

Schwarzschild Solution

Thm(s) (Schwart 1916) The following metric is a spherically symmetric soln of empty space Einstein equations $G_{ij} = 0 \Leftrightarrow R_{ij} = 0$

$$(S) \quad ds^2 = -\left(1 - \frac{2GM}{c^2 r}\right) dt^2 + \left(1 - \frac{2GM}{r}\right)^{-1} dr^2 + r^2 d\Omega^2$$

Thm (Birkhoff 1923) (S) is the only spherically symmetric soln of $G_{ij} = 0$ in the sense that any other soln of form

$$ds^2 = -A(x^0; r) dt^2 + D(x^0; r) dx^0 dr + B(x^0; r) dr^2 + C(x^0; r) d\Omega^2$$

is equivalent under coordinate transformation to (S).

Note: (S) has a singularity at $r = 2GM$ and at $r = 0$. The one at $r = 0$ is essential ($R \rightarrow \infty$ as $r \rightarrow 0$) but the singularity at $r = 2GM$ is a coordinate singularity.

(2)

Note: in limit $r \rightarrow \infty$, (5) approaches

$$ds^2 = -dx^0)^2 + dr^2 + r^2 d\Omega^2,$$

the flat metric in spherical coordinates

$$d\Omega^2 = d\theta^2 + \sin^2\theta d\phi^2$$

the metric on unit sphere.

In the Newtonian limit,

$$\phi = -\frac{2GM}{r}$$

$\Rightarrow M = \text{mass of sun}$.

$G = \text{Newt grav. const that enters the law}$

$$F = -\nabla \phi = -G \frac{M_s M_e}{r^2} \frac{\vec{r}}{|\vec{r}|}$$

check: $[\phi] = \frac{L^2}{T^2} \Rightarrow \left[\frac{\phi}{c^2} \right] = 1$ as required in g_{00} .

Set $m = \frac{GM}{c^2}$

Thm: The invariants $R = R^\alpha_\alpha$ and $R_{\text{Ricke}} R^{\text{Ricke}}$ are continuous across the Schwarzschild radius. In fact

$$R_{\text{Ricke}} R^{\text{Ricke}} = 48M^2/r^6 \quad (\text{FIP})$$

ref MTW
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Thm(K): (Kruskal - Szekeres) \exists a coordinate transformation $(x^0, r) \mapsto (u, v)$ such that in uv-coordinates (S) takes the form

$$(K) \quad ds^2 = -f^2(u, v)(dv^2 - du^2) + r^2 d\Omega^2$$

In fact,

$$f^2(u, v) = \frac{32M^3}{r} e^{-r/2M} \quad m = \frac{GM}{c^2}$$

and the coordinate transformation is given

by

$$\left. \begin{aligned} u^2 - v^2 &= \left(\frac{r}{2m} - 1 \right) e^{r/2m} \\ \frac{v}{u} &= \tanh \frac{x^0}{4m} \end{aligned} \right\} \quad r > 2m \quad u > |v|$$

$$\left. \begin{aligned} v^2 - u^2 &= \left(1 - \frac{r}{2m} \right) e^{r/2m} \\ \frac{u}{v} &= \tanh \frac{x^0}{4m} \end{aligned} \right\} \quad r < 2m \quad v > |u|$$

Since: $r = 2m \Leftrightarrow u = v$, u & v are smooth across Schwarzs radius, & (K) smooth everywhere except at $r = 0$, which corresponds to $v^2 - u^2 = +1$.

Note: singularity $r=0$ is spread out over hyperbola

Note: metric extends smoothly to $u < |v|$ and $v < |u| \Rightarrow$ universe of (S) can be extended to a "mirror universe" not seen in (S)

We discuss Them (s) & Thm (k) :

Derivation of (s) :

Look for soln $G=0 \Leftrightarrow R=0$ of form

$$ds^2 = -A(r) dx^0{}^2 + B(r) dr^2 + C(r) d\Omega^2.$$

"The general static spherically symmetric metric".

• WLOG assume $C(r) = r^2 > 0$ (on. not sgn η_{ij})

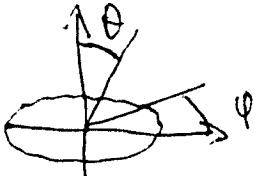
i.e., $r = \psi(\bar{r}) \Rightarrow$

$$ds^2 = -\bar{A}(\bar{r}) dx^0{}^2 + \bar{B}(\bar{r}) d\bar{r}^2 + C(\psi(\bar{r})) d\Omega^2$$

so choose $\psi(\bar{r})$ st $C \circ \psi = \bar{r}^2$ ✓

This ensures that the 2-sphere at radius r
has circumference $2\pi r$

$$2\pi r = \int_0^{2\pi} \sqrt{r^2 d\Omega^2} = \int_0^{2\pi} r d\phi \quad \leftarrow \text{at } \theta = \frac{\pi}{2}$$



- Assume $A(r) = e^{\nu(r)}$, $B(r) = e^{\lambda(r)}$ \Rightarrow

$$-e^{\nu(r)} d(x^0)^2 + e^{\lambda(r)} dr^2 + r^2 d\Omega^2$$

- The E-equations are $\Rightarrow R_{ij} = 0$:

$$R_{ij} = R_{i0j0} = \Gamma_{ij,0}^\sigma - \Gamma_{i0,j}^\sigma + \Gamma_{r0}^\sigma \Gamma_{ij}^r - \Gamma_{ij}^\sigma \Gamma_{r0}^r = 0$$

But: $\Gamma_{\sigma,k}^\sigma = \{\log \sqrt{-g}\}_{,k}$ from before \Rightarrow

$$-g = e^{\nu+\lambda} r^4 \sin^2 \theta$$

$$\log \sqrt{-g} = \frac{1}{2} (\nu + \lambda) + 2 \log r + \log |\sin \theta|$$

$$\Rightarrow \boxed{\begin{aligned} \Gamma_{00}^\sigma &= 0 \\ \Gamma_{01}^\sigma &= \frac{1}{2} (\nu' + \lambda') + \frac{2}{r} \\ \Gamma_{02}^\sigma &= \frac{\cos \theta}{\sin \theta} = \cot \theta \\ \Gamma_{03}^\sigma &= 0 \end{aligned}}$$

Thus we can rewrite the field equations:

(6B)

$$-R_{ij} = (\log \sqrt{g})_{,ij} - \Gamma_{ij,\sigma}^\sigma + \Gamma_{\tau j}^\sigma \Gamma_{i\sigma}^\tau - \Gamma_{ij}^\tau (\log \sqrt{g})_{,\tau}$$

(R_{ii})

- To obtain the Γ_{jk}^i explicitly, we work
backwards from the variational formulation:

$$\delta S = \delta \int g_{ij} \dot{x}^i \dot{x}^j ds = 0$$

$$\Leftrightarrow \ddot{x}^i + \Gamma_{jh}^i \dot{x}^j \dot{x}^h = 0$$

$$\text{But } \delta S = 0 \Leftrightarrow \frac{d}{ds} \frac{\partial L}{\partial \dot{x}^i} - \frac{\partial L}{\partial x^i} = 0, \quad L = g_{ij} \dot{x}^i \dot{x}^j.$$

In case of (S),

$$L = -e^v (\dot{x}^0)^2 + e^\lambda (\dot{x}^1)^2 + (x^1)^2 \{ (\dot{x}^2)^2 + \sin^2 x^2 (\dot{x}^3)^2 \}$$

$$\Leftrightarrow L = -e^v \dot{t}^2 + e^\lambda \dot{r}^2 + r^2 \{ \dot{\theta}^2 + \sin^2 \theta \dot{\phi}^2 \}$$

$$\boxed{i=0} \quad \frac{d}{ds} \frac{\partial L}{\partial \dot{x}^0} = \frac{d}{ds} \{ -e^v \dot{t} \} = -e^v \dot{t} - e^v \ddot{t} = 0$$

$$\Leftrightarrow \ddot{t} + v' \dot{r} \dot{t} = 0$$

$$\Leftrightarrow \boxed{\Gamma_{01}^0 = v' = \Gamma_{10}^0}, \quad \Gamma_{ij}^0 = 0 \quad \text{o.w.}$$

$$\frac{\partial L}{\partial x^0}$$

$i=1$

$$\frac{d}{ds} \frac{\partial L}{\partial \dot{x}^1} = \frac{d}{ds} \frac{\partial L}{\partial \dot{r}} = \frac{d}{ds} \{ 2e^\lambda \dot{r} \}$$

$$= 2\lambda' e^\lambda \dot{r}^2 + 2e^\lambda \ddot{r}$$

$$\frac{\partial L}{\partial x^1} = \frac{\partial L}{\partial r} = -v' e^v \dot{t}^2 + \lambda' e^\lambda \dot{r}^2 + 2r \{ \dot{\theta}^2 + \sin^2 \theta \dot{\phi}^2 \}$$

$$\frac{d}{ds} \frac{\partial L}{\partial \dot{x}^1} - \frac{\partial L}{\partial x^1} = \ddot{r} + \frac{1}{2} \lambda' \dot{r}^2 + \frac{1}{2} v' e^{v-\lambda} \dot{t}^2 - \bar{e}^{-\lambda} r \dot{\theta}^2 - r \sin^2 \theta \dot{\phi}^2 \bar{e}^{-\lambda} = 0$$

$\Gamma_{00}^1 = \frac{1}{2} v' e^{v-\lambda}$
$\Gamma_{11}^1 = \frac{1}{2} \lambda'$
$\Gamma_{22}^1 = -\bar{e}^{-\lambda} r$
$\Gamma_{33}^1 = -\bar{e}^{-\lambda} r \sin^2 \theta$

$$\Gamma_{ij}^1 = 0 \quad \text{o.w.}$$

$$[i=2] \quad \frac{d}{ds} \frac{\partial L}{\partial \dot{x}^2} = \frac{d}{ds} \{ 2r^2 \dot{\theta} \} = 4r\ddot{\theta} + 2r^2 \dot{\phi}^2$$

$$\frac{\partial L}{\partial x^2} = \frac{\partial L}{\partial \theta} = 2r^2 \sin \theta \cos \theta \dot{\phi}^2$$

$$0 = \frac{d}{ds} \frac{\partial L}{\partial \dot{x}^2} - \frac{\partial L}{\partial x^2} = 2r^2 \ddot{\theta} + 4r\dot{\theta} \dot{\phi} - 2r^2 \sin \theta \cos \theta \dot{\phi}^2$$

$$\Leftrightarrow \ddot{\theta} + \frac{2}{r} \dot{\theta} \dot{\phi} - \sin \theta \cos \theta \dot{\phi}^2 = 0$$

$$\boxed{\begin{aligned} \Gamma_{12}^2 &= \frac{1}{r} = \Gamma_{21}^2 \\ \Gamma_{33}^2 &= -\sin \theta \cos \theta \end{aligned}}$$

$$\Gamma_{ij}^2 = 0 \quad \text{o.w.}$$

$$[i=3] \quad \frac{d}{ds} \frac{\partial L}{\partial \dot{\phi}^2} = \frac{d}{ds} \{ 2r^2 \sin^2 \theta \dot{\phi} \} = 4r \sin \theta \dot{\theta} \dot{\phi} + 4r^2 \sin \theta \cos \theta \dot{\theta} \dot{\phi} + 2r^2 \sin^2 \theta \ddot{\phi}$$

$$\frac{\partial L}{\partial \dot{\phi}} = 0$$

$$0 = \frac{d}{ds} \frac{\partial L}{\partial \dot{\phi}^2} - \frac{\partial L}{\partial \dot{\phi}} \Leftrightarrow \ddot{\phi} + \frac{2}{r} \dot{\theta} \dot{\phi} + 2 \cot \theta \dot{\theta} \dot{\phi} = 0$$

$$\boxed{\begin{aligned} \Gamma_{13}^3 &= \frac{1}{r} = \Gamma_{31}^3 \\ \Gamma_{23}^3 &= \cot \theta = \Gamma_{32}^3 \end{aligned}}$$

$$\Gamma_{ij}^3 = 0 \quad \text{o.w.}$$

• Thus from (R_{ij}) :

$$-R_{00} = 0 = \left\{ \log \sqrt{-g} \right\}_{,00} - \Gamma_{00,0}^0 + \Gamma_{00}^0 \Gamma_{00}^r - \Gamma_{00}^r (\log \sqrt{-g})_{,r}$$

0

$$= -\Gamma_{00,1}^1 + 2\Gamma_{00}^1 \Gamma_{01}^0 - \Gamma_{00}^1 \log(\sqrt{g})_{,1}$$

$$= \left\{ -\frac{1}{2} v^1 e^{v-\lambda} \right\}' + \frac{1}{2} v^1 v^1 e^{v-\lambda} - \left(\frac{1}{2} v^1 e^{v-\lambda} \right) \cdot$$

$\left(\frac{1}{2}(v^1 + \lambda^1) + \frac{2}{r} \right)$

\approx

$v'' + \frac{1}{2}(v')^2 - \frac{1}{2}\lambda' v^1 + \frac{2v^1}{r} = 0$

 $(0,0)$

Similarly:

$$-R_{11} = \frac{1}{2} \left(v'' + \frac{1}{2}(v')^2 - \frac{1}{2}\lambda' v^1 - \frac{2\lambda^1}{r} \right)$$

$v'' + \frac{1}{2}(v')^2 - \frac{1}{2}\lambda' v^1 - \frac{2\lambda^1}{r} = 0$

 $(1,1)$

$$-R_{22} = \frac{\partial^2}{\partial \theta^2} (\log |\sin \theta|) + (e^{-\lambda} r)' + 2(-e^{-\lambda}) + (\cot^2 \theta) \\ + e^{-\lambda} r \left(\frac{\lambda' + \nu'}{2} + \frac{2}{r} \right) = 0 \quad (2)$$

• we show that the 3-equations (0,0) (1,1) and (2,2) are consistent & determining the soln to within a constant m . One can then check (FIP) that all other equations $R_{ij}=0$ are identically satisfied on this solution:

(In fact, $R_{ii}=0$ if i , $R_{33}=\sin^2 \theta R_{22}$)

Note: $\frac{\partial^2}{\partial \theta^2} (\log |\sin \theta|) = \frac{\partial}{\partial \theta} \cot \theta = -\csc^2 \theta$
 $-\csc^2 \theta + \cot^2 \theta = -1$

$\Rightarrow (2,2)$ is equiv to

$$0 = -1 + (e^{-\lambda} r)' - 2e^{-\lambda} + e^{-\lambda} r \left(\frac{\lambda' + \nu'}{2} + \frac{2}{r} \right) \quad (2)$$

(12)

Subtract (1,1) from (0,0):

$$\frac{2\nu^1}{r} + \frac{2\lambda^1}{r} = 0$$

$$\nu^1 + \lambda^1 = 0$$

$$(\nu + \lambda) = \text{const.} = C.$$

(1)

Note: wlog, we can take $C=0$ because a change of coords $\tilde{t} = \alpha t$ takes metric (5) to

$$ds^2 = - \underbrace{\alpha^2 e^\nu dt^2}_{\sim} + e^\lambda dr^2 + r^2 d\Omega^2$$

$$= - e^{\nu+\beta} d\tilde{t}^2 + e^\lambda dr^2 + r^2 d\Omega^2$$

\Rightarrow if $\beta = C$, in \tilde{t} -coords $\nu + \lambda = 0$.

Thus: If \exists a soln satis (1) with C , then it is \equiv to a soln satis (1) with $C=0$ ✓

Thus

$$\nabla = -\lambda \quad (2)$$

Substituting into (1,1) gives

$$\boxed{\cancel{\lambda'' + \frac{1}{2}(\lambda')^2 - \frac{1}{2}\lambda'^2} + \frac{2\nabla'}{r}}$$

$$\lambda'' - \frac{1}{2}(\lambda')^2 - \frac{1}{2}\lambda'^2 + \frac{2\lambda'}{r} = 0$$

$$\lambda'' - (\lambda')^2 + \frac{2\lambda'}{r} = 0$$

$$\Leftrightarrow (re^{-\lambda})'' = 0$$

$$\Rightarrow (re^{-\lambda})' = C = \text{constant.} \quad (3)$$

Thus: (0,0) and (1,1), two second order equations in $\nabla(r)$ & $\lambda(r)$ \Rightarrow determine ∇ & λ to within 4 arb. consts in general. Then $C=0$ in (2) reduces these to two in (3).

We show that (2,2) reduces these two to one !!

• (2,2) reads:

$$0 = -1 + (\bar{e}^{-\lambda} r)' - 2 \bar{e}^{-\lambda} + r \bar{e}^{-\lambda} \left(\frac{\lambda' + \bar{\lambda}'}{2} + \frac{2}{r} \right)$$

0

\Leftrightarrow

$$1 = (\bar{e}^{-\lambda} r)' - 2 \bar{e}^{-\lambda} + 2 \bar{e}^{-\lambda}$$

∴ $c = 1$ in (3)!

Thus:

$$\bar{e}^{-\lambda} r = r - 2M$$

$$\bar{e}^{-\lambda} = 1 - \frac{2M}{r}$$

$$\bar{e}^{\lambda} = \left(1 - \frac{2M}{r}\right)^{-1}$$

$$e^{\nu} = e^{-\lambda} = \left(1 - \frac{2M}{r}\right)$$

(4)

$$\Rightarrow ds^2 = - \left(1 - \frac{2M}{r}\right) dt^2 + \left(1 - \frac{2M}{r}\right)^{-1} dr^2 + r^2 d\Omega^2$$

Claim all other equations in $R_{ij} = 0$
are identically satisfied when $e^x e^v$ are
given by (4) (a miracle). (FIP)

Actually: $R_{ij} = 0$ if $i \neq j$ and $R_{33} = R_{22} \sin^2 \theta$

- Ex: we see what happened to the 4 free constants of integration in the PDE
two 2nd order equations (0,0) & (1,1) for (v, λ) :

$$\textcircled{1} (0,0) + (1,1) \Rightarrow \lambda' + v' = C \Rightarrow (0,0) \text{ & } (1,1)$$

are equivalent to a degenerate system:

$$\begin{array}{ll} \lambda' + v' = C & \text{1st order} \\ (\#), 1 & \text{2nd order} \end{array}$$

\rightsquigarrow expect 3 constants

② gauge freedom in τ allows us to set $C = 0$

\rightsquigarrow 2 remaining constants

~~Ex (2) is consistent~~

③ (2,2) is consistent with (0,0) & (1,1)
(why??) but restricts the two free
constants to a single constant M.

Problem: What general principles are
working behind this to make all the
equations consistent, and with the interesting
reduction of free parameters?
(I have seen no satisfying answer to this)

◆ The Schwarzschild Singularity

$$(S) \quad ds^2 = -\left(1 - \frac{2M}{r}\right)dt^2 + \left(1 - \frac{2M}{r}\right)^{-1}dr^2 + r^2 d\Omega^2$$

- singularity at $r=2M$
- $R \equiv 0 \Rightarrow R$ is cont through the singularity
- Calculation: $R_{ijkl} R^{ijkl} = \frac{48 M^2}{r^6}$
continuous thru $r=2M$.
- note: $r > 2M \Rightarrow t$ timelike ~~pos~~ ~~timelike~~
 $r < 2M \Rightarrow r$ timelike

But: assuming $\frac{\partial}{\partial t}$ is positively oriented
at $r=\infty$, by cont. we know $\frac{\partial}{\partial t}$ pos oriented
for $r > \frac{2M}{r}$.

Q: how do we know whether $\frac{\partial}{\partial r}$ or $-\frac{\partial}{\partial r}$ is
pos oriented for $r < 2M$ when metric is not
cont. thru $r=2M$?

- Red Shift: $\frac{\lambda_2}{\lambda_1} = \frac{\sqrt{1 - \frac{2M}{r_2}}}{\sqrt{1 - \frac{2M}{r_1}}}$

$$r_2 = \infty \Rightarrow \lambda_2 = \left(1 - \frac{2M}{r_1}\right)^{-1/2} \lambda_1$$

$\Rightarrow \lambda_2 \rightarrow \infty$ as r_1 (emitter) $\rightarrow 2M$

$\Rightarrow \infty$ -red-shift

- Geodesics: $ds^2 = -\left(1 - \frac{2M}{r}\right)c^2 dt^2 + \left(1 - \frac{2M}{r}\right)^{-1} dr^2 + r^2 d\Omega^2$

Consider geodesic $(t(s), r(s), \theta(s), \phi(s))$:

Divide (s) by $ds^2 \Rightarrow$

$$1 = -\left(1 - \frac{2M}{r}\right)c^2 \dot{t}^2 + \left(1 - \frac{2M}{r}\right)^{-1} \dot{r}^2 + r^2(\dot{\theta}^2 + \sin^2 \theta \dot{\phi}^2)$$
(A)

Obtain the 3 other equations for geodesic from E-L equation directly:

(19)

$$0 = \delta \int \left\{ -\left(1 - \frac{2M}{r}\right) c^2 \dot{t}^2 + \left(1 - \frac{2M}{r}\right)^{-1} \dot{r}^2 + r^2 [\dot{\theta}^2 + \sin^2 \theta \dot{\phi}^2] \right\} ds$$

$$\Rightarrow 3 \text{ E-L equations } \frac{d}{ds} \frac{\partial L}{\partial \dot{x}^i} - \frac{\partial L}{\partial x^i} = 0 \quad i=0, 1, 2, 3$$

$$\frac{d}{ds} (r^2 \dot{\theta}) = r^2 \sin \theta \cos \theta \dot{\phi}^2 \quad (B)$$

$$\frac{d}{ds} (r^2 \sin^2 \theta \dot{\phi}) = 0 \quad (C)$$

$$\frac{d}{ds} \left[\left(1 - \frac{2M}{r}\right) \dot{t} \right] = 0 \quad (D)$$

Note: (A) - (D) give 4 2nd order eqn's for (t, r, θ, ϕ) along geodesic.

If initially $\theta = \frac{\pi}{2}$, $\dot{\theta} = 0$, then (B) is identically satisfied by $\theta = \frac{\pi}{2}$ & (A) - (D) reduces to 3 eqn's in (t, r, ϕ) :

$$1 = -\left(1 - \frac{2M}{r}\right)c^2 \dot{t}^2 + \left(1 - \frac{2M}{r}\right)^{-1} \dot{r}^2 + r^2 \dot{\phi}^2 \quad (\text{A}')$$

$$\frac{d}{ds} (r^2 \dot{\phi}) = 0 \quad (\text{C}')$$

$$\frac{d}{ds} \left[\left(1 - \frac{2M}{r}\right) \dot{t} \right] = 0 \quad (\text{D}')$$

Then (C') gives

$$2 \frac{dA}{dt} = r^2 \dot{\phi} = h = \text{const} \quad (\text{E})$$

\Leftrightarrow "equal area in equal time"

Also, (D') becomes

$$\dot{t} = \left(1 - \frac{2M}{r}\right)^{-1} L \quad L = \text{const.} \quad (\text{F})$$

Note: substituting (E), (F) into (A') gives

a 1st order ODE in r :

$$l = -L^2 C^2 \left(1 - \frac{2M}{r}\right)^{-1} + \left(1 - \frac{2M}{r}\right)^{-1} \dot{r} + \frac{h}{r^2}$$

\Leftrightarrow

$$\dot{r}^2 = \left(1 - \frac{2M}{r} + L^2 C^2\right) - \frac{h}{r^2} \left(1 - \frac{2M}{r}\right)$$

Thus the equations for r & t become:

$$\dot{r} = \pm \sqrt{\left(L^2 C^2 + 1 - \frac{2M}{r}\right) - \frac{h}{r^2} \left(1 - \frac{2M}{r}\right)} \quad (G)$$

$$\dot{t} = \left(1 - \frac{2M}{r}\right)^{-1} L \quad (H)$$

Note: choosing the minus sign in (G), it is clear that as $r \rightarrow 2M+$, (G) $\sim \dot{r} = -L^2 C^2$ and (H) $\sim \dot{t} = \infty \Rightarrow$ the r equation is regular, but in the ~~t-equation~~ $t \rightarrow \infty$ as $r \rightarrow 2M$.

Note: letting $r = \frac{1}{u}$, and obtaining the equation for $r = r(\phi)$ through the replacement of s by ϕ as indept variable using (E)

$$\frac{d\phi}{ds} = \frac{h}{r^2}$$

leads to the exact equation:

$$u'' + u = \frac{m}{h^2} + 3mu^2 \quad m = \frac{G_0 M}{c^2}$$

for the geodesic. The corresponding $u = u(\phi)$ in Newton's theory is (Binet Eqn)

$$u'' + u = \frac{G_0 M}{h^2} \approx \frac{m}{h^2} \text{ in classical limit}$$

\Rightarrow Same except for nonlinear quadratic term $3mu^2$. Ref: Te/Tracy Monthly A-B-S