

Connection

- II-translations: we wish to construct the notion of a vector "parallel" along a curve " $c(s)$ " = "the non-rotating vectors of constant length carried with an observer in free fall"
- In a coord system x , look for a displacement rule of the form

$$dy^i = - \Gamma_{jk}^i y^j dx^k \quad (1)$$

↗

increment in coord
 y^i when x is II-translated
from x to $x+dx$

$\Gamma_{jk}^i(p) = \#$'s given at each pt in each coord system
that tell you how to construct II-translation in that
coord. system

- Specifically: given Γ_{jk}^i , $y_p = y^i \frac{\partial}{\partial x^i} \Big|_p \in T_p M$ b a curve $C(\xi)$, $C(0) = p$ with x -word representation $x(\xi) = \tilde{x}_0 C(\xi)$, we define the II-translation $y^i(\xi) \frac{\partial}{\partial x^i}$ along $x(\xi)$ as the soln of the ODE

$$\begin{cases} \frac{dy^i}{d\xi} = - \Gamma_{jk}^i y^j(\xi) \frac{dx^k}{d\xi} \\ y^i(0) = y_p^i \end{cases} \quad (*)$$

Here $\dot{x}^i(\xi) = \frac{dx^i}{d\xi} = \tilde{x}_0^i x^i \frac{\partial}{\partial x^i} = \frac{dc}{d\xi}$ is the x -word tangent to C .

- Q: How must the Γ_{jk}^i transform so that $y^i(\xi)$ transforms like a vector \equiv is indep of coordinates.

(3)

Theorem: $y^i(s)$ transforms like a vector
 $\forall x, y$ iff Γ_{jk}^i satisfies the transformation
rule (not a tensor):

$$\Gamma_{\beta\gamma}^\alpha = \Gamma_{ijk}^i \frac{\partial x^j}{\partial y^\beta} \frac{\partial x^k}{\partial y^\gamma} \frac{\partial y^\alpha}{\partial x^i} + \frac{\partial^2 x^i}{\partial y^\beta \partial y^\gamma} \frac{\partial y^\alpha}{\partial x^i} \quad (2)$$

Proof: Let $y^\alpha \frac{\partial}{\partial y^\alpha}$, $x^\beta \frac{\partial}{\partial y^\beta}$ be x, y in
y-coords, so $y^i = y^\alpha \frac{\partial x^i}{\partial y^\alpha}$, $x^i = x^\alpha \frac{\partial x^i}{\partial y^\alpha}$.
Then (*) is

$$\underbrace{\frac{d}{ds} \left(y^\alpha \frac{\partial x^i}{\partial y^\alpha} \right)}_{\parallel} = - \Gamma_{ijk}^i \frac{\partial x^j}{\partial y^\beta} \frac{\partial x^k}{\partial y^\gamma} y^\beta x^\gamma \quad (3)$$

↑
 $\left(\frac{d}{ds} y^\alpha \right) \frac{\partial x^i}{\partial y^\alpha} + \underbrace{y^\alpha \frac{d}{ds} \frac{\partial x^i}{\partial y^\alpha}}_{\text{chng summation to } \gamma}$

$$y^\gamma x^\beta \frac{\partial^2 x^i}{\partial y^\beta \partial y^\gamma}$$

(4)

50

$$\frac{d}{ds} \left(y^{\alpha} \frac{\partial x^i}{\partial y^{\alpha}} \right) = \frac{d}{ds} \frac{y^{\alpha}}{\partial y^{\alpha}} \frac{\partial x^i}{\partial x^j} + \frac{\partial y^{\alpha}}{\partial x^j} \frac{\partial^2 x^i}{\partial y^{\alpha} \partial y^j} X^j y^{\alpha}$$

Multiply (3) thru by $\left(\frac{\partial x^i}{\partial y^{\alpha}} \right)^{-1}$ gives

$$\frac{d}{ds} y^{\alpha} = - \left\{ \Gamma_{jk}^i \frac{\partial x^j}{\partial y^{\alpha}} \frac{\partial x^k}{\partial y^{\alpha}} \frac{\partial y^{\alpha}}{\partial x^i} + \frac{\partial y^{\alpha}}{\partial x^j} \frac{\partial^2 x^i}{\partial y^{\alpha} \partial y^j} \right\} X^j y^{\alpha}$$

giving (2)

check:
 "mult thru by $y^{\alpha} \frac{\partial x^i}{\partial y^{\alpha}}$ "
 $= y^{\alpha} \frac{\partial x^i}{\partial x^j} \frac{\partial x^j}{\partial y^{\alpha}}$

$$\Gamma_{jk}^{\alpha}$$

Note: indept
of P 's

Conclude: The P 's transform like a (1)
 tensor with a correction term that is
 indept of P = the same for every connection.

(5)

• Defn : We say Γ 's define a connection

Γ_{ijk}^i = Christoffel symbols (of 2nd kind)

Cor ① The difference betw two connections
is a tensor. ✓ ("Correction cancels out")

Cor ② Given Γ_{ijk}^i , $\Gamma_{ijk}^i - \Gamma_{kij}^i$ transforms
like a tensor ✓ ("Correction cancels out")

Defn : $\Gamma_{ijk}^i - \Gamma_{kij}^i = T_{ijk}^i$ is the torsion
tensor. (Measure "twist rel to nearby)
geodesics")

Cor ③ Symmetry = " $\Gamma_{ijk}^i = \Gamma_{kij}^i$ " is a
coord indept prop of connections

P.f. $T_{ijk}^i = 0$ in one coord syst $\Rightarrow 0$ in all \Rightarrow

Cor ④ $\Gamma_{ijk}^{ijk} = 0$ @ P in x-coords $\Rightarrow \Gamma$ symmetric ($T_{ijk}^i = 0$)

Cor (5): If $\Gamma_{jk}^i(p) = 0$ in x -words (\equiv Locally Inertial coordinates) then Γ symmetric & $\frac{dy^i}{ds}|_p = 0$

$$\frac{dy^i}{ds}\Big|_p = 0, \quad X(Y)_p^i = 0 \quad \forall X \in T_p M$$

so $y^i(s) = y^i(0) + O(s^2)$ \equiv "parallel translation"
 ↑ ↑
 p [dist from p]
 Keeps comp's constant to
 order s^2 "

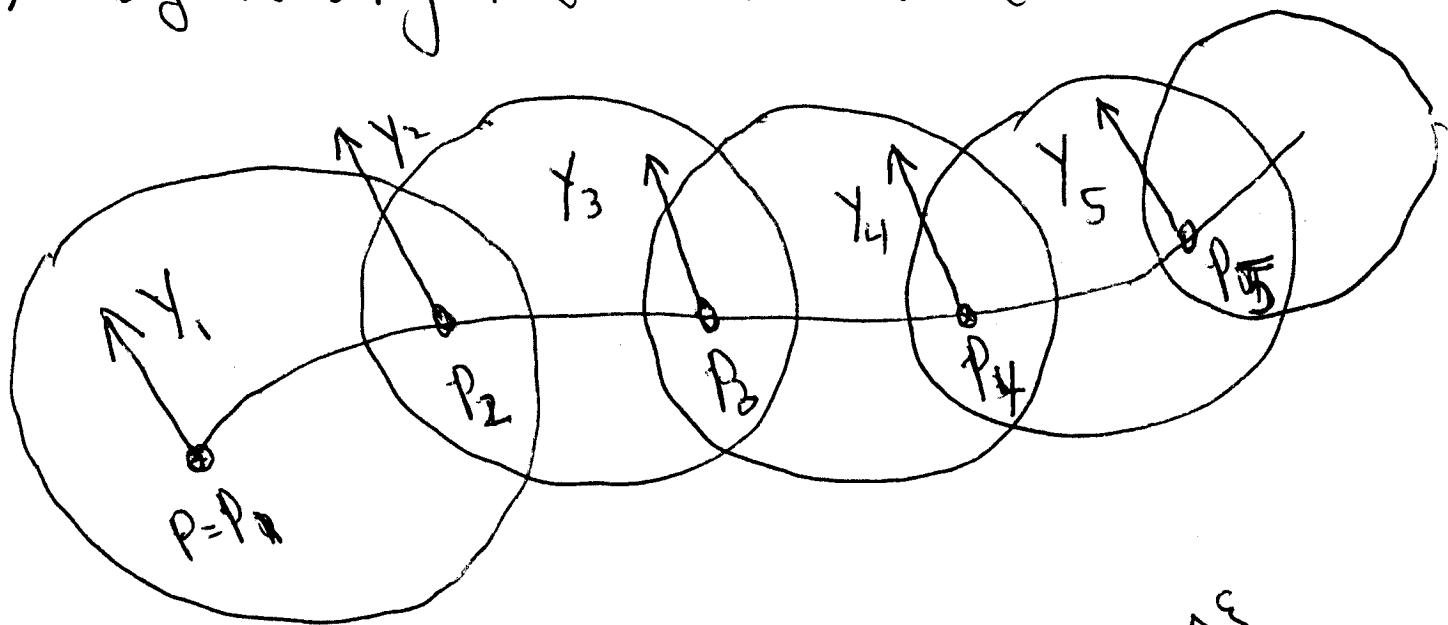
- Assumption (Special Relativity) In flat space,
 $g_{ij} = \eta_{ij}$ & $\Gamma \equiv 0$ in global Lorentz Frame

- Assumption (General Relativity) $\Gamma_{jk}^i(p) = 0$
 in every locally inertial frame @ p:

\approx locally inertial: $\begin{cases} g_{ij}(p) = \eta_{ij} \\ g_{ij,k}(p) = 0 \end{cases}$

$\Rightarrow \Gamma_{jk}^i$ for metric must be symmetric ($T_{jkl}^i = 0$)

- Conclude: In principle, given g , one can obtain the metric connection of GR by constructing a locally inertial frame @ p , & using (*) to obtain Γ_{jk}^i in any coord. syst.
- Turn this around: You can get II-trans. of y by locally inertial frames:



- Cover $C(i)$ by n pts spaced $O(\frac{1}{n}) = \Delta\xi$ apart
- II translate y^i as constant in each coord syst
- Transform y^i to $(i+1)$'s coord system in overlap.
- Incur error $\Delta\xi'$ in each $\Delta\xi$ step
- $y_n^i = y_1^i + \sum_{j=1}^n \Delta\xi^2 \xrightarrow{\text{S''}} n \Delta\xi^2 = \frac{1}{\Delta\xi} \Delta\xi^2 = \Delta\xi \rightarrow 0$

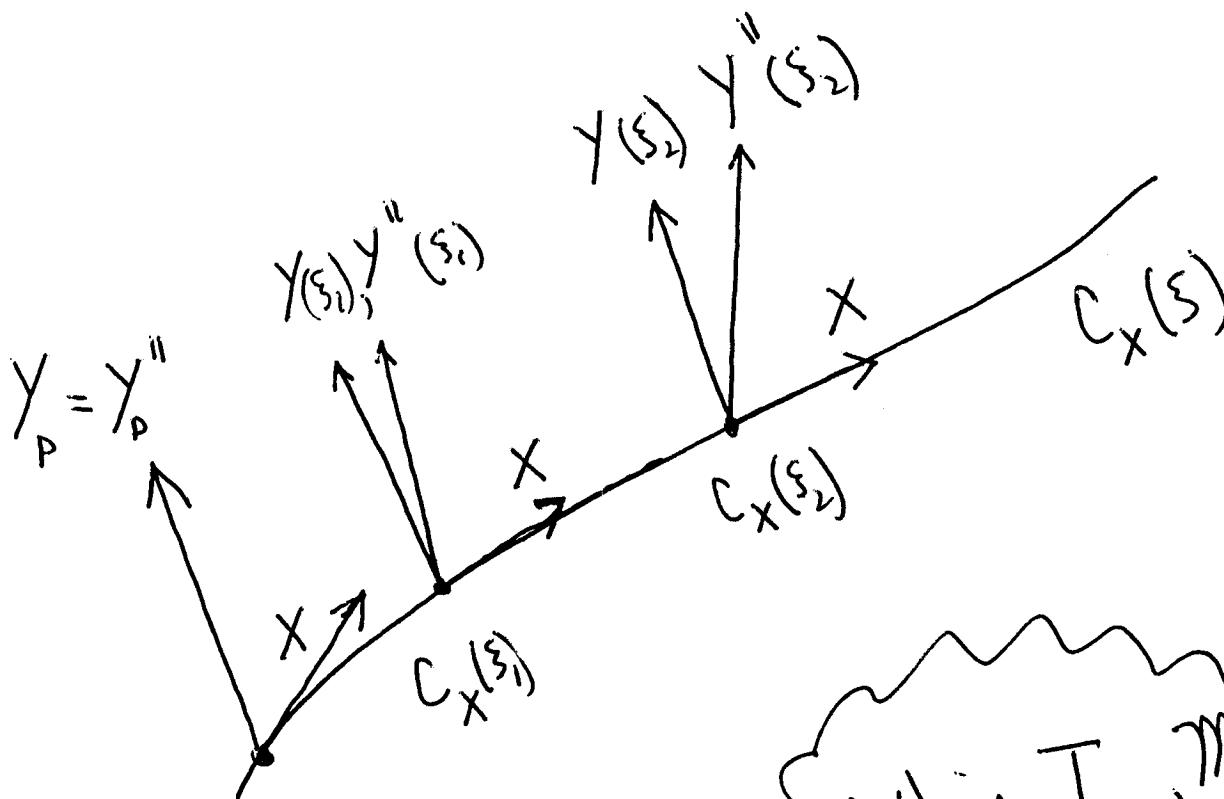
(89) Q Covariant Derivative: $\nabla_X Y$ defined by P

- Given 2 vector fields X, Y
- Let $c_x(s)$ be integral curve of X starting at $c_x(0) = p$, so $\frac{dc_x(s)}{ds} = X_{c_x(s)}$
- Let $Y(s) = Y_{c_x(s)}$
 $Y_{||}(s) \equiv \parallel\text{-trans of } Y_p \text{ to } c_x(s)$
 along c_x
- Defn: $\nabla_X Y|_p = \lim_{s \rightarrow 0} \frac{Y(s) - Y_{||}(s)}{s}$

Since both $Y(s)$ & $Y_{||}(s)$ are word indept,
 this gives word indept notion of deriv of
 vector field Y in X direction.

(only depends on $X(p)$!)

Picture $\nabla_x Y$:



$$C_x(0) = p$$

both in $T_{C_x(s)}$

$$(\nabla_x Y)_p = \lim_{s \rightarrow 0} \frac{Y(s) - Y_p}{s}$$

- The covariant derivative corrects vector differentiation to a tensor operation: $\nabla_X Y$, (9A)

$$\nabla_X Y|_p = \lim_{\xi \rightarrow 0} \frac{Y(\xi) - Y(0)}{\xi} + \lim_{\xi \rightarrow 0} \frac{Y(0) - Y_{||}(0)}{\xi}$$

$$= X(Y) - \frac{dy^i}{d\xi} \frac{\partial}{\partial x^i}$$

$$= X(Y) + \Gamma_{jk}^i y^j \frac{\partial}{\partial x^i}$$

We
only have a
coord way to
express this
limit 0

coord indent
but not a tensor

Γ gives us a coord
expression for a coord
indent thing

- In coordinates:

$$(\nabla_X Y)^i = \frac{dy^i}{d\xi} - \frac{dy^i_{||}}{d\xi} = X^\alpha y^i_{,\alpha} + \underbrace{\Gamma_{jk}^i y^j}_{\text{corrects } X(Y)} x^k$$

corrects $X(Y)$
to a tensor

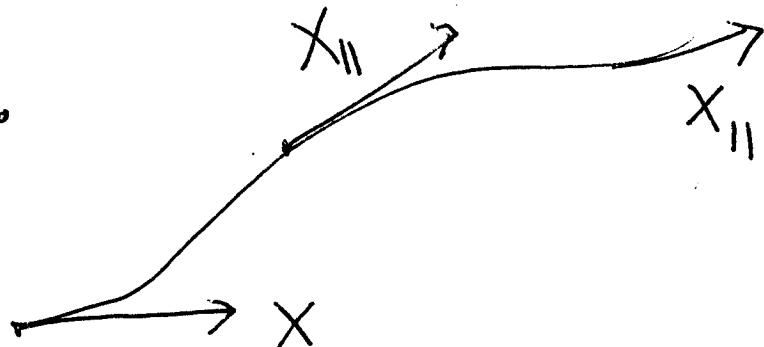
- Conclude: ∇ gives a local indept expression to the Γ 's

- Defn: Y is parallel along $c(s)$ if

$$\nabla_X Y = 0, \quad X = \frac{dc}{ds}$$

- Defn: a curve $\gamma(s)$ is a geodesic of Γ if $X = \frac{d\gamma}{ds}$ is parallel along γ .

Geodesic Equation:



$$\nabla_X X = 0 \Leftrightarrow$$

$$(\nabla_X X)^i = X^i \frac{\partial}{\partial x^i} X_{\gamma(s)} + \Gamma^i_{j k} X^j X^k = 0$$

$$\text{Since } \ddot{\gamma}(s) = \dot{\gamma}^i \Rightarrow X^i \frac{\partial}{\partial x^i} \dot{\gamma}^i = \ddot{\gamma}^i$$

$$\Leftrightarrow \boxed{\ddot{\gamma}^i + \Gamma^i_{jk} \dot{\gamma}^j \dot{\gamma}^k = 0}$$

- Conclude: ∇ gives a coordinate indept expression to the Γ 's

Properties: ($x_i \in T_p M$, y a vector field)

$$\textcircled{1} \quad \nabla_{ax_1 + bx_2} y = a \nabla_{x_1} y + b \nabla_{x_2} y \quad \left\{ \begin{array}{l} \text{any smooth fn's} \\ a, b : M \rightarrow \mathbb{R} \end{array} \right.$$

$$\textcircled{2} \quad \nabla_x (y_1 + y_2) = \nabla_x y_1 + \nabla_x y_2$$

$$\textcircled{3} \quad \nabla_x [f(p)y] = f(p) \nabla_x y + \underbrace{x(f)}_{\text{defn } \nabla_x f = X(f) \text{ so Liebniz rule holds}} \nabla_x y$$

defn $\nabla_x f = X(f)$ so Liebniz rule holds

$$\textcircled{4} \quad \nabla_x y - \nabla_y x = [x, y] = L_x y \quad (\text{when } \Gamma_{ij}^i = \Gamma_{ij}^i)$$

$$\text{Pf } \textcircled{4}: \quad \nabla_x y - \nabla_y x = X(Y) + \Gamma_{ijk}^i Y^j X^k$$

$$\begin{aligned} & [x, y] && -Y(X) - \Gamma_{ijk}^i X^j Y^k \\ & = \underbrace{X(Y) - Y(X)}_{= X(Y) - Y(X)} + \Gamma_{ijk}^i X^j Y^k && \text{We assume symmetry here on } \Gamma \end{aligned}$$

Extend ∇ to Covectors ω by requiring:

$$(\nabla_x \omega)(y) = \nabla_x(\omega(y)) \quad \forall y \text{ s.t } \nabla_x y = 0$$

"so that $\nabla_x \omega = 0$ when $\omega(y)$ evaluates parallel vector fields y along $c_x(s)$ as constant."

That is: $\nabla_x \omega = (\nabla_x \omega)_\alpha dx^\alpha$

so $(\nabla_x \omega)(y) = (\nabla_x \omega)_\alpha y^\alpha$

subject to $(\nabla_x \omega)_\alpha y^\alpha = \nabla_x(\omega(y))$ when $\nabla_x y = 0$.

So assume $\nabla_x Y = 0$, and calculate

$$\nabla_x \omega(Y) = X(\omega(Y)) = X^i \frac{\partial}{\partial x^i} (\omega_\sigma Y^\sigma)$$

$$= X^i \left(\frac{\partial}{\partial x^i} \omega_\sigma \right) Y^\sigma + X^i \omega_\sigma \frac{\partial}{\partial x^i} (Y^\sigma)$$

$$= \left(X^i \frac{\partial}{\partial x^i} \omega_\sigma \right) Y^\sigma + \omega_\sigma \left((\nabla_x Y)^\sigma - \Gamma_{ik}^\sigma Y^j X^k \right)$$

$$= \left(X^i \frac{\partial}{\partial x^i} \omega_\sigma - \Gamma_{\sigma k}^r \omega_r X^k \right) Y^\sigma$$

$$= (\nabla_x \omega)_\sigma Y^\sigma$$

$$\Rightarrow (\nabla_x \omega)_\sigma = X^i \omega_{\sigma i} - \Gamma_{\sigma k}^r \omega_r X^k$$

We ~~can~~ also write

$$\nabla_i Y = \nabla_{\frac{\partial}{\partial x^i}} Y = \left(Y_{,i}^\sigma + \Gamma_{ij}^\sigma Y^j \right) \frac{\partial}{\partial x^\sigma}$$

$$= Y^\sigma ;_i \frac{\partial}{\partial x^\sigma}$$

$$\nabla_i \omega = \omega_{\sigma ;i} dx^\sigma = (\omega_{\sigma,i} - \Gamma_{\sigma i}^r \omega_r) dx^\sigma$$

• we can extend ∇ to arb. tensor field by asking:

$$[\nabla_x T](x_1, \dots, x_n, w^1, \dots, w^k) \\ = \nabla_x [T(x_1, \dots, x_n, w^1, \dots, w^k)]$$

scalar

for all $x_1 \cdots x_n w^1 \cdots w^k \wedge$ along $C_x(\xi)$.

Formula:

$\nabla_x (T^i_j dx^j \otimes \frac{\partial}{\partial x^i})$ has components

$$x^k \frac{\partial}{\partial x^k} T^i_j + \Gamma_{\alpha\gamma}^i T^{\alpha}_j x^\gamma - \Gamma_{j\gamma}^{\alpha} T^i_{\alpha} x^\gamma = (\nabla_x T)^i_j$$

\uparrow \uparrow

a term for every
contravariant index

a term for every
covariant index.

Defn: we let ∇T denote the (tensor) with components $T_{i_1 \dots i_r}^{j_1 \dots j_s}$ when T has components $T_{i_1 \dots i_r}$.

$$(\nabla x)_j^i = x_{;j}^i = x_{,j}^i + \Gamma_{\alpha,j}^i x^\alpha \text{ etc.}$$

Properties:

① $\nabla_x T$ is a tensor for any tensor T .

② $\nabla_x (A \otimes B) = \nabla_x A \otimes B + A \otimes \nabla_x B$

~~Proof of ③~~

③ $\nabla_x (T^i_{;i}) = (\nabla_x T)^i_{;i}$

More generally, ∇_x commutes with contraction.

Ref MTW pg 223

- geodesics of a connection:

Defn: a geodesic is a curve along which the tangent vector is parallel.

Eqn for geodesic of connection:

Let $x(\xi)$ be the x -coord curve, with tangent vector $\frac{dx}{d\xi} = X$

i.e., $\frac{dx^i}{d\xi} = \dot{x}^i$.

then in x -coords, the condition $\nabla_X X = 0 \Rightarrow$

$$(\nabla_X X)^i = X^\sigma \frac{\partial}{\partial x^\sigma} X^i + \Gamma_{\sigma\tau}^i X^\sigma X^\tau$$

$$= \frac{d}{d\xi} X^i(\xi) + \Gamma_{\sigma\tau}^i X^\sigma X^\tau$$

$$= \boxed{\frac{d^2 x^i}{d\xi^2} + \Gamma_{\sigma\tau}^i \dot{x}^\sigma \dot{x}^\tau} = 0$$

! soln w i.e. $x^i(0) = x_0^i$
 $\dot{x}_i|_{\xi=0} = \dot{x}_i$

(***)

Note: if $x(s)$ solves $(\star\star)$ with initial vector X , then $x(cs)$ solves $(\star\star)$ with initial vector cX . (10c)

Thm: ^① Two symmetric connections having the same geodesics agree. ^② Geodesics for Γ_{AB} agree with geodesics for $\frac{1}{2}(\Gamma_{AB} + \Gamma_{BA})$.

Pf i.e. $\Gamma, \bar{\Gamma}$ two connections \Rightarrow in x -coord ($\frac{d^2x^i}{ds^2} + \bar{\Gamma}_{ijk}^i \dot{x}^j \dot{x}^k = 0$ iff $\frac{d^2x^i}{ds^2} + \bar{\Gamma}_{ijk}^i \dot{x}^j \dot{x}^k = 0$)

$$\frac{d^2x^i}{ds^2} + \bar{\Gamma}_{ijk}^i \dot{x}^j \dot{x}^k = 0 \text{ iff } \frac{d^2x^i}{ds^2} + \bar{\Gamma}_{ijk}^i \dot{x}^j \dot{x}^k = 0$$

$$\begin{aligned} x^i(0) &= x_0^i && \text{same i.c.'s.} \\ \dot{x}^i(0) &= \dot{x}_0^i \end{aligned}$$

$$\text{choose: } \dot{x}_0^i = \begin{cases} 1 & i=\alpha \\ 0 & \text{ow} \end{cases} \quad \text{fix } x_0^\alpha = x(p)$$

Then at p:

$$\Rightarrow \frac{d^2x^\alpha}{ds^2} = -\bar{\Gamma}_{\alpha\alpha}^\alpha (\dot{x}_0^\alpha)^2 = -\bar{\Gamma}_{\alpha\alpha}^\alpha (\dot{x}_0^\alpha)^2$$

$$\Rightarrow \bar{\Gamma}_{\alpha\alpha}^\alpha = \bar{\Gamma}_{\alpha\alpha}^\alpha \quad \text{all } \alpha$$

$$\dot{x}_0^i = \begin{cases} 1 & i=\lambda, i=\beta \\ 0 & \text{ow} \end{cases}$$

$$\Rightarrow \frac{d^2x^\lambda}{ds^2} = -\bar{\Gamma}_{\alpha B}^\lambda \dot{x}^\alpha \dot{x}^B - \bar{\Gamma}_{B\lambda}^\lambda \dot{x}^B \dot{x}^\lambda = -\bar{\Gamma}_{\alpha B}^\lambda \dot{x}^\alpha \dot{x}^B - \bar{\Gamma}_{B\lambda}^\lambda \dot{x}^B \dot{x}^\lambda$$

$$\Rightarrow \frac{1}{2}(\bar{\Gamma}_{\alpha B}^\lambda + \bar{\Gamma}_{B\lambda}^\lambda) = \frac{1}{2}(\bar{\Gamma}_{\alpha B}^\lambda + \bar{\Gamma}_{B\lambda}^\lambda)$$

(11)

Conclude: Symmetry $\Rightarrow \Gamma_{\alpha\beta}^i = \Gamma_{\beta\alpha}^i$

Non-symmetry \Rightarrow geodesics for Γ are the same as the geodesics for the symmetric connection $\tilde{\Gamma}_{\alpha\beta}^i = \frac{1}{2}(\Gamma_{\alpha\beta}^i + \Gamma_{\beta\alpha}^i) \leftarrow$

~~Assume Γ is the connection for metric~~

In a local Lorentz frame at P , the geodesics for g agree with the geodesics for Γ , $\Gamma(P) = 0$, to 1st order.

Their geodesics to agree:

Theorem 1:

Theorem: (The connection that goes with metric g) (2.1)

Assume g is a Lorentzian metric with signature $\gamma = \text{diag}(-1, 1, 1, 1)$. Let Γ be a connection whose components vanish in a coordinate frame x where (conds for local inertial frame)

$$g_{ij}(p) = \gamma \quad (i)$$

$$g_{ij,h}(p) = 0. \quad (ii)$$

Then in any other coord. frame y we must have (3iii)

$$\Gamma_{\alpha\beta}^{\gamma} = \frac{1}{2} g^{\delta\sigma} \left\{ -g_{x\beta,\sigma} + g_{\sigma\alpha,x} + g_{\beta\sigma,x} \right\}$$

thus giving a formula for the Christoffel symbols for a unique symmetric connection determined by the metric g .

Proof: The transformation law for a connection is given by

$$\bar{\Gamma}_{\alpha\beta}^\gamma = \Gamma_{ijk}^i \frac{\partial y^\gamma}{\partial x^i} \frac{\partial x^j}{\partial y^\alpha} \frac{\partial x^k}{\partial y^\beta} + \frac{\partial^2 x^i}{\partial y^\alpha \partial y^\beta} \frac{\partial y^\gamma}{\partial x^i}. \quad (\text{iv})$$

Since $\Gamma_{ijk}^i = 0$ at p , we have

$$\bar{\Gamma}_{\alpha\beta}^\gamma = \Gamma_{\alpha\beta}^\gamma(p) = \frac{\partial^2 x^i}{\partial y^\alpha \partial y^\beta} \frac{\partial y^\gamma}{\partial x^i}. \quad (\text{v})$$

Now the components of the metric $g_{\alpha\beta}$ are given by

$$g_{\alpha\beta} = \frac{\partial x^i}{\partial y^\alpha} \gamma_{ij} \frac{\partial x^j}{\partial y^\beta} \quad (\text{vi})$$

$$\Leftrightarrow g = J^T \gamma J \quad (\text{matrix notation}) \quad (\text{vii})$$

Differentiating (v²) and using (ii) gives

$$g_{\alpha B, \gamma}(\eta) = \eta_{ij} \underbrace{\frac{\partial^2 x^i}{\partial y^\alpha \partial y^\gamma} \frac{\partial x^j}{\partial y^B}}_{\Delta_{\alpha B, \gamma}} + \eta_{ii} \underbrace{\frac{\partial x^i}{\partial y^\alpha} \frac{\partial^2 x^i}{\partial y^B \partial y^\gamma}}_{\Delta_{B \gamma, \alpha}}.$$

Now

$$\Delta_{\alpha B, \gamma}$$

$$\Delta_{B \gamma, \alpha}$$

Notation

so $\Delta_{\alpha B, \gamma} = \Delta_{\gamma \alpha, B}$. (equality of mixed partials)

Therefore,

$$\begin{aligned}
 -g_{\alpha B, \gamma} + g_{\gamma \alpha, B} + g_{B \gamma, \alpha} &= -\cancel{\Delta_{\alpha B, \gamma}} - \cancel{\Delta_{\gamma \alpha, B}} \\
 &\quad + \cancel{\Delta_{B \gamma, \alpha}} + \Delta_{\alpha B, \gamma} \\
 &\quad + \Delta_{B \gamma, \alpha} + \cancel{\Delta_{\gamma \alpha, B}} \\
 &= 2 \Delta_{\alpha B, \gamma} = 2 \eta_{ij} \frac{\partial^2 x^i}{\partial y^\alpha \partial y^B} \frac{\partial x^j}{\partial y^\gamma}
 \end{aligned}$$

Now consider:

$$\left(g^{\alpha\beta} \right)_{4 \times 4} = \left(g_{\alpha\beta} \right)^{-1}_{4 \times 4} = (J^t \gamma J)^{-1} = J^{-1} \gamma (J^t)^{-1}$$

Consider now the expression

$$\frac{1}{2} g^{\alpha\sigma} \left\{ -g_{\alpha B, \sigma} + g_{\sigma d, B} + g_{B \sigma, d} \right\}$$

$$= g^{\alpha\sigma} \left\{ \gamma_{ij} \underbrace{\frac{\partial^2 x^j}{\partial y^\alpha \partial y^B}}_{J^{-1} \gamma (J^t)^{-1}} \underbrace{\frac{\partial x^i}{\partial y^\sigma}}_{J^t \gamma M_B} \right\}$$

$$J^{-1} \gamma (J^t)^{-1} \quad J^t \gamma M_B \quad M_B = \frac{\partial^2 x^j}{\partial y^\alpha \partial y^B}$$

$$= J^{-1} \gamma (J^t)^{-1} J^t \gamma M_B = J^{-1} M_B$$

$$= \frac{\partial y^x}{\partial x^i} \frac{\partial^2 x^i}{\partial y^x \partial y^B} = \Gamma_{\alpha B}^x \quad \checkmark$$

(12.5)

Cor ①: The geodesics for metric g satisfy the geodesic equation, Γ given in (ii):

$$\frac{d^2x^i}{ds^2} + \Gamma_{jk}^i \frac{dx^j}{ds} \frac{dx^k}{ds} = 0. \quad (\text{GD})$$

Thm: curves that satisfy (GD) are critical points of the $(\text{length})^2$ (Do both & spacetime curves separately)

$$\begin{aligned} \text{Length} \in A[c(\cdot)] &= \int_{\xi_1}^{\xi_2} \|\dot{x}(s)\|^2 ds \\ &= \int_{\xi_1}^{\xi_2} \langle \dot{x}, \dot{x} \rangle ds = \int_{\xi_1}^{\xi_2} g_{ij} \dot{x}^i \dot{x}^j ds. \end{aligned}$$

\Rightarrow The Euler-Lagrange eqns are equiv. to (GD) Ref Spivak. Dubrovin Novikov Modern geom I

Cor(2). Let $T_{\alpha B}^\gamma$ be any torsion tensor, (12.6)

$$T_{\alpha B}^\gamma = \Gamma_{\alpha B}^\gamma - \Gamma_{\beta \alpha}^\gamma,$$

so $T_{\alpha B}^\gamma$ any antisymmetric tensor. Then

if $\tilde{\Gamma}_{\alpha B}^\gamma$ is given by (iii), it follows that

$$\tilde{\Gamma}_{\alpha B}^\gamma = \Gamma_{\alpha B}^\gamma + T_{\alpha B}^\gamma$$

has the same geodesics as Γ , but is not symmetric.

We could show: non-symmetry introduces a twist rel to nearby geodesics.

Cor(3) 3! symmetric connection whose geodesics are geodesics of the metric.

Lemma: Let g have connection $\Gamma \leftrightarrow \nabla$.

Then

$$\textcircled{1} \quad \nabla_z g = 0 \quad \forall z$$

and

$$\textcircled{2} \quad \nabla_z (g_{ij}(x^i, x^j)) = g_{ij}(\nabla_z x^i)^j + g_{ij}(x^i(\nabla_z))^j$$

Note: $\textcircled{2} \Rightarrow$ angles & lengths are preserved under
lt-translations.

Proof: For $\textcircled{1}$, go to a locally Cartesian

coord frame where $g_{ij,h} = 0$ & $\Gamma_{jh}^i = 0$.

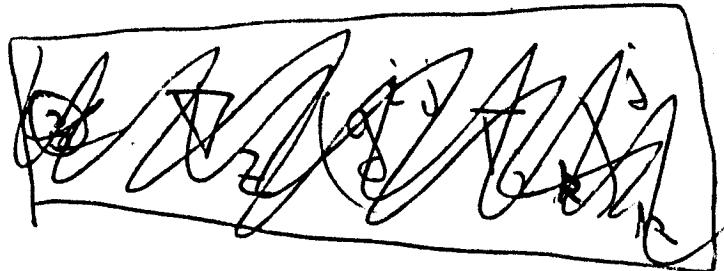
Formula for cov. deriv $\Rightarrow \nabla_z g = 0$.

$\nabla_z g$ a tensor $\Rightarrow \nabla_z g = 0$ in all coords. ✓

~~For $\textcircled{2}$, write $\nabla_z(g_{ij}(x^i, x^j))$~~

Corollary: For metric connection: ∇ for g :

$$\textcircled{2} \quad \nabla_Z \langle X, Y \rangle = \langle \nabla_Z X, Y \rangle + \langle X, \nabla_Z Y \rangle$$



$$\textcircled{3} \quad \nabla_Z (g_{\alpha i} X^\alpha dx^i)_i = g_{\alpha i} \nabla_Z (X^\alpha \frac{\partial}{\partial x^\alpha})^i$$

More generally - ∇_Z commutes with raising & lowering of indices (FIP)

Note:

\textcircled{2} \Rightarrow if X, Y are parallel along $C_X(\xi)$,
then $\nabla_Z \langle X, Y \rangle = Z(\langle X, Y \rangle) = 0 \Rightarrow$

II-translations preserves lengths & angles
btw vectors.

ProofFor ②, write $T = g \otimes X \otimes Y$. Then

$$\nabla_z T = \underbrace{\nabla_z g}_{0} \otimes X \otimes Y + g \otimes \nabla_z X \otimes Y + g \otimes X \otimes \nabla_z Y$$

But: ∇_z (a contraction of T) = contraction of $(\nabla_z T)$

LHS : $\nabla_z (g_{ij} x^k y^\ell dx^i \otimes dx^j \otimes \frac{\partial}{\partial x^k} \otimes \frac{\partial}{\partial x^\ell})$

$\brace{contract \ twice}$

$$\Rightarrow \nabla_z (g_{ij} x^i y^j) = \nabla_z \langle x, y \rangle$$

RHS : $g_{ij} (\nabla_z x)^k y^\ell dx^i \otimes dx^j \otimes \frac{\partial}{\partial x^k} \otimes \frac{\partial}{\partial x^\ell}$

$\brace{contract \ twice}$

$$\Rightarrow g_{ij} (\nabla_z x)^i y^j = \langle \nabla_z x, y \rangle$$

Sim: contract: $g \otimes X \otimes \nabla_z Y \rightarrow \langle X, \nabla_z Y \rangle$ 

Corollary : along a geodesic, $\langle X, X \rangle$

is constant (i.e., $\nabla_X X = 0$) \Rightarrow

timelike geodesics remain timelike

spacelike " " spacelike

null " " null. ✓

Assume : Free fall paths are timelike geodesics

light rays follow null geodesics.

□ Lie Deriv as a Covariant Derivative

Theorem: Let Γ be any connection & ∇ its covariant derivative. Then

$$(L_y T)_j^i \equiv \left(\frac{d}{ds} \Big|_{s=0} T_{\varphi_s(p)} \Big|_{s=0} \right)_j^i$$

$$= (\nabla_y T)_j^i - T_j^\sigma (\nabla_\sigma y)_j^i + T_i^\sigma (\nabla_j y)_\sigma^i \quad (*)$$

Cor

↑ one for every
up index

↑ one for
every down
index

$$\text{Cor: } (L_y g)_{ij} = (\nabla_y g)_{ij} + g_{\sigma j} \nabla_i y^\sigma + g_{i\sigma} \nabla_j y^\sigma$$

$$= \nabla_i y_j + \nabla_j y_i = y_{j;i} + y_{i;j}$$

P.F. of theorem: $L_y f = Y(f)$; $L_y X = [Y, X]$ (5c)

$$L_y (W_\sigma X^\sigma) = Y(W_\sigma X^\sigma)$$

*apply to every
down index $T_{-\sigma}$*

Also

$$L_y (W_\sigma X^\sigma) = (L_y W)_\sigma X^\sigma + W_\sigma (L_y X)^\sigma$$

$$= (L_y W)_\sigma X^\sigma + W_\sigma [Y, X]^\sigma \quad (A)$$

$$= (L_y W)_\sigma X^\sigma + W_\sigma \underbrace{((\nabla_y X)^\sigma - (\nabla_x Y)^\sigma)}$$

$$Y(W_\sigma X^\sigma) = (\nabla_y W)_\sigma X^\sigma + W_\sigma \underbrace{(\nabla_y X)^\sigma} \quad (B)$$

Equating (A) & (B) :

$$(\nabla_y W)_\sigma X^\sigma = (L_y W)_\sigma X^\sigma - W_\sigma (\nabla_x Y)^\sigma$$

$$X = \frac{\partial}{\partial x^i} : \quad (L_y W)_i = (\nabla_y W)_i + W_\sigma \nabla_{\frac{\partial}{\partial x^i}} Y^\sigma$$

* Divergence: Given a vector field X , define

$$\operatorname{div} X = X^i_{,i} \quad \text{a scalar.}$$

• in Local Current coord's, $\operatorname{div} X = X^i_{,i} \equiv$ classical divergence.

Theorem: $\operatorname{div} X = \frac{1}{\sqrt{g}} (X^i \sqrt{g})_{,i}$

Proof: $X^i_{,i} = X^i_{,i} + \Gamma^i_{\alpha i} X^\alpha$

We evaluate $\Gamma^i_{\alpha i} = \Gamma^i_{i\alpha}$:

We know from $\nabla g = 0$ that

$$0 = g_{ij,k} - \Gamma^{\alpha}_{ik} g_{\alpha j} - \Gamma^{\alpha}_{jk} g_{\alpha i}$$

Mult by g^{ij} & contract:

$$0 = g^{ij} g_{ij,k} - \Gamma^i_{ik} - \Gamma^j_{jk} \Rightarrow \Gamma^i_{ik} = \frac{1}{2} g^{ij} g_{ij,k}$$

i.e., $g_{\alpha j} g^{ij} = \delta_\alpha^i$

$$\text{But: } g^{ij} = \frac{1}{g} \Delta^{ij}$$

matrix
of
cofactors

$$g = \det g_{ij} \quad (17)$$

$$\Delta^{ij} = (-1)^{i+j} \text{subdet } g_{ij}$$

$$\Delta^{ij} = \frac{\partial g}{\partial g_{ij}} \quad \leftarrow \text{just expand } g \text{ by } i\text{th column.}$$

$$\Rightarrow \Gamma_{ik}^i = \frac{1}{2} g^{ij} g_{ij,k} = \frac{1}{2} \frac{\partial g}{\partial g_{ij}} \frac{\partial g_{ij}}{\partial x^k} = \frac{1}{2} \frac{\partial}{\partial x^k} \ln |g|$$

$$= \frac{\partial}{\partial x^k} \log \sqrt{-g} = \frac{1}{\sqrt{-g}} \frac{\partial}{\partial x^k} \sqrt{-g}$$

Thus:

$$\boxed{\Gamma_{ik}^i = \frac{\partial}{\partial x^k} \log \sqrt{-g}},$$

and

$$\text{div } X = X^i_{,i} + \underbrace{\frac{1}{\sqrt{-g}} \left(\frac{\partial}{\partial x^k} \sqrt{-g} \right)}_{\text{from above}} X^k$$

$$= \sqrt{-g} (X^i \sqrt{-g})_{,i}$$

(12)

 Gauss Theorem: A coordinate indept version of div theorem that holds for vector fields:

Theorem: $F = F^i \frac{\partial}{\partial x_i}$ a vector field. Then

$$\int_{\Omega^4} \operatorname{div} F \, \eta = \int_{\partial\Omega^4} \underbrace{\langle F, n \rangle}_{\langle n, n \rangle} \, \eta \lrcorner n = \int_{\partial\Omega^4} F^\alpha d\Sigma_\alpha$$

Here: $\eta = \sqrt{g} \epsilon$ volume form

$\Omega \in$ 4-dimensional region

$\operatorname{div} F = F^\alpha ;_\alpha$ a scalar

n = unit outward normal to $\partial\Omega$,
normal relative to metric $g, \langle \rangle$.

$$d\Sigma_\alpha = \eta \lrcorner \frac{\partial}{\partial x^\alpha}$$

Proof: By previous result,

(19)

$$F_{;\alpha}^\alpha = \frac{1}{\sqrt{g}} (F \sqrt{g}),_\alpha .$$

Assume Ω lies in a single coord chart: x :
Then the Classical Divergence Thm holds as follows:

$$\int_{\Omega} F_{;\alpha}^\alpha \varepsilon = \int_{\Omega} F_{;\alpha}^\alpha \sqrt{g} \varepsilon = \int_{\Omega} \frac{1}{\sqrt{g}} (F^\alpha \sqrt{g})_{,\alpha} \sqrt{g} \varepsilon$$

$$= \int_{\Omega} (F^\alpha \sqrt{g})_{,\alpha} \varepsilon \quad \begin{matrix} \uparrow \\ \text{coordinate} \\ \text{volume } dV \end{matrix} \quad = \int_{\partial\Omega} F \cdot \vec{n} \sqrt{g} \varepsilon \underbrace{\downarrow \vec{n}}_{ds} = *$$

↑
 $\partial\Omega$

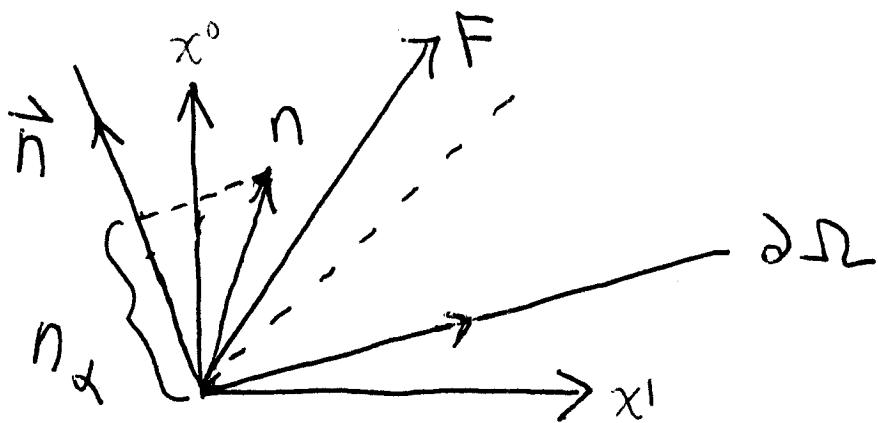
Classical
Divergence
Thm

\equiv Euclidean
surface area

where \vec{n} is the coordinate unit ^{outer} normal to $\partial\Omega$,

(20)

Now: if \vec{n} is the Euclidean coordinate normal,
 and $n = n^\alpha \frac{\partial}{\partial x^\alpha}$ is the metric unit normal,
 then $\vec{n}^i \neq n_i$: Eg



$$* = \int_{\partial\Omega} F \cdot g \in \perp \{ (F \cdot \vec{n}) \vec{n} + F - (F \cdot \vec{n}) \vec{n} \}_{\text{in } T_p \partial\Omega}$$

$$= \int_{\partial\Omega} \eta \perp F = \int_{\partial\Omega} F^\alpha d\Sigma_\alpha$$

no contribution
for $x_1 \dots x_3 \in T_p \partial\Omega$

$$d\Sigma_\alpha = \eta \perp \frac{\partial}{\partial x^\alpha}$$

(21)

But we can also write

$$\int_{\partial\Omega} \eta \lrcorner F = \int_{\partial\Omega} \eta \lrcorner \left\{ \frac{\langle F, n \rangle}{\langle n, n \rangle} n + F - \frac{\langle F, n \rangle}{\langle n, n \rangle} n \right\}$$

in $T\partial\Omega$

$$= \int_{\partial\Omega} \eta \lrcorner \left\{ \frac{\langle F, n \rangle}{\langle n, n \rangle} n \right\} = \int_{\partial\Omega} \underbrace{\frac{\langle F, n \rangle}{\langle n, n \rangle}}_{\substack{\text{metric} \\ \text{version of} \\ "F \cdot n"}}, \eta \lrcorner n$$

\uparrow
 \uparrow
metric
version
of
"ds"

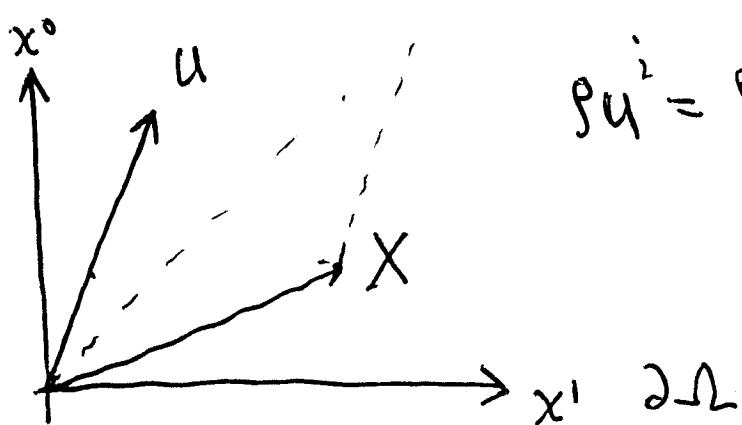
Application: Cons. of mass principle

Ex: $\rho(x) = \frac{\text{mass}}{3\text{-vol}}$ in rest frame \approx dust.

$$u = \frac{dx^i}{d\xi} \quad \text{4-velocity of particles}$$

$$d\xi = \sqrt{(dx^0)^2 - |dx|^2} = \sqrt{1 - |\vec{v}|^2} dx^0$$

$$\frac{dx^0}{d\xi} = \frac{1}{\sqrt{1 - |\vec{v}|^2}} = \text{Lorentz contraction Factor}$$



$$\rho u^i = \rho \frac{dx^0}{d\xi} \frac{dx^i}{dx^0}$$

$$\frac{\text{mass}}{3\text{-vol}} \text{ in } x\text{-frame} = \rho \frac{dx^0}{d\xi} = \left\langle \rho u, \frac{\partial}{\partial x^0} \right\rangle$$

$$\frac{\text{mass}}{\text{area } \Delta x^0} \text{ in } x\text{-frame} = \underbrace{\rho \frac{dx^0}{d\xi}}_{\frac{\text{mass}}{3\text{-vol}}} \underbrace{\frac{dx^1}{dx^0}}_{\frac{\text{dist}}{\text{time}}} = \left\langle \rho u, \frac{\partial}{\partial x^1} \right\rangle$$

Conclude: At each pt. on $\partial\Omega$

$$\langle \rho u, n \rangle = \frac{\text{mass}}{\text{metric 3-vol}} \equiv \begin{cases} \text{density if } n \text{ timelike} \\ \text{mass flux if } n \text{ spacelike} \end{cases}$$

$\uparrow \quad \uparrow$
coordinate indept
meaning

$$\therefore \frac{\langle \rho u, n \rangle}{\langle n, n \rangle} \eta \downarrow n (x_1, x_2, x_3)$$

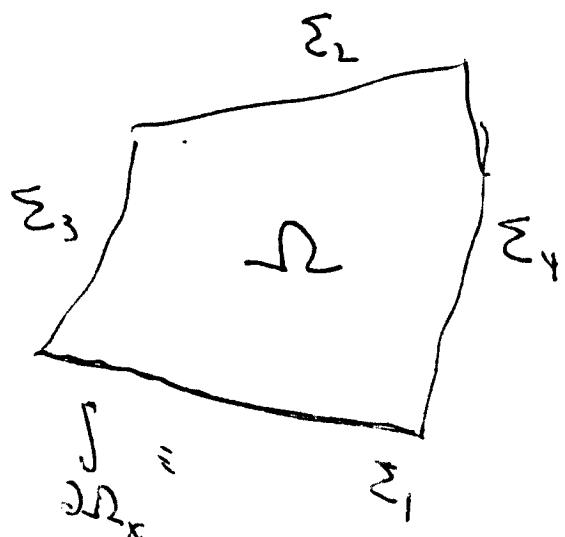
evaluates the total mass in 3-hypervolume x_1, x_2, x_3
(per 100rd vol)

$$\int_{\partial\Omega} \frac{\langle \rho u, n \rangle}{\langle n, n \rangle} \eta \downarrow n = \int_{\partial\Omega_x} \frac{\langle \rho u, n \rangle}{\langle n, n \rangle} n \downarrow n \left(\frac{\partial}{\partial x^1} \frac{\partial}{\partial x^2} \frac{\partial}{\partial x^3} \right) dx^1 dx^2 dx^3$$

$$\int_{\Sigma_1} = \text{"total mass at } \Sigma_1\text{"}$$

$$\int_{\Sigma_2} = \text{"total mass at } \Sigma_2\text{"}$$

$$\int_{\Sigma_3, \Sigma_4} = \text{"total mass passing out of } \Omega\text{ through } \Sigma_3, \Sigma_4\text{"}$$



\Rightarrow Global coord indept statement of law of mass is

$$0 = \int_{\partial\Omega} \frac{\langle \rho u, n \rangle}{\langle n, n \rangle} \eta \downarrow_n = \int_{\Omega} \operatorname{div} \rho u \Leftrightarrow \boxed{\operatorname{div} \rho u = 0}$$

- Note: since $\int_{\partial\Omega} \frac{\langle \rho u, n \rangle}{\langle n, n \rangle} \eta \downarrow_n = \int_{\partial\Omega} \rho u^i d\Sigma_i$,

we can think of $\rho u^i d\Sigma_i$ as "eating 3-vols $x_1 x_2 x_3$ " & evaluating the total mass in them \equiv mass flux if one of the x_i is timelike

Ref MTW.

For energy & momentum:

$\rho \frac{dx^0}{ds} u$ energy flux vector

$\rho \frac{dx^i}{ds} u$ i -momentum flux vector

extra factor of $\frac{dx^0}{ds}$ needed because
~~energy~~ increases with velocity due to
 Lorentz Contr effect + increase in KE.

Components of tensor: $T^{ij} = \rho u^i u^j$

Conclude: $F = \rho \frac{dx^0}{ds} u$ satisfies Global Cons

law

$$\int \frac{\langle F, n \rangle}{\partial \Omega \langle n, n \rangle} d\Gamma n = 0 \quad (\star)$$

only so long as F transforms like a
 Vector. It does under Linear coord

(21)

transformations \Rightarrow global inv. chas. law

holds in Special Relativity when we restrict to ~~exact~~ Lorentz transformations.

In general relativity, we can only require local cons of energy

$$\boxed{\text{div } T = 0 = T^{\sigma}_{\sigma; \alpha}}$$

This reproduces (*) in flat space & approximately reproduces (*) in loc Lorentz frames where $g_{ij} = \eta_{ij} + O(|x|^2)$.