

Connection

- \parallel -translation: we wish to construct the notion of a vector "parallel" along a curve " $C(s)$ " \equiv "the non-rotating vectors of constant length carried with an observer in freefall"
- In a coord system x , look for a displacement rule of the form

$$dy^i = - \Gamma_{jk}^i y^j dx^k \quad (1)$$

↑
increment in coord
 y^i when x is \parallel -translated
from x to $x+dx$

$\Gamma_{jk}^i(p) \equiv$ #'s given at each pt in each coord system
that tell you how to construct \parallel -translation in that
coord. system

- ②
- Specifically: given Γ_{jk}^i , $Y_p = Y^i \frac{\partial}{\partial x^i} \Big|_p \in T_p M$
 & a curve $c(s)$, $c(0) = p$ with x -word
 representation $x(s) = \tilde{x} \circ c(s)$, we define
 the \parallel -translation $Y^i(s) \frac{\partial}{\partial x^i}$ along $x(s)$
 as the soln of the ODE

$$\begin{cases} \frac{dY^i}{ds} = - \Gamma_{jk}^i Y^j(s) \frac{dx^k}{ds} \\ Y^i(0) = Y_p^i \end{cases} \quad (*)$$

Here $\dot{x}^i(s) = \frac{dx^i}{ds} = \dot{x}^i$ so $x^i \frac{\partial}{\partial x^i} = \frac{dc}{ds}$ is the
 \tilde{x} -word tangent to c .

- Q: How must the Γ_{jk}^i transform so that
 $Y^i(s)$ transforms like a vector \in is indept
 of coordinates.

(3)

Theorem: $y^i(\xi)$ transform like a vector
 $\forall X, Y$ iff Γ_{jk}^i satisfies the transformation
 rule (not a tensor):

$$\Gamma_{\beta\gamma}^\alpha = \Gamma_{jk}^i \frac{\partial x^j}{\partial y^\beta} \frac{\partial x^k}{\partial y^\gamma} \frac{\partial y^\alpha}{\partial x^i} + \frac{\partial^2 x^i}{\partial y^\beta \partial y^\gamma} \frac{\partial y^\alpha}{\partial x^i} \quad (2)$$

Proof: Let $Y^\alpha \frac{\partial}{\partial y^\alpha}$, $X^\beta \frac{\partial}{\partial y^\beta}$ be X, Y in
 y -words, so $y^i = y^\alpha \frac{\partial x^i}{\partial y^\alpha}$, $x^i = x^\alpha \frac{\partial x^i}{\partial y^\alpha}$.

Then (*) is

$$\underbrace{\frac{d}{d\xi} \left(y^\alpha \frac{\partial x^i}{\partial y^\alpha} \right)}_{= - \Gamma_{jk}^i \frac{\partial x^j}{\partial y^\beta} \frac{\partial x^k}{\partial y^\gamma} y^\beta x^\gamma} = - \Gamma_{jk}^i \frac{\partial x^j}{\partial y^\beta} \frac{\partial x^k}{\partial y^\gamma} y^\beta x^\gamma \quad (3)$$

$$\left(\frac{d}{d\xi} y^\alpha \right) \frac{\partial x^i}{\partial y^\alpha} + \underbrace{y^\alpha \frac{d}{d\xi} \frac{\partial x^i}{\partial y^\alpha}}_{y^\beta x^\gamma \frac{\partial^2 x^i}{\partial y^\beta \partial y^\gamma}} \quad \leftarrow \text{chg summation to } \gamma$$

so

$$\frac{d}{ds} \left(y^\alpha \frac{\partial x^i}{\partial y^\alpha} \right) = \frac{d y^\alpha}{ds} \frac{\partial x^i}{\partial y^\alpha} + \frac{\partial y^\alpha}{\partial x^j} \frac{\partial^2 x^i}{\partial y^\beta \partial y^\gamma} X^\beta y^\gamma$$

Multiply thru by $\left(\frac{\partial x^i}{\partial y^\alpha} \right)^{-1}$ gives

$$\frac{d}{ds} y^\alpha = - \left\{ \sum_{j \neq i} \frac{\partial x^j}{\partial y^\beta} \frac{\partial x^k}{\partial y^\gamma} \frac{\partial y^\alpha}{\partial x^i} + \frac{\partial y^\alpha}{\partial x^i} \frac{\partial^2 x^i}{\partial y^\beta \partial y^\gamma} \right\} X^\beta y^\gamma$$

giving (2)

check: $y^\alpha \frac{\partial x^i}{\partial y^\alpha} = 1$
 "mult thru by $\left(\frac{\partial x^i}{\partial y^\alpha} \right)^{-1}$ "
 $= y^\alpha \frac{\partial x^i}{\partial x^i} = y^\alpha$

$$\sum_{\beta \neq \gamma}^\alpha$$

Note: indept of P 's

Conclude: The P 's transform like a $\begin{pmatrix} 1 \\ 2 \end{pmatrix}$ tensor with a correction term that is indept of $P \equiv$ the same for every connection.

(5)

• Defn: We say Γ 's define a connection

$\Gamma_{jk}^i \equiv$ Christoffel Symbols (of 2nd kind)

Cor ① The difference betw two connections is a tensor, ✓ ("Correction cancels out")

Cor ② Given Γ_{jk}^i , $\Gamma_{jk}^i - \Gamma_{kj}^i$ transforms like a tensor ✓ ("Correction cancels out")

Defn: $\Gamma_{jk}^i - \Gamma_{kj}^i \equiv T_{jk}^i$ is the torsion tensor. (Measure "twist rel to nearby geodesics")

Cor ③ Symmetry $\equiv \Gamma_{jk}^i = \Gamma_{kj}^i$ is a coord indept prop of connections

P.f. $T_{jk}^i = 0$ in one coord syst $\Rightarrow 0$ in all... ✓

Cor ④ $\Gamma_{jk}^{i0} = 0$ @ P in \underline{x} -coords $\Rightarrow \Gamma$ symmetric ($T_{jk}^i = 0$ 0)

Cor ⑤: If $\Gamma_{jk}^i(p) = 0$ in \underline{x} -coords (\equiv Locally Inertial coordinates) then Γ symmetric & $dy^i = 0|_p$

$$\left. \frac{dy^i}{ds} \right|_p = 0, = X(Y)^i_p = 0 \quad \forall X \in T_p M$$

so $y^i(s) = y^i(0) + O(s^2) \equiv$ "parallel translation"
 (dist from p) keeps comp's constant to order s^2

• Assumption (Special Relativity) In flat space, $g_{ij} = \eta_{ij}$ & $\Gamma \equiv 0$ in global Lorentz Frame

• Assumption (General Relativity) $\Gamma_{jk}^i(p) = 0$ in every locally inertial frame @ p :

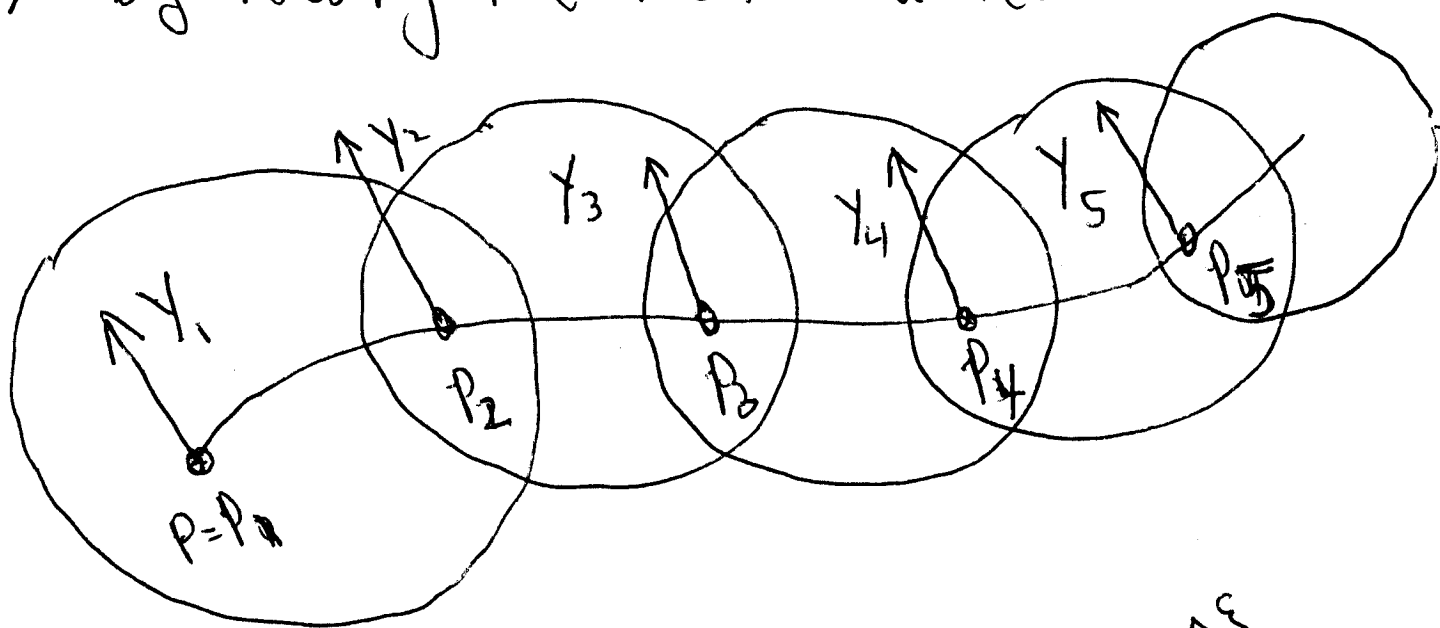
$$\underline{x} \text{ locally inertial: } \begin{cases} g_{ij}(p) = \eta_{ij} \\ g_{ij,k}(p) = 0 \end{cases}$$

$\Rightarrow \Gamma_{jk}^i$ for metric must be symmetric ($\Gamma_{jk}^i = \Gamma_{kj}^i$)

(7)

• Conclude: In principle, given g , one can obtain the metric connection of GR by constructing a locally inertial frame @ p , & using (*) to obtain Γ_{jk}^i in any coord. syst.

• Turn this around: You can get ll-trans. of γ by locally inertial frames:



• Cover $C(\xi)$ by n pts spaced $O(\frac{1}{n}) = \Delta\xi$ apart

• ll translate γ^i as constant in each coord syst

• Transform γ^i to $(i+1)$'s coord system in overlap

• Incur error $\Delta\xi^2$ in each $\Delta\xi$ step

• $\gamma_n^i = \gamma_{11}^i + \sum_{j=1}^n \Delta\xi^2 \leftarrow S'' n \Delta\xi^2 = \frac{1}{\Delta\xi} \Delta\xi^2 = \Delta\xi \rightarrow 0$

② Covariant Derivative: $\nabla_X Y$ defined by Γ ⁽⁸⁹⁾

- Given 2 vector fields X, Y

- Let $C_X(s)$ be integral curve of X starting

③ $C_X(0) = p$, so $\frac{dC_X(s)}{ds} = X_{C_X(s)}$

- Let $Y(s) = Y_{C_X(s)}$

$Y_{||}(s) \equiv$ \parallel -trans of Y_p to $C_X(s)$
along C_X

- Defn: $\nabla_X Y|_p = \lim_{s \rightarrow 0} \frac{Y(s) - Y_{||}(s)}{s}$

Since both $Y(s)$ & $Y_{||}(s)$ are coord indept,
this gives coord indept notion of deriv of
vector field Y in X direction.

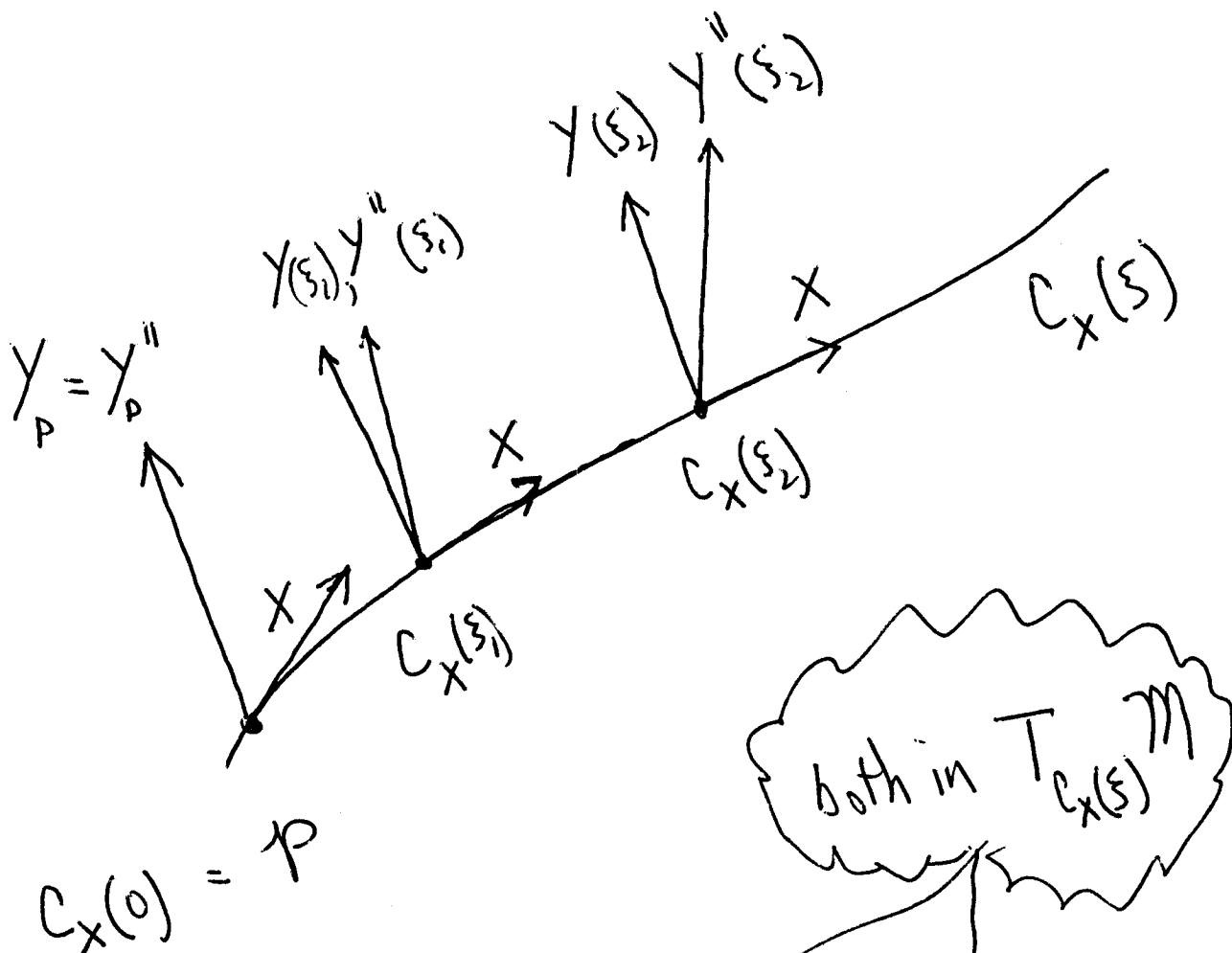
(only depends on $X(p)$!)



Picture

$\nabla_x Y :$

(86)



$$(\nabla_x Y)_p = \lim_{\xi \rightarrow 0} \frac{Y(\xi) - Y''(\xi)}{\xi}$$

- The covariant derivative corrects vector differentiation to a tensor operation: I.e.,

$$\nabla_X Y|_p = \lim_{\xi \rightarrow 0} \frac{Y(\xi) - Y(0)}{\xi} + \lim_{\xi \rightarrow 0} \frac{Y(0) - Y_{||}(\xi)}{\xi}$$

$$= X(Y) - \frac{dy^i}{d\xi} \frac{\partial}{\partial x^i}$$

$$= X(Y) + \Gamma_{jk}^i y^{\dot{j}} X^k \frac{\partial}{\partial x^i}$$

↑ We only have a coord way to express this limit!

↑ coord indept but not a tensor

↑ Γ gives us a coord expression for a coord indept thing

- In coordinates:

$$(\nabla_X Y)^i = \frac{dy^i}{d\xi} - \frac{dy_{||}^i}{d\xi} = X^\sigma Y_{,\sigma}^i + \underbrace{\Gamma_{jk}^i y^{\dot{j}} X^k}_{\text{corrects } X(Y) \text{ to a tensor}}$$

corrects $X(Y)$ to a tensor

• Conclude: ∇ gives a good indept expression to the Γ 's (9B)

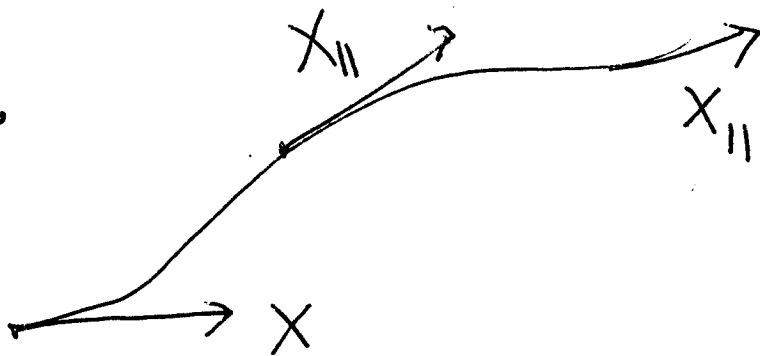
• Defn: Y is parallel along $c(s)$ if

$$\nabla_X Y = 0, \quad X = \frac{dc}{ds}$$

• Defn: a curve $\gamma(s)$ is a geodesic of Γ if $X = \frac{d\gamma}{ds}$ is parallel along γ .

Geodesic Equation:

$$\nabla_X X = 0 \quad (\Leftrightarrow)$$



$$(\nabla_X X)^i = X^j \frac{\partial}{\partial X^j} X^i_{\gamma(s)} + \Gamma^i_{jk}(\gamma(s)) X^j X^k = 0$$

$$\text{Since } \dot{\gamma}^i(s) = X^i \Rightarrow X^j \frac{\partial}{\partial X^j} \dot{\gamma}^i(s) = \ddot{\gamma}^i(s)$$

$$(\Leftrightarrow) \quad \boxed{\ddot{\gamma}^i + \Gamma^i_{jk} \dot{\gamma}^j \dot{\gamma}^k = 0}$$

• Conclude: ∇ gives a coordinate indept expression to the Γ 's (10/17)

Properties: ($X_i \in T_p M$, Y a vector field)

$$\textcircled{1} \quad \nabla_{aX_1 + bX_2} Y = a \nabla_{X_1} Y + b \nabla_{X_2} Y \quad \begin{cases} \text{any smooth fn's} \\ a, b: M \rightarrow \mathbb{R} \end{cases}$$

$$\textcircled{2} \quad \nabla_X (Y_1 + Y_2) = \nabla_X Y_1 + \nabla_X Y_2$$

$$\textcircled{3} \quad \nabla_X [f(p) Y] = f(p) \nabla_X Y + \underbrace{X(f)} \nabla_X Y$$

define $\nabla_X f = X(f)$ so
Liebniz rule holds

$$\textcircled{4} \quad \nabla_X Y - \nabla_Y X = [X, Y] \equiv L_X Y \quad (\text{when } \Gamma_{jk}^i = \Gamma_{kj}^i)$$

$$\text{Pf } \textcircled{4}: \quad \nabla_X Y - \nabla_Y X = X(Y) + \Gamma_{jk}^i Y^j X^k$$

$$\begin{aligned} &= \underbrace{[X, Y]}_{X(Y) - Y(X)} - Y(X) - \Gamma_{jk}^i X^j Y^k \\ &= X(Y) - Y(X) + T_{jk}^i X^j Y^k \end{aligned}$$

we assume Γ symmetric here on

◆ Extend ∇ to Covectors ω by requiring:

$$(\nabla_x \omega)(Y) = \nabla_x(\omega(Y)) \quad \forall Y \text{ st } \nabla_x Y = 0$$

"so that $\nabla_x \omega = 0$ when $\omega(Y)$ evaluates parallel vector fields Y along $c_x(s)$ as constant."

That is: $\nabla_x \omega = (\nabla_x \omega)_i dx^i$

so $(\nabla_x \omega)(Y) = (\nabla_x \omega)_i Y^i$

subject to $(\nabla_x \omega)_\sigma Y^\sigma = \nabla_x(\omega(Y))$ when $\nabla_x Y = 0$.

(2)

So assume $\nabla_x Y = 0$, and calculate

$$\nabla_x \omega(Y) = X(\omega(Y)) = X^i \frac{\partial}{\partial x^i} (\omega_\sigma Y^\sigma)$$

$$= X^i \left(\frac{\partial}{\partial x^i} \omega_\sigma \right) Y^\sigma + X^i \omega_\sigma \frac{\partial}{\partial x^i} (Y^\sigma)$$

$$= \left(X^i \frac{\partial}{\partial x^i} \omega_\sigma \right) Y^\sigma + \omega_\sigma \left(\underbrace{(\nabla_x Y)^\sigma}_0 - \Gamma_{ik}^{\sigma} Y^j X^k \right)$$

$$= \left(X^i \frac{\partial}{\partial x^i} \omega_\sigma - \Gamma_{\sigma k}^{\tau} \omega_\tau X^k \right) Y^\sigma$$

$$= (\nabla_x \omega)_\sigma Y^\sigma$$

$$\Rightarrow (\nabla_x \omega)_\sigma = X^i \omega_{\sigma,i} - \Gamma_{\sigma k}^{\tau} \omega_\tau X^k$$

We ~~can~~ also write

$$\nabla_i Y = \nabla \frac{\partial}{\partial x^i} Y = \left(Y_{,i}^\sigma + \Gamma_{ij}^{\sigma} Y^j \right) \frac{\partial}{\partial x^\sigma}$$

$$= Y_{;i}^\sigma \frac{\partial}{\partial x^\sigma}$$

$$\nabla_i \omega = \omega_{\sigma;i} dx^\sigma = (\omega_{\sigma,i} - \Gamma_{\sigma i}^{\tau} \omega_\tau) dx^\sigma$$

we can extend ∇ to arb. tensor field, by asking: (10)

$$\begin{aligned} & [\nabla_x T](X_1, \dots, X_n, \omega^1, \dots, \omega^k) \\ &= \nabla_x \underbrace{[T(X_1, \dots, X_n, \omega^1, \dots, \omega^k)]}_{\text{scalar}} \end{aligned}$$

for all $X_1, \dots, X_n, \omega^1, \dots, \omega^k$ \wedge along $C_x(\mathcal{E})$.

Formula:

$\nabla_x (T^i_j dx^j \otimes \frac{\partial}{\partial x^i})$ has components

$$X^k_j \frac{\partial}{\partial x^k} T^i_j + \underbrace{\Gamma^i_{\sigma\tau} T^{\sigma}_j X^{\tau}}_{\text{a term for every contravariant index}} - \underbrace{\Gamma^{\sigma}_{j\tau} T^i_{\sigma} X^{\tau}}_{\text{a term for every covariant index}} = (\nabla_x T)^i_j$$

(*)
Defn: we let ∇T denote the (tensor)
 with components $T_{i_1 \dots i_T}^{j_1 \dots j_T}$ when T has
 components $T_{i_1 \dots i_T}^{j_1 \dots j_T}$.

$$(\nabla X)^i_j = X^i_{;j} = X^i_{,j} + \Gamma^i_{\sigma j} X^\sigma \text{ etc.}$$

→ Properties:

① $\nabla_x T$ is a tensor for any tensor T .

$$\textcircled{2} \quad \nabla_x (A \otimes B) = \nabla_x A \otimes B + A \otimes \nabla_x B$$

~~Ref MTW pg 223~~

$$\textcircled{3} \quad \nabla_x (T^i_i) = (\nabla_x T)^i_i$$

More generally, ∇_x commutes with contraction.

Ref MTW pg 223

- geodesics of a connection:

Defn: a geodesic is a curve along which the tangent vector is parallel.

Eqn for geodesic of connection:

Let $x(s)$ be the x -coord curve $c_x(s)$ with tangent vector $\frac{dc_x}{ds} = X$

ie., $\frac{dx^i}{ds} = X^i$

then in x -coords, the condition $\nabla_X X = 0 \Rightarrow$

$$\begin{aligned} (\nabla_X X)^i &= X^\sigma \frac{\partial}{\partial x^\sigma} X^i + \Gamma_{\sigma\tau}^i X^\sigma X^\tau \\ &= \frac{d}{ds} X^i(s) + \Gamma_{\sigma\tau}^i X^\sigma X^\tau \end{aligned}$$

$$= \boxed{\frac{d^2 x^i}{ds^2} + \Gamma_{\sigma\tau}^i \dot{x}^\sigma \dot{x}^\tau = 0}$$

(*)

! soln w i.c. $x^i(0) = x_0^i$
 $\dot{x}^i(0) = \dot{x}_0^i$

Note: if $x(s)$ solves (xx) with initial vector X , then $x(cs)$ solves (xx) with initial vector cX .

(100)

Thm: ① Two symmetric connections having the same geodesics agree. ② Geodesics for $\Gamma_{\alpha\beta}^i$ agree with geodesics for $\frac{1}{2}(\Gamma_{\alpha\beta}^i + \Gamma_{\beta\alpha}^i)$.

Pf L.e. $\Gamma, \bar{\Gamma}$ two connections \Rightarrow in \mathcal{X} -local (\mathcal{B}_x) ,

$$\frac{d^2 x^i}{ds^2} + \bar{\Gamma}_{jk}^i \dot{x}^j \dot{x}^k = 0 \text{ iff } \frac{d^2 x^i}{ds^2} + \Gamma_{jk}^i \dot{x}^j \dot{x}^k = 0$$

$$x^i(0) = x_0^i$$

$$\dot{x}^i(0) = \dot{x}_0^i$$

same i.c.'s.

choose: $\dot{x}_0^i = \begin{cases} 1 & i = \alpha \\ 0 & \text{ow} \end{cases}$ fix $x_0^i = x(p)$

Then at p :

$$\Rightarrow \frac{d^2 x^i}{ds^2} = -\bar{\Gamma}_{\alpha\alpha}^i (\dot{x}_0^\alpha)^2 = -\Gamma_{\alpha\alpha}^i (\dot{x}_0^\alpha)^2$$

$$\Rightarrow \bar{\Gamma}_{\alpha\alpha}^i = \Gamma_{\alpha\alpha}^i \quad \text{all } \alpha$$

$$\dot{x}_0^i = \begin{cases} 1 & i = \alpha, i = \beta \\ 0 & \text{ow} \end{cases}$$

$$\Rightarrow \frac{d^2 x^i}{ds^2} = -\bar{\Gamma}_{\alpha\beta}^i \dot{x}^\alpha \dot{x}^\beta - \bar{\Gamma}_{\beta\alpha}^i \dot{x}^\beta \dot{x}^\alpha = -\Gamma_{\alpha\beta}^i \dot{x}^\alpha \dot{x}^\beta - \Gamma_{\beta\alpha}^i \dot{x}^\alpha \dot{x}^\beta$$

$$\Rightarrow \frac{1}{2}(\bar{\Gamma}_{\alpha\beta}^i + \bar{\Gamma}_{\beta\alpha}^i) = \frac{1}{2}(\Gamma_{\alpha\beta}^i + \Gamma_{\beta\alpha}^i)$$

Conclude: Symmetry $\Rightarrow \Gamma_{\alpha\beta}^i = \Gamma_{\beta\alpha}^i$

(11)

Non-symmetry \Rightarrow geodesics for Γ are the same as the geodesics for the symmetric connection $\tilde{\Gamma}_{\alpha\beta}^i = \frac{1}{2}(\Gamma_{\alpha\beta}^i + \Gamma_{\beta\alpha}^i)$ ✓

~~Assume Γ is the connection for metric g at p~~

~~In a local Lorentz frame, the geodesics for g agree with the geodesics for Γ , $\Gamma(p) = 0$, to 1st order.~~

~~their geodesics to agree:~~

Theorem:

Theorem: (The connection that goes with metric g) (2.1)
 Assume g is a Lorentzian metric with signature $\eta = \text{diag}(-1, 1, 1, 1)$. Let Γ be a connection whose components vanish in a coordinate frame x where (conds for local inertial frame)

$$g_{ij}(p) = \eta \quad (i)$$

$$g_{ij,h}(p) = 0. \quad (ii)$$

Then in any other coord. frame y we must have

$$\Gamma_{\alpha\beta}^{\gamma} = \frac{1}{2} g^{\gamma\sigma} \{ -g_{\alpha\beta,\sigma} + g_{\sigma\alpha,\beta} + g_{\beta\sigma,\alpha} \} \quad (3ii)$$

thus giving a formula for the Christoffel symbols for a unique symmetric connection determined by the metric g .

Proof: The transformation law for a connection is given by

$$\bar{\Gamma}_{\alpha\beta}^{\gamma} = \Gamma_{jk}^i \frac{\partial y^{\gamma}}{\partial x^i} \frac{\partial x^j}{\partial y^{\alpha}} \frac{\partial x^k}{\partial y^{\beta}} + \frac{\partial^2 x^i}{\partial y^{\alpha} \partial y^{\beta}} \frac{\partial y^{\gamma}}{\partial x^i} \quad (iv)$$

Since $\Gamma_{jk}^i = 0$ at p , we have

$$\bar{\Gamma}_{\alpha\beta}^{\gamma} \equiv \Gamma_{\alpha\beta}^{\gamma}(p) = \frac{\partial^2 x^i}{\partial y^{\alpha} \partial y^{\beta}} \frac{\partial y^{\gamma}}{\partial x^i} \quad (v)$$

Now the components of the metric $g_{\alpha\beta}$ are given by

$$g_{\alpha\beta} = \frac{\partial x^i}{\partial y^{\alpha}} \eta_{ij} \frac{\partial x^j}{\partial y^{\beta}} \quad (vi)$$

$$\Rightarrow g = J^t \eta J \quad (\text{matrix notation}) \quad (vii)$$

12.3

Differentiating (v2) and using (ii) gives

$$g_{\alpha\beta,\gamma}(p) = \underbrace{\eta_{ij} \frac{\partial^2 x^i}{\partial y^\alpha \partial y^\gamma} \frac{\partial x^j}{\partial y^\beta}} + \underbrace{\eta_{ij} \frac{\partial x^i}{\partial y^\alpha} \frac{\partial^2 x^j}{\partial y^\beta \partial y^\gamma}}.$$

Now

$$\Delta_{\alpha\beta}$$

$$\Delta_{B\gamma, \alpha}$$

↖ notation ↗

So $\Delta_{\alpha\gamma, \beta} = \Delta_{\gamma\alpha, \beta}$. (equality of mixed partials)

Therefore,

$$\begin{aligned}
 -g_{\alpha\beta,\gamma} + g_{\gamma\alpha,\beta} + g_{\beta\gamma,\alpha} &= -\cancel{\Delta_{\alpha\gamma,\beta}} - \cancel{\Delta_{\beta\gamma,\alpha}} \\
 &\quad + \cancel{\Delta_{\gamma\beta,\alpha}} + \Delta_{\alpha\beta,\gamma} \\
 &\quad + \Delta_{\beta\alpha,\gamma} + \cancel{\Delta_{\gamma\alpha,\beta}} \\
 &= 2\Delta_{\alpha\beta,\gamma} = 2\eta_{ij} \frac{\partial^2 x^i}{\partial y^\alpha \partial y^\beta} \frac{\partial x^j}{\partial y^\gamma}
 \end{aligned}$$

Now consider:

$$\left(g^{\alpha\beta}\right)_{4 \times 4} \equiv \left(g_{\alpha\beta}\right)_{4 \times 4}^{-1} = \left(J^t \eta J\right)^{-1} = J^{-1} \eta (J^t)^{-1}$$

Consider now the expression

$$\frac{1}{2} g^{\sigma\alpha} \left\{ -g_{\alpha\beta,\sigma} + g_{\sigma\alpha,\beta} + g_{\beta\sigma,\alpha} \right\}$$

$$= g^{\sigma\alpha} \left\{ \eta_{ij} \frac{\partial^2 x^j}{\partial y^\alpha \partial y^\beta} \frac{\partial x^i}{\partial y^\sigma} \right\}$$

$$\underbrace{J^{-1} \eta (J^t)^{-1}}_{J^{\text{tr}} \eta M_B} \quad M_B = \frac{\partial^2 x^j}{\partial y^\alpha \partial y^\beta}$$

$$= J^{-1} \eta (J^t)^{-1} J^{\text{tr}} g M_B = J^{-1} M_B$$

$$= \frac{\partial y^\sigma}{\partial x^i} \frac{\partial^2 x^j}{\partial y^\alpha \partial y^\beta} = \Gamma_{\alpha\beta}^\sigma \quad \checkmark$$

Cor ①: The geodesics for metric g satisfy the geodesic equation, Γ given in (iii);

$$\frac{d^2 x^i}{d\xi^2} + \Gamma_{jk}^i \frac{dx^j}{d\xi} \frac{dx^k}{d\xi} = 0. \quad (GD)$$

Thm: curves that satisfy (GD) are critical points of the $(\text{length})^2$ (Do this separately for each curve separately)

$$\text{Length} \equiv A[c(\cdot)] = \int_{\xi_1}^{\xi_2} \|\dot{x}(\xi)\|^2 d\xi$$

$$= \int_{\xi_1}^{\xi_2} \langle \dot{x}, \dot{x} \rangle d\xi = \int_{\xi_1}^{\xi_2} g_{ij} \dot{x}^i \dot{x}^j d\xi$$

\Rightarrow The Euler-Lagrange eqns are equiv. to

(GD) Ref Spivak / Dubrovin Novikov
Modern Geom I

Cor(2). Let $T_{\alpha\beta}^\gamma$ be any torsion tensor, (12.6)

$$T_{\alpha\beta}^\gamma = \Gamma_{\alpha\beta}^\gamma - \Gamma_{\beta\alpha}^\gamma$$

so $T_{\alpha\beta}^\gamma$ any antisymmetric tensor. Then
if $\Gamma_{\alpha\beta}^\gamma$ is given by (iii), it follows that

$$\overline{\Gamma}_{\alpha\beta}^\gamma = \Gamma_{\alpha\beta}^\gamma + T_{\alpha\beta}^\gamma$$

has the same geodesics as Γ , but is
not symmetric.

We could show: non-symmetry introduces a
twist rel to nearby geodesics.

Cor(3) \nexists ! symmetric connection whose geodesics
are geodesics of the metric.

Lemma: Let g have connection $\Gamma \leftrightarrow \nabla$.

Then

$$\textcircled{1} \quad \nabla_z g = 0 \quad \forall z$$

and

$$\textcircled{2} \quad \nabla_z (g_{ij} x^i x^j) = g_{ij} (\nabla_z x^i) x^j + g_{ij} x^i (\nabla_z x^j)$$

Note: $\textcircled{2} \Rightarrow$ angles & lengths are preserved under ∇ -translation.

Proof: For $\textcircled{1}$, go to a locally Cartesian coord frame where $g_{ij,h} = 0$ & $\Gamma_{jh}^i = 0$.

Formula for cov. deriv $\Rightarrow \nabla_z g = 0$.

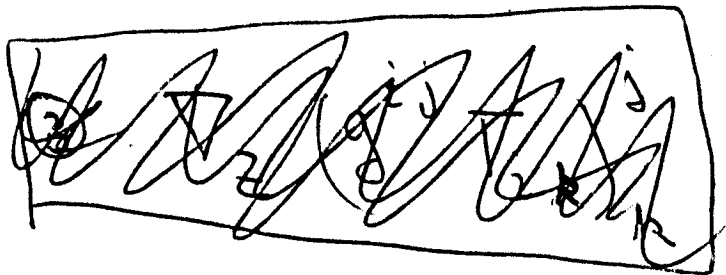
$\nabla_z g$ a tensor $\Rightarrow \nabla_z g = 0$ in all coords, \checkmark

~~For $\textcircled{2}$, write $\nabla_z (g_{ij} x^i x^j)$~~

(13B)

Corollary: For metric connection: ∇ for g :

$$\textcircled{2} \quad \nabla_Z \langle X, Y \rangle = \langle \nabla_Z X, Y \rangle + \langle X, \nabla_Z Y \rangle$$



$$\textcircled{3} \quad \nabla_Z (g_{\alpha i} X^{\alpha} dx^i)_i = g_{\alpha i} \nabla_Z (X^{\alpha} \frac{\partial}{\partial x^{\alpha}})^{\wedge}$$

More generally - ∇_Z commutes with raising & lowering of indices (FIP)

Note:

$\textcircled{2} \Rightarrow$ if X, Y are parallel along $C_X(s)$,
then $\nabla_Z \langle X, Y \rangle = Z(\langle X, Y \rangle) = 0 \Rightarrow$

||-translation preserves length & angles
betw vectors.

Proof

For ②, write $T = g \otimes X \otimes Y$. Then

⑭

$$\nabla_z T = \nabla_z g \otimes X \otimes Y + g \otimes \nabla_z X \otimes Y + g \otimes X \otimes \nabla_z Y$$

\swarrow
0

But: ∇_z (a contraction of T) = contraction of $(\nabla_z T)$

$$\text{LHS: } \nabla_z \left(g_{ij} X^k Y^l dx^i \otimes dx^j \otimes \frac{\partial}{\partial x^k} \otimes \frac{\partial}{\partial x^l} \right)$$

contract twice

$$\Rightarrow \nabla_z (g_{ij} X^i Y^j) = \nabla_z \langle X, Y \rangle$$

$$\text{RHS: } g_{ij} (\nabla_z X)^k Y^l dx^i \otimes dx^j \otimes \frac{\partial}{\partial x^k} \otimes \frac{\partial}{\partial x^l}$$

contract twice

$$\Rightarrow g_{ij} (\nabla_z X)^i Y^j = \langle \nabla_z X, Y \rangle$$

$$\text{Sim: } \underline{\text{contract}}: g \otimes X \otimes \nabla_z Y \rightarrow \langle X, \nabla_z Y \rangle$$

✓

Corollary : along a geodesic, $\langle X, X \rangle$ (15)

is constant (i.e., $\nabla_X X = 0$) \Rightarrow

timelike geodesics remain timelike

Spacelike " " spacelike

Null " " null. ✓

Assmt : Free fall paths are timelike geodesics
light rays follow null geodesics.

□ Lie Deriv as a Covariant Derivative

Theorem: Let Γ be any connection & ∇ its covariant derivative. Then

$$(L_Y T)^i_j \equiv \left(\frac{d}{ds} \varphi_{s*} T_{\varphi_{-s}(p)} \Big|_{s=0} \right)^i_j$$

$$= (\nabla_Y T)^i_j - T^{\sigma}_j (\nabla_{\sigma} Y)^i + T^i_{\sigma} (\nabla_j Y)^{\sigma} \quad (*)$$

Cor

↑ one for every
up index

↑ one for
every down
index

$$\underline{\text{Cor}}: (L_Y g)_{ij} = \cancel{(\nabla_Y g)_{ij}} + g_{\sigma j} \nabla_i Y^{\sigma} + g_{i\sigma} \nabla_j Y^{\sigma}$$

$$= \nabla_i Y_j + \nabla_j Y_i \equiv Y_{j;i} + Y_{i;j}$$

P.P. of theorem: $L_Y f = Y(f)$; $L_Y X = [Y, X]$

$$\bullet L_Y (W_\sigma X^\sigma) = Y(W_\sigma X^\sigma)$$

← apply to every
down index $T_{-\sigma} \dots$

Also

$$L_Y (W_\sigma X^\sigma) = (L_Y W)_\sigma X^\sigma + W_\sigma (L_Y X)^\sigma$$

$$= (L_Y W)_\sigma X^\sigma + W_\sigma [Y, X]^\sigma \quad (A)$$

$$= (L_Y W)_\sigma X^\sigma + W_\sigma \left(\underbrace{(\nabla_Y X)^\sigma} - (\nabla_X Y)^\sigma \right)$$

$$Y(W_\sigma X^\sigma) = (\nabla_Y W)_\sigma X^\sigma + W_\sigma \underbrace{(\nabla_Y X)^\sigma} \quad (B)$$

Equating (A) & (B):

$$(\nabla_Y W)_\sigma X^\sigma = (L_Y W)_\sigma X^\sigma + W_\sigma (\nabla_X Y)^\sigma$$

$$X = \frac{\partial}{\partial x^i} : (L_Y W)_i = (\nabla_Y W)_i + W_\sigma \nabla_{\frac{\partial}{\partial x^i}} Y^\sigma$$

◆ Divergence: Given a vector field X , define

$$\text{div } X = X^i{}_{;i} \quad \text{a scalar.}$$

• in local Lorentz coord's, $\text{div } X = X^i{}_{,i} \equiv$ classical divergence.

Theorem: $\text{div } X = \frac{1}{\sqrt{-g}} (X^i \sqrt{-g})_{,i}$

Proof: $X^i{}_{;i} = X^i{}_{,i} + \Gamma_{\sigma i}^i X^\sigma$

We evaluate $\Gamma_{\sigma i}^i = \Gamma_{i\sigma}^i$:

We know from $\nabla g = 0$ that

$$0 = g_{ij,k} - \Gamma_{ik}^\sigma g_{\sigma j} - \Gamma_{jk}^\sigma g_{\sigma i}$$

mult by g^{ij} & contract:

$$0 = g^{ij} g_{ij,k} - \Gamma_{ik}^i - \Gamma_{jk}^j \Rightarrow \Gamma_{ik}^i = \frac{1}{2} g^{ij} g_{ij,k}$$

i.e., $g_{\sigma j} g^{ij} = \delta_\sigma^i$ ✓

But!

$$g^{ij} = \frac{1}{g} \Delta^{ij}$$

matrix
of
cotactors

$$g = \det g_{ij} \quad \Delta^{ij} = (-1)^{i+j} (\text{subdet } g_{ij}) \quad (17)$$

$$\Delta^{ij} = \frac{\partial g}{\partial g_{ij}}$$

← just expand g by i th
column.

$$\Rightarrow \Gamma_{ik}^i = \frac{1}{2} g^{ij} g_{ij,k} = \frac{1}{2} \frac{1}{g} \frac{\partial g}{\partial g_{ij}} \frac{\partial g_{ij}}{\partial x^k} = \frac{1}{2} \frac{\partial}{\partial x^k} \ln |g|$$

$$= \frac{\partial}{\partial x^k} \log \sqrt{-g} = \frac{1}{\sqrt{-g}} \frac{\partial}{\partial x^k} \sqrt{-g}$$

Thus:

$$\boxed{\Gamma_{ik}^i = \frac{\partial}{\partial x^k} \log \sqrt{-g}},$$

and

$$\text{div } X = X^i_{,i} + \frac{1}{\sqrt{-g}} \left(\frac{\partial}{\partial x^k} \sqrt{-g} \right) X^k$$

$$= \frac{1}{\sqrt{-g}} (X^i \sqrt{-g})_{,i}$$

Gauss Theorem: A coordinate indept version of div theorem that holds for vector fields:

Theorem: $F \equiv F^i \frac{\partial}{\partial x^i}$ a vector field. Then

$$\int_{\Omega^4} \text{div } F \, \eta = \int_{\partial \Omega^4} \frac{\langle F, n \rangle}{\langle n, n \rangle} \eta \lrcorner n = \int_{\partial \Omega^4} F^\alpha d\Sigma_\alpha$$

Here: $\eta \equiv \sqrt{-g} \, \varepsilon$ volume form

$\Omega \in$ 4-dimensional region

$\text{div } F \equiv F^\sigma{}_{;\sigma}$ a scalar

$n \equiv$ unit outward normal to $\partial \Omega$,
normal relative to metric $g, \langle \rangle$.

$$d\Sigma_\alpha = \eta \lrcorner \frac{\partial}{\partial x^\alpha}$$

Proof: By previous result,

$$F^\sigma_{;\sigma} = \frac{1}{\sqrt{-g}} (F^\sigma \sqrt{-g})_{,\sigma}$$

Assume Ω lies in a single coord chart: x :
Then the Classical Divergence Thm holds as follows:

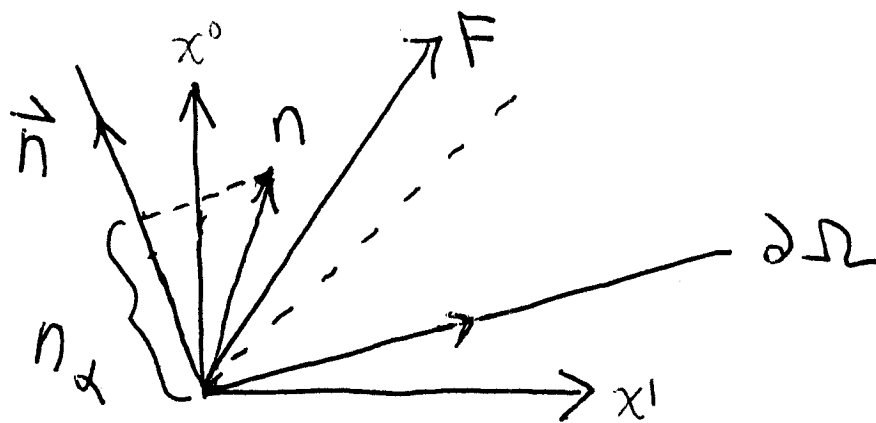
$$\int_{\Omega} F^\sigma_{;\sigma} \eta = \int_{\Omega} F^\sigma_{;\sigma} \sqrt{-g} \mathcal{E} = \int_{\Omega} \frac{1}{\sqrt{-g}} (F^\sigma \sqrt{-g})_{,\sigma} \sqrt{-g} \mathcal{E}$$

$$= \int_{\Omega} (F^\sigma \sqrt{-g})_{,\sigma} \mathcal{E} = \int_{\partial\Omega} F \cdot \vec{n} \sqrt{-g} \mathcal{E} \underbrace{\downarrow \vec{n}}_{ds} = *$$

\uparrow coordinate volume dV \uparrow Classical Divergence Thm \equiv Euclidean surface area

where \vec{n} is the coordinate unit^{outer} normal to $\partial\Omega$,

Now: if \vec{n} is the Euclidean coordinate ^{unit} normal, (20)
 and $n \equiv n^\alpha \frac{\partial}{\partial x^\alpha}$ is the metric unit normal,
 then $\vec{n}^i \neq n_i$: Eg



$$* = \int_{\partial\Omega} \sqrt{-g} \, \epsilon \lrcorner (F \cdot \vec{n}) \vec{n} = \int_{\partial\Omega} \sqrt{-g} \, \epsilon \lrcorner \left\{ (F \cdot \vec{n}) \vec{n} + \underbrace{F - (F \cdot \vec{n}) \vec{n}}_{\text{in } T_p \partial\Omega} \right\}$$

$$= \int_{\partial\Omega} \eta \lrcorner F = \int_{\partial\Omega} F^\alpha d\Sigma_\alpha$$

\Downarrow
 no contribution
 for $x_1, \dots, x_3 \in T\partial\Omega$

$$d\Sigma_\alpha = \eta \lrcorner \frac{\partial}{\partial x^\alpha}$$

(21)

But we can also write

$$\int_{\partial\Omega} \eta \lrcorner F = \int_{\partial\Omega} \eta \lrcorner \left\{ \underbrace{\frac{\langle F, n \rangle}{\langle n, n \rangle} n + F - \frac{\langle F, n \rangle}{\langle n, n \rangle} n}_{\text{in } T\partial\Omega} \right\}$$

$$= \int_{\partial\Omega} \eta \lrcorner \left\{ \frac{\langle F, n \rangle}{\langle n, n \rangle} n \right\} = \int_{\partial\Omega} \underbrace{\frac{\langle F, n \rangle}{\langle n, n \rangle}}_{\substack{\text{metric} \\ \text{version of} \\ "F \cdot n"}} \underbrace{\eta \lrcorner n}_{\substack{\text{metric} \\ \text{version} \\ \text{"of"} \\ "ds"}}$$

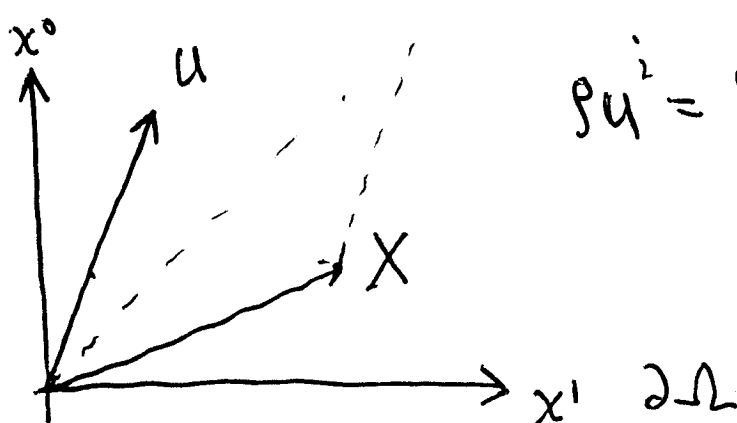
◆ Application: Cons. of mass principle

Ex: $\rho(x) \equiv \frac{\text{mass}}{\text{3-vol}}$ in rest frame \approx dust.

$u = \frac{dx^i}{d\tau}$ 4-velocity of particles

$$d\tau = \sqrt{(dx^0)^2 - |dx|^2} = \sqrt{1 - |v|^2} dx^0$$

$$\frac{dx^0}{d\tau} = \frac{1}{\sqrt{1 - |v|^2}} \equiv \text{Lorentz contraction Factor}$$



$$\rho u^i = \rho \frac{dx^0}{d\tau} \frac{dx^i}{dx^0}$$

$$\frac{\text{mass}}{\text{3-vol}} \text{ in } x\text{-frame} = \rho \frac{dx^0}{d\tau} = \langle \rho u, \frac{\partial}{\partial x^0} \rangle$$

$$\frac{\text{mass}}{\text{area } \Delta x^0} \text{ in } x\text{-frame} = \underbrace{\rho \frac{dx^0}{d\tau}}_{\substack{\text{mass} \\ \text{3-vol}}} \underbrace{\frac{dx^1}{dx^0}}_{\substack{\text{dist} \\ \text{time}}} = \langle \rho u, \frac{\partial}{\partial x^1} \rangle$$

Conclude: At each pt. on $\partial\Omega$

$$\langle \rho u, n \rangle = \frac{\text{mass}}{\text{metric 3-vol}} \equiv \begin{cases} \text{density if } n \text{ timelike} \\ \text{mass flux if } n \text{ spacelike} \end{cases}$$

\uparrow
coordinate indept
meaning

$$\therefore \frac{\langle \rho u, n \rangle}{\langle n, n \rangle} n \lrcorner n (X_1, X_2, X_3)$$

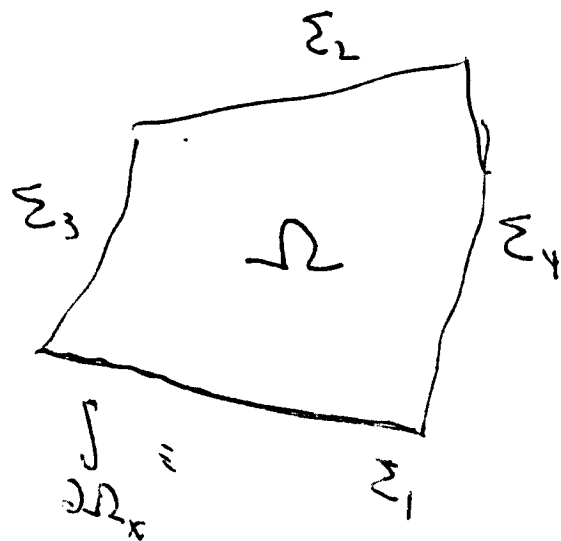
evaluates the total mass in 3-volume X_1, X_2, X_3
(per coord vol)

$$\int_{\partial\Omega} \frac{\langle \rho u, n \rangle}{\langle n, n \rangle} n \lrcorner n \equiv \int_{\partial\Omega_x} \frac{\langle \rho u, n \rangle}{\langle n, n \rangle} n \lrcorner n \left(\frac{\partial}{\partial x^1} \frac{\partial}{\partial x^2} \frac{\partial}{\partial x^3} \right) dx^1 dx^2 dx^3$$

$$\int_{\Sigma_1} = \text{"total mass at } \Sigma_1 \text{"}$$

$$\int_{\Sigma_2} = \text{"total mass at } \Sigma_2 \text{"}$$

$$\int_{\Sigma_3, \Sigma_4} = \text{"total mass passing out of } \Omega \text{ through } \Sigma_3, \Sigma_4 \text{"}$$



⇒ Global coord indept statement of cons.
of mass is (24)

$$0 = \int_{\partial\Omega} \frac{\langle \rho u, n \rangle}{\langle n, n \rangle} \eta \lrcorner n = \int_{\Omega} \operatorname{div} \rho u \quad \Leftrightarrow \quad \boxed{\operatorname{div} \rho u = 0}$$

• Note: since $\int_{\partial\Omega} \frac{\langle \rho u, n \rangle}{\langle n, n \rangle} \eta \lrcorner n = \int_{\partial\Omega} \rho u^i d\Sigma_i,$

we can think of $\rho u^i d\Sigma_i$ as "eating 3-vol's X_1, X_2, X_3 & evaluating the total mass in them \equiv mass flux if one of the X_i is timelike"

Ref MTW.

For energy & momentum:

$\rho \frac{dx^0}{d\zeta} u$ energy flux vector

$\rho \frac{dx^i}{d\zeta} u$ i-momentum flux vector

extra factor of $\frac{dx^0}{d\zeta}$ needed because

$\frac{\text{energy}}{\text{vol}}$ increases with velocity, due to

Lorentz Contr effect + increase in KE.

Components of tensor: $T^{ij} = \rho u^i u^j$

Conclude: $F = \rho \frac{dx^0}{d\zeta} u$ satisfies Global Cons

Law

$$\int_{\partial \Omega} \frac{\langle F, n \rangle}{\langle n, n \rangle} n \lrcorner n = 0$$

(*)

only so long as F transforms like a Vector. It does under Linear coord

transformations \Rightarrow global inv. cons. law
 holds in Special Relativity when we
 restrict to ~~exact~~ Lorentz transformations.
 In general relativity, we can only
 require local cons of energy

$$\boxed{\text{div } T = 0 = T_{i\sigma}^{\sigma}{}_{; \sigma}}$$

This reproduces (*) in flat space &
 approximately reproduces (*) in loc Lorentz
 frames where $g_{ij} = \eta_{ij} + O(|x|^2)$.