

7.3.1

$$\begin{aligned}\dot{x} &= x - y - x(x^2 + 5y^2) \\ \dot{y} &= x + y - y(x^2 + y^2)\end{aligned}$$

a) FIXED POINTS $(x^*, y^*) = (0, 0)$

STABILITY

$$\det \begin{bmatrix} 1 - 3x^2 - 5y^2 - \lambda & -1 - x^{10}y \\ 1 - 2xy & 1 - x^2 - 3y^2 - \lambda \end{bmatrix}_{\substack{x=0 \\ y=0}} = 0$$

$$(1 - \lambda)^2 + 1 = \lambda^2 - 2\lambda + 2 = 0$$

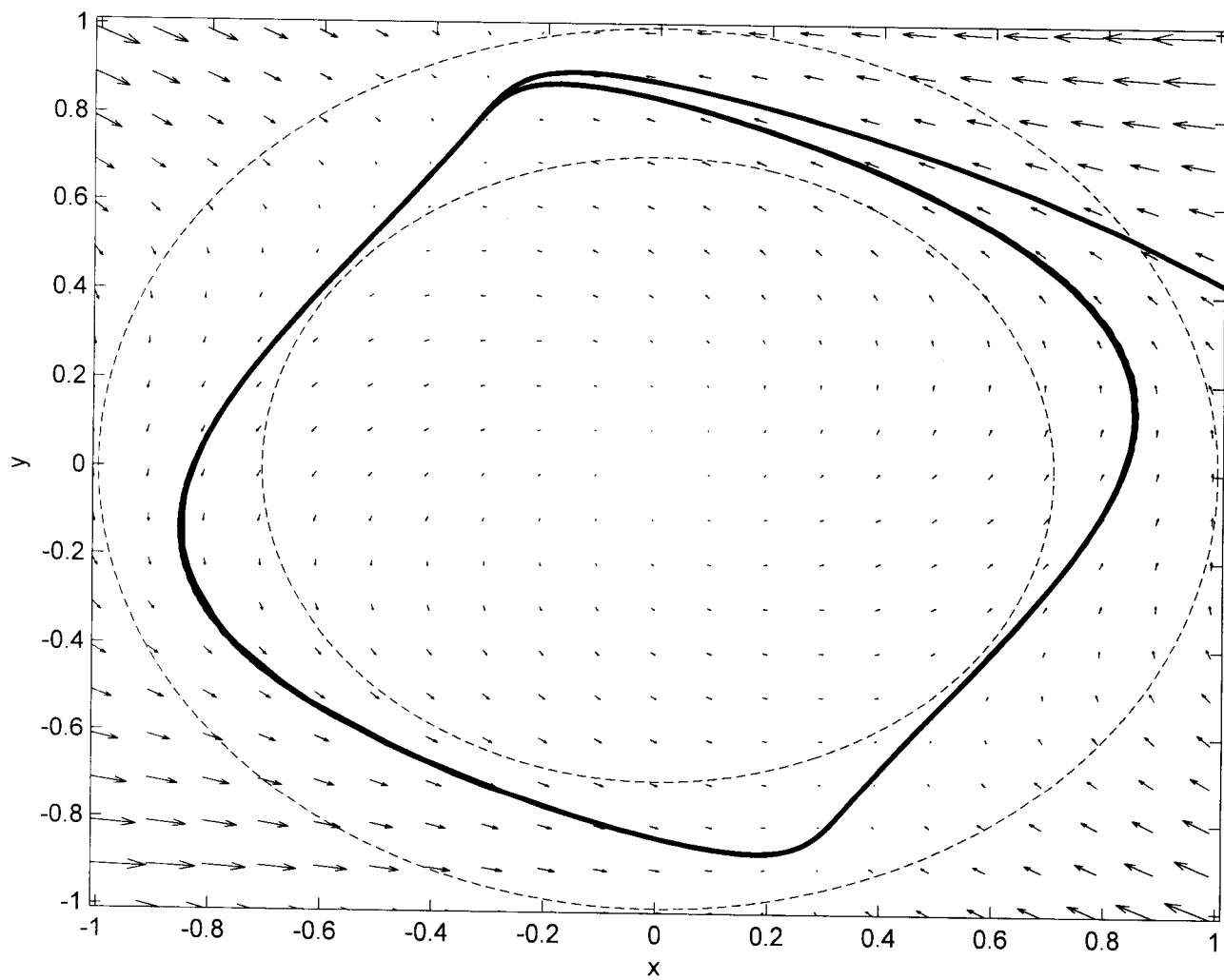
$$\lambda = 1 \pm i$$

$(0, 0)$ IS AN UNSTABLE SPIRAL.

b) POLAR CO-ORDS

$$\begin{aligned}r \dot{r} &= x \dot{x} + y \dot{y} \\ &= x^2 - xy - x^2(x^2 + 5y^2) \\ &\quad + xy + y^2 - y^2(x^2 + y^2) \\ &= r^2 - r^4 - 4r^4 \sin^2 \theta \cos^2 \theta \leftarrow \left(\frac{\sin 2\theta}{2}\right)^2\end{aligned}$$

$$\begin{aligned}r^2 \dot{\theta} &= x \dot{y} - y \dot{x} \\ &= x^2 + xy - xy(x^2 + y^2) \\ &\quad - xy + y^2 + xy(x^2 + 5y^2) \\ &= r^2 + 4r^4 \cos \theta \sin^3 \theta\end{aligned}$$



$$\begin{cases} \dot{r} = r - r^3 - r^3 \sin^2 2\theta \\ \dot{\theta} = 1 + 2r^2 \sin 2\theta \sin^2 \theta \end{cases}$$

* THERE'S SEVERAL WAYS TO EXPRESS THE TRIG FNS.

$$c) \quad \dot{r} = 0 \Rightarrow r = 0, \quad r = \frac{1}{\sqrt{1 + \sin^2 2\theta}}$$

$$\dot{r} > 0 \quad \text{WHEN} \quad 0 < r < \frac{1}{\sqrt{2}} \leq \frac{1}{\sqrt{1 + \sin^2 2\theta}}$$

THEREFORE THE CIRCLE WITH MAXIMUM RADIUS CENTERED AT THE ORIGIN SUCH THAT ALL TRAJECTORIES HAVE A RADIALLY OUTWARD COMPONENT IS $r = r_1 = \frac{1}{\sqrt{2}} - \epsilon$, WHERE $\epsilon > 0$ IS ARBITRARILY SMALL.

$$d) \quad \dot{r} < 0 \quad \text{WHEN} \quad r > 1 \geq \frac{1}{\sqrt{1 + \sin^2 2\theta}}$$

THEREFORE THE CIRCLE WITH MINIMUM RADIUS CENTERED AT THE ORIGIN SUCH THAT ALL TRAJECTORIES HAVE A RADIALLY INWARD COMPONENT IS $r = r_2 = 1 + \epsilon$, WHERE $\epsilon > 0$ IS ARBITRARILY SMALL.

e) THE REGION D BETWEEN THE CIRCLES
 $r = r_1 = 1/\sqrt{2}$ AND $r = r_2 = 1$ IS A
TRAPPING REGION WITH NO FIXED POINTS*
IN IT. THEREFORE, BY THE POINCARÉ -
BENDIXSON THM, ALL TRAJECTORIES IN
 D MUST APPROACH CLOSED PERIODIC
ORBIT(S) AS $t \rightarrow \infty$.

* NO INTERSECTIONS OF $\dot{r} = 0$ AND $\dot{\theta} = 0$ IN D !

7.3.4

$$\begin{aligned}\dot{x} &= x(1-4x^2-y^2) - \frac{1}{2}(1+x)y \\ \dot{y} &= y(1-4x^2-y^2) + 2x(1+x)\end{aligned}$$

a) FIXED POINT @ (0,0)

STABILITY

$$\det \begin{bmatrix} 1-12x^2-y^2-\frac{1}{2}y-\lambda & -2xy-\frac{1}{2}(x+1) \\ -8xy+2+4x & 1-4x^2-3y^2-\lambda \end{bmatrix} = 0$$

$x=0$
 $y=0$

$$\det \begin{bmatrix} 1-\lambda & -\frac{1}{2} \\ 2 & 1-\lambda \end{bmatrix} = \lambda^2 - 2\lambda + 2 = 0$$

$$\Rightarrow \lambda = 1 \pm i$$

(0,0) IS AN UNSTABLE SPIRAL.

b) $V(x,y) = (1-4x^2-y^2)^2$

USE V AS A LYAPUNOV-LIKE FUNCTION

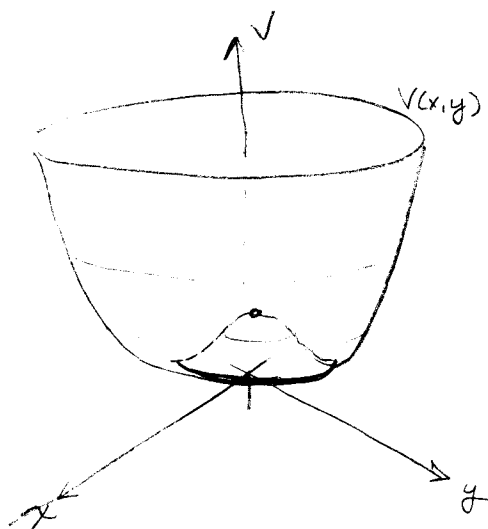
$$\begin{aligned}\frac{dV}{dt}(x(t), y(t)) &= \nabla V \cdot (\dot{x}, \dot{y}) \\ &= \frac{\partial V}{\partial x} \frac{dx}{dt} + \frac{\partial V}{\partial y} \frac{dy}{dt}\end{aligned}$$

$$\begin{aligned}\frac{dV}{dt} &= -4(1-4x^2-y^2) [(4x, y) \cdot (\dot{x}, \dot{y})] \\ &= -4(1-4x^2-y^2) [4x^2(1-4x^2-y^2) - \cancel{2xy(1+x)} \\ &\quad + y^2(1-4x^2-y^2) + \cancel{2xy(1+x)}]\end{aligned}$$

$$\frac{dV}{dt}(x(t), y(t)) = -4(1-4x^2-y^2)^2(4x^2+y^2)$$

$$< 0 \quad \text{unless } (x, y) = (0, 0) \\ \text{or } 4x^2 + y^2 = 1.$$

- $(0, 0)$ IS A LOCAL MAX OF $V(x, y)$
- $V(x, y)$ IS MINIMUM ON $4x^2 + y^2 = 1$ WHERE $V(x, y) = 0$.



THEREFORE ALL TRAJECTORIES*
MOVE DOWNHILL WITH
RESPECT TO $V(x, y)$ AND
APPROACH THE ELLIPSE
 $4x^2 + y^2 = 1$, WHICH
MINIMIZES $V(x, y)$ AND
WHERE $\frac{dV}{dt} = 0$.

* EXCEPT THE POINT $(0, 0)$.

7.4.2

$$\ddot{x} + \underbrace{\mu(x^2-1)}_{f(x)} \dot{x} + \underbrace{\tanh x}_{g(x)} = 0$$

$$\begin{cases} \dot{x} = y \\ \dot{y} = -g(x) - f(x)y \\ \quad = -\tanh x - \mu(x^2-1)y \end{cases}$$

a) $\mu > 0$

- (i) $f(x)$ and $g(x)$ are continuously differentiable
- (ii) $g(x) = \tanh(x)$ is ODD
i.e. $g(-x) = -g(x)$ for all x
- (iii) $\tanh(x) = g(x) > 0$ for all $x > 0$
- (iv) $f(x) = \mu(x^2-1)$ is EVEN
i.e. $f(-x) = +f(x)$ for all x
- (v) $F(x) = \int_0^x f(\tilde{x}) d\tilde{x} = \int_0^x \mu(\tilde{x}^2-1) d\tilde{x} = \mu\left(\frac{x^3}{3} - x\right)$

NOTE:
 $F(x)$ is ODD.

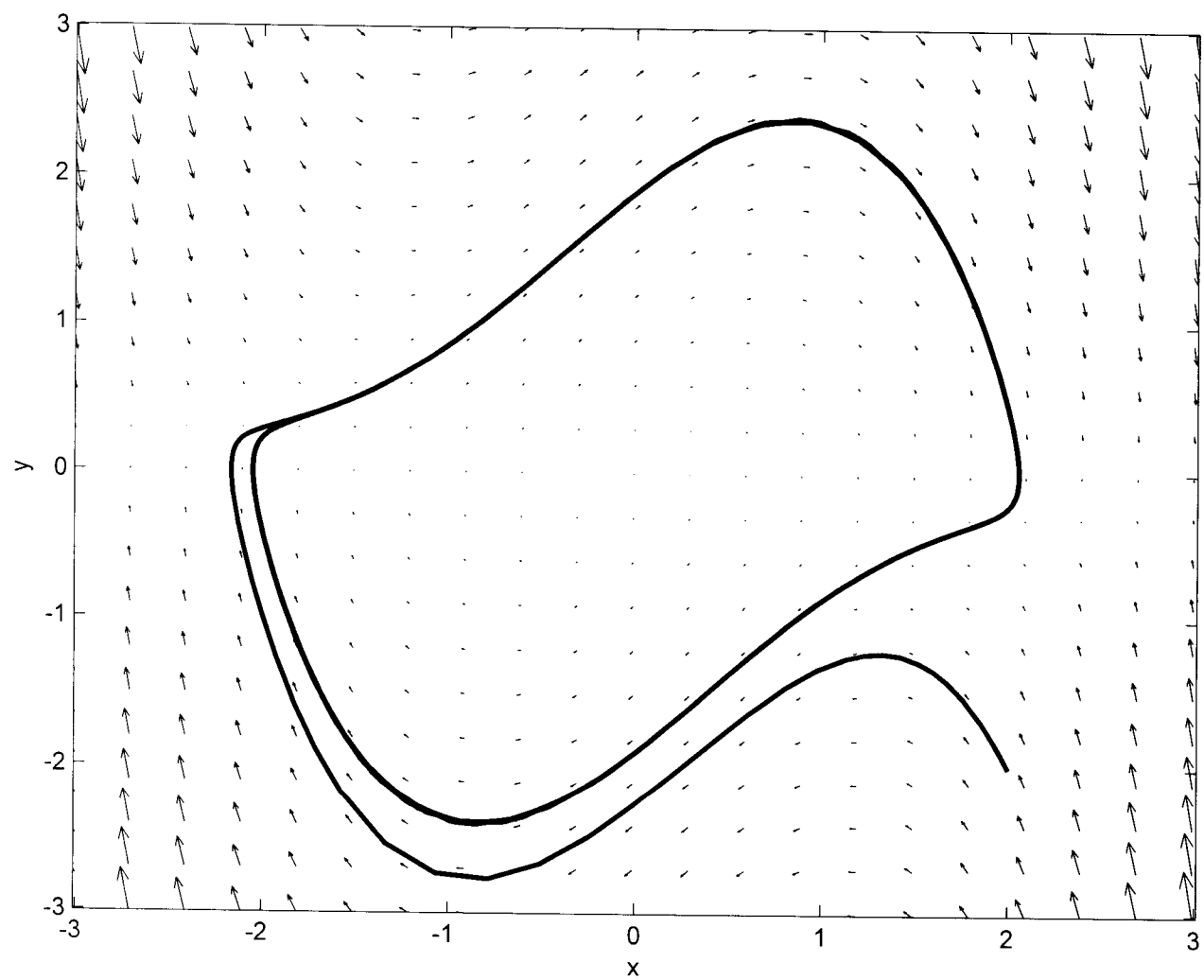
$$F(x) = 0 \text{ at } x=0 \text{ and } x = \pm\sqrt{3}$$

$$F(x) < 0 \text{ for } 0 < x < \sqrt{3}$$

$$F(x) > 0 \text{ and } F'(x) \geq 0 \text{ for } x > \sqrt{3}$$

$$\text{and } F(x) \rightarrow \infty \text{ as } x \rightarrow \infty$$

i.e. ALL CONDITIONS FOR LIÉNARD'S THM HOLD, AND THEREFORE THE SYSTEM HAS AN UNIQUE STABLE LIMIT CYCLE IN THE PHASE PLANE FOR $\mu > 0$.



c) $\underline{\mu < 0}$

LET $t = -\tau$ AND $\gamma = -\mu > 0$

$$\Rightarrow \frac{d^2x}{d\tau^2} + \underbrace{\gamma(x^2-1)}_{f(x)} \frac{dx}{d\tau} + \underbrace{\tan h x}_{g(x)} = 0 \dots (*)$$

AS BEFORE, ALL CONDITIONS FOR LIÉNARD'S
THM HOLD, AND THEREFORE SYSTEM (*) HAS
AN UNIQUE STABLE LIMIT CYCLE FOR $\gamma > 0$.

THIS IMPLIES THAT, WHEN THE SYSTEM IS
REVERTED BACK TO ORIGINAL VARIABLE t
AND PARAMETER μ , THE ^{ORIGINAL} SYSTEM HAS
AN UNSTABLE LIMIT CYCLE FOR $\mu < 0$.

8.1.6

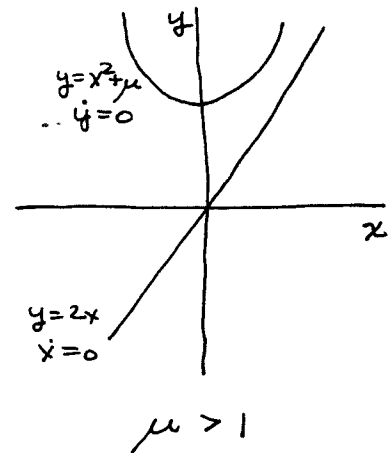
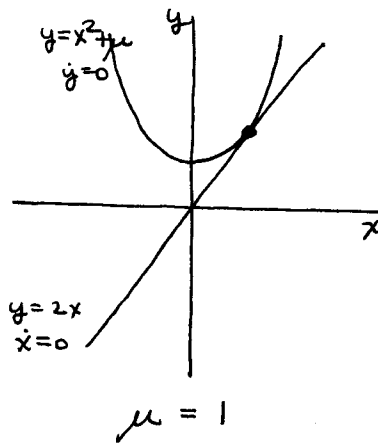
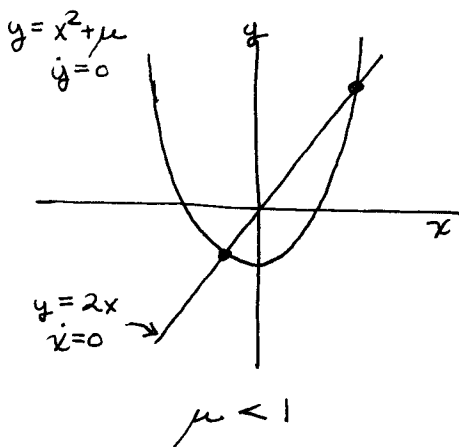
$$\dot{x} = y - 2x$$

$$\dot{y} = \mu + x^2 - y$$

a) NULLCLINES

$$\dot{x} = 0 \Rightarrow y = 2x$$

$$\dot{y} = 0 \Rightarrow y = x^2 + \mu$$



b) FIXED PTS $\dot{x} = 0, \dot{y} = 0$

$$y^* = 2x^* = x^{*2} + \mu$$

$$x^{*2} - 2x^* + \mu = 0$$

$$x^* = 1 \pm \sqrt{1 - \mu}$$

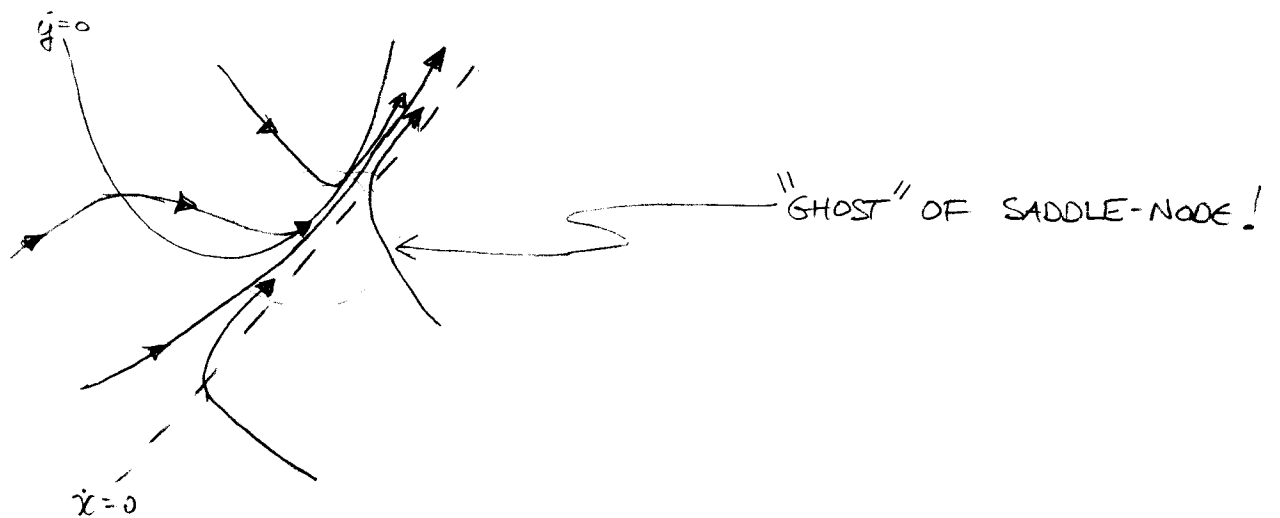
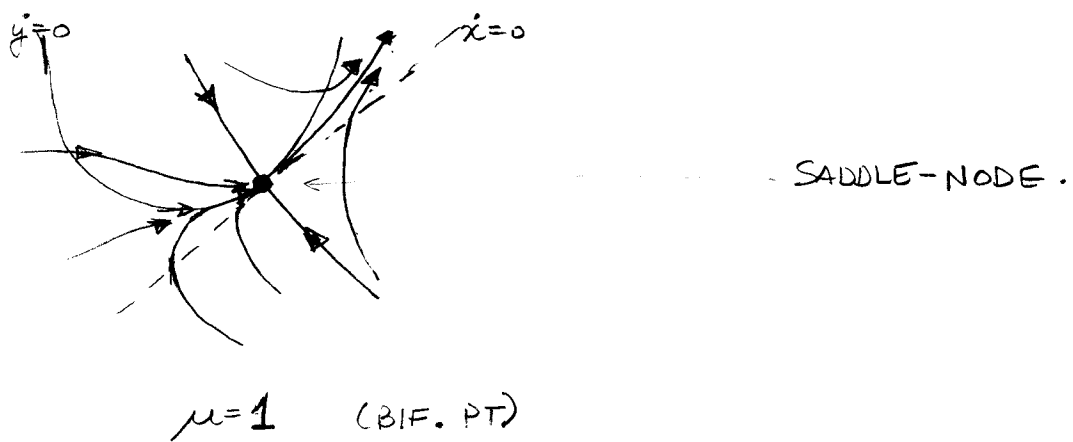
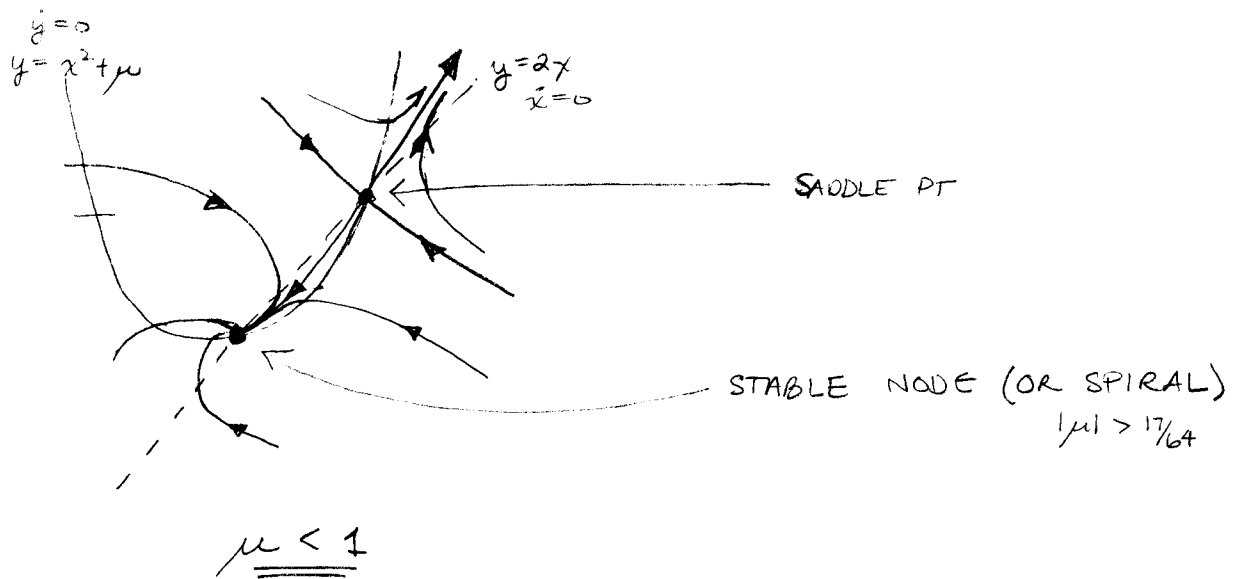
$\Rightarrow$ • ONE FIXED PT AT $\mu = 1$ ($x^* = 1, y^* = 2$).

• TWO FIXED PTS FOR $\mu < 1$.

• NO FIXED PTS FOR $\mu > 1$.

THERE IS A SADDLE-NODE BIFURCATION

AT $\mu_{\text{CRIT}} = 1$, $(x^*, y^*)_{\text{CRIT}} = (1, 2)$.



8.1.9

$$\ddot{x} + bx - kx + x^3 = 0$$

$$\begin{cases} \dot{x} = y \\ \dot{y} = -by - x^3 + kx \end{cases}$$

- FIXED PTS. $\dot{x} = 0, \dot{y} = 0$

$$\Rightarrow (x^*, y^*) = (0, 0), (\pm\sqrt{k}, 0)$$

ONLY EXIST IF $k > 0$.

* PITCHFORK BIF OCCURS AT $k=0, (0,0)$.

- STABILITY OF $(0,0), (\pm\sqrt{k}, 0)$

$$\det \begin{bmatrix} 0 - \lambda & 1 \\ -3x^2 + k & -b - \lambda \end{bmatrix} = 0$$

$$\lambda^2 + b\lambda - (k - 3x^2) = 0$$

$$\lambda = -\frac{b}{2} \pm \sqrt{\left(\frac{b}{2}\right)^2 + k - 3x^2}$$

$$(0,0) \Rightarrow \lambda = -\frac{b}{2} \pm \sqrt{\left(\frac{b}{2}\right)^2 + k}$$

- IF $k > 0$, THEN $\lambda_1 < 0 < \lambda_2$ AND $(0,0)$ IS A SADDLE PT.

- IF $k < 0$, THEN

(i) IF $|k| < \left(\frac{b}{2}\right)^2$ THEN λ REAL.

$(0,0)$ IS A STABLE NODE

IF $b > 0$, AND AN UNSTABLE NODE

IF $b < 0$.

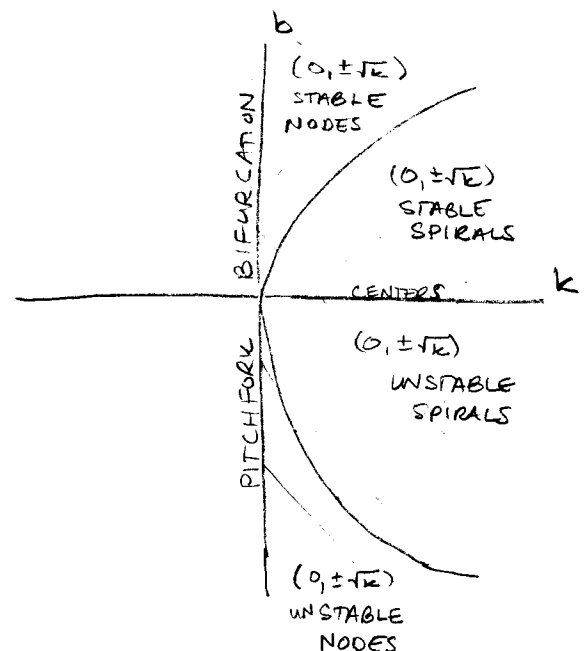
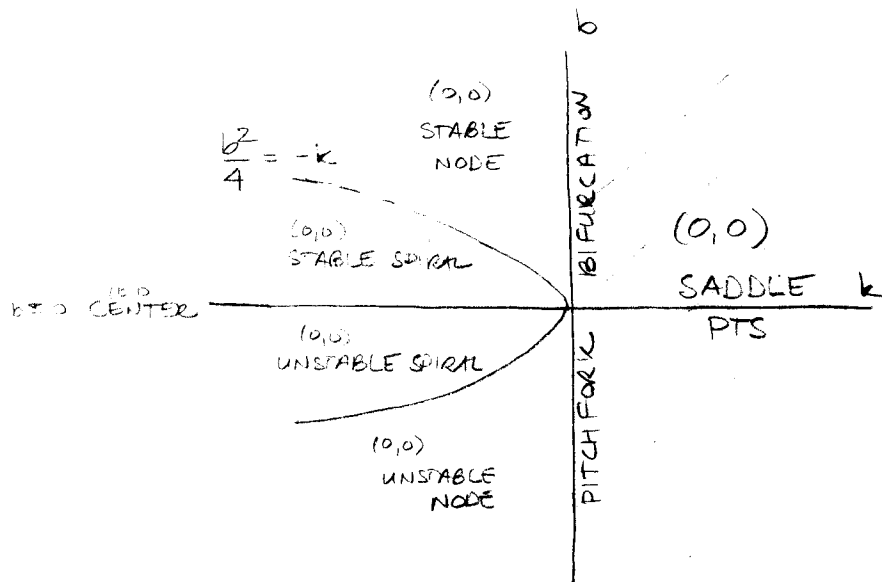
(ii) IF $|k| > (\frac{b}{2})^2$, THEN $\lambda \in \mathbb{C}$ w, $\text{Im}(\lambda) \neq 0$
AND $(0,0)$ IS A STABLE ($b > 0$) OR
UNSTABLE ($b < 0$) SPIRAL.

(iii) IF $b = 0$, THEN $(0,0)$ IS A (NON-LINEAR)
CENTER.

$$(0, \pm\sqrt{k}) \Rightarrow \lambda = -\frac{b}{2} \pm \sqrt{\left(\frac{b}{2}\right)^2 - 2k}$$

$k > 0$, (i) $(\frac{b}{2})^2 > 2k$, $(0, \pm\sqrt{k})$ ARE
STABLE NODES IF $b > 0$ OR
UNSTABLE NODES IF $b < 0$.

(ii) $(\frac{b}{2})^2 < 2k$, $(0, \pm\sqrt{k})$ ARE
STABLE SPIRALS IF $b > 0$ OR
UNSTABLE SPIRALS IF $b < 0$.



8.2.1

$$\ddot{x} + \mu(x^2 - 1)\dot{x} + x = a$$

$$\begin{cases} \dot{x} = y \\ \dot{y} = -\mu(x^2 - 1)y - x + a \end{cases}$$

UNIQUE

• FIXED PT $y^* = 0, x^* = a.$

• STABILITY

$$\det \begin{bmatrix} -\lambda & 1 \\ -\mu a x^* y^* - 1 & -\mu(x^{*2} - 1) - 1 \end{bmatrix} = 0$$

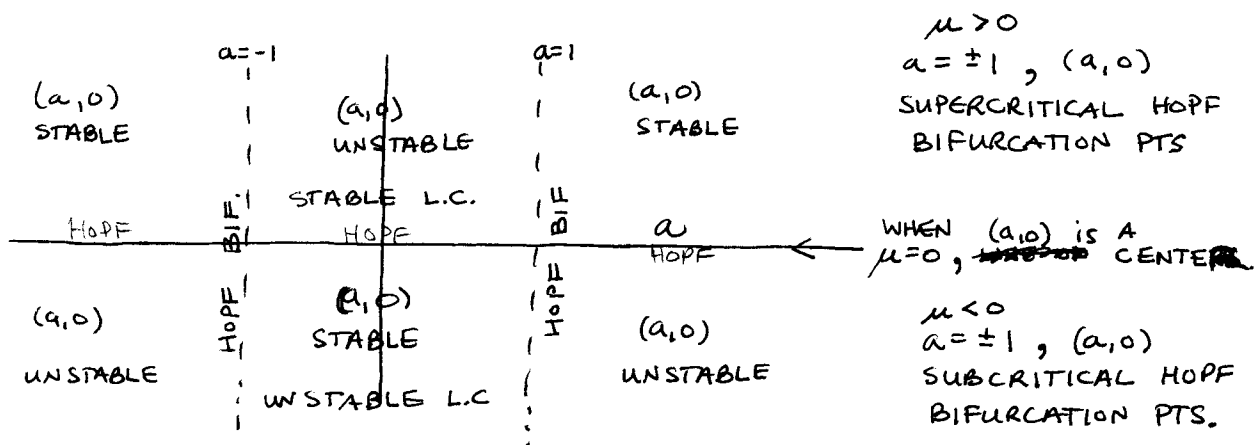
$x^* = a$
 $y^* = 0$

$$\lambda^2 + \mu(a^2 - 1)\lambda + 1 = 0$$

$$\lambda = \frac{-\mu(a^2 - 1)}{2} \pm \sqrt{\frac{\mu^2(a^2 - 1)^2}{4} + 1}$$

HOPF BIFURCATION WHEN $\text{Re}(\lambda) = 0$

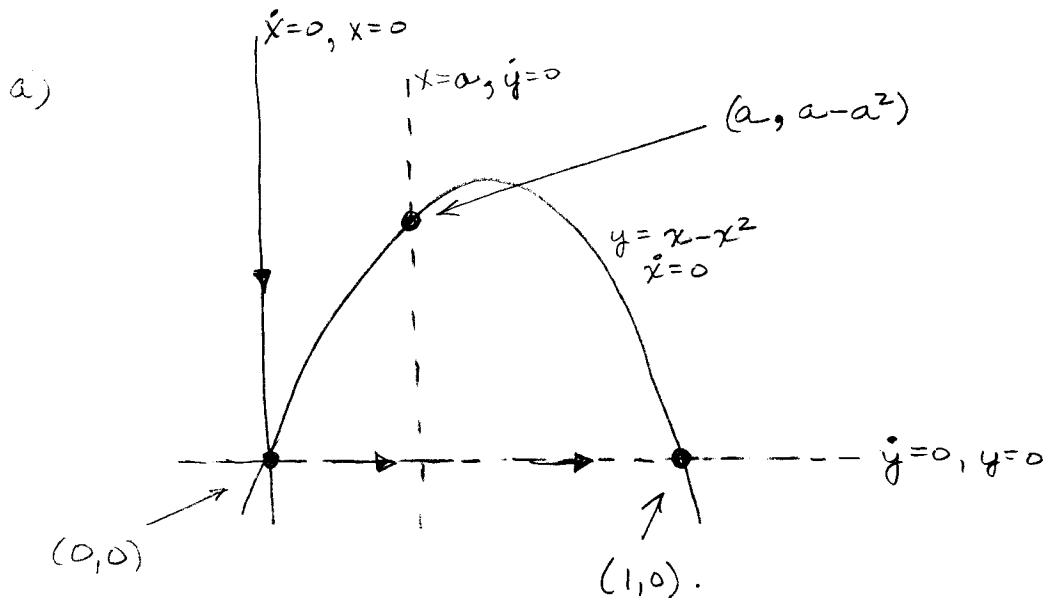
ie. $-\mu(a^2 - 1) = 0$ WHERE $\lambda = \pm i$.



8.2.8

$$\begin{aligned}\dot{x} &= x[x(1-x) - y] = x^2 - x^3 - xy \\ \dot{y} &= y(x-a) = yx - ya\end{aligned}$$

$$x \geq 0, y \geq 0, a > 0.$$



c) $\det \begin{bmatrix} 2x^* - 3x^{*2} - y^* - \lambda & -x^* \\ y^* & (x^* - a) - \lambda \end{bmatrix} = 0$

$$(0,0) : \lambda^2 + \lambda a = 0 \quad \lambda = 0, -a$$

by examining phase plane, SADDLE-NODE

$$(1,0) : \lambda = -1, \lambda = 1-a$$

For $0 < a < 1$, SADDLE POINT

For $a > 1$, STABLE NODE

For $a = 1$, SADDLE-NODE

$$(a, a-a^2) : \lambda^2 - (a-2a^2)\lambda + a^2(1-a) = 0$$

$$\lambda = \pm \frac{a(1-2a)}{2} \pm \sqrt{\left(\frac{a(1-2a)}{2}\right)^2 - a^2(1-a)}$$

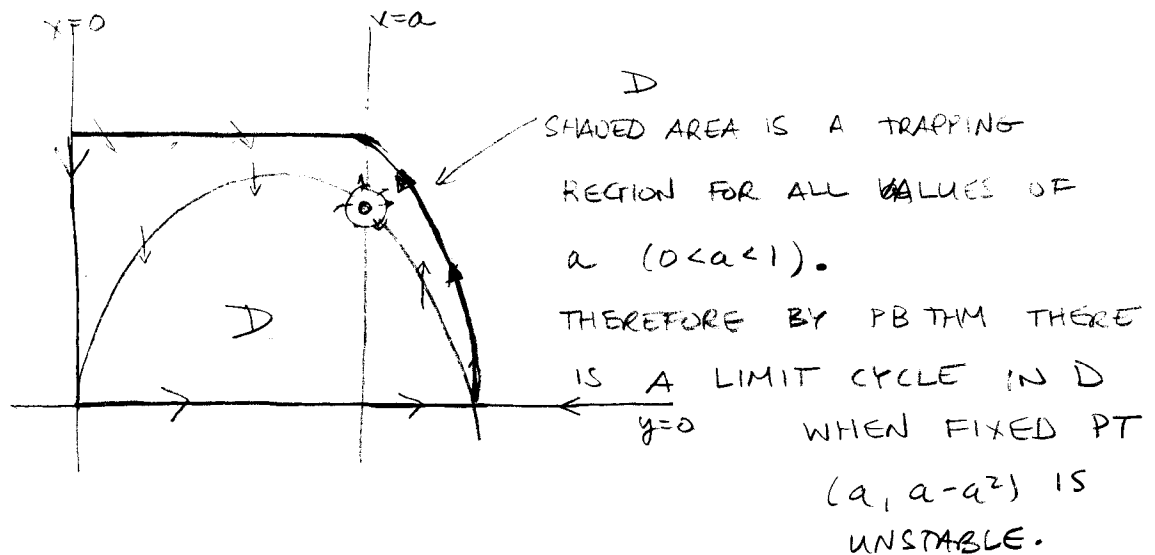
$$\lambda = a \left[\frac{(1-2a)}{2} \pm \sqrt{\frac{-3+4a^2}{2}} \right]$$

FOR $0 < a < \frac{1}{2}$, STABLE SPIRAL

FOR $\frac{1}{2} < a < \sqrt{3}/4$, UNSTABLE SPIRAL.

FOR $\sqrt{3}/4 < a < 1$, UNSTABLE NODE

- d) HOPF BIF OCCUR AT $(a, a-a^2)$ WHEN
 $a = \frac{1}{2}$ i.e. WHEN $\text{Re}(\lambda) = 0$, $\text{Im}(\lambda) \neq 0$.
 i.e. $a_{\text{CRIT, HB}} = \frac{1}{2}$, $(x^*, y^*) = (\frac{1}{2}, \frac{1}{4})$.

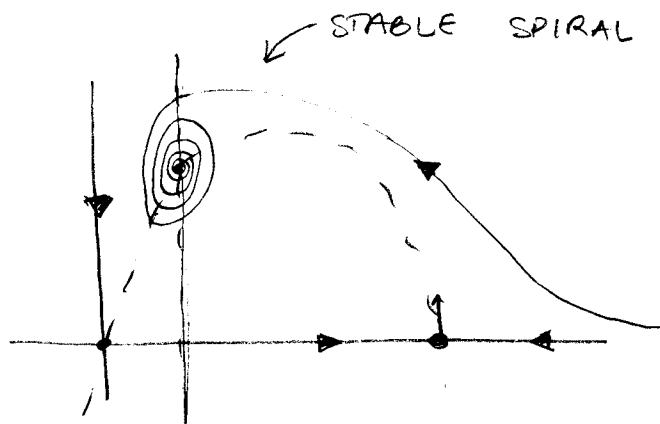


THIS SUGGEST A
 SUPERCRITICAL HOPF
 BIF. OCCURS AT $a_{\text{CRIT}} = \frac{1}{2}$.

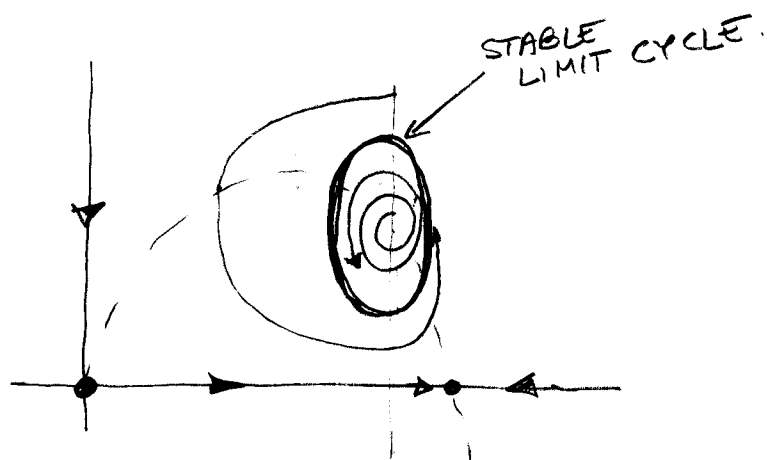
- e) freq. of LIMIT CYCLE CLOSED TO BIF PT

$$\text{IS } f \approx \frac{2\pi}{|\text{Im}(\lambda(a=\frac{1}{2}))|} = \frac{2\pi}{\frac{1}{\sqrt{2}}} = \sqrt{2} \pi$$

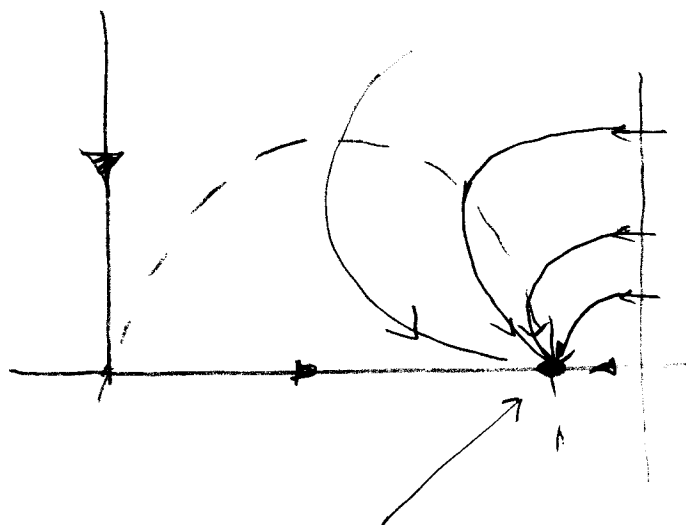
f) $0 < a < \frac{1}{2}$



$\frac{1}{2} < a < 1$



$a > 1$



(1, 0) IS A STABLE NODE

AND IS GLOBALLY ATTRACTING IN $x, y > 0$

ie. PREDATORS ALWAYS DIE OUT!