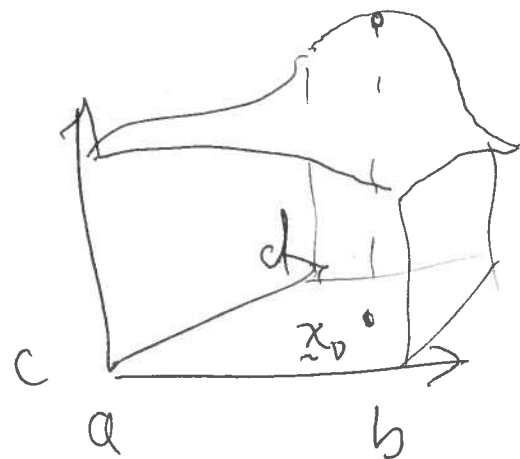
x_0 is an inflection pt if $f''(x_0) = 0$

Note: If there are pts where $f, f'(x_0)$ does not exist, then these are also critical pts.

• How Theory carries over to $\mathbb{R}^2$

Assume $z = f(x, y)$ has two derivatives

Find max/min of f on
 $[a, b] \times [c, d]$



Defn: $\underline{x}_0 = (x_0, y_0)$ is a
critical point of f if

$$\nabla f(\underline{x}_0) = 0.$$

Critical pts come in four types -

① $\underline{x}_0$ is a rel max ($|H| > 0, f_{xx} < 0$)

② $\underline{x}_0$ is a rel min ($|H| > 0, f_{xx} > 0$)

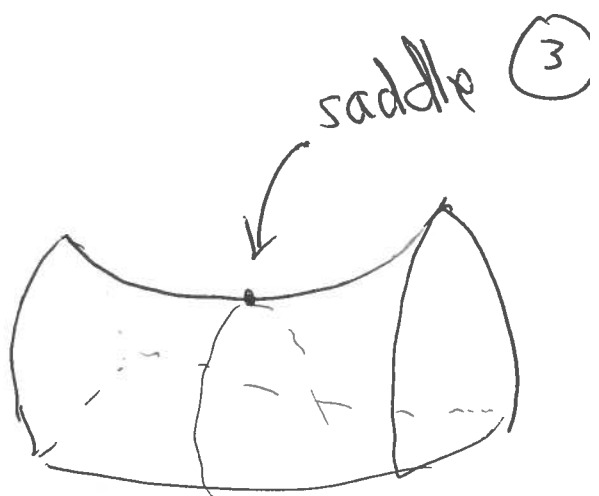
③ $\underline{x}_0$ is a saddle pt ($|H| < 0$)

④ $\underline{x}_0$ is an inflection pt ($|H| = 0$)

Saddle Point (new to $\mathbb{R}^2$)

A saddle point is a
local min in one direction

& a local max in another direction.



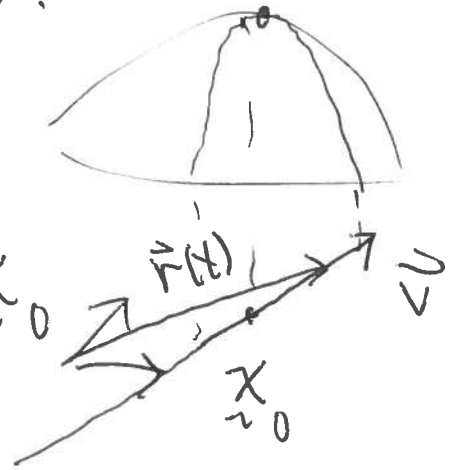
Thm: max/min occurs at rel max/rel min/
inflection or on boundary $x=a, b$ $y=c, d$
but never at a saddle pt.

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How do we understand this —

Assume $\underline{x}_0$ is a rel max.

Then it's a rel max
along every line thru $\underline{x}_0$.



• Line thru $\underline{x}_0$:

$$\vec{r}(t) = \underline{x}_0 + t \vec{v}, \quad -\infty < t < \infty$$

Consider $f(\vec{r}(t)) = f(\underline{x}_0 + t \vec{v})$

$$\frac{df}{dt} = \nabla f_0 \cdot \vec{v} = 0; \text{ assume } \nabla f(\underline{x}_0) = 0$$

ie $\underline{x}$ not critical

$$\begin{aligned} \frac{d^2 f}{dt^2} &= \frac{d}{dt} \left(\frac{\partial f}{\partial x}(\vec{r}(t)), \frac{\partial f}{\partial y}(\vec{r}(t)) \right) \cdot \vec{v} \\ &= \left[\left(\nabla \frac{\partial f}{\partial x} \right) \cdot \vec{r}'(t) + \left(\nabla \frac{\partial f}{\partial y} \right) \cdot \vec{r}'(t) \right] \cdot \vec{v} \end{aligned}$$

$$\frac{df}{dt} = \left(\frac{\partial f}{\partial x}(\underline{x}_0 + t\vec{v}), \frac{\partial f}{\partial y}(\underline{x}_0 + t\vec{v}) \right) \cdot \overrightarrow{(a, b)} \quad (5)$$

$$= \frac{\partial f}{\partial x}(\underline{x}_0 + t\vec{v}) \cdot a + \frac{\partial f}{\partial y}(\underline{x}_0 + t\vec{v}) \cdot b$$

$$\left. \frac{d^2 f}{dt^2} \right|_{t=0} = \left(\frac{\partial^2 f}{\partial x^2} a + \frac{\partial^2 f}{\partial y \partial x} b \right) a + \left(\frac{\partial^2 f}{\partial x \partial y} a + \frac{\partial^2 f}{\partial y^2} b \right) b$$

$$= (a, b) \begin{bmatrix} f_{xx} & f_{xy} \\ f_{yx} & f_{yy} \end{bmatrix} \begin{bmatrix} a \\ b \end{bmatrix}$$

$$f_{xy} = \frac{\partial}{\partial y} \frac{\partial}{\partial x} f$$

↑ ↑
1st 2nd

$$f_{xy} = f_{yx}$$

$H \equiv$ Hessian of f @ $\underline{x}_0$

Conclude: For $\underline{x}_0$ to be a rel min
we need $\vec{v}^T H \vec{v} < 0 \quad \forall \quad \vec{v} \neq 0$!
0

Similarly: For $\underline{x}_0$ to be a rel min, ⁽⁶⁾
we need $\vec{v}^T H \vec{v} > 0 \quad \forall \vec{v} \neq 0$.

Q: When will $\vec{v}^T H \vec{v}$ have the same sign for every $\vec{v} = (\vec{a}, \vec{b})$??

Ans: When $\boxed{\det H > 0}$

$$\boxed{f_{xx}f_{yy} - f_{xy}^2 > 0}$$

To determine whether it's max/min
check one value of $\vec{v}$, say $\vec{v} = (1, 0)$.

Then $(1, 0) H \begin{pmatrix} 1 \\ 0 \end{pmatrix} = f_{xx} < 0$ rel max
 > 0 rel min.

⑦

Thm: $\vec{v}^T H \vec{v}$ has one sign for every $\vec{v}$ iff $\det H > 0$.

"Proof": We need facts from matrix theory (linear alg)
 $M = \begin{pmatrix} a & b \\ c & d \end{pmatrix}$ 2×2 matrix

(1) If $M\vec{R} = \lambda\vec{R}$ some vector $\vec{R}$
we say λ is an eigenvalue and
 $\vec{R}$ its eigenvector

(2) Theorem (Symmetric Matrix Thm Big)

A symmetric matrix has real
eigenvalues and an orthonormal basis
of eigenvectors. I.e. $|\vec{R}_1| = 1 = |\vec{R}_2|$, $\lambda_1, \lambda_2 \in \mathbb{R}$
 $M\vec{R}_1 = \lambda_1\vec{R}_1$, $M\vec{R}_2 = \lambda_2\vec{R}_2$, $\vec{R}_1 \cdot \vec{R}_2 = 0$

(3) $H = \begin{bmatrix} f_{xx} & f_{xy} \\ f_{yx} & f_{yy} \end{bmatrix}$ symmetric

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$$\begin{bmatrix} -R_1 \\ -R_2 \end{bmatrix} H \begin{bmatrix} R_1 & R_2 \\ 1 & 1 \end{bmatrix} = \begin{bmatrix} \lambda_1 & 0 \\ 0 & \lambda_2 \end{bmatrix}$$

rows are eigenvectors

columns are e-vectors

$$\begin{bmatrix} -R_1 \\ -R_2 \end{bmatrix} \begin{bmatrix} R_1 & R_2 \\ 1 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

(4) $|A \cdot B \cdot C| = |A| |B| |C|$ property of matrices

$$|A^{-1}| = \frac{1}{|A|}$$

$$\left| \begin{bmatrix} -R_1 \\ -R_2 \end{bmatrix} \right| |H| \left| \begin{bmatrix} R_1 & R_2 \\ 1 & 1 \end{bmatrix} \right| = \lambda_1 \cdot \lambda_2$$

Conclude $|H| > 0$ means both eigenvalues have the same sign

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$$\textcircled{5} \quad R = \begin{bmatrix} | & | \\ R_1 & R_2 \\ | & | \end{bmatrix}$$

$$R^T H R = \begin{bmatrix} \lambda_1 & 0 \\ 0 & \lambda_2 \end{bmatrix}$$

$$H = R \begin{bmatrix} \lambda_1 & 0 \\ 0 & \lambda_2 \end{bmatrix} R^T$$

$$\vec{v}^T H \vec{v} = \underbrace{\vec{v}^T R}_{\vec{b}^T} \begin{bmatrix} \lambda_1 & 0 \\ 0 & \lambda_2 \end{bmatrix} \underbrace{R^T \vec{v}}_{\vec{b}} = \lambda_1 b_1^2 + \lambda_2 b_2^2$$

sign $\Delta \vec{v}$ sign $\Delta \vec{v}$ sign

Conclude: $\frac{d^2}{dt^2} f(\underline{x}_0 + t \vec{v})$ has sign

sign $\Delta \vec{v}$ iff $\boxed{\text{Det } H > 0}$!

Ex: A rectangular box of sides

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x, y, z has to satisfy $2x + 2y + z = 2$.

Find box that max's vol $V = xyz$.

Soln: $V = xyz = xy(2 - 2x - 2y)$
 $= 2xy(1 - x - y)$

Crit pts: $\frac{\partial V}{\partial x} = \cancel{2y}(1 - x - y) - \cancel{2xy} = 0$
 $= 2y(1 - 2x - y) = -2y^2 + 2y - 4yx$
 $\frac{\partial V}{\partial y} = \cancel{2x}(1 - x - y) - \cancel{2xy} = 0$
 $= 2x(1 - x - 2y) = -2x^2 + 2x - 4xy$
 $1 - x - y - x = 0 \quad 1 - 2x - y = 0 \quad y = 1 - 2x$
 $1 - x - y - y = 0 \quad 1 - x - 2y = 0$
 $1 - x - 2(1 - 2x) = 0$
 $\boxed{x = \frac{1}{3}, y = \frac{1}{3}}$

$$H = \begin{bmatrix} V_{xx} & V_{xy} \\ V_{yx} & V_{yy} \end{bmatrix} = \begin{bmatrix} -4y, -4y - 4x + 2 \\ -4x - 4y + 2, -4x \end{bmatrix} \quad (11)$$

$$H\left(\frac{1}{3}, \frac{1}{3}\right) = \begin{bmatrix} -\frac{4}{3}, -\frac{4}{3} + 2 \\ -\frac{8}{3} + 2, -\frac{4}{3} \end{bmatrix}$$

$$= \begin{bmatrix} -\frac{4}{3}, -\frac{2}{3} \\ -\frac{2}{3}, -\frac{4}{3} \end{bmatrix}$$

$$|H\left(\frac{1}{3}, \frac{1}{3}\right)| = \frac{16}{9} - \frac{12}{9} > 0 \quad \checkmark$$

$$V_{xx} = -\frac{4}{3} < 0 \Rightarrow \text{rel } \underline{\underline{\text{max}}} \quad \checkmark$$

Note: $V=0$ on boundary $x=0$ or $y=0$
 so only candidate is the crit pt
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