

## Shock Waves in GR. / Oppenheimer-Snyder Model

- Three relevant metrics

$$(S) \quad d\bar{s}^2 = -\left(1 - \frac{2GM}{\bar{r}}\right) d\bar{t}^2 + \left(1 - \frac{2GM}{\bar{r}}\right)^{-1} d\bar{r}^2 + \bar{r}^2 d\Omega^2$$

(Schwarzschild)

$$(IS) \quad d\bar{s}^2 = -B(\bar{r}) d\bar{t}^2 + A(\bar{r}) d\bar{r}^2 + \bar{r}^2 d\Omega^2$$

(Interior Schwarzschild)

$$(R-W) \quad ds^2 = -dt^2 + R^2(t) \left\{ \frac{1}{1-kr^2} dr^2 + r^2 d\Omega^2 \right\}$$

(Robertson-Walker.)

- (S) is the "only" empty space spherically symmetric soln of  $G=0$ .
- (IS) is a spherically symm. soln of  $G=KT$  with stationary source  $T^{ii} = (\rho+p)u^i u_i + p g^{ij}$

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• (R-W) is the metric that is maximally symmetric at each fixed  $t$ . "isotropic" ~~about~~ ~~each point~~ and homogeneous about each point.

- (2)
- (R-W) is the maximally symmetric homogeneous isotropic space of constant positive curvature. In fact,  $r \rightarrow \alpha r$  changes  $K$  by a factor  $\alpha^2$  and  $R$  by a factor  $\alpha$ . When  $K=1$ ,

$$3\text{-d Ricci Scalar Curvature} = [n(n-1)R^2]^{-1}$$

Ref Wein Ch 13

▣ I-S  $A, B, \rho, \rho$  all fn's of  $r$  alone:  $G=KT \Leftrightarrow$

$$(1) \quad \frac{B'}{B} = -\frac{2\rho'}{\rho + \rho}$$

Comoving  $\Leftrightarrow u^i = (\sqrt{B}, 0, 0, 0)^i$   
is assumed

$$(2) \quad A = \left(1 - \frac{2GM(r)}{r}\right)^{-1}$$

$$(3) \quad M(r) = \int_0^r 4\pi \xi^2 \rho(\xi) d\xi \Leftrightarrow M' = 4\pi r^2 \rho$$

$$(4) \quad -r^2 \rho'(r) = GM\rho \left(1 - \frac{\rho}{\rho}\right) \left(1 + \frac{4\pi r^3 \rho(r)}{M}\right) \left(1 - \frac{2GM}{r}\right)^{-1}$$

(3)+(4) +  $\rho = \rho(\rho)$  yield 2 equn's in 2 unknowns:

$$\begin{pmatrix} \rho \\ M \end{pmatrix}' = F \begin{pmatrix} \rho \\ M \end{pmatrix}$$

▣ (R-W) We assume fluid is co-moving,

$\Rightarrow u^i = (1, 0, 0, 0)^i$ . Then  $G = kT \Rightarrow$

$$3\ddot{R} = -4\pi G (\rho + 3p)R \quad (0,0)$$

$$R\ddot{R} + 2\dot{R}^2 + 2k = 4\pi G (\rho - p)R^2 \quad (i,i)$$

Eliminating  $\ddot{R}$  yields

$$\dot{R}^2 + k = \frac{8\pi G}{3} \rho R^2 \quad (5)$$

$\text{div } T = 0$  (a consequence of  $G = kT$ , & hence of (0,0) and (i,i)) yields

$$p = \frac{-\frac{d}{dt}(\rho R^3)}{3R^2 \dot{R}} \quad (6)$$

Given  $p = p(\rho)$  (equation of state), (5) + (6) give 2 eqns in 2 unknowns  $(R, \rho)$  of form

$$\begin{pmatrix} \dot{R} \\ \dot{\rho} \end{pmatrix} = F \begin{pmatrix} R \\ \rho \end{pmatrix} \quad R \equiv R(t) \quad \rho \equiv \rho(t)$$

Matching R-W and I-S solutions:

• Let  $(\bar{t}, \bar{r})$  be coords for I-S soln with eqn of state  $\bar{P} = \bar{P}(\bar{P})$ .

Let  $(t, r)$  be coord for R-W soln with eqn of state  $P = P(P)$

Q: Can we create a dynamical solution of  $G = KT$  by matching the I-S soln to the R-W soln across a "shock" interface?

I.e. can we make the metrics  $g_{IS}$  and  $g_{RW}$  continuous across a shock interface?

Idea: define a smooth mapping

$$\Psi: (r, t) \rightarrow (\bar{r}, \bar{t})$$

so that the metric  $g_{RW}$  map agrees with  $g_{IS}$  on a surface  $r = r(t)$  when mapped by

$\Psi$  to  $\bar{r}\bar{t}$ -coordinates

(5)

$$\bullet \quad d\bar{s}^2 = -B(r) d\bar{t}^2 + A(r) d\bar{r}^2 + \bar{r}^2 d\Omega^2 \quad (\text{E-S})$$

$$ds^2 = -dt^2 + R(t)^2 \left\{ \frac{dr^2}{1-kr^2} + r^2 d\Omega^2 \right\}$$

In order that 2-spheres of symmetry agree under  $\bar{\Psi}$ , ask that

$$\bar{r} = r R(t) = \bar{\Psi}_2(t, r) \quad \left( \begin{array}{l} \text{determining} \\ \bar{\Psi}_2 \end{array} \right) \quad (8)$$

This implies that

$$d\bar{r} = R dr + \dot{R} r dt$$

which yields

$$dr^2 = \frac{1}{R^2} d\bar{r}^2 + \frac{\dot{R}^2}{R^2} r^2 dt^2 - 2 \frac{\dot{R}}{R^2} \bar{r} dt d\bar{r}$$

$\Rightarrow$  in  $t, \bar{r}$  coords, the R-W metric is given by

$$ds^2 = - \left\{ 1 - \frac{\dot{R}^2 \bar{r}^2}{R^2 - k\bar{r}^2} \right\} dt^2 + \frac{R^2}{R^2 - k\bar{r}^2} d\bar{r}^2 + \frac{2R\dot{R}\bar{r}}{R^2 - k\bar{r}^2} dt d\bar{r} + \bar{r}^2 d\Omega^2 \quad (9)$$

This is non-diagonal.

(6)

Idea: define a mapping  $\bar{t} = \bar{t}(t, r)$  that diagonalizes (9), and equate this diagonal form of (R-W) to (I-S):

• Lemma: if

$$d\tilde{s}^2 = -C(t, \bar{r}) dt^2 + D(t, \bar{r}) d\bar{r}^2 + 2E(t, \bar{r}) dt d\bar{r} \quad (10)$$

and  $\psi = \psi(t, \bar{r})$  satisfies

$$\frac{\partial}{\partial \bar{r}} (\psi C) = - \frac{\partial}{\partial t} (\psi E)$$

then

$$d\bar{t} = \psi(t, \bar{r}) \{ C dt - E d\bar{r} \}$$

is exact, can be integrated to  $\bar{t} = \bar{t}(t, \bar{r})$ ,

and in  $(\bar{t}, \bar{r})$  coords (10) becomes

$$d\tilde{s}^2 = -(\psi^2 C^{-1}) d\bar{t}^2 + (D + \frac{E^2}{C}) d\bar{r}^2 \quad (11)$$

(7)

For (9),

$$C = 1 - \frac{\dot{R}^2 \bar{r}^2}{R^2 - k\bar{r}^2} \quad D = \frac{R^2}{R^2 - k\bar{r}^2} \quad E = \frac{R\dot{R}\bar{r}}{R^2 - k\bar{r}^2}$$

If we now ask that the coeff of  $d\bar{r}^2$  in (11) = coeff of  $d\bar{r}^2$  in E-S, we obtain (after simplification)

$$M(\bar{r}) = \frac{4\pi}{3} \rho(t) \bar{r}^3 \quad (12)$$

This defines "shock surface"  $\bar{r} = \bar{R}(t)$ .

To match the  $d\bar{t}^2$  coeff's as well, we need

$$\gamma^{-2} c^{-1} = B$$

$$\Rightarrow \gamma^2 = \frac{1}{cB} \quad (13)$$

But  $\psi$  solves

$$\frac{\partial}{\partial \bar{r}} \psi C = - \frac{\partial}{\partial t} \psi E \quad (14)$$

in  $(t, \bar{r})$ -coords. So we can satisfy

$$\psi^2 = \frac{1}{CB} \text{ on initial surface } \bar{r} = \bar{r}(t) \quad (15)$$

(which determines values of  $C$  and  $B$  on surface)  
and then solve PDE (14) with  $\bar{r}$ -values on  
surface.

Miracle: the shock surface equation  ~~$\bar{r} = \bar{r}(t)$~~

$$M = \frac{4\pi}{3} \rho \bar{r}^3 \quad (*)$$

uncouples from the difficult  $\psi$  equation  $\Rightarrow$

we can pose the ivp for  $\psi$ !

Conclude: if  $\bar{r} = \bar{r}(t)$  is non-char. for (14) (which  
we show it is) then (\*) defines the "shock  
surface across which the metrics match.

- Note: (\*) gives a global cons. of mass principle:

$$M(\bar{r}) = \frac{4\pi}{3} \rho(t) \bar{r}^3 \quad *$$

total mass inside  $\bar{r}$  if IS soln is continued on in to origin

total mass inside  $\bar{r}$  if  $\rho = \rho(t) = \text{const.}$  i.e. "at fixed  $t$ "

- set  $\bar{r} = \bar{r}(t)$  & diff (\*):

$$M(\bar{r}(t)) = \frac{4\pi}{3} \rho(t) \bar{r}(t)^3$$

$$M' = 4\pi \bar{\rho} \bar{r}^2$$

$$\cancel{4\pi \bar{\rho} \bar{r}^2} \dot{\bar{r}} = \frac{4\pi}{3} \dot{\rho} \bar{r}^3 + \cancel{4\pi \rho \bar{r}^2} \dot{\bar{r}}$$

$$(\bar{\rho} - \rho) \dot{\bar{r}} = \frac{\dot{\rho} \bar{r}^3}{3}$$

$$\boxed{\frac{d\bar{r}}{dt} = \frac{\dot{\rho} \bar{r}}{(\bar{\rho} - \rho) 3}}$$

gives shock speed in  $(t, \bar{r})$ -words.

• Note: if  $\bar{p} = \bar{p} = 0$  ( $\mathcal{I}S \rightarrow S$ ) we have  
 Oppenheimer-Snyder Core  $\approx$  matched surface  
 is  $\partial$  of star. Then  ~~$M(\bar{r}) = M_0$~~   $M(\bar{r}) = M_0$  &  
 \*  $\Rightarrow$

$$M_0 = \frac{4\pi}{3} \rho(t) \bar{r}(t)^3 = \frac{4\pi}{3} \rho(t) R(t)^3 r(t)^3$$

~~Problem: its energy a~~

$$\Rightarrow r(t) = \left( \frac{3}{4\pi} \frac{M_0}{\rho(t) R(t)^3} \right)^{1/3}$$

From

$$p = - \frac{\frac{d}{dt} (\rho R^3)}{3 R^2 \dot{R}} \quad (6)$$

we have that when  $p=0$  (0-S case)

$$\rho R^3 = \text{const} = \rho(0) \quad \text{if } R(0) = 1 \checkmark$$

$$\Rightarrow r(t) = \text{const.} = \left( \frac{3}{4\pi} \frac{M_0}{\rho(0)} \right)^{1/3}$$

### 3 Conservation

We have: given any  $(\bar{t}-s)$  ~~metric~~ <sup>metric</sup> with equn of state  $\bar{p} = \bar{p}(\bar{\rho})$  and (R-W) metric with  $p = p(\rho)$ ,  $\exists$  a coord mapping  $(t, r) \mapsto (\bar{t}, \bar{r})$ ,

$$\bar{r} = r R$$

$$\bar{t} = \bar{t}(t, r)$$

such that the metrics match in a Lip cont fashion along shock surface

$$M(\bar{r}) = \frac{4\pi}{3} \rho \bar{r}^3$$

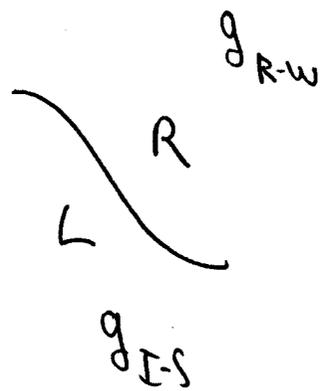
Q: does cons. of energy & momentum hold across the surface.

1st Guess:  $G = kT$ ,  $\text{div} G = 0$  by construction  $\Rightarrow$  <sup>local</sup> cons of energy-mom in smooth soln's

Might expect: since  $\text{div } G_{RW} = 0$  on one side (12)  
of shock &  $\text{div } G_{IS} = 0$  on other, and  
 $g$  Lipschitz cont across the shock  $\stackrel{??}{\implies}$   
 $G$  satisfies the weak form of cons. at each pt  
on the shock

$$[G^{is}] n_i = 0$$

$$[G] = G_R - G_L$$



"Rankine-Hugoniot Jump Relations"

Not so: but following is true:

Theorem (ISRAEL) Assume two metrics match

Lip cont across a shock  $\Sigma$ . Let  $K$   
denote the second fundamental form on the  
shock surface:

$$K: T_\Sigma \rightarrow T_\Sigma \quad X \mapsto \nabla_n X$$

(13)

so that  $K$  is determined separately by the covariant derivative  $\nabla$  on each side of  $\Sigma$ .

Assume that  $[K] = 0$  at each pt on  $\Sigma$ .

Then

①  $\exists$  a  $C^1$  coord transformation in a nbhd of each pt on  $\Sigma$  st the metric is  $C^1$  across  $\Sigma$  in the new coords.

$\Rightarrow$  "  $G =$  a second order operator on  $g$  contains jumps, but no  $\delta$ -fn singularities on  $\Sigma$ ."

②  $[G^{ij}]n_i = 0$  at each pt on  $\Sigma$ .

◆ We show that for the spherically symmetric case,  $[K] = 0$  across  $\Sigma$  iff

$$(*) \quad [T^{ij}] n_i n_j = 0$$

Conclude: Conservation  $[T^{ij}] n_i = 0$

$\Leftrightarrow$  two nontrivial conditions reduces to the single condition  $(*)$  when the metric is Lip.schitz cont across the shock.

We use this derive the following condition for conservation:

$$[T^{ij}] n_i n_j = (\bar{p} + \bar{s}) \dot{r}^2 - \frac{\bar{s} + \bar{p}}{R^2 \gamma^2 c^2} \dot{r}^2 + (p - \bar{p}) \frac{1 - \dot{r}^2}{R^2} = 0 \quad (\text{Cons})$$

Note: in case of Oppenheimer-Snyder: (15)

$$\bar{p} = \bar{p} = 0 \Rightarrow$$

$$[T^{ij}] n_i n_j = \rho \dot{r}^2 + p \frac{1 - kr^2}{R^2} = 0$$

$$\Rightarrow \dot{r} = 0 \text{ and } p = 0 \quad (1 - kr^2 > 0)$$

$\Rightarrow$  "can only match to empty space Schwarzschild <sup>conservatively</sup> when  $p = 0$ , in which case shock surface is  $\dot{r} = 0$ ."

• When  $p \neq 0$ , we assume E-S solution fixed:  
Then R-W satisfies

$$\dot{R}^2 + k = \frac{8\pi G}{3} \rho R^2 \quad (A)$$

$$p = \frac{-\frac{d}{dt}(\rho R^3)}{3R^2 \dot{R}} \quad (B)$$

To accommodate (cons), we let  $p = p(t)$  be determined by (B), in which case the

ODE is

(16)

$$\dot{R}^2 + k = \frac{8\pi G}{3} \rho R^2 \quad (c)$$

↗

$$(\bar{p} + \bar{s}) \dot{\bar{r}}^2 - \frac{\bar{p} + \bar{p}}{R^2 \gamma^2 c^2} \dot{\bar{r}}^2 + (\bar{p} - \bar{p}) \frac{1 - k r^2}{R^2} = 0 \quad (d)$$

holds on shock surface.

But: on shock surface,  $\bar{r}(t) = R(t)r(t)$ ,

$\Rightarrow \bar{p}(\bar{r}), \bar{s}(\bar{r}), \bar{r}$  can be replaced with  
fn's of  $(r, R)$ . Moreover, on shock  
surface,

$$\gamma^2 c^2 = \frac{A(\bar{r})}{B(\bar{r})(1 - k r^2)}$$

$\Rightarrow$  also a fn of  $(R, r)$ . Moreover,

$$M = \frac{4\pi}{3} \rho \bar{r}^3$$

$$\Rightarrow \rho(t) = \frac{M(R, r)}{(Rr)^3} = \frac{M(R(t)r(t))}{(R(t)r(t))^3}$$

Conclude: (c) & (d) give two autonomous (17)  
ODE's in  $R(t)$  and the shock position  $r(t)$

$$\begin{pmatrix} \dot{r} \\ \dot{R} \end{pmatrix} = F \begin{pmatrix} r \\ R \end{pmatrix}.$$

These determine R-W metric ( $R(t)$ ) and  
pressure  $p(t)$  thru

$$p = \frac{-\frac{d}{dt}(SR^3)}{3R^2 \dot{R}}$$

Problems: ① local soln near  $\dot{r}=0$   $\dot{R}=0$   $R=1$

(lack of Lip. cont)

② Global behavior of shock